ELASTIC NOTES

Author Madison Sheridan

Contents

| 1 | Anisotropic Derivation | | | |
|---|------------------------|----------------------------------|--|--|
| | 1.1 | Notation | | |
| | 1.2 | Hyperelasticity | | |
| | 1.3 | Uniaxial Tension Test | | |
| | 1.4 | Reduced Invariant Implementation | | |

1 Anisotropic Derivation

1.1 Notation

Recall the deformation gradient

$$\mathbb{J} := \frac{\partial \Phi \left(\boldsymbol{\xi}, t \right)}{\partial \boldsymbol{\xi}} \tag{1}$$

where Φ is the mapping from reference to current configuration. The right Cauchy-Green deformation tensor is defined as

$$C := \mathbb{J}^{\mathsf{T}} \mathbb{J}. \tag{2}$$

The reduced right Cauchy-Green deformation tensor is defined as

$$\boldsymbol{c} := \frac{\boldsymbol{C}}{|\boldsymbol{C}|^{1/3}} \tag{3}$$

1.2 Hyperelasticity

In order to guarantee the existence of solutions, the strain energy function must be sequentially weakly lower semicontinuous (s.w.l.s.) and must meet a coercivity condition [3].

[[MS: Define s.w.l.s. and coercivity condition.]]

Adopting Ball's polyconvexity framework [1] guarantees sequential weak lower semicontinuity and coercivity and, in particular, implies ellipticity. For this reason, we formulate the strain-energy function to be polyconvex.

Definition 1.1 (Polyconvexity). A function $W \in C^2(\mathbb{M}^{3\times 3}, \mathbb{R})$ is polyconvex if there exists a convex function $P : \mathbb{R}^{3\times 3} \times \mathbb{R}^{3\times 3} \times \mathbb{R} \to \mathbb{R}$ such that

$$W(\mathbb{J}) = P(\mathbb{J}, \operatorname{Adj} \mathbb{J}, \det \mathbb{J}) \tag{4}$$

for all $\mathbb{J} \in \mathbb{R}^{3 \times 3}$ with det $\mathbb{J} > 0$.

1.3 Uniaxial Tension Test

In [2, Sec. 4.1] for the Uniaxial tension tests on coronary arteries the authors describe their fiber based stress to account for the anisotropic case. They define the strain energy function in Eq. (39) as

$$e^{s} = \left(1 - 2w_{1}^{1}\right) \left[\frac{A_{1}}{2} \left(I_{1} - 3\right) + \frac{B_{1}}{2} \left(\frac{I_{2}}{I_{3}} - 3\right)\right] + 2w_{1}^{1}D_{1} \left[\frac{1}{A_{1}} \left(e^{A_{1}\left(J_{4i} - 1\right)} - 1\right) + \frac{1}{B_{1}} \left(e^{B_{1}\left(K_{5i}^{\text{inc}} - 1\right)} - 1\right)\right]$$
(5)

where

$$I_1 = \operatorname{tr} \left[\boldsymbol{C} \right]$$

$$I_2 = \frac{1}{2} \left(\operatorname{tr} \left[\boldsymbol{C} \right]^2 - \operatorname{tr} \left[\boldsymbol{C}^2 \right] \right)$$

$$I_3 = \det \left[\boldsymbol{C} \right]$$

$$I_3 = \det \left[\boldsymbol{C} \right]$$

$$I_{3i} = \operatorname{tr} \left[\boldsymbol{C}^2 \boldsymbol{G}_i \right]$$

Remark 1.2. Notice that in [2] they work in the Cauchy-Green Strain tensor C, not the reduced tensor c. To work with the reduced invariants there is no issue since in Chaimoon (2019) the work is done under the assumption of incompressibility (det |C| = 1).

Remark 1.3. Notice also that the strain energy function given in (5) is in terms of K_{5i} . This is because the invariant J_{5i} is not convex with respect to \mathbb{J} , as shown in

Reduced Invariant Implementation

We adopt the following reduced invariants

$$j_1 = \operatorname{tr} [\boldsymbol{c}]$$
 $j_{4i} = \operatorname{tr} [\boldsymbol{c}\boldsymbol{G}_i]$ $j_2 = \operatorname{tr} [\boldsymbol{c}^2]$ $j_{5i} = \operatorname{tr} [\boldsymbol{c}^2\boldsymbol{G}_i]$ $j_3 = \det [\boldsymbol{c}] = 1$ $k_{5i} = j_{5i} - j_1 j_{4i} + j_2 \operatorname{tr} [\boldsymbol{G}_i]$.

Then we have the following relationships between the invariants:

$$I_{1} = |\mathbf{C}|^{1/3} j_{1}$$

$$I_{2} = |\mathbf{C}|^{2/3} \frac{j_{1}^{2} - j_{2}}{2}$$

$$J_{5i} = |\mathbf{C}|^{2/3} j_{5i}$$

$$K_{5i} = |\mathbf{C}|^{2/3} \left(j_{5i} - j_{1} j_{4i} + \frac{j_{1}^{2} - j_{2}}{2} \right).$$

Then the strain energy function (5) becomes

$$e^{s} = \left(1 - 2w_{1}^{1}\right) \left[\frac{A_{1}}{2} \left(j_{1} - 3\right) + \frac{B_{1}}{2} \left(j_{1}^{2} - j_{2} - 6\right)\right] + 2w_{1}^{1}D_{1} \left[\frac{1}{A_{1}} \left(\exp\left\{A_{1} \left(j_{4i} - 1\right)\right\} - 1\right) + \frac{1}{B_{1}} \left(\exp\left\{\left(B_{1} \left(j_{5i} - j_{1}j_{4i} + \frac{j_{1}^{2} - j_{2}}{2}\right) - 1\right)\right\} - 1\right)\right]$$

$$(6)$$

To compute the stress, we need the partial derivatives of the strain energy function with respect to the invariants:

$$\frac{\partial e^{s}}{\partial j_{1}} = \left(1 - 2w_{1}^{1}\right) \left[\frac{A_{1}}{2} + \frac{B_{1}}{2}j_{1}\right] + 2w_{1}^{1}D_{1}\left(-j_{4i} + j_{1}\right) \exp\left\{B_{1}\left(j_{5i} - j_{1}j_{4i} + \frac{j_{1}^{2} - j_{2}}{2}\right) - 1\right\}$$
(7a)
$$\frac{\partial e^{s}}{\partial j_{2}} = -\left(1 - 2w_{1}^{1}\right) \frac{B_{1}}{4} - w_{1}^{1}D_{1} \exp\left\{B_{1}\left(j_{5i} - j_{1}j_{4i} + \frac{j_{1}^{2} - j_{2}}{2}\right) - 1\right\}$$
(7b)
$$\frac{\partial e^{s}}{\partial j_{4i}} = 2w_{1}^{1}D_{1} \left[\exp\left\{A_{1}\left(j_{4i} - 1\right)\right\} - j_{1} \exp\left\{B_{1}\left(j_{5i} - j_{1}j_{4i} + \frac{j_{1}^{2} - j_{2}}{2}\right) - 1\right\}\right]$$
(7c)
$$\frac{\partial e^{s}}{\partial j_{5i}} = 2w_{1}^{1}D_{1} \exp\left\{B_{1}\left(j_{5i} - j_{1}j_{4i} + \frac{j_{1}^{2} - j_{2}}{2}\right) - 1\right\}$$
(7d)

(7d)

We must also compute the partial derivatives of the invariants with respect to C:

$$\begin{split} \frac{\partial j_1}{\partial \mathbf{C}} &= \frac{\partial}{\partial \mathbf{C}} \left(\operatorname{tr} \left(\mathbf{c} \right) \right) \\ &= \frac{\partial}{\partial \mathbf{C}} \left[\left| \mathbf{C} \right|^{-1/3} \operatorname{tr} \left(\mathbf{C} \right) \right] \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbb{I}_d - \frac{1}{3} \left| \mathbf{C} \right|^{-4/3} \operatorname{tr} \left(\mathbf{C} \right) \operatorname{adj} \left(\mathbf{C}^T \right) \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbb{I}_d - \frac{1}{3} \left| \mathbf{C} \right|^{-1/3} \operatorname{tr} \left(\mathbf{C} \right) \operatorname{C}^{-1} \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbb{I}_d - \frac{1}{3} j_1 \mathbf{C}^{-1} \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbb{I}_d - \frac{1}{3} j_1 \mathbf{C}^{-1} \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbb{I}_d - \frac{1}{3} j_1 \mathbf{C}^{-1} \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbb{I}_d - \frac{1}{3} j_1 \mathbf{C}^{-1} \\ &= \left| \mathbf{C} \right|^{-2/3} \mathbf{C} - \frac{2}{3} \left| \mathbf{C} \right|^{-5/3} \operatorname{tr} \left(\mathbf{C}^2 \right) \operatorname{adj} \left(\mathbf{C}^T \right) \\ &= 2 \left| \mathbf{C} \right|^{-2/3} \mathbf{C} - \frac{2}{3} \left| \mathbf{C} \right|^{-5/3} \operatorname{tr} \left(\mathbf{C}^2 \right) \mathbf{C}^{-1} \\ &= 2 \left| \mathbf{C} \right|^{-2/3} \mathbf{C} - \frac{2}{3} j_2 \mathbf{C}^{-1} \\ &= 2 \left| \mathbf{C} \right|^{-2/3} \mathbf{C} - \frac{2}{3} j_2 \mathbf{C}^{-1} \\ &= \frac{\partial}{\partial \mathbf{C}} \left[\left| \mathbf{C} \right|^{-1/3} \operatorname{tr} \left(\mathbf{C} \mathbf{G}_i \right) \right] \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbf{G}_i^T - \frac{1}{3} \left| \mathbf{C} \right|^{-4/3} \operatorname{tr} \left(\mathbf{C} \mathbf{G}_i \right) \operatorname{adj} \left(\mathbf{C}^T \right) \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbf{G}_i^T - \frac{1}{3} j_{4i} \mathbf{C}^{-1} \\ &= \left| \mathbf{C} \right|^{-1/3} \mathbf{G}_i^T - \frac{1}{3} j_{4i} \mathbf{C}^{-1} \\ &= \frac{\partial}{\partial \mathbf{C}} \left[\left| \mathbf{C} \right|^{-2/3} \operatorname{tr} \left(\mathbf{C}^2 \mathbf{G}_i \right) \right] \\ &= \frac{\partial}{\partial \mathbf{C}} \left[\left| \mathbf{C} \right|^{-2/3} \operatorname{tr} \left(\mathbf{C}^2 \mathbf{G}_i \right) \right] \\ &= \left| \mathbf{C} \right|^{-2/3} \left(\mathbf{G}_i^T \mathbf{C}^T + \mathbf{C}^T \mathbf{G}_i^T \right) - \frac{2}{3} \left| \mathbf{C} \right|^{-5/3} \operatorname{tr} \left(\mathbf{C}^2 \mathbf{G}_i \right) \operatorname{adj} \left(\mathbf{C}^T \right) \\ &= \left| \mathbf{C} \right|^{-2/3} \left(\mathbf{G}_i^T \mathbf{C}^T + \mathbf{C}^T \mathbf{G}_i^T \right) - \frac{2}{3} \left| \mathbf{C} \right|^{-2/3} \operatorname{tr} \left(\mathbf{C}^2 \mathbf{G}_i \right) \mathbf{C}^{-1} \\ &= \left| \mathbf{C} \right|^{-2/3} \left(\mathbf{G}_i^T \mathbf{C}^T + \mathbf{C}^T \mathbf{G}_i^T \right) - \frac{2}{3} j_{5i} \mathbf{C}^{-1} \\ &= 2 \left| \mathbf{C} \right|^{-2/3} \mathbf{C} \mathbf{G}_i - \frac{2}{2} j_{5i} \mathbf{C}^{-1} \end{aligned}$$

where particularly for the derivation of $\frac{\partial j_{5i}}{\partial C}$ we have used the fact that

$$rac{\partial}{\partial oldsymbol{C}}\operatorname{tr}\left(oldsymbol{C}^2oldsymbol{G}_i
ight) = oldsymbol{G}_i^{\mathsf{T}}oldsymbol{C}^{\mathsf{T}} + oldsymbol{C}^{\mathsf{T}}oldsymbol{G}_i^{\mathsf{T}}$$

and since C and G_i are both symmetric. In particular, this implies for the Cauchy stress tensor that

$$\mathbb{J}\frac{\partial j_1}{\partial \mathbf{C}}\mathbb{J}^{\mathsf{T}} = \mathbf{b} - \frac{1}{3}j_1\mathbb{I}$$
 (8a)

$$\mathbb{J}\frac{\partial j_2}{\partial \mathbf{C}}\mathbb{J}^{\mathsf{T}} = 2\mathbf{b}^2 - \frac{2}{3}j_2\mathbb{I}$$
 (8b)

$$\mathbb{J}\frac{\partial j_{4i}}{\partial \boldsymbol{C}}\mathbb{J}^{\mathsf{T}} = \boldsymbol{b}\boldsymbol{G}_{i} - \frac{1}{3}j_{4i}\mathbb{I}$$
(8c)

$$\mathbb{J}\frac{\partial j_{5i}}{\partial \boldsymbol{C}}\mathbb{J}^{\mathsf{T}} = 2\boldsymbol{b}^{2}\boldsymbol{G}_{i} - \frac{2}{3}j_{5i}\mathbb{I}$$
(8d)

With the definition of the strain energy and the above partial derivatives, our stress tensor then takes the form

$$\sigma = 2\rho \frac{\partial e^{s}}{\partial \mathbf{C}} \mathbf{C} - \rho^{2} \frac{\partial e^{h}}{\partial \rho} \mathbb{I}$$

$$= 2\rho \left[\frac{\partial e^{s}}{\partial j_{1}} \frac{\partial j_{1}}{\partial \mathbf{C}} \mathbf{C} + \frac{\partial e^{s}}{\partial j_{2}} \frac{\partial j_{2}}{\partial \mathbf{C}} \mathbf{C} \right] - \rho^{2} \frac{\partial e^{h}}{\partial \rho} \mathbb{I} + 2\rho \left[\frac{\partial e^{s}}{\partial j_{4i}} \frac{\partial j_{4i}}{\partial \mathbf{C}} \mathbf{C} + \frac{\partial e^{s}}{\partial j_{5i}} \frac{\partial j_{5i}}{\partial \mathbf{C}} \mathbf{C} \right]$$

$$= 2\rho \left[\frac{\partial e^{s}}{\partial j_{1}} \left(\mathbf{c} - \frac{1}{3} j_{1} \mathbb{I} \right) + 2 \frac{\partial e^{s}}{\partial j_{2}} \left(\mathbf{c}^{2} - \frac{1}{3} j_{2} \mathbb{I} \right) \right] - \rho^{2} \frac{\partial e^{h}}{\partial \rho} \mathbb{I}$$

$$+ 2\rho \left[\frac{\partial e^{s}}{\partial j_{4i}} \left(\mathbf{c} \mathbf{G}_{i} - \frac{1}{3} j_{4i} \mathbb{I} \right) + 2 \frac{\partial e^{s}}{\partial j_{5i}} \left(\mathbf{c}^{2} \mathbf{G}_{i} - \frac{1}{3} j_{5i} \mathbb{I} \right) \right]$$

References

- [1] John M Ball. Convexity conditions and existence theorems in nonlinear elasticity. Archive for rational mechanics and Analysis, 63(4):337–403, 1976.
- [2] Krit Chaimoon and Prinya Chindaprasirt. An anisotropic hyperelastic model with an application to soft tissues. European Journal of Mechanics A/Solids, 78:103845, 2019. ISSN 0997-7538. doi: https://doi.org/10.1016/j.euromechsol.2019.103845. URL https://www.sciencedirect.com/science/article/pii/S0997753818309884.
- [3] J. Schröder, P. Neff, and V. Ebbing. Anisotropic polyconvex energies on the basis of crystallographic motivated structural tensors. <u>Journal of the Mechanics and Physics of Solids</u>, 56(12):3486-3506, 2008. ISSN 0022-5096. doi: https://doi.org/10.1016/ j.jmps.2008.08.008. URL https://www.sciencedirect.com/science/article/pii/ S0022509608001373.
- [4] Jörg Schröder and Patrizio Neff. Invariant formulation of hyperelastic transverse isotropy based on polyconvex free energy functions. International Journal of Solids and Structures, 40(2):401-445, 2003. ISSN 0020-7683. doi: https://doi.org/10.1016/S0020-7683(02)00458-4. URL https://www.sciencedirect.com/science/article/pii/S0020768302004584.