Lab 1. Cross Development Environment

1. Purpose

- Set up Ubuntu environment on PC and Debian on Beaglebone
- Construct a cross-development system on PC, cross complete some programs and run it.
- Construct a module program development environment on a PC, cross compile embedded module program and run it.
- Set up NFS between PC and Beaglebone

2. Experiment sequence and Experimental results

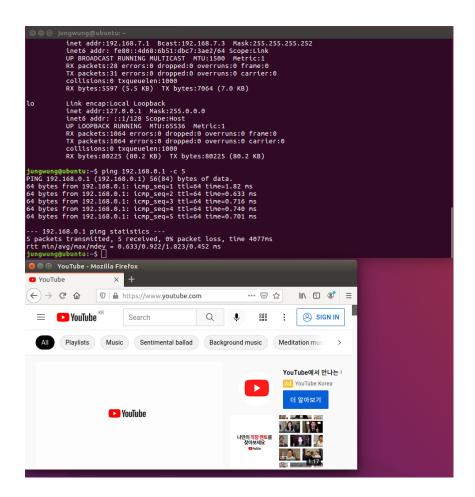
Step 1. Test operation of development PC with Ubuntu

Check the kernel version of Ubuntu 16.04 and network connection.

```
jungwung@ubuntu:~$ uname -r
4.15.0-112-generic
```

The kernel version of Ubuntu 16.04 is 4.15.0-112-generic.

IP address is 192.168.0.13.



Ping 192.168.0.1 and firefox web browser also worked well.

Step 2. Install Beaglebone Debian on microSD

Download proven Debian OS image.

Unpack the file and Check size using the commands.

\$ cd ~/Downloads

\$ unxz -k bone-debian-7.9-lxde-4gb-armhf-2015-11-12-4gb.img.xz

\$ ls -la

size of files, sha256 match with the provided Lab1 supplement pdf data.

Write Debian image to uSD.

```
<mark>yeolia@ubuntu:~$</mark> df
Filesystem 1K-blocks
                                                  Used Available Use% Mounted on
                                                              1977436 0% /dev
390212 3% /run
7080480 62% /
udev
                            1977436
                                                    0
                                                            1977436
tmpfs
/dev/sda1
                              401592
                                                11380
                           19525500 11430136
                                                             7080480 62% /
1950552 3% /dev/shm
5116 1% /run/lock
2007952 0% /sys/fs/cgroup
401464 1% /run/user/1000
1147812 63% /media/yeolia/rootfs
67734 31% /media/yeolia/BEAGLEBONE
tmpfs
                            2007952
                                               57400
                                                  4
tmpfs
                                5120
tmpfs
                             2007952
tmpfs
/dev/sdb2
/dev/sdb1
                                                   128
                              401592
                             3263536 1930228
                                98094
                                                30360
```

The device name of microSD is /dev/sdb, which contains two partitions.

```
yeolla@ubuntu:-S unount /dev/sdb1
yeolla@ubuntu:-S unount /dev/sdb2
yeolla@ubuntu:-S undo fdisk /dev/sdb

Melcome to fdisk (util·linux 2.27.1).
Changes will remain in memory only, until you decide to write them.
Be careful before using the write command.

Command (m for help): d
Partition number (1,2, default 2): 1
Partition 1 has been deleted.

Command (m for help): d
Selected partition 2
Partition 2 has been deleted.

Command (m for help): d
Selected partition 2
Partition 2 has been deleted.

Command (m for help): w

The partition is delived yeti
could not delete partition 1

Command (m for help): w

The partition is delived yeti
could not delete partition 1

Command (m for help): w

The partition table has been altered.
Calling loct() to re-read partition table.
Syncing disks.

yeolla@ubuntu:-S sudo mkfs.ext3 /dev/sdb
mko2fd.i.42.13 (17 hay-2015) in /dev/sdb
Froceed anyway? (y, n)

reating filesystem with 957440 4k blocks and 239520 inodes
Filesystem UUID: cf99c69d-fbic-4a48-81e2-490277b4eea1

Superblock backups stored on blocks:

32768, 98304, 163840, 229376, 294912, 819200, 884736

Allocating group tables: done

Kriting superblock backups stored on blocks:

32768, 98304, 163840, 229376, 294912, 819200, 884736

Allocating group tables: done

Kriting superblock and filesystem accounting information: done

yeolla@ubuntu:-S sudo dd ff=./Downloads/bone-deblan-7.9-lxde-4gb-armhf-2015-11-12-4gb.ing of=/dev/sdb status=progress
3304388472 bytes (3.6 GB, 3.3 GIB) copled, 3550 s, 1.0 MB/s
696320049 records out
3505158400 bytes (3.6 GB, 3.3 GIB) copled, 3555.47 s, 1.0 MB/s
```

cleaned original usb data and made a new partition using above commands.

Connect Beaglebone on PC.





Beaglebone is connected with 5V adapter, USB connection between computer, and LAN connection with local router.

Prepare PC for Bone console.

Type the command "\$ sudo minicom -s -w".

Select "Serial port setup" and change Serial Device to "/dev/ttyACM0".

Select "Save setup as dfl" and "Configuration saved".

Start Beaglebone and login as user "debian" with password "temppwd".

```
beaglebone login: debian
Password:
Last login: Thu Nov 12 19:10:10 UTC 2015 on ttyGS0
Linux beaglebone 3.8.13-bone79 #1 SMP Tue Oct 13 20:44:55 UTC 2015 armv7l
The programs included with the Debian GNU/Linux system are free software; the exact distribution terms for each program are described in the individual files in /usr/share/doc/*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent permitted by applicable law.
```

Check Beaglebone Debian kernel version.

```
debian@beaglebone:~$ uname -r
3.8.13-bone79
```

Add superuser, become superuser, and see the directory "/root" using the commands.

```
debian@beaglebone:-$ sudo passwd root
Enter new UNIX password:
Retype new UNIX password:
passwd: password updated successfully
debian@beaglebone:-$ su
Password:
root@beaglebone:/home/debian# ls -la /root
total 32
drwx----- 5 root root 4096 Nov 12 2015 .
drwxr-xr-x 22 root root 4096 Nov 12 2015 .
-rw----- 1 root root 252 Nov 12 2015 .bash_history
-rw-r--r-- 1 root root 570 Jan 31 2010 .bashrc
drwxr-xr-x 8 root root 4096 Nov 12 2015 .c9
drwxr-xr-x 3 root root 4096 Nov 12 2015 .cache
drwxr-xr-x 3 root root 4096 Nov 12 2015 .cache
drwxr-xr-x 3 root root 4096 Nov 12 2015 .node-gyp
-rw-r--r-- 1 root root 140 Nov 19 2007 .profile
```

Add user, check "/home" directory, and exit.

```
root@beaglebone:/home/debian# adduser jungwungpark
Adding user `jungwungpark' ...
Adding new group `jungwungpark' (1002) ...
Adding new user `jungwungpark' (1002) with group `jungwungpark' ...
Creating home directory '/home/jungwungpark' ...
Copying files from '/etc/skel' ...
Enter new UNIX password:
Retype new UNIX password:
Retype new UNIX password:
passwd: password updated successfully
Changing the user information for jungwungpark
Enter the new value, or press ENTER for the default
Full Name []:
Room Number []:
Work Phone []:
Home Phone []:
Other []:

Is the information correct? [Y/n] Adding new user `jungwungpark' to extra groups ...
Adding user `jungwungpark' to group `dialout' ...
Adding user `jungwungpark' to group `jcc' ...
Adding user `jungwungpark' to group `cdrom' ...
Adding user `jungwungpark' to group `cdrom' ...
Adding user `jungwungpark' to group `cdrom' ...
Adding user `jungwungpark' to group `video' ...
Adding user `jungwungpark' to group `users' ...
root@beaglebone:/home/debian# su
root@beaglebone:/home/debian# su
root@beaglebone:/home/debian# adduser jungwungpark sudo
Adding user `jungwungpark' to group `sudo' ...
```

We can exit using the command "# exit". With command adduser jungwungpark sudo, we became superuser.

Login as user you just made.

```
Debian GNU/Linux 7 beaglebone ttyGS0

BeagleBoard.org Debian Image 2015-11-12

Support/FAQ: http://elinux.org/Beagleboard:BeagleBoneBlack_Debian

default username:password is [debian:temppwd]

The IP Address for usb0 is: 192.168.7.2

beaglebone login: jungwungpark
Password:
Linux beaglebone 3.8.13-bone79 #1 SMP Tue Oct 13 20:44:55 UTC 2015 armv7l

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
```

Check network.

The IP address is 192.168.0.12.

Use remote login.

```
jungwung@ubuntu:~$ ssh jungwungpark@192.168.0.12
Debian GNU/Linux 7

BeagleBoard.org Debian Image 2015-11-12

Support/FAQ: http://elinux.org/Beagleboard:BeagleBoneBlack_Debian
default username:password is [debian:temppwd]
jungwungpark@192.168.0.12's password:
Last looin: Thu Seo 16 14:55:13 2021 from ubuntu.local
```

Update package.

```
jungwungpark@beaglebone:-$ sudo apt-get update
[sudo] password for jungwungpark:
Get:1 http://repos.rcn-ee.com wheezy Release.gpg
Ign http://security.debian.org wheezyyRelease.gpg
Ign http://security.debian.org wheezyyRelease.gpg
Get:2 http://repos.rcn-ee.com wheezy Release.gpg
Get:2 http://repos.rcn-ee.com wheezy Release.gpg
Ign http://ftp.us.debian.org wheezyyupdates Release.gpg
Ign http://security.debian.org wheezyyupdates Release
Ign http://ftp.us.debian.org wheezy/updates Release
Ign http://ftp.us.debian.org wheezy/updates Release
Get:3 http://repos.rcn-ee.com wheezy/main armhf Packages
Get:1 http://security.debian.org wheezy/updates Release
Ign http://security.debian.org wheezy/updates/main armhf Packages
404 Not Found [IP: 151.101.130.132 80]
Irr http://security.debian.org wheezy/updates/contrib armhf Packages
404 Not Found [IP: 151.101.130.132 80]
Irr http://ftp.us.debian.org wheezy/updates/non-free armhf Packages
404 Not Found [IP: 151.101.130.132 80]
Irr http://ftp.us.debian.org wheezy/contrib armhf Packages
404 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy/contrib armhf Packages
404 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy/contrib armhf Packages
404 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy/contrib armhf Packages
404 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy/contrib armhf Packages
404 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy/contrib armhf Packages
404 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy-updates/contrib armhf Packages
404 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy-updates/contrib armhf Packages
405 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org wheezy-updates/contrib parmhf Packages
405 Not Found [IP: 208.80.154.15 80]
Irr http://ftp.us.debian.org/debian.org/dists/wheezy/updates/contrib/binary-armhf/Packages
408 Not Found [IP: 151.101.130.132 80]
W: Failed to fetch http://security.debian.org/dists/
```

With Debian 7.9, there is some error. As support for Debian 7.9 has ended, we need to change source.list file to use apt-get command.

```
© □ jungwung@ubuntu: ~

sudo apt-get update
Hit http://archive.debian.org wheezy Release.gpg
Hit http://archive.debian.org wheezy Release
Hit http://archive.debian.org wheezy/main armhf Packages
Reading package lists... Done
jungwungpark@beaglebone:~$ cd /etc/apt
jungwungpark@beaglebone:/etc/apt$ sudo vim sources.list

CTRL-A Z for help | 115200 8N1 | NOR | Minicom 2.7 | VT102 | Online 0:10 | ttyACM0
```

```
Jungwung@ubuntu:~

Jedeb http://ftp.us.debian.org/debian/ wheezy main contrib non-free

#deb-src http://ftp.us.debian.org/debian/ wheezy-updates main contrib non-free

#deb http://ftp.us.debian.org/debian/ wheezy-updates main contrib non-free

#deb-src http://ftp.us.debian.org/debian/ wheezy-updates main contrib non-free

#deb http://security.debian.org/ wheezy/updates main contrib non-free

#deb-src http://security.debian.org/ wheezy/updates main contrib non-free

#deb http://ftp.debian.org/debian wheezy-backports main contrib non-free

##deb-src http://ftp.debian.org/debian wheezy-backports main contrib non-free

###deb-src http://ftp.debian.org/debian wheezy-backports main contrib non-free

###deb-src http://ftp.debian.org/debian wheezy-backports main contrib non-free

#### contribution of the contribution of th
```

We made every line as a comment in original source.list file and added one command at last

:"deb http://archive.debian.org/devian wheezy main".

With this change, we could successfully update packages.

```
Reading package lists... Done
jungwungpark@beaglebone:/etc/apt$ sudo apt-get upgrade
Reading package lists... Done
Bullding dependency tree
Reading state information... Done
The following packages will be upgraded:
base-files bind9-host cpio dpkg dpkg-dev gir1.2-gdkpixbuf-2.0 git git-core
git-man isc-dhcp-client isc-dhcp-common libavcodec-dev libavcodec53
libavformat-dev libavformat53 libavutil-dev libavutil51 libbind9-80 libc-bin
libc-dev-bin libc6 libc6-dev libdns88 libdpkg-perl libfreetype6
libfreetype6-dev libgcrypt11 libgd2-xpm libgdk-pixbuf2.0-0
libgdk-pixbuf2.0-common libgdk-pixbuf2.0-dev libgif4 libgnutls26
libgssapi-krb5-2 libgtk-3-0 libgtk-3-bin libgtk-3-common libimlib2 libisc84
libisccc80 libisccfg82 libjasper-dev libjasper1 libk5crypt03 libkrb5-3
libkrb5support0 libldap-2.4-2 liblwres80 libnspr4 libpixman-1-0
libpixman-1-dev libpng12-0 libpng12-dev libpsstproc52 librsvg2-2
librsvg2-common libsmbclient libssh2-1 libssl-dev libssl-doc libssl1.0.0
libswscale-dev libswscale2 libwbclient0 libxapian22 libxml2 libxml2-dev
libxml2-utils linux-libc-dev locales multiarch-support openssh-client
openssh-server openssl perl perl-base perl-modules sudo tzdata xscreensaver
xscreensaver-data
81 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
Need to get 66.6 MB of archives.
After this operation, 5,292 kB disk space will be freed.
Do you want to continue [Y/n]? y
Get:1 http://archive.debian.org/debian/ wheezy/main base-files armhf 7.1wheezy11 [67.1
```

Shut down using the command.

```
jungwungpark@beaglebone:~$ sudo shutdown -h now
[sudo] password for jungwungpark:
Sorry, try again.
[sudo] password for jungwungpark:
Broadcast message from root@beaglebone (ttyGS0) (Thu Sep 16 15:49:43 2021):
The system is going down for system halt NOW!
```

Step 3. Test Cross-compile on PC Ubuntu

Install cross-compiler for ARM in the PC.

```
jungwung@ubuntu:~$ sudo apt-get install gcc-arm-linux-gnueabihf
[sudo] password for jungwung:
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following additional packages will be installed:
    binutils-arm-linux-gnueabihf cpp-5-arm-linux-gnueabihf
    cpp-arm-linux-gnueabihf cpp-5-arm-linux-gnueabihf
    gcc-5-arm-linux-gnueabihf-base gcc-5-cross-base libasan2-armhf-cross
    libatomic1-armhf-cross libc6-armhf-cross libc6-dev-armhf-cross
    libgcc-5-dev-armhf-cross libc6c1-armhf-cross libgonp1-armhf-cross
    substdc++6-armhf-cross libubsan0-armhf-cross libgonp1-armhf-cross
Suggested packages:
    binutils-doc gcc-5-locales cpp-doc gcc-5-multilib-arm-linux-gnueabihf
    gcc.5-doc libgcc1-dbg-armhf-cross libgonp1-dbg-armhf-cross
    libitm1-dbg-armhf-cross libatomic1-dbg-armhf-cross libusan0-dbg-armhf-cross
    libitm1-dbg-armhf-cross libtsan0-dbg-armhf-cross
    liblsan0-dbg-armhf-cross libtsan0-dbg-armhf-cross
    liblyuadmath0-dbg-armhf-cross autoconf automake libtool flex bison
    gdb-arm-linux-gnueabihf gcc-doc
The following NEW packages will be installed:
    binutils-arm-linux-gnueabihf ccpp-5-arm-linux-gnueabihf
    cpp-arm-linux-gnueabihf gcc-5-arm-linux-gnueabihf
    cpp-arm-linux-gnueabihf gcc-5-arm-linux-gnueabihf
```

```
jungwung@ubuntu:~$ arm-linux-gnueabihf-gcc --version
arm-linux-gnueabihf-gcc (Ubuntu/Linaro 5.4.0-6ubuntu1~16.04.9) 5.4.0 20160609
Copyright (C) 2015 Free Software Foundation, Inc.
This is Free software; see the source for copying conditions. There is NO
warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.
```

Cross-compiler is installed.

Make a working directory.

```
jungwung@ubuntu:~$ mkdir -p ~/DesignLab/1_CrossDevEnv/a_GetStarted
jungwung@ubuntu:~$ cd ~/D
DesignLab/ Desktop/ Documents/ Downloads/
jungwung@ubuntu:~$ cd ~/DesignLab/1_CrossDevEnv/a_GetStarted/
```

Edit the example program and cross-compile the program.

```
●●●● *hello_es.c (-/DesignLab/1_CrossDevEnv/a_GetStarted) - gedit

Open ▼ □

Save

#include <stdio.h>
votd main()
{
    printf("Hello, application program for embedded system!\n");
}
```

```
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ gedit hello_es.c
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ ls
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ arm-linux-gnueabihf-gcc -o hello_es hello_es.c
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ ls -la
total 24
drwxrwxr-x 2 jungwung jungwung 4096 Sep 17 02:15 .
drwxrwxr-x 3 jungwung jungwung 4096 Sep 17 02:12 .
-rwxrwxr-x 1 jungwung jungwung 8248 Sep 17 02:15 hello_es
-rw-rw-r-- 1 jungwung jungwung 97 Sep 17 02:14 hello_es.
```

Use makefile.

```
Makefile (~/DesignLab/1_CrossDevEnv/a_GetStarted) - gedit

Open ▼ □ Save

# Embedded Systems Lab1 Testgcc Makefile
# Source file: hello_es.c
# Do everything
alt: nc cc
# Native compile
nc:
gcc -o hello_es_pc hello_es.c
# Cross compile for Bone Ubuntu
cc:
arm-linux-gnueabihf-gcc -o hello_es hello_es.c
# Clean up
clean:
rm -f hello_es-_pc hello_es

jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ gedit Makefile
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ make clean
rm -f hello_es-_pc hello_es
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ ls
hello_es.c Makefile
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ make all
gcc -o hello_es_pc hello_es.c
arm-linux-gnueabihf-gcc -o hello_es hello_es.c
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ ls
hello_es hello_es.c hello_es_pc Makefile
```

"make clean" can remove all the compiled files.

"make all" can compile all the files to run on the PC and Bone each.

Try to run on PC.

```
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ ./hello_es_pc
Hello, application program for embedded system!
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ ./hello_es
pash: ./hello_es: cannot execute binary file: Exec format error
```

On PC, we can only run "hello_es_pc". "hello_es" is not executable as it is binary for ARM CPU Debian in Beaglebone, not Ubuntu AMD64.

Download.

On Bone console, make a working directory.

```
jungwungpark@beaglebone:~$ mkdir -p ~/test_scp
jungwungpark@beaglebone:~$ cd ~/test_scp
```

On PC terminal, type the commands.

On Bone console, check the files. Two files were transmitted correctly.

```
jungwungpark@beaglebone:~/test_scp$ ls
hello_es hello_es_pc
```

Run on Beaglebone.

```
jungwungpark@beaglebone:~/test_scp$ ./hello_es
Hello, application program for embedded system!
jungwungpark@beaglebone:~/test_scp$ ./hello_es_pc
-bash: ./hello_es_pc: cannot execute_binary file
```

On Beaglebone, we can only run "hello_es". "hello_es_pc" is not executable in Beaglebone. "hello_es_pc" is executable only in amd64 architecture and "hello_es" is executable in ARM architecture. Cross-compile enable us to compile arm-executable files on the amd64-based Ubuntu.

Step 4. Setup NFS

Install NFS server on PC using the command.

\$ sudo apt-get install nfs-kernel-server

Configure NFS and start PC NFS server.

Write the command and edit the file.

\$ sudo gedit /etc/exports

```
exports
//etc/exports: the access control list for filesystems which may be exported
to NFS clients. See exports(5).

# Example for NFSv2 and NFSv3:
# /srv/homes hostname1(rw,sync,no_subtree_check) hostname2(ro,sync,no_subtree_check)
# # Example for NFSv4:
# /srv/nfs4
gss/krb5i(rw,sync,fsid=0,crossmnt,no_subtree_check)
# /srv/nfs4/homes gss/krb5i(rw,sync,no_subtree_check)
# /srv/nfs4/homes gss/krb5i(rw,sync,no_subtree_check)

# nfs from Beablebone - Embedded
# PC Directory Allowed-IP-to-nfc-PC
/home/jungwung/DesignLab 192.168.0.12(rw,sync,no_root_squash,no_subtree_check)

jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ sudo exportfs -a
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ sudo /etc/init.d/nfs-kernel-server start
[ ok ] Starting nfs-kernel-server (via systemctl): nfs-kernel-server.service.
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/a_GetStarted$ ps -aux | grep nfs
root 7520 0.0 0.0 0 0 ? S 02:28 0:00 [nfsd]
root 7521 0.0 0.0 0 0 ? S 02:28 0:00 [nfsd]
root 7523 0.0 0.0 0 0 ? S 02:28 0:00 [nfsd]
root 7524 0.0 0.0 0 0 ? S 02:28 0:00 [nfsd]
root 7524 0.0 0.0 0 0 ? S 02:28 0:00 [nfsd]
root 7524 0.0 0.0 0 0 ? S 02:28 0:00 [nfsd]
root 7524 0.0 0.0 0 0 ? S 02:28 0:00 [nfsd]
```

We checked that NFS started.

Install NFS client in Bone using the command.

sudo apt-get install nfs-common

Make the mount point and start Beaglebone NFS client.

```
jungwungpark@beaglebone:-$ mkdir ~/nfs_client
s_clientpark@beaglebone:-$ sudo mount 192.168.0.13:/home/jungwung/DesignLab ~/nf
jungwungpark@beaglebone:-$
```

Due to the bug when shortening the command window, the last texts were overlapped to the front.

0:00

For later use, edit ~/bone_nfs_client.sh using vi.

sudo vi ~/bone_nfs_client.sh

Now, we can use "# ~/bone_nfs_client.sh" to start Beaglebone NFS client.

Run hello_es using NFS.

```
jungwungpark@beaglebone:~$ cd ~/nfs_client/
jungwungpark@beaglebone:~/nfs_client$ ls
1_CrossDevEnv
jungwungpark@beaglebone:~/nfs_client$ cd 1_CrossDevEnv/
jungwungpark@beaglebone:~/nfs_client/1_CrossDevEnv$ cd a_GetStarted/
jungwungpark@beaglebone:~/nfs_client/1_CrossDevEnv/a_GetStarted$ ./hello_es
Hello, application program for embedded system!
```

It works well.

Step 5. Prepare Module Build

Get Kernel source from Web for RoboCam.

We got "Kernel3.8.13-bone79_linux.tgz".

Install Kernel source.

```
jungwung@ubuntu:~$ cd Downloads/
jungwung@ubuntu:~/Downloads$ tar -xvf Kernel3.8.13-bone79_linux.gz
```

```
defconfig
                       include
                                              modules.builtin REPORTING-BUGS
                                                                                System.map vmlinux.o
lock
        Documentation
                                              modules.order
                                                               samples
                                                                                tools
                                MAINTAINERS
OPYING
       drivers
                                              Module.symvers
                                                               scripts
        firmware
fs
                       Kbuild
                                Makefile
                                                                               virt
REDITS
                                              net
                                                               security
                                              README
                       Kconfig
гурtо
                                                               sound
                                                                               vmlinux
```

Configure cross compile environment.

```
■ *cde_bd_k3813_bone79 (~/Downloads) - gedit
 #!/bin/bash
### Shell script cde_bd_k3813-bone79
### Setup cross-compile environment for Bone-Debian with Kernel 3.8.13-bone79 ### Usage: source sh/
cde_bd_k3813-bone79
## \widetilde{\text{Line}} starting with '#' means comment line.
## Set MACHINE
MACHINE=beaglebone
## Set SYSROOTSDIR & STAGEDIR
SYSROOTSDIR=/usr
STAGEDIR=${SYSROOTSDIR}
## Set CROSSBINDIR (where cross compiler exists)
CROSSBINDIR=/usr/bin
## Set KERNELDIR (where the Linux kernel source is located)
## NOTE: This path to KernelDir should be exact.
export KERNELDIR=/home/jungwung/Downloads/linux
## Set PATH
PATH=${CROSSBINDIR}:${PATH}
unset CFLAGS CPPFLAGS CXXFLAGS LDFLAGS MACHINE
export ARCH="a
export CROSS_COMPILE="arm-linux-gnueabihf-"
export CC="arm-linux-gnueabihf-gc
export LD="arm-linux-gnueabihf-ld
export STRIP="arm-linux-gnueabihf-strip"
echo "Set cross-development environment for Beaglebone Debian (3.8.13-bone79 kernel)."
jungwung@ubuntu:~/Downloads$ gedit cde_bd_k3813_bone79
jungwung@ubuntu:~/Downloads$ source cde_bd_k3813_bone79
Set cross-development environment for Beaglebone Debian (3.8.13-bone79 kernel)
jungwung@ubuntu:~/Downloads$
```

set KERNELDIR as /home/jungwung/Downloads/linux

Step 6. MODULE COMPILE

Make another working directory and edit Makefile.

```
jungwung@ubuntu:~$ mkdir -p ~/DesignLab/1_CrossDevEnv/b_ModuleBuild
jungwung@ubuntu:~$ cd ~/DesignLab/1_CrossDevEnv/b_ModuleBuild/
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/b_ModuleBuild$ gedit Makefile
```

Edit hellomod.c.

Use make clean and make.

Insert module on Beaglebone.

Go to the working directory.

cd ~/nfs_client/1_CrossDevEnv/b_ModuleBuild

Become superuser.

su

We can insert module and check the module.

```
d hellomod.kone:/home/jungwungpark/nfs_client/1_CrossDevEnv/b_ModuleBuild# insmd
Module Size Used bys_client/1_CrossDevEnv/b_ModuleBuild# lsmod
hellomod 775 0
nfsd 187513 2
g_multi 50407 2
libcomposite 15028 1 g_multi
omap_rng 4062 0
mt7601Usta 458758 0
```

We can check output using "# dmesg" command.

```
[ 2438.290489] net eth0: phy found : id is : 0x7c0f1
[ 2438.290527] libphy: PHY 4a101000.mdio:01 not found
[ 2438.295602] net eth0: phy 4a101000.mdio:01 not found on slave 1
[ 2438.311421] IPv6: ADDRCONF(NETDEV_UP): eth0: link is not ready
[ 2440.298433] libphy: 4a101000.mdio:00 - Link is Up - 100/Full
[ 2440.298555] IPv6: ADDRCONF(NETDEV_CHANGE): eth0: link becomes ready
[ 3153.554158] Installing knfsd (copyright (C) 1996 okir@monad.swb.de).
[ 5134.020000] Hello, hellomod!
```

We can check output using "# modinfo hellomod.ko" command.

```
filename: /home/jungwungpark/nfs_client/1_CrossDevEnv/b_ModuleBuild/hellomod.ko license: GPL description: Hello Module Example author: Christoper Hallinan srcversion: 8AE57EE0AB2FDCB308B7263 depends: vermagic: 3.8.13 SMP mod unload modversions ARMv7 thumb2 p2v8
```

Remove the module.

We can remove module using "# rmmod hellomod" command and check output using "# dmesg" command.

```
[ 2440.298433] libphy: 4a101000.mdio:00 - Link is Up - 100/Full [ 2440.298555] IPv6: ADDRCONF(NETDEV_CHANGE): eth0: link becomes ready [ 3153.554158] Installing knfsd (copyright (C) 1996 okir@monad.swb.de). [ 5134.020000] Hello, hellomod! [ 5239.302012] Goodbve. hellomod!
```

Step 7. Exercise Gnu Debugger gdb

Make factorial.c

Compile factorial.c and start gdb

```
heejin@heejin-HP-Compaq-6531s:~/Random$ gcc -o factorial factorial.c -ggdb
heejin@heejin-HP-Compaq-6531s:~/Random$ gdb factorial
GNU gdb (Ubuntu 7.11.1-@ubuntu1~16.5) 7.11.1
Copyright (C) 2016 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <a href="http://gnu.org/licenses/gpl.html">http://gnu.org/licenses/gpl.html</a>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law. Type "show copying"
and "show warranty" for details.
This GDB was configured as "i686-linux-gnu".
Type "show configuration" for configuration details.
For bug reporting instructions, please see:
<a href="http://www.gnu.org/software/gdb/bugs/">http://www.gnu.org/software/gdb/bugs/</a>,
Find the GDB manual and other documentation resources online at:
<a href="http://www.gnu.org/software/gdb/documentation/">http://www.gnu.org/software/gdb/documentation/</a>.
For help, type "help".
Type "apropos word" to search for commands related to "word"...
Reading symbols from factorial...done.
(gdb) T
```

Test gdb commands.

```
(gdb) l 10
5     int i, num;
6     int j = 1;
7
8     printf("Enter the number: ");
9     scanf("%d", &num);
10
11     for (i=1; i<=num; i++)
12         j=j*i;
13
14     printf("The factorial of %d is %d\n",num,j);
(gdb) b 12
Breakpoint 1 at 0x804850b: file factorial.c, line 12.</pre>
```

"list" command shows the code.

"break number" command sets a break point in line "number".

"run" command runs the program.

"print variable" command shows the value of variable in that time.

We can go to next break point using "continue" command.

We can go next instruction using "next" and "step" commands.

However, "step" can go into function and "next" cannot.

```
(gdb) c
Continuing.
The factorial of 4 is 24
[Inferior 1 (process 3263) exited normally]
(gdb) quit
heejin@heejin-HP-Compaq-6531s:~/Random$
```

We can quit gdb using "quit" command.

Step 8. Test Reaction Timer Components

Test test_rand_pc on PC

```
pingwung@ubuntu: ~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_rand
hellomod.ko hellomod.mod.o Makefile Module.symvers
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv/b_ModuleBuild$ cd ..
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer\cdot c test_rand/
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer$ cd test_rand/
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer\test_rand$ make
gcc -o test_rand_c test_rand.c
arm-linux-gnueabihf-gcc -o test_rand test_rand.c
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu: ~/DesignLab/1_CrossDevEnv\c_ReactionTimer/test_rand$ ./test_rand_pc
Rand(1 to 10) Avg= 5.92142, Min= 1.14671, Max= 9.99032
jungwung@ubuntu
```

"./test_rand_pc" program produces same results, not random, because seed for rand() function is fixed. Let's change the seed using srand() function.

We modified test_rand.c as below.

```
Program test_rand.c
         Test function rand()
         Programmed by Byung Kook Kim, Feb. 1, 2017
// Declare include hader files
#include <stdio.h>
#include <stdlib.h>
                           // rand(), srand()
// time()
#include <time.h>
int main(void)
         // Declare variables to be used
int k; // Loop index
         double Lower, Upper, Range; // Random number range double rn[100]; // Random number array // 1. Init variables
         Lower = 1.;
Upper = 10.;
         Range = Upper - Lower;
         srand((unsigned int)time(NULL));
         // 2. Loop 100 times
         for (k=0; k<100; ++k) {
    // Generate a random number [Lower, Upper] to rn[k]
    rn[k] = Lower + Range*rand()/RAND_MAX;</pre>
         \} // 3. Compute avg, min, and max of rm[k]
         double Min = 1e9;
         double Max = -1e9;
double sum = 0.;
         for (k=0; k<100; ++k) {
                  sum += rn[k];
if (rn[k] < Min) Min = rn[k];
if (rn[k] > Max) Max = rn[k];
         double Avg = sum/100.;
         // 4. Print result
         printf("Rand(1 to 10) Avg= %g, Min= %g, Max= %g\n", Avg, Min, Max);
         return 0;
}
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_rand$ make clean
rm -f test_rand test_rand_pc
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_rand$ make
```

The results came out randomly. We used time() function as a input parameter of srand() fuction. As the minimum unit in time() function is second, we need to execute "test_rand_pc" with the time term larger than 1 second.

Test test_gettimeofday_usleep_pc on PC

```
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_gettimeofday$ make clean
rm -f test_gettimeofday_usleep test_gettimeofday_usleep_pc
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_gettimeofday$ make
gcc -o test_gettimeofday_usleep_pc test_gettimeofday_usleep.c
arm-linux-gnueabihf-gcc -o test_gettimeofday_usleep test_gettimeofday_usleep.c
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_gettimeofday$ ls
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_gettimeofday$ ./test_gettimeofday_usleep_pc
Elapsed_time= 2000.73 ms.
Elapsed_time= 2000.55 ms.
Elapsed_time= 2000.55 ms.
```

The results came out in close to 2 seconds.

Test test_getch_pc on PC

--Number & lower alphabet & upper alphabet

```
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_getCh$ make clean
rm -f test_getch test_getch_pc
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_getch$ make
gcc -g -o test_getch_pc getche.c test_getche.c
arm-linux-gnueabinf-gcc -o test_getch getche.c test_getche.c
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_getch$ ./test_getch_pc
a, 97, 61h
b, 98, 62h
c, 99, 63h
d, 100, 64h
e, 101, 65h
f, 102, 66h
g, 103, 67h
h, 104, 68h
i, 105, 69h
j, 106, 6ah
1, 49, 31h
2, 50, 32h
3, 51, 33h
4, 52, 34h
5, 53, 35h
6, 54, 36h
```

The lower case letters increase by one from 97 in alphabetical order.

The numbers increase by one from 49.

```
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_getch$ ./test_getch_pc
A, 65, 41h
B, 66, 42h
C, 67, 43h
D, 68, 44h
E, 69, 45h
F, 70, 46h
G, 71, 47h
H, 72, 48h
I, 73, 49h
J, 74, 4ah
K, 75, 4bh
L, 76, 4ch
M, 77, 4dh
N, 78, 4eh
O, 79, 4fh
P, 80, 50h
```

The upper case letters increase by one from 65 in alphabetical order.

This result comes from the ASCII code. For example, ASCII value for a is 97 and its hex form is 0x61. For the number & lower alphabet & upper alphabet, "test_getch_pc" produced a good result.

-- Function keys

Above image shows the result when we pushed F1 to F6.

F1 did not show any results, instead it showed terminal help page. It is because default keyboard shortcut for terminal help page is F1 key.

For F2 to F6, each key showed 3 results at once. For example, F2 showed 27, 79, 81 and leftmost value is strange. It is because ASCII code does not contain any information about function keys. Every i/o system is abstracted as stream of characters. Thus, keyboard is also abstracted as a stream of characters. If we press function keys, keyboard will send some stream of characters to Ubuntu, but the data is not meaningful in ASCII code encoding, which results in showing a strange output.

- ESC & Ctrl + C

```
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_getch$ ./test_getch_pc
27, 1bh
```

ASCII code has a information about ESC key. ESC key produced some strange alphabet, 27, and 1bh.

However, when we pressed Ctrl+C key, program stopped. It's because Ctrl+C ket sends a signal to process and the default action is to terminate process.

Test test_rand on Bone

```
rand# ./test_randome/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Rand(1 to 10) Avg= 5.40768, Min= 1.05992, Max= 9.99733
_rand# aglebone:/home/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
rand# ./test_randome/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Rand(1 to 10) Avg= 6.05708, Min= 1.32201, Max= 9.98721
_rand# ./test_randome/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Rand(1 to 10) Avg= 5.28894, Min= 1.14769, Max= 9.92859
_rand# ./test_randome/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Rand(1 to 10) Avg= 5.76566, Min= 1.03479, Max= 9.94936
_rand# ./test_randome/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Rand(1 to 10) Avg= 5.16356, Min= 1.08344, Max= 9.98669
_rand# ./test_randome/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Rand(1 to 10) Avg= 5.58231, Min= 1.04518, Max= 9.93013
```

Due to the bug when shortening the command window, the last texts were overlapped to the front.

The results came out randomly.

Test test_gettimeofday_usleep on Bone

```
_gettimeofday# ./test_gettimeofday_usleepient/1_CrossDevEnv/c_ReactionTimer/test_
Elapsed_time= 2000.27 ms.
Elapsed_time= 2000.19 ms.
Elapsed_time= 2000.19 ms.
gettimeofday# !/home/jungwungpark/nfs client/1 CrossDevEnv/c ReactionTimer/test
```

The results came out in close to 2 seconds.

Test test_getch on Bone

--Number & lower alphabet & upper alphabet

```
_getCh# ./test_getche/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
a, 97, 61h
b, 98, 62h
c, 99, 63h
d, 100, 64h
e, 101, 65h
f, 102, 66h
g, 103, 67h
h, 104, 68h
i, 105, 69h
j, 106, 6ah
1, 49, 31h
2, 50, 32h
3, 51, 33h
4, 52, 34h
5, 53, 35h
6, 54, 36h
```

The lower case letters increase by one from 97 in alphabetical order.

The numbers increase by one from 49.

```
_getch# ./test_getche/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
A, 65, 41h
B, 66, 42h
C, 67, 43h
D, 68, 44h
E, 69, 45h
F, 70, 46h
G, 71, 47h
H, 72, 48h
I, 73, 49h
J, 74, 4ah
K, 75, 4bh
L, 76, 4ch
M, 77, 4dh
N, 78, 4eh
O, 79, 4fh
P, 80, 50h
```

The upper case letters increase by one from 65 in alphabetical order.

-- Function keys

Pressed F1 to F6. Same result with PC.

- ESC & Ctrl + C

```
_getch# ./test_getche/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
27, 1bh
```

Same result with PC.

Step 9. Test reaction_timer

Test reaction_timer on PC

```
Type the 'f' character: f
Correct response f in 481.445ms.
Type the 'f' character: f
Correct response f in 441.604ms.
Type the 'j' character: f
InCorrect response f in 302.184ms.
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_reaction$ ./reaction_pc
Type the 'j' character: f
InCorrect response f in 341.037ms.
j
Type the 'j' character: j
Correct response j in 0.004ms.
Type the 'f' character:
InCorrect response
in 0.005ms.
jungwung@ubuntu:~/DesignLab/1_CrossDevEnv/c_ReactionTimer/test_reaction$ ./reaction_pc
Type the 'f' character: f
Correct response f in 660.577ms.
Type the 'j' character: j
Correct response j in 564.093ms.
Type the 'f' character: f
Correct response f in 571.708ms.
```

If the input is incorrect, an incorrect message is displayed and reaction rate is measured.

If the input is correct, a correct message is displayed and reaction rate is measured.

Test reaction timer on Bone

```
_reaction# ./reaction/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Type the 'f' character: f
Correct response f in 671.646ms.
Type the 'j' character: j
Correct response j in 378.624ms.
Type the 'j' character: j
Correct response j in 646.529ms.
_reaction# ./reaction/jungwungpark/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_
Type the 'f' character: f
Correct response f in 495.266ms.
Type the 'j' character: j
Correct response j in 473.238ms.
Type the 'j' character: j
Correct response j in 453.833ms.
```

```
jungwungpark@beaglebone:~/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_reaction

$ ./reaction

Type the 'f' character: f
Correct response f in 1683.960ms.

Type the 'f' character: f
Correct response f in 300.365ms.

Type the 'j' character: f
InCorrect response f in 402.727ms.

jungwungpark@beaglebone:~/nfs_client/1_CrossDevEnv/c_ReactionTimer/test_reaction
```

If the input is incorrect, an incorrect message is displayed and reaction rate is measured.

If the input is correct, a correct message is displayed and reaction rate is measured.

Works well!