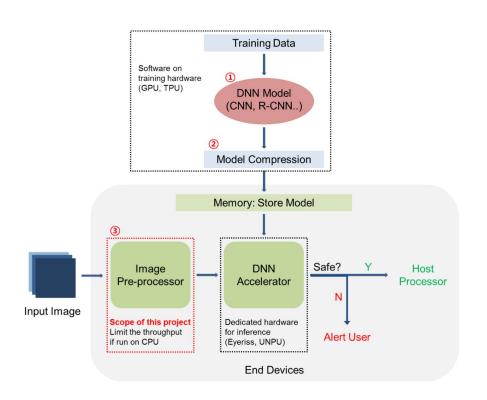
Massachusetts Institute of Technology 6.374 Final Project

Image Pre-processor for Robust Deep Neural Network Inference Hardware

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Motivation and Background



Three possible ways to achieve robust DNN:

- 1 Train DNN model itself
- 2 Model compression
- ③ Image preprocessor (Scope of this project)

Model Overview

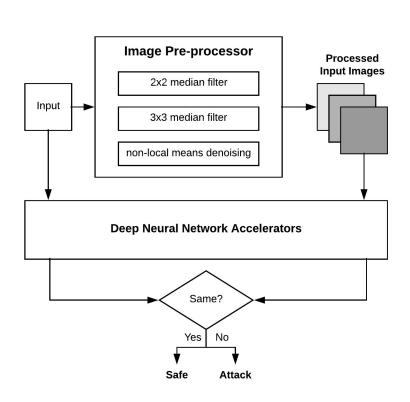
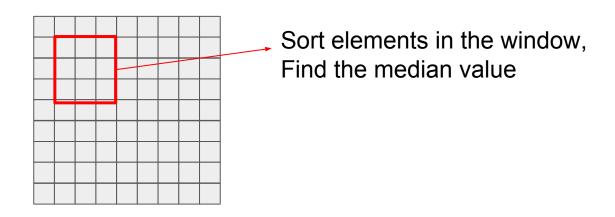
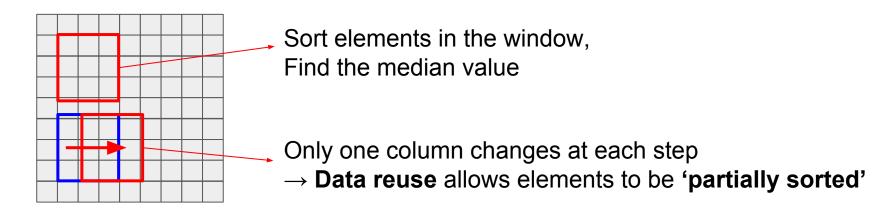
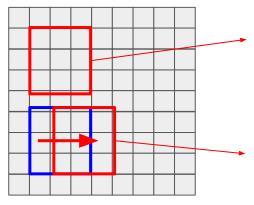


Image pre-processor includes:

- 2x2 median filter
- 3x3 median filter
- Non-Local means denoising
 - conventional NL-means denoising
 - optimized NL-means denoising







Sort elements in the window, Find the median value

Only one column changes at each step

- → Data reuse allows elements to be 'partially sorted'
 - 1. Sort the **new** column (i.e. 3 pixels)
 - 2. **Find median** value with 6 pixels (sorted from the previous window) and the sorted 3 new pixels
 - 3. Prepare sorted 6 pixels for the **next** cycle

Reduce Computation

- Data reuse
 partially sorted array can be easily sorted with selection sort
- finding median and preparing partially sorted array for the next cycle do not require sorting of all elements in the window

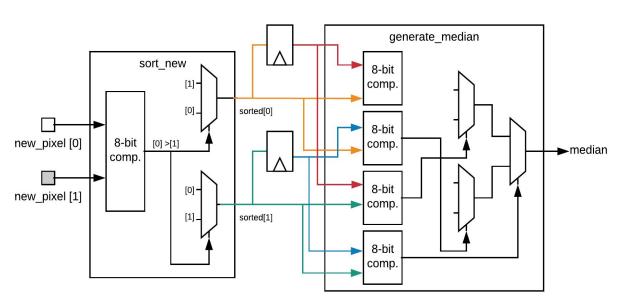
Reduced reconfigurability

Increase Throughput

- Unroll operations in sorting sequential sorting operations to unrolled comparisons and mux-trees
- Pipelining
 prepare data for the next cycle while finding the median for the current window

Increased combinational logics, Careful timing control @ edges

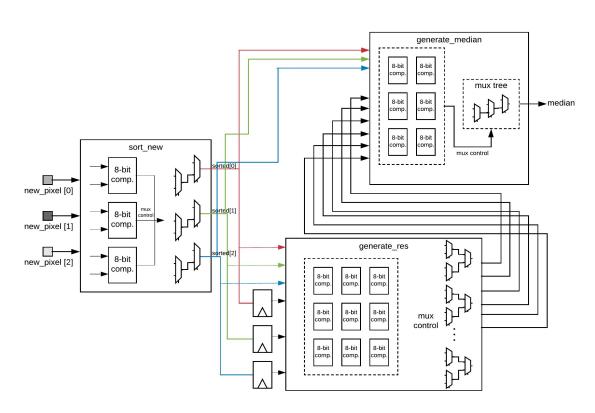
2x2 Median Filter



Two submodules:

- sort_new:
 - 1 comparison, 2 mux
- generate_median:
 - 4 comparison, 3 mux

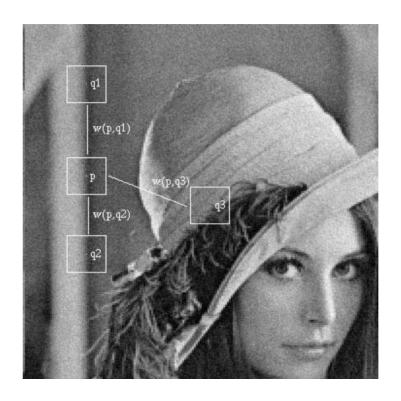
3x3 Median Filter



Three submodules:

- sort_new
 - 3 comparison, 6 mux
- generate_res
 - 9 comparison, 18 mux
- generate_median
 - 6 comparison, 6 mux

Non-local Means Denoising



 Pixel denoising: weighting average of all pixels in the image

$$NL[v](i) = \sum_{j \in I} w(i, j)v(j)$$

 Weight: depend on the similarity between pixels i and i

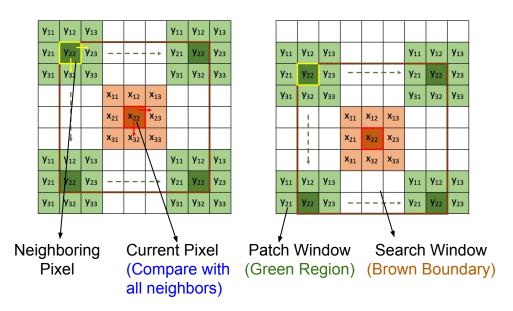
$$w(i,j) = \frac{1}{Z(i)} e^{-\frac{\|v(\mathcal{N}_i) - v(\mathcal{N}_j)\|_{2,a}^2}{h^2}}$$

Normalizing Constant

$$Z(i) = \sum_{j} e^{-\frac{\|v(\mathcal{N}_{i}) - v(\mathcal{N}_{j})\|_{2,a}^{2}}{h^{2}}}$$

Non-local Means Denoising

Conventional Method:



For each comparable patch window: 9-pixel pairs' distances

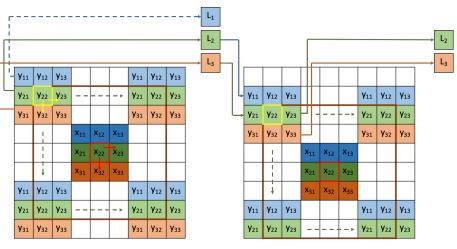
Denoising one pixel: calculate 3x3x7x7 distances

Non-local Means Denoising

Conventional Method:

y₁₂ | y₁₃ y₁₁ | y₁₂ | y₁₃ **y**₁₁ **Y**21 y₁₂ y₁₃ y₁₁ y₁₂ y₃₃ **y**₃₁ V₃₁ V₃₂ V₃₃ Y₂₂ Y₂₃ y₂₁ y₂₂ X₁₂ | X₁₃ **y**₃₁ y₃₂ y₃₃ y₃₁ y₃₂ y₃₃ X₁₁ X₁₂ x₃₂\ x₃₃ V₁₂ V₁₃ y₁₂ y₁₃ X₃₂ **Y**₁₁ y₁₁ y₁₁ y₁₂ y₁₃ **y**₂₁ Y₁₂ Y₁₃ Y₃₂ Y₃₃ y₃₁ | y₃₂ | y₃₃ Y₂₁ Y₂₂ Neighboring **Current Pixel** Patch Window Search Window Pixel (Compare with (Green Region) (Brown Boundary) all neighbors)

• Optimized Method:

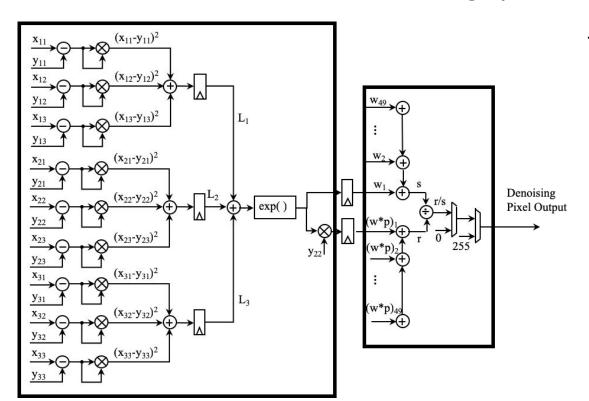


For each comparable patch window: 9-pixel pairs' distances Denoising one pixel: calculate 3x3x7x7 distances

Reuse Distances

For each comparable patch window: 3-pixel pairs' distances Denoising one pixel: calculate 3x7x7 distances

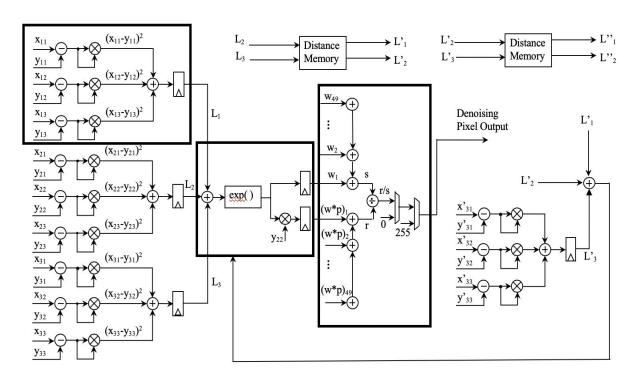
Non-local Means Denoising (Conventional)



Two submodules:

- Weight Calculation for one patch window
- Weight Calculation for one search window and denoising for one pixel

Non-local Means Denoising (Optimized)



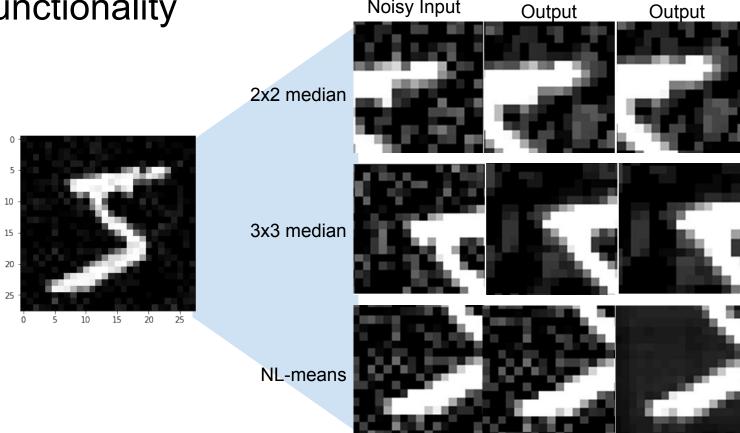
Three submodules:

- one row in patch
- one patch
- one search & one pixel denoising

Two hardware Issues:

- Trade-offs
- exp. and div. units

Functionality

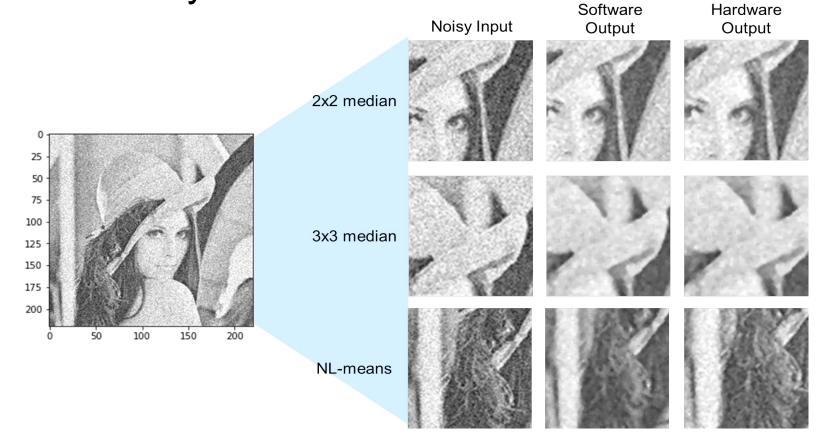


Noisy Input

Software

Hardware

Functionality



Simulation Results

	2x2 median	3x3 median	NL-means	NL-means opt		
Area (µm2)	1395.7	4478.6	41052	31391		
MNIST Input (28x28), Operation @ 50MHz, 1.2V						
Energy (nJ per image)	1.052	2.653	376.315	286.627		
Energy with memory (nJ per image)	14.938	20.608	445.52	801.749		
# of cycles	868	896	41552	40234		
Speedup	22.47	25.28	7.06	9.26		
ImageNet Size Input (3x220x220), Operation @ 50MHz, 1.2V						
Energy (nJ per image)	178.41	417.57	68615.52	54135.46		
Energy with memory (nJ per image)	2879.91	4046.4	70143.2	133150.6		
# of cycles	147180	147840	2510320	2506880		
Throughput	339 images	338 images	13 images	13 images		
Speedup	2.8	7.79	9.41	10.08		

Median Filter: Voltage Scaling Simulation

Voltage Scaling Simulation							
	Freq (MHz)	Lowest Vdd (V)	Computational Energy (nJ per image)	Throughput			
2x2 Median Filter	10	0.35	10.199574	67.94401413			
	50	0.38	14.9888112	339.7200707			
	100	0.45	21.7038987	679.4401413			
	200	0.5	24.041853	1358.880283			
3x3 Median Filter	10	0.35	21.422016	67.64069264			
	50	0.41	39.48422016	338.2034632			
	100	0.5	53.85072	676.4069264			
	200	0.57	71.73236763	1352.813853			

Non-local Means: Architecture Comparison

Comparison of three different NL-means architectures

- 18-pixel input conventional NL-means architecture
- 2 6-pixel input conventional NL-means architecture
- 3 6-pixel input optimized NL-means architecture

Evaluation	1	2	3	Compare
Area (µm2)	41052	29149	31391	1 < 3 < 2
Energy without memory (nJ)	376.32	361.2	286.6	1 < 2 < 3
Energy with memory (nJ)	442.52	892.1	801.71	2 < 3 < 1
# of cycles	41552	121664	40234	2<1<3
speed up	7.06	2.41	9.26	2<1<3

Conclusion and Contribution

Conclusion

- Hardware implementation of 2x2 median filter, 3x3 median filter and NL-means denoising
- Design choices for improved throughput and reduced computation

Contribution

- Effective implementation of median filters with data reuse and unrolled sorting operations
- Energy and resource aware implementation of NL-means denoising with weight reuse, and approximation on expensive calculations.
- Explore diverse trade-offs in designing the image-preprocessor with voltage scaling analysis and architecture comparisons.

Future work

- Efficient I/O design:
 Streaming instead of SRAM to reduce read/write power and area overhead
- Approximation of NL-means instead of exact calculation:
 Effect on detecting adversarial attacks
- Application of the image pre-processor in other domains:
 ex) NL algorithms are widely used for texture synthesis

Thank you!

.... Questions?

