Machine Learning

4771

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01:11:00

Topic 13

- Expectation Maximization as Bound Maximization
- EM for Maximum A Posteriori

Step1.
Max likelihood

$l(\theta)=\prod_{n=1}^{N} \log p(X_n|\theta) \Rightarrow \log l(\theta) = \sum_{n=1}^{N}\sum_{z} \log p(X_n|\theta) = \sum_{n=1}^{N}\sum_{z} \log p(X_n,z|\theta)\frac{p(z|X_n,\theta_t)}{p(z|X_n,\theta_t)} = \sum_{n=1}^{N}\sum_{z} \log p(z|X_n,\theta_t)\frac{p(X_n,z|\theta)}{p(z|X_n,\theta_t)}$

$\sum_z p(X_n,z|\theta)=1,\ p(X_n,z|\theta) \to = T_{n,k}$ probability of X_n belongs to z.

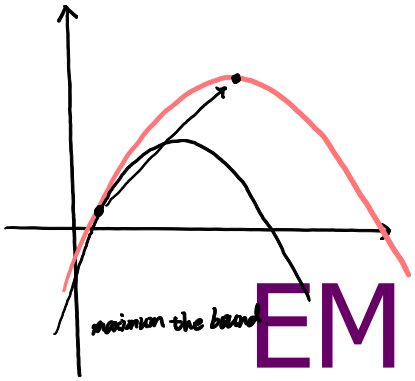
$\geq \sum_{n=1}^{N}\sum_{z} T_{n,z} \log p(X_n,z|\theta) - \sum_{n=1}^{N}\sum_{z} T_{n,z} \log p(z|X_n,\theta_t) = Q(\theta|\theta_t) - \text{const.}$ [Not related to θ]

Step2.

$\theta^{t+1} = \arg\max_{\theta} Q(\theta|\theta_t) \Rightarrow \frac{\partial Q(\theta)}{\partial \vec{u}_k} = \sum_{n=1}^{N}\sum_{z} T_{n,k} \frac{\partial \log p(X_n,z|\theta)}{\partial u_k} = \sum_{n=1}^{N}\sum_{z} T_{n,z} \frac{\partial \left(\log \pi_k + \sum_{n=1}^{N}\sum_{z} T_{n,k} \cdot N(\vec{x}_n|\vec{u}_k,\Sigma_k)\right)}{\partial u_1}$

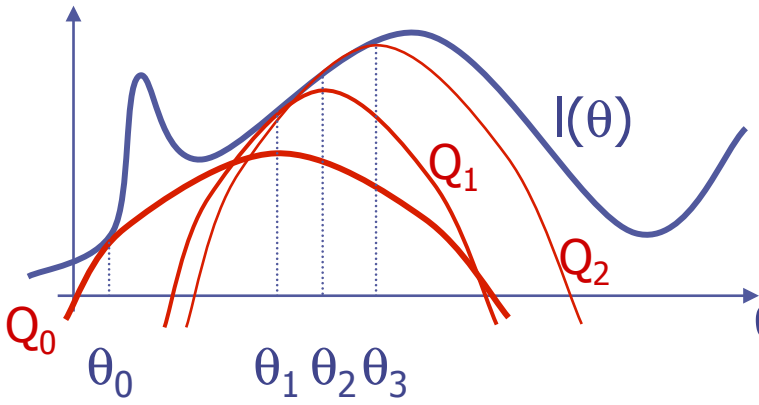
$= \sum_{n=1}^{N} T_{n,k}\left\{-\frac{1}{2}(\vec{x}_n-\vec{u}_k)^T\Sigma_k^{-1}(\vec{x}_n-\vec{u}_k)\right\}$

$\Rightarrow \frac{\partial Q(\theta)}{\partial \Sigma_k} \Rightarrow \frac{\partial Q(\theta)}{\partial \pi}$



EM as Bound Maximization

- Let's now show that EM indeed maximizes likelihood
- Bound Maximization: optimize a lower bound on $l(\theta)$
- Since log-likelihood $l(\theta)$ not concave, can't max it directly
- Consider an auxiliary function $Q(\theta)$ which is concave
- $Q(\theta)$ kisses $l(\theta)$ at a point and is less than it elsewhere



$$l(\theta) \geq Q_t(\theta) \quad \forall\theta \; \forall t$$

$$l(\theta_t) = Q_t(\theta_t)$$

Q_t kissing l(θ) at point θ_t

$$\theta_{t+1} = \arg\max_\theta Q_t(\theta_t)$$

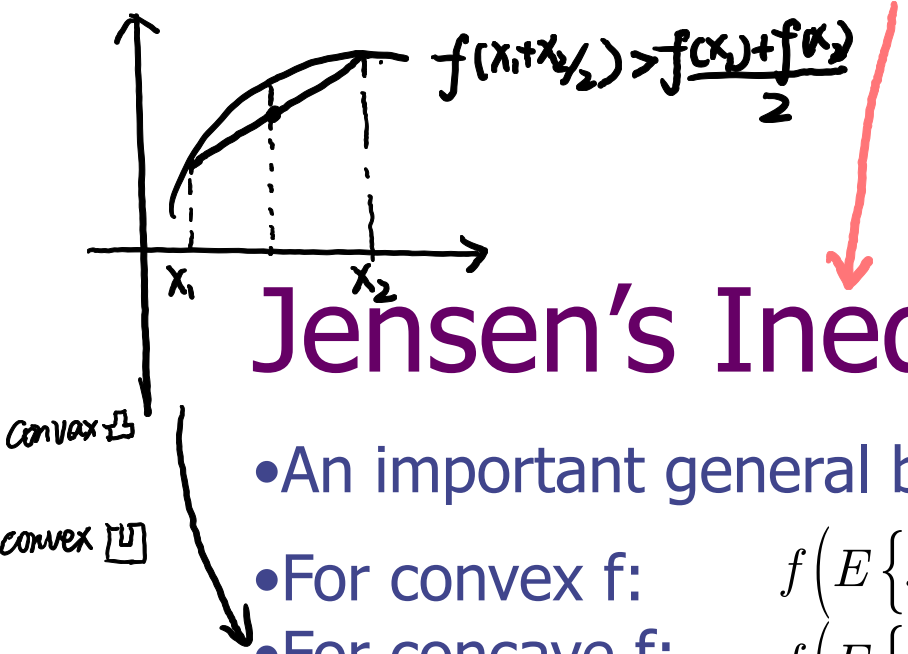
$$Q_t(\theta_{t+1}) > Q_t(\theta_t)$$

$$l(\theta_{t+1}) \geq Q_t(\theta_{t+1}) > Q_t(\theta_t)$$

$$l(\theta_{t+1}) > l(\theta_t)$$

- Monotonically increases log-likelihood
- But how to find a bound and guarantee we max it?

Jensen's Inequality

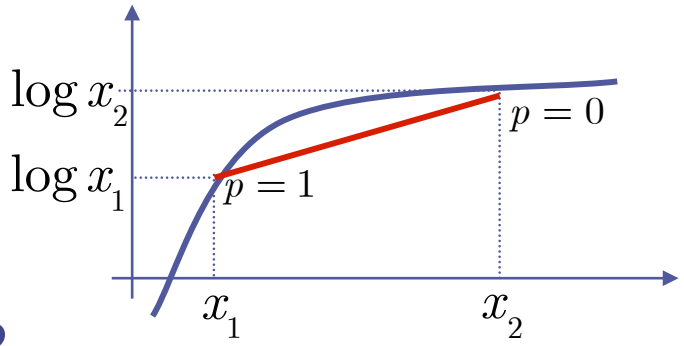


Tony Jebara, Columbia University

Jensen's Inequality

- An important general bound from Jensen (1906)
- For convex f: $f\left(E\left\{x\right\}\right) \le E\left\{f\left(x\right)\right\}$
- For concave f: $f\left(E\left\{x\right\}\right) \ge E\left\{f\left(x\right)\right\}$
- Expectation in discrete case is sum weight by probability
- For convex f: $f\left(\sum_{i=1}^{M} p_i x_i\right) \le \sum_{i=1}^{M} p_i f\left(x_i\right) \;\; when \;\; \sum_{i=1}^{M} p_i = 1, \;\; p_i \ge 0$
- For concave f: $f\left(\sum_{i=1}^{M} p_i x_i\right) \ge \sum_{i=1}^{M} p_i f\left(x_i\right) \;\; when \;\; \sum_{i=1}^{M} p_i = 1, \;\; p_i \ge 0$
- Example: f(x)=log(x)=concave and M=2

$$\log\left(p x_1 + \left(1-p\right) x_2\right) \ge p \log x_1 + \left(1-p\right) \log x_2$$



- Bound log(sum) with sum(log)
- How to apply this to mixture models?

Expectation-Maximization

$$l(\theta) = \sum_{n=1}^{N} \log p(x_n \mid \theta)$$

Original Log-Likelihood

$$= \sum_{n=1}^{N} \log \sum_z p(x_n, z \mid \theta)$$

Has Hidden Variables (messy)

$$= \sum_{n=1}^{N} \log \sum_z p(x_n, z \mid \theta) \left[\frac{p(z \mid x_n, \theta_t)}{p(z \mid x_n, \theta_t)} = 1 \right]$$

Multiply by 1
Ratio of hidden posterior density

function = log( )

$f(\sum_i p_i x_i) \geq \sum_i p_i f(x_i)$

$$= \sum_{n=1}^{N} \log \sum_z p(z \mid x_n, \theta_t) \frac{p(x_n, z \mid \theta)}{p(z \mid x_n, \theta_t)}$$

Rearrange

$$\geq \sum_{n=1}^{N} \sum_z p(z \mid x_n, \theta_t) \log \frac{p(x_n, z \mid \theta)}{p(z \mid x_n, \theta_t)}$$

Jensen $\log(\Sigma_i p_i x_i)$

$$= \sum_{n=1}^{N} \sum_z p(z \mid x_n, \theta_t) \log p(x_n, z \mid \theta)$$
$$- \sum_{n=1}^{N} \sum_z p(z \mid x_n, \theta_t) \log p(z \mid x_n, \theta_t)$$

New auxiliary function called Q (not messy)

$$= Q(\theta \mid \theta_t) - const$$

independent with θ. $\theta_t \neq \theta$

EM as Bound Maximization

- Now have the following bound and maximize it:

$$l(\theta) \geq Q(\theta \mid \theta_t) - \sum_{n=1}^{N} \sum_z p(z \mid x_n, \theta_t) \log p(z \mid x_n, \theta_t) \quad \text{(constant)}$$

$$\theta^{t+1} = \arg\max_\theta Q(\theta \mid \theta_t) = \arg\max_\theta \sum_{n=1}^{N} \sum_z p(z \mid x_n, \theta_t) \log p(x_n, z \mid \theta) = Q(\theta|\theta_t)$$

$$= \arg\max_\theta \sum_{n=1}^{N} \sum_z \tau_{n,z} \log p(x_n, z \mid \theta) \qquad \tau_{n,z} = p(z = \delta_z \mid x_n, \theta_t)$$

- $Q(\theta|\theta_t)$ is called Auxiliary Function... take derivatives of it
- This is easy for e-families... just weighted max likelihood!
- For example, Gaussian mixture:

$$\log p(x_n, z|\theta) \quad \log p(\vec{x}_n|\theta) \cdot p(z=\delta_k|\vec{x}_n) \quad = \log \pi_k \cdot N(\vec{x}_n|\vec{\mu}_k, \Sigma)$$

$$\frac{\partial Q(\theta)}{\partial \vec{\mu}_k} = \frac{\partial}{\partial \vec{\mu}_k} \sum_{n=1}^{N} \sum_k \tau_{n,k} \log \pi_k N(\vec{x}_n \mid \vec{\mu}_k, \Sigma_k) =$$

Derivative to μ_k, only parameters in k class will be left

$$0 = \sum_{n=1}^{N} \tau_{n,k} \frac{\partial}{\partial \vec{\mu}_k} \left(-\frac{1}{2} (\vec{x}_n - \vec{\mu}_k)^T \Sigma_k^{-1} (\vec{x}_n - \vec{\mu}_k) \right)$$

$$\vec{\mu}_k = \frac{\sum_{n=1}^{N} \tau_{n,k} \vec{x}_n}{\sum_{n=1}^{N} \tau_{n,k}}$$

... similarly get π_k and Σ_k

EM as Expected Log-Likelihood

- Incomplete Log-Likelihood
- Complete Log-Likelihood

$$l(\theta) = \log p(observed \mid \theta) = \sum_{n=1}^{N} \log \sum_{z} p(x_n, z \mid \theta)$$

$$l^C(\theta) = \log p(observed, hidden \mid \theta) = \sum_{n=1}^{N} \log p(x_n, z_n \mid \theta)$$

- We don't know the hidden variables z
- EM computes expected values of hidden z under current θ_t
- EM chooses Q to be the Expected Complete Log-Likelihood

$$\begin{aligned}
E\{l^C(\theta)\} &= \sum_{hidden} p(hidden \mid observed, \theta_t) l^C(\theta) \\
&= \sum_{z_1} \cdots \sum_{z_N} p(z_1, \ldots, z_n \mid x_1, \ldots, x_n, \theta_t) l^C(\theta) \\
&= \sum_{z_1} \cdots \sum_{z_N} \prod_n p(z_n \mid x_n, \theta_t) l^C(\theta) \\
&= \sum_{z_1} \cdots \sum_{z_N} \prod_n p(z_n \mid x_n, \theta_t) \sum_n \log p(x_n, z_n \mid \theta) \\
&= \sum_n \sum_{z_n} p(z_n \mid x_n, \theta_t) \log p(x_n, z_n \mid \theta) \sum_{z_1} \cdots \sum_{z_{i \neq n}} \cdots \sum_{z_N} \prod_{i \neq n} p(z_i \mid x_i, \theta_t) \\
&= \sum_n \sum_{z_n} p(z_n \mid x_n, \theta_t) \log p(x_n, z_n \mid \theta) = Q(\theta \mid \theta_t)
\end{aligned}$$

EM for Max A Posteriori

- We can also do MAP instead of ML with EM (stabilizes sol'n)

$$\log posterior\left(\theta\right) = \sum_{n=1}^{N} \log \sum_{z} p\left(x_n, z \mid \theta\right) + \log p\left(\theta\right)$$

- Prior doesn't have log-sum
- The E-step remains the same: lower bound log-sum

$$\log posterior\left(\theta\right) = l\left(\theta\right) + \log p\left(\theta\right) \geq E\left\{l^C\left(\theta\right)\right\} + const + \log p\left(\theta\right)$$

- The M-step becomes slightly different for each model
- For example, mixture of Gaussians with prior on covariance

$$\log posterior\left(\theta\right) = \sum_{n=1}^{N} \log \sum_{k} \pi_k N\left(\vec{x}_n \mid \vec{\mu}_k, \Sigma_k\right) + \log \prod_{k} p\left(\Sigma_k \mid S, \eta\right)$$

$$\log posterior\left(\theta\right) \geq \sum_{n=1}^{N} \sum_{k} \tau_{n,k} \log \pi_k N\left(\vec{x}_n \mid \vec{\mu}_k, \Sigma_k\right) + \sum_{k} \log p\left(\Sigma_k \mid S, \eta\right) + const$$

- Updates on π and μ stay the same, only Σ is:

$$\Sigma_k \leftarrow \frac{1}{\sum_{n=1}^{N} \tau_{n,k} + \eta}\left(\sum_{n=1}^{N} \tau_{n,k}\left(\vec{x}_n - \vec{\mu}_k\right)\left(\vec{x}_n - \vec{\mu}_k\right)^T + \eta S\right)$$

- Typically, we use the identity matrix I for S and a small eta.