Bolinho

Solution for data gathering, processing and interaction

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1. Home

1.1 Home

Documentation of the FullStack solution **bolinho**.

This documentation automatically generates a PDF file from it's content. You can download it here.

1.1.1 You can see the React Front-end HERE!

This is a static version of the app, without access to the server, therefore most features won't work.

Info

Remember that you need to build the app for it to show on the static page, so run npm run buildweb or something similar to build it.

Use the **Tabs** above to navigate through the documentation.

1.1.2 Running

As for running the program we have a few options:

- Run only the frontend npm run startWeb
- Run only the backend npm run startEel
- Serve the full application npm run serve

This command will start the eel as headless and start the web serve, it doesn't need to build the front end before executing. Less performant.

To update the backend ability to call front end functions you should first build the front.

• Run the full application npm run start

With this command it will first build the react front end, then run the python script.

- Build the react frontend npm run buildWeb
- * Build binaries. npm run buildBin
- You can build the "binaries", more like a python environment wrapper, it uses PyInstaller to generate the bins.
- The output path is bolinho/src/dist/

Did you like this documentation? You can check out the repo ZRafaF/ReadTheDocksBase for more info 😜.



1.2 Setup

This page will define the step-by-step to build this project.

This project assumes you have the latest version of Python, PIP and GIT,

This project was developed using python version Python 3.10.x

1.2.1 Clone the repo

```
Bash
git clone https://github.com/HefestusTec/bolinho
cd bolinho
```

1.2.2 Creating a virtual environment

The following step isn't mandatory but **recommended**.

```
Bash

python -m pip install --user virtualenv

python -m venv venv
```

The a directory venv should be created in the root folder.

How to activate:

Windows activation venv/Scripts/activate

or

Linux activation source venv/bin/activate

1.2.3 Installing dependencies

```
Bash
npm run installDep
```

1.2.4 Documentation

The following step is only required for those that want to **edit the documentation**.

Installing dependencies

Bash

pip install -r docs/requirements.txt

Build

We have two options to create a build:

· Serve:

This option is used for debugging, it will open the static page in one of the localhost ports.

mkdocs serve

• Build:

This option creates a build of the documentation and saves it on de directory /site/.

mkdocs build

Note

Be aware of the $Environment\ Variable\$ ENABLE_PDF_EXPORT , it will only generate the PDF if this variable is set to 1.

You can change the mkdocs.yml file and remove this line if you so choose.

For more info about the documentation please checkout ZRafaF/ReadTheDocksBase.

2. Back End

2.1 Back End

2.1.1 DBHandler.py

Defines database models using orm_sqlite

2.1.2 Models

- Material
- Experiment
- Body
- Reading

2.1.3 Classes

DBHandler

Handles database connection and CRUD operations

METHODS

- init(self, db_path)
- add_material(self, name, batch)
- add experiment(self, name, material, date, time, load loss limit, max load, max travel, max time, compress, z axis speed)
- add_reading(self, experiment, load, z_pos, time)
- get_materials(self)
- get material by id(self, id)
- get_bodies(self)
- get_body_by_id(self, id)
- get bodies by material(self, material)
- get_bodies_by_type(self, body_type)
- get_bodies_by_material_and_type(self, material, body_type)
- get_experiments(self)
- get_experiment_by_id(self, id)
- get_experiments_by_material(self, material)
- get_experiments_by_date(self, date)
- get_experiments_by_date_and_material(self, date, material)
- get_experiment_readings(self, experiment)
- delete_experiment_by_id(self, id)
- delete material by id(self, id)
- populate(self)

2.2

Handles Raspberry Pi GPIO and data acquisition

2.2.1 Classes

DataHandler

Abstract class for data acquisition

LoadCell

Handles load cell data acquisition

StepMotor

Handles step motor data acquisition

2.3 DBHandler

2.3.1 DBHandler.py

Defines database models using orm_sqlite

2.3.2 Models

- Material
- id : Integer Primary Key
- name: String
- batch: String
- Experiment
- id : Integer Primary Key
- name: String
- material: Integer Foreign Key
- date: Date
- time: Time
- load_loss_limit: Float
- max_load: Float
- max_travel: Float
- max_time: Float
- compress: Boolean
- z_axis_speed: Float
- Body
- id : Integer Primary Key
- body_type: String
- material: Integer Foreign Key
- param_a: Float
- param_b: Float
- height: Float
- Reading
- id: Integer Primary Key
- experiment: Integer Foreign Key
- load: Float
- \bullet z_pos: Float
- time: Float

2.3.3 Classes

DBHandler

Handles database connection and CRUD operations

METHODS

- init(self, db path)
- Creates database connection, binds models to database, creates and populates the database if it doesn't exist
- db path: Path to database file
- add material(self, name, batch)
- name: Name of the material
- batch: Batch number of the material
- add_experiment(self, name, material, date, time, load_loss_limit, max_load, max_travel, max_time, compress, z_axis_speed)
- name: Name of the experiment
- material: Name of the material
- date: Date of the experiment
- time: Time of the experiment
- load_loss_limit: Load loss limit of the experiment
- max_load: Maximum load of the experiment
- \bullet max_travel: Maximum travel of the experiment
- \bullet $max_time : Maximum time of the experiment$
- \bullet compress: Whether the experiment is compressive or not
- z axis speed: Speed of the z axis
- add reading(self, experiment, load, z pos, time)
- experiment: Name of the experiment
- load: Load of the reading
- z pos: Z position of the reading
- time: Time of the reading
- get materials(self)
- Returns all materials in the database
- get material by id(self, id)
- id: Id of the material
- Returns the material with the given id
- get bodies(self)
- Returns all bodies in the database
- get_body_by_id(self, id)
- id: Id of the body
- Returns the body with the given id

- . get bodies by material(self, material)
- material: Name of the material
- Returns all bodies with the given material
- get_bodies_by_type(self, body_type)
- body type: Type of the body
- Returns all bodies with the given type
- get_bodies_by_material_and_type(self, material, body_type)
- material: Name of the material
- body type: Type of the body
- Returns all bodies with the given material and type
- get experiments(self)
- Returns all experiments in the database ordered by date and time descending
- get experiment by id(self, id)
- id: Id of the experiment
- Returns the experiment with the given id
- get experiments by material(self, material)
- material: Name of the material
- Returns all experiments with the given material
- get experiments by date(self, date)
- date: Date of the experiment
- Returns all experiments with the given date
- get experiments by date and material(self, date, material)
- date: Date of the experiment
- \bullet material: Name of the material
- Returns all experiments with the given date and material
- get_experiment_readings(self, experiment)
- experiment: Name of the experiment
- Returns all readings of the given experiment
- delete experiment by id(self, id)
- id: Id of the experiment
- Deletes the experiment with the given id and all its readings
- delete material by id(self, id)
- id: Id of the material
- Deletes the material with the given id and all its experiments and readings
- populate(self)
- Populates the database with some dummy data

2.4 DataHandler

2.4.1 DataHandler.py

Handles Raspberry Pi GPIO and data acquisition

2.4.2 Classes

DataHandler

Abstract class for data acquisition

LoadCell

[NOT IMPLEMENTED]

Handles load cell data acquisition

StepMotor

[NOT IMPLEMENTED]

Handles step motor data acquisition

2.5 Routines

This page is a summary of the routines of the machine.

3. Front End

3.1 Front End

As front end framework/library we are using ReactJs.

You can check out the about page for a list of the third party projects being used.

Global variables

The global variables can be found at variables.css. You can import it into your stylesheet using

```
css
@import url(./variables.css);
```

3.1.1 Component architecture

```
flowchart TD

App --> MainPage

App --> ExperimentPage

MainPage --> SideBar

SideBar --> Header

MainPage --> Content

Content --> Início

Content --> Calibrar

Content --> Controlar

Content --> Config.

Content --> Sobre
```

3.2 Pages

The following pages are just place holders / mockups of the final application.

3.2.1 Initial page



Main

Initial page of the application, you are able to:

- Visualize previous experiments;
- Exclude experiments;
- Exclude materials;
- Access different sub-pages;
- Generate report; and more!.



Calibration sub-page



Control sub-page



Configuration sub-page



3.2.2 Experiment page



3.3 Components

Most custom React components are here

3.3.1 ZoomComponent

Component that enables zooming on it's contents, press and hold to zoom in.

It uses the use-long-press rook to handle this action.

You can enable/disable and change the activation time on the GlobalConfigContext context.

Props

```
React
{
    scaleOrigin = "top",
    className = "",
    children,
}
```

- scaleOrigin: What is the origin point (which direction does it grows).
- className : ClassName of the component.
- children: Children props, Don't worry about it.

Usage example

3.3.2 ExperimentInspector

This component makes use of the SelectedObjectsContext.

The experiment inspector component holds the following children:

- ColorPicker: Color picker component for choosing the color of the active experiment.
- ExperimentButton: Buttons that make the list of selected experiments.
- ExperimentDescription: Component that parses the description of the active material.

Props

none

Usage example

```
React
import { eel } from "./App";
import ExperimentsInspector from "./experimentsInspector/experimentsInspector";
export default function exampleComponent(){
    const getMaterialList = async () => {
        try {
            const materialList = JSON.parse(await eel.get_material_list()());
            return materialList;
        } catch (error) {
            return [];
    };
    return(
        <SelectedObjectsContext.Provider>
            <ExperimentsInspector />
        </SelectedObjectsContext.Provider>
    );
}
```

3.3.3 Material Selector

The MaterialSelector component holds the following children:

- MaterialSelectorButton: Buttons that make the list of available experiments.
- DropdownButton: Buttons that make a dropdown, so the user can choose which experiment they want to inspect.

It can be wrapped with the **ZoomComponent** to allow zooming.

Props

```
React
{
    materialList // List of available materials, fetched from the backend
}
```

Usage example

```
React
import { eel } from "./App";
import MaterialSelector from "./materialSelector/materialSelector";
export default function exampleComponent(){
    const getMaterialList = async () => {
        try {
            const materialList = JSON.parse(await eel.get_material_list()());
            return materialList;
        } catch (error) {
            return [];
        }
    };
    return(
        <MaterialSelector materialList={getMaterialList} />
    );
}
```

3.4 Contexts

This page contains all the contexts used on the application.

3.4.1 GlobalConfigContext

```
React

{
    theme: "light", // light | dark
    animationSpeed: "slow", // fast | slow | off
    animateGraph: "on", // on | off
    enableZoom: true, // Should zooming be enable?
    zoomDelay: 300, // How long [ms] should I press to zoom
    blurOnZoom: true, // Should it blur when zooming?
    absoluteMaximumForce: 10000,
}
```

3.4.2 SelectedObjectsContext

This context is accessible to the children of the MainPage component. It holds a list of the selected objects "experiments data".

```
React
{
    material, // material_fragment
    experiment, // experiment_fragment
    data_array, // data_array_fragment,
    color, // color associated to an experiment
}
```

3.5 Alerts

This project is using react-toastify to handle alerts. If you want more in-depth info about them please refer to the documentation.

3.5.1 Usage

Here is an exemple of how you can create an alert.

3.6 Styling

Here we will show some tips and styling techniques used on this project.

3.6.1 Linking stylesheets to a component

Stylesheets are made with style.module.css and imported into the .jsx or .tsx allowing us to use it as an object to name className s.

As for naming convention snake case is being used for styling names

```
import styleModule from "./mainPage.module.css";

<div className={styleModule.my_custom_div}>
    Im a styled div
<div>
```

3.6.2 Adding ellipsis

You can add ellipsis to most texts using the following code

```
white-space: nowrap;
overflow: hidden;
text-overflow: ellipsis;
```

Tip

This **must not be wrapped in a flex div**, therefore we recommend you using a div only for the text, for example:

4. Embedded

4.1 Embedded

Bolinho uses a microcontroller esp32-s3 for controlling the hardware.

The microcontroller communicates via serial to the host, and is responsible for reading the load cell and controlling the stepper motor.

5. API

5.1 API

In this section you will be able to finde every API call available.

These calls are exposed to the **front-end** via the **eel** object, giving it access to the **data base**, **systems** and **hardware**. This solutions makes use of the **eel** library to realize the communication between the front-end and back-end;

This API reference will show the methods being called by the front-end in JavaScript, and every call should be made **asynchronously**.

5.1.1 How to create and expose functions to the backend

```
function myJsFunction(message){
    console.log(`Got this from the back end ${message}`)
}

// This line exposes the function to the back end, note the second argument, it is the name that the back end needs to call
window.eel.expose(myJsFunction, "myJsFunction");
```

Python

```
try:
    eel.myJsFunction("IT'S WORKING")
except:
    pass
```

5.2 Front end API

This page gathers all the API calls that can be used by the backend.

Backend -> Front end

Warning

The functions can only be called if they are available on the <code>web/build</code> directory, therefore if you make a change using <code>npm run</code> serve won't show it, you will need to rebuild the front end with <code>npm run</code> buildWeb or by using <code>npm run</code> start .

Note

These functions can only be called after eel is initiated with eel.init().

5.2.1 Core API

Collection of all functions/API calls available to the backend. You can find them in the bolinho_api/core.py file.

The JavaScript file can be found in the api folder.

ping()

ping()

Tries to ping the bolinho front-end, returns 1 if it worked

```
from bolinho_api.core import core_api

while True:
    try:
        if core_api.ping():
            print("got a ping!")
            break
        pass
    except:
        eel.sleep(1)
```

get_config_params()

get_config_params()

Tries to ping the bolinho front-end, returns 1 if it worked

Python usage example

```
from bolinho_api.core import core_api

config = core_api.get_config_params()
current_save_version = config["configVersion"]
print(current_save_version)
```

This function is located at src/web/src/App.js

go_to_experiment_page()

go_to_experiment_page()

Asks the front end to go to the experiment page.

Returns 1 if succeeded.

Python usage example

```
from bolinho_api.core import core_api

change_pages = True
if change_pages:
    core_api.go_to_experiment_page()
```

go_to_home_page()

go_to_home_page()

Asks the front end to go to the home page.

Returns 1 if succeeded.

```
from bolinho_api.core import core_api

change_pages = True
if change_pages:
    core_api.go_to_home_page()
```

show_connect_prompt()

show_connect_prompt()

Asks the front end to show the connection prompt.

The connection prompt is used to select the serial port.

Returns 1 if succeeded.

```
Python usage example

from bolinho_api.core import core_api

config = core_api.get_config_params()
device_port = config["port"]

while not device_port:
    core_api.show_connect_prompt()
    device_port = config["port"]
```

5.2.2 UI API

Collection of all functions/API calls available to the backend for UI in general. You can find them in the bolinho_api/ui.py file.

The JavaScript file can be found in the api folder.

success_alert(text)

success_alert(text)

Uses React-Toastify to create an success alert.

```
from bolinho_api.ui import ui_api
ui_api.success_alert("Success!")
```

error_alert(text)

```
error_alert(text)

Uses React-Toastify to create an error alert.

Python usage example
from bolinho_api.ui import ui_api
ui_api.error_alert("Error!")
```

prompt_user(description, options, callback_func)

prompt_user(description, options, callback_func)

Prompts the user with a 'description', and shows the 'options' to the user.

The result is passed to the callback_function

Python usage example

```
from bolinho_api.ui import ui_api

def get_result(result):
    if result == "yes":
        print("The user chose yes")
    print("The user chose no")

ui_api.prompt_user(
    description="Do you want to pay 1000?",
```

options=["yes", "no"],
callback_func= get_result,

set_focus(focus_element: str)

error_alert(focus_element: str)

Focus in an specific element on the frontend.

WARNING Pay attention to the name of the element you are trying to focus

You can find them at https://github.com/HefestusTec/bolinho/blob/main/src/web/src/api/apiTypes.ts

Python usage example

```
from bolinho_api.ui import ui_api
ui_api.set_focus("connection-component")
```

5.2.3 Experiment page API

Collection of all functions/API calls available to the backend for the **experiment** routine. You can find them in the bolinho_api/experiment.py file.

The JavaScript file can be found at web/src/api/contexts/ExperimentPageContext.tsx.

get_load_percentage()

get_load_percentage()

Asks the front for the current load percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

Returns the load percentage value

```
from bolinho_api.experiment import experiment_api
print(experiment_api.get_load_percentage())
```

set_load_percentage(newValue)

set_load_percentage(newValue)

Sets the current load percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

Python usage example

```
from bolinho_api.experiment import experiment_api

for number in range(100):
    experiment_api.set_load_percentage(number)
    eel.sleep(0.1)
```

get_time_percentage()

get_time_percentage()

Asks the front for the current time percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

Returns the load percentage value

Python usage example

```
from bolinho_api.experiment import experiment_api
print(experiment_api.get_time_percentage())
```

set_time_percentage(newValue)

set_time_percentage(newValue)

Sets the current time percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

```
from bolinho_api.experiment import experiment_api
experiment_api.set_time_percentage(22)
```

get_distance_percentage()

get_distance_percentage()

Asks the front for the current distance percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

Returns the load percentage value

Python usage example

```
from bolinho_api.experiment import experiment_api
print(experiment_api.get_distance_percentage())
```

set_distance_percentage(newValue)

set_distance_percentage(newValue)

Sets the current distance percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

Python usage example

```
from bolinho_api.experiment import experiment_api
experiment_api.set_distance_percentage(22)
```

get_delta_load_percentage()

get_delta_load_percentage()

Asks the front for the current delta load percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

Returns the load percentage value

```
from bolinho_api.experiment import experiment_api
print(experiment_api.get_delta_load_percentage())
```

set_delta_load_percentage(newValue)

set_delta_load_percentage(newValue)

Sets the current delta load percentage.

This variable is shown to the user in a progress bar. And is usually between 0-100.

Python usage example

```
from bolinho_api.experiment import experiment_api
experiment_api.set_delta_load_percentage(22)
```

get_experiment_parameters()

get_experiment_parameters()

Asks the front for the current experiment parameters.

Returns a formatted string

Python usage example

```
from bolinho_api.experiment import experiment_api
print(experiment_api.get_experiment_parameters())
```

set_experiment_parameters(newValue)

set_experiment_parameters(newValue)

Sets the current experiment parameters.

Receives a formatted string.

Python usage example

```
from bolinho_api.experiment import experiment_api
```

 ${\tt experiment_api.set_experiment_parameters("Experiment 202 < br/> {\tt Load cell: lxi92"})}$

get_readings()

get_readings()

Asks the front for the current Readings.

Returns an object of type Readings, this object gathers all the current readings of the machine. Such as Current z axis position, current load, and status

Python usage example

```
from bolinho_api.experiment import experiment_api
reading_obj = experiment_api.get_readings()
print(reading_obj.status)
```

set_readings(newValue)

set_readings(newValue)

Sets the current Readings.

Receives an object of type Readings, this object gathers all the current readings of the machine. Such as Current z axis position, current load, and status.

This function dumps the object to a JSON and sends it to the front end

```
from bolinho_api.experiment import experiment_api
from bolinho_api.classes import Readings

new_machine_readings = Readings(299, 87, 300, "not good")

experiment_api.set_readings(new_machine_readings)
```

get_description()

get_description()

Asks the front for the current description.

Returns a formatted string

Python usage example

```
from bolinho_api.experiment import experiment_api
print(experiment_api.get_description())
```

set_description(newValue)

set_description(newValue)

Sets the current description.

Receives a formatted string.

Python usage example

```
from bolinho_api.experiment import experiment_api
experiment_api.set_description("New Experiment description")
```

get_material()

get_material()

Asks the front for the current Material.

Returns an object of type Material.

```
from bolinho_api.experiment import experiment_api
material_obj = experiment_api.get_material()
print(material_obj.name)
```

set_material(newValue)

set_material(newValue)

Sets the current Material.

Receives an object of type Material

This function dumps the object to a JSON and sends it to the front end

```
from bolinho_api.experiment import experiment_api
from bolinho_api.classes import Material

current_material = Material(
   id=23,
   name="aço 22",
   batch="1",
   experimentArray=[1, 3, 2],
   supplier="Metalúrgica JOSÉ",
   extraInfo="Cilindro",
)

experiment_api.set_material(current_material)
```

5.3 Backend API

This page gathers all the API calls that can be used by the front end.

Front end -> Backend

5.3.1 Global configuration

Collection of all functions/API calls available to the front end that handles the global variables.

saveConfigParams(configParams)

```
saveConfigParams(configParams)

Saves the config parameters to the persistent file

React usage example
import { saveConfigParams } from "./api/backend-api";
saveConfigParams(globalConfig);
```

loadConfigParams()

```
loadConfigParams()

Loads the config parameters from the persistent file

React usage example
  import { loadConfigParams } from "./api/backend-api";
  globalConfig = loadConfigParams();
```

5.3.2 Data base

Collection of all functions/API calls available to the front end that handles the communication with the data base, such as fetching and storing data.

getMaterialList()

```
getMaterialList()

TODO

React usage example
  import { getMaterialList } from "./api/backend-api";
  globalConfig = getMaterialList();
```

getMaterialAt(index)

```
getMaterialAt(index)

Returns the material at an index from the database.

React usage example
import { getMaterialAt } from "./api/backend-api";

const elem21 = getMaterialAt(21);
```

getExperimentAt(index)

```
getExperimentAt(index)

Returns the experiment at an index from the database.

React usage example
import { getExperimentAt } from "./api/backend-api";

const elem21 = getExperimentAt(21);
```

getDataPointArrayAt(index)

getDataPointArrayAt(index)

Returns an array of DataPoint at an index from the database.

```
React usage example
import { getDataPointArrayAt } from "./api/backend-api";
import { DataPointType } from "types/DataPointTypes";

const dataPointArrya: DataPointType[] = getDataPointArrayAt(21);
```

5.3.3 Core

startExperimentRoutineJS()

start Experiment Routine JS ()

This function calls the start_experiment_routine() on the backend.

Usually it should be used to handle when the user press a "start experiment" button or something similar.

```
React usage example
import { getMaterialList } from "./api/backend-api";

onClick(()=>{
    startExperimentRoutineJS();
};)
```

endExperimentRoutineJS()

endExperimentRoutineJS()

This function calls the end_experiment_routine() on the backend.

Usually it should be used to handle when the user press a "end experiment" button or something similar.

```
React usage example
import { getMaterialList } from "./api/backend-api";

onClick(()=>{
    endExperimentRoutineJS();
};)
```

setCustomMovementDistanceJS()

set Custom Movement Distance JS ()

Warning

DEPRECATED

This function calls the set_custom_movement_distance(new_movement_distance) on the backend.

Sets the movement distance that the z-axis moves when the user is controlling the machine manually.

This distance is set in MILLIMETERS

Returns 1 if succeeded.

```
React usage example
import { setCustomMovementDistanceJS } from "./api/backend-api";

onClick(()=>{
    // Sets the movement distance to 50 mm
    setCustomMovementDistanceJS(50);
};)
```

returnZAxisJS()

returnZAxisJS()

This function calls the return_z_axis() on the backend.

Returns the z-axis to the origin.

Returns 1 if succeeded (if the function was acknowledged).

```
React usage example
```

```
import { returnZAxisJS } from "./api/backend-api";

onClick(()=>{
    returnZAxisJS();
};)
```

stopZAxisJS()

stopZAxisJS()

This function calls the stop_z_axis() on the backend.

Stops the z-axis.

Returns 1 if succeeded (if the function was acknowledged).

```
React usage example
import { stopZAxisJS } from "./api/backend-api";
onClick(()=>{
    stopZAxisJS();
};)
```

moveZAxisMillimetersJS()

moveZAxisMillimetersJS()

This function calls the <code>move_z_axis_millimeters()</code> on the backend. Moves the z-axis [distance]mm. This distance is set in MILLIMETERS Returns 1 if succeeded (if the function was acknowledged).

```
React usage example
import { moveZAxisMillimetersJS } from "./api/backend-api";

onClick(()=>{
    moveZAxisMillimetersJS(10);
};)
```

getAvailablePortsListJS()

getAvailablePortsListJS()

This function calls the <code>get_available_ports_list()</code> on the backend. Returns a JSON object containing the available COM ports:

```
{
    "port": x,
    "desc": y,
}

React usage example
import { getAvailablePortsListJS } from "./api/backend-api";

onClick(()=>{
    getAvailablePortsListJS().then((availablePorts)=>{
        if(availablePorts) console.log(availablePorts);
    });
};
```

connectToPortJS()

connectToPortJS()

This function calls the $connect_to_port()$ on the backend. Connects to a port. The port argument is a string like cond

Returns 1 connection was successful

```
React usage example
import { connectToPortJS } from "./api/backend-api";

onClick(()=>{
    connectToPortJS("COM3");
};)
```

5.4 Data types

All different data types will be shown in this page

ATTENTION

To see a more up to date version of the different data types pleas see src/bolinho_api/classes.py!

5.4.1 DataPoint

```
Python

class DataPoint:
    def __init__(self, x=0, y=0):
        self.x = x
        self.y = y

* x: Position at the mesure moment

* type: float

* Unity: mm

* y: Force at the mesure moment

* Type: float

* Unity: N
```

5.4.2 DataPointArray

```
class DataPointArray:
    def __init__(self, id=0, data_array=[]):
        self.id = id
        self.data_array = data_array

• id : Identification (or key) of this element on the data base.

• type: int

• Unity: mm

• data_array : Array of data points, this is the "reading" of an experiment.

• Type: [DataPoint...]

• Unity: N/A
```

5.4.3 AutoStopParams

```
Python
   class AutoStopParams:
       def __init__(self, force_loss=20, max_force=1000, max_travel=100, max_time=600):
           self.force_loss = force_loss
            self.max_force = max_force
            self.max_travel = max_travel
            self.max_time = max_time

    force_loss: Max force loss to trigger auto-stop.

• Type: float
• Unity: %
• max_force : Max force limit to trigger auto-stop.
• Type: float
• Unity: N
• max_travel: Max distance the experiment head can travel during the experiment.
• Type: float
• Unity: mm
• max_time: Experiment time limit.
• Type: float
• Unity: s
```

5.4.4 BodyParams

```
Python
   class BodyParams:
       def __init__(self, type=0, param_a=0, param_b=0, height=0):
           # Body format | 1 = Rectangle | 2 = Cylinder | 3 = Tube
            self.type = type
            # Rectangle = length | Cylinder = External diameter | Tube = External diameter
            self.param_a = param_a
            # Rectangle = depth | Cylinder = NULL | Tube = Internal diameter
            self.param_b = param_b
            # Height of the test body
            self.height = height
• type : Body format
• 1 = Rectangle
• 2 = Cylinder
• 3 = Tube
• Type: int
• Unity: N/A
• param_a : Param 'a' of the body
• Rectangle = length
• Cylinder = External diameter
• Tube = External diameter
• Type: float
• Unity: mm
• param_b : Param 'b' of the body
• Rectangle = depth
• Cylinder = NULL
• Tube = Internal diameter
• Type: float
• Unity: mm
• height : Height of the test body
• Type: float
• Unity: mm
```

5.4.5 ExperimentParams

```
Python
   class ExperimentParams:
       def __init__(
           self,
            stop_params=AutoStopParams(),
            body_params=BodyParams(),
            compress=True,
            z_speed=5,
        ):
            self.stop_params = stop_params
            self.body_params = body_params
            self.compress = compress
            self.z_speed = z_speed
• stop_params: Auto stop parameters of the experiment.
• Type: AutoStopParams
• Unity: N/A
• body_params : Body parameters of the experiment.
• Type: BodyParams
• Unity: N/A
• compress: Dictates if the experiment head move up or down. true = compress | false = expand.
• Type: bool
• Unity: N/A
• z_speed : Z axis speed during the experiment.
• Type: float
• Unity: mm/s
```

5.4.6 Date

```
Python
   class Date:
      def __init__(
          self,
            day=1,
            month=1,
            year=<mark>2023</mark>,
       ):
            self.day = day
            self.month = month
            self.year = year
• day : Day.
• Type: int
• Unity: N/A
• month: Month.
• Type: int
• Unity: N/A
• year : Year.
• Type: int
• Unity: N/A
```

5.4.7 Experiment

```
Python
   class Experiment:
       def __init__(
           self,
            id=0,
            date=Date(),
            experiment_params=ExperimentParams(),
            data_array_id=0,
            extra_info="",
        ):
            self.experiment_params = experiment_params
            self.id = id
            self.data_array_id = data_array_id
            self.extra_info = extra_info
• id: id (or key) of the experiment on the data base.
• Type: int
• Unity: N/A
• date: Date of the experiment.
• Type: Date
• Unity: N/A
• experiment_params : Parameters of the experiment.
• Type: ExperimentParams
• Unity: N/A
• data_array_id : Identification (or key) of this experiment DataPointArray or "reading", on the data base
• Type: int
• Unity: N/A
• extra_info: Extra information about the experiment.
• Type: String
• Unity: N/A
```

5.4.8 Supplier

```
Python

class Supplier:
    def __init__(self, name="NONE", email=""):
        self.name = name
        self.email = email

    name: Name of the material supplier.

    Type: String
    Unity: N/A
    email: E-mail of the supplier.

    Type: String
    Unity: N/A
```

5.4.9 Material

```
Python
   class Material:
       def __init__(
            self, id=0, name="NONE", batch=0, experiment_array=[], supplier=Supplier(), extra_info=""
        ):
            self.id = id
            self.name = name
            self.batch = batch
            # array of the ids of experiments with this material
            self.experiment_array = experiment_array
            self.supplier = supplier
            self.extra_info = extra_info
• id : Id (or key) of the material on the data base.
• Type: int
• Unity: N/A
• name : Name of the material.
• Type: String
• Unity: N/A
• batch : Batch of the material.
• Type: int
• Unity: N/A
• experiment_array : Array with the ids or keys of the experiments made with this material.
• Type: [int...]
• Unity: N/A
• supplier : Supplier of the material.
• Type: Supplier
• Unity: N/A
• extra_info: Extra information about the material.
• Type: String
• Unity: N/A
```

6. About

6.1 About

This page will present extra info about the project.

6.1.1 Licenses

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