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```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Exercise 6      TTK4130      Helene Hogstad Fossum      %
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
```

PROBLEM 4C

Parameters

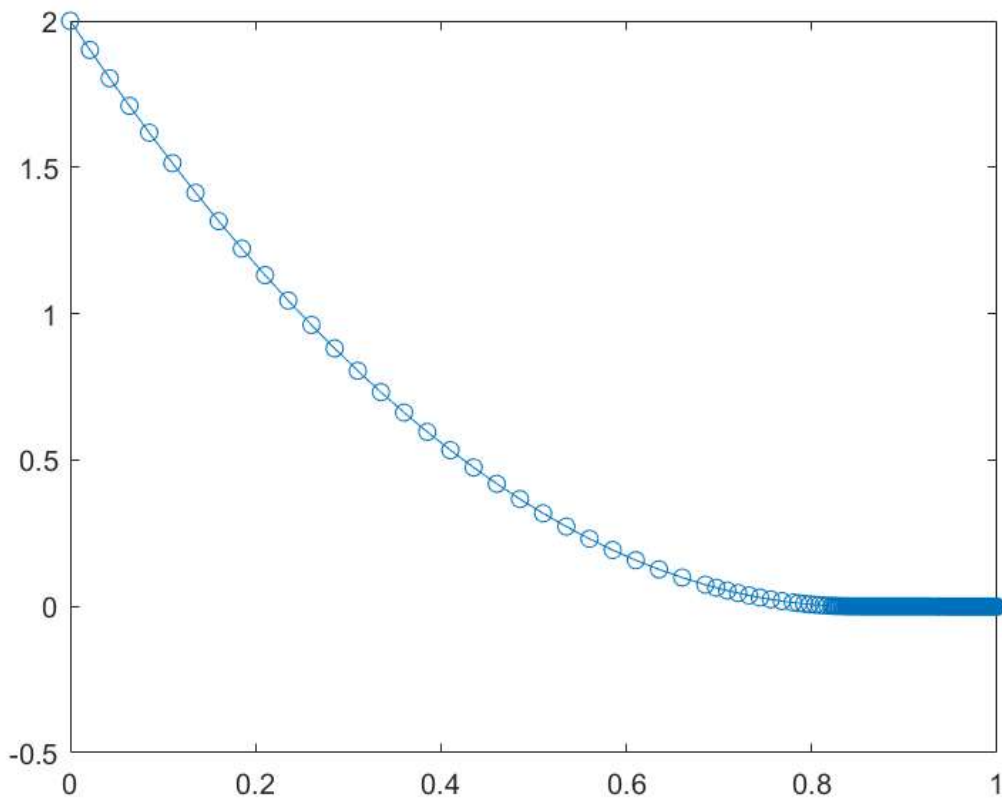
```
rho = 1000;      % [kg/m^3]
A = 4.5;         % [m^2]
g = 10;          % [m/s^2]
C_v = 0.15;      % [m^3/(s*sqrt(Pa))] The valve constant
h_0 = 2;         % [m] Initial value

f = @(t,h) (-C_v/A)*sqrt(rho*g*h);      % The function for dh/dt
tspan = [0 1];                          % The time span we want to simulate

% Solving
[t,h] = ode45(f,tspan,h_0);

% % Plot
plot(t,h,'o-');
```

Warning: Imaginary parts of complex X and/or Y arguments ignored



Comments

The steplengths decreases as h approaches 0 as we would expect judging from Problem 4b.