

# CS 341: Algorithms

## Module 7: Graph Algorithms

Armin Jamshidpey, Eugene Zima

Based on lecture notes by many previous CS 341 instructors

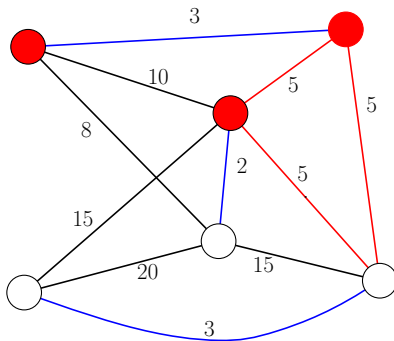
David R. Cheriton School of Computer Science, University of Waterloo

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# Minimum spanning tree

- Problem: In an undirected graph with non-negative weights on edges, find a spanning tree of minimum total weight
- Motivation: cheapest interconnection (electrical circuit, computer network, highway system)
- Important subroutine for network optimization problems

## Example of MST



Blue edges with any two of red edges give an MST

# MST approaches

- Solution is not necessarily unique
- There are many algorithms
- General idea of greedy algorithms:

$A \leftarrow \emptyset$

while  $A$  is not a spanning tree

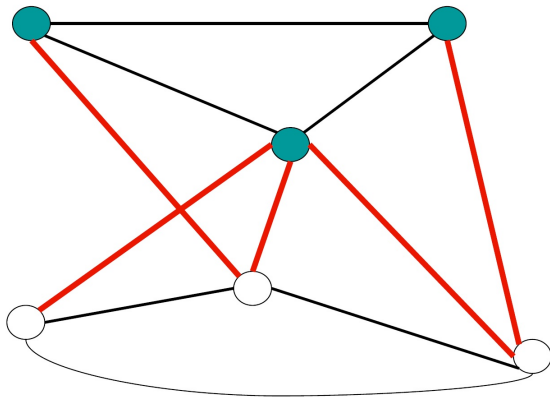
    find edge  $e$  of least weight with

    "certain properties"

    add  $e$  to  $A$

## Finding an edge to add

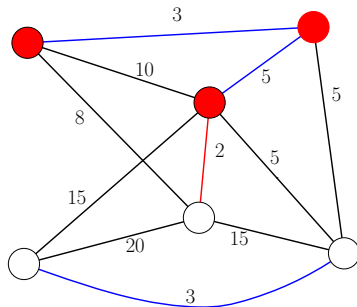
- Cut: partition of  $V = (S, V - S)$
- Crossing edge: has endpoint in each set



# Correctness of MST algorithm

## Theorem 1

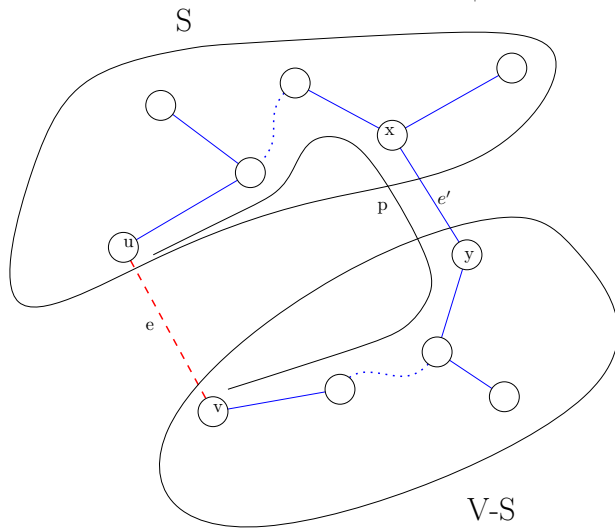
If  $A$  can be extended to a MST, and no edge in  $A$  crosses  $(S, V - S)$ , then the edge of minimum weight crossing this cut can be added to  $A$ .



# Proof of Theorem 1

- Suppose we can find  $A$ ,  $S$ , and edge  $e$  contradicting this. Then  $A \cup \{e\}$  cannot be extended to a MST.
- Let  $T$  be a MST extending  $A$ .
- Adding  $e$  to  $T$  creates a unique cycle.

# Proof of Theorem 1



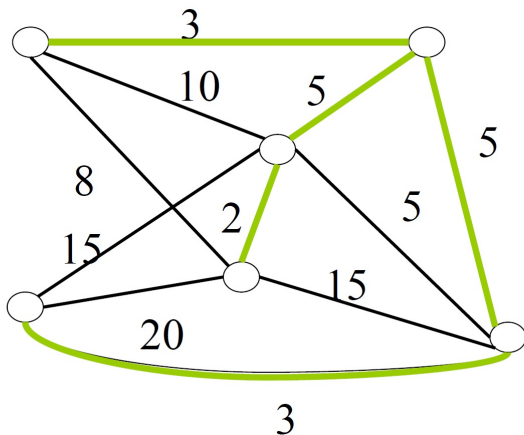


# Proof of Theorem 1

- Adding  $e$  to  $T$  creates unique cycle
- Some other edge  $e'$  in this cycle also crosses the cut defined by  $S$
- $e'$  is not in  $A$  since it crosses the cut
- Weight of  $e'$  is at least weight of  $e$
- $T \cup \{e\} - \{e'\}$  is also a spanning tree and must have weight no greater than  $T$
- This is a MST extending  $A \cup \{e\}$ .

# Kruskal's algorithm

- “certain property” = can be added to  $A$  without forming a cycle



# Correctness of Kruskal's algorithm

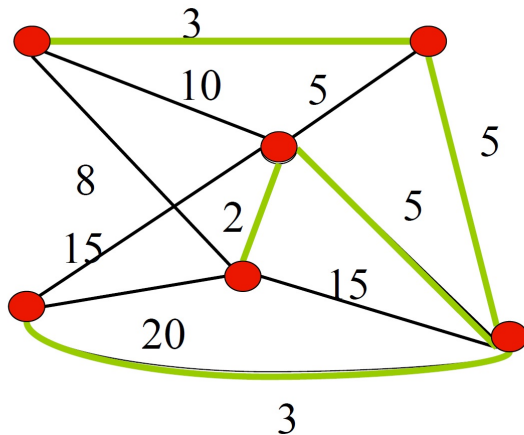
- During the algorithm,  $A$  is a forest of trees (stops when it is a single tree)
- What is the cut we can use in Theorem 1?
- $e = (u, v)$  is lightest edge that can be added without forming a cycle
- Let  $S$  be the vertices in the tree in  $A$  containing  $u$
- $v$  must be in  $V - S$  (or  $e$  would form cycle)
- $e$  must be lightest edge crossing this cut

# Running time of Kruskal's algorithm

- Maintain components of  $A$
- Presort edges, run through them in order
- Given  $e = (u, v)$ , it can be added to  $A$  if and only if  $u, v$  are in different components
- Adding  $e$  to  $A$  merges these components
- Need union-find data structure
- Loop executed  $n - 1$  times
- Sequence of  $n - 1$  unions and  $2m$  finds can be done in  $O(m \log n)$  time
- Algorithm takes  $\Theta(m \log n)$  time

# Prim's algorithm

- “certain property” = one endpoint shared with edge in  $A$ , one is not (i.e. leaves  $A$ )



# Correctness of Prim's algorithm

- $A$  is always a single tree (stops when it is a spanning tree)
- What is the cut we can use in Thm 1?
- $S$  = endpoints of edges in  $A$  (or starting vertex  $s$  if  $A$  is empty)
- Implementation is not so obvious: how do we find lightest edge crossing cut  $(S, V - S)$ ?

# Implementation of Prim's algorithm

- For each vertex  $v$  in  $V - S$ , maintain  $near[v] = a \in S$  such that edge  $(v, a)$  is lightest edge from  $v$  to  $S$
- Initially  $near[v] = s$
- Add to  $S$  the vertex  $w$  minimizing weight of  $(near[w], w)$  [takes  $\Theta(n)$  time]
- When  $w$  added to  $S$ , update  $near[v]$  if  $(w, v)$  is lighter than  $(near[v], v)$  [takes  $\Theta(n)$  time]
- Total running time  $\Theta(n^2)$

## Better implementation

- Keep vertices not in  $S$  in heap, ordered by near values
- Removing min or updating single near value takes takes  $\Theta(\log n)$  time
- $n - 1$  removals,  $m$  updates
- Running time is  $\Theta(m \log n)$
- Even better improvement uses Fibonacci heaps to get time of  $\Theta(m + n \log n)$ .



# Single-source shortest path

- Think of weights as lengths of edges
- Given a weighted graph and source  $s$ ,  $\delta(s, v)$  = length of shortest  $s - v$  path
- We wish to compute all  $\delta(s, v)$  [and the corresponding paths]
- If edge weights are nonnegative, a greedy algorithm will work (Dijkstra's algorithm)
- General proof in book simplified here

# Dijkstra's algorithm

- Looks similar to Prim's MST algorithm
- Start with source  $s$  in set  $S$
- For vertices  $v$  not in  $S$ , maintain quantities
  - ▶  $\pi[v]$ , a vertex in  $S$
  - ▶  $d[v]$  which is  $\delta(s, \pi[v]) + w(\pi[v], v)$
- Intuition:  $d[v]$  is the length of the shortest path to  $v$  using vertices in  $S$  only (call this an  $S$ -internal path), and  $\pi[v]$  is the last vertex in  $S$  on this path

# Dijkstra's algorithm

- Initially  $S \leftarrow \{s\}$ ,  $d[s] \leftarrow 0$  and for all  $v$  not in  $S$ , if  $(s, v) \in E$  then  $\pi[v] \leftarrow s$  and  $d[v] \leftarrow w(s, v)$  otherwise  $\pi[v] \leftarrow nil$  and  $d[v] \leftarrow \infty$
- To choose a vertex  $u$  to add to  $S$ , pick one with smallest  $d$ -value
- Update other  $d$ -values with

$$d[v] \leftarrow \min\{d[v], d[u] + w(u, v)\}$$

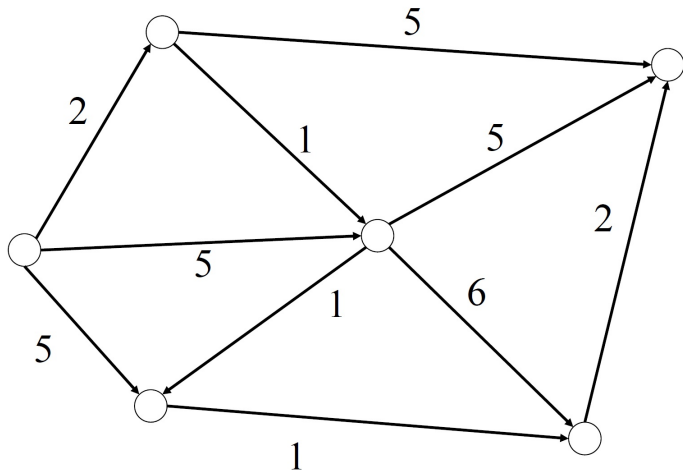
- We prove this works by induction on the size of  $S$

# Pseudocode for Dijkstra's algorithm

```
Initialize  $S, d, \pi$ 
while  $S \neq V$ 
     $u \leftarrow v \notin S$  minimizing  $d[v]$ 
    add  $u$  to  $S$ 
    for  $v \notin S$ 
         $d[v] \leftarrow \min\{d[v], d[u] + w(u, v)\}$ 
        (if  $d[v]$  changes,  $\pi[v] \leftarrow u$ )
```

- Running time of algorithm is  $\Theta(n^2)$

## Example of Dijkstra's alg'm



# Proof of Dijkstra's algorithm

- Prove by induction on  $|S|$  that
  - ① For all  $v \in S$ ,  $d[v] = \delta(s, v)$
  - ② For all  $w \notin S$ ,  $d[w]$  = length of minimum  $S$ - internal  $s - w$  path (so  $d[w] \geq \delta(s, w)$ ) and  $\pi[w]$  = last vertex on such a path
  - ③ For any  $v \in S$ ,  $w \notin S$ ,  $d[v] \leq d[w]$
- Base case:  $|S| = 1$ 
  - ▶ Since  $d[s] = 0$  and for all  $v$  not in  $S$ ,  $\pi[v] = s$  and  $d[v] = w(s, v)$ , these are trivially true

# Proving statement 1

- Assume statements true for  $|S| = k - 1$
- When  $k^{th}$  vertex  $u$  chosen to be added to  $S$ ,  $d[u]$  = length of a shortest  $S$ -internal path to  $u$  (by inductive hypothesis 2)
- Suppose  $d[u] > \delta(s, u)$
- Choose any shortest  $s - u$  path  $P$
- It leaves  $S$  for the first time by some edge  $(x, y)$  and by ind.hyp. 1,  $d[x] = \delta(s, x)$
- The segment of  $P$  from  $s$  to  $y$  has length  $d[y]$  (by ind.hyp 2) so  $d[y] \leq \delta(s, u) < d[u]$ , contradicting the choice of  $u$ ; so statement 1 is true

## Proving statement 2

- Thus when  $k^{th}$  vertex  $u$  added to  $S$ ,  $d[u] = \delta(s, u)$ , as required
- After  $u$  added, what do shortest  $S$ -internal path to  $v \notin S$  look like?
- If one does not use  $u$ , then it must be the shortest  $(S - \{u\})$ -internal path to  $v$ , and this path has length  $d[v] \leq d[u] + w(u, v)$ , so the algorithm does not change anything
- If one uses  $u$  and  $(u, v)$  is the last edge, the path has length  $\delta(s, u) + w(u, v)$ , so the algorithm updates correctly



## Proving statements 2 and 3

- If one uses  $u$  but some  $(y, v)$  is the last edge
  - ▶  $d[y] \leq d[u]$  (ind. hyp. 3)
  - ▶  $u$  was just added, so the shortest  $s - y$  path doesn't use  $u$
  - ▶ Adding  $(y, v)$  gives a shortest  $S$ -internal path to  $v$  avoiding  $u$
  - ▶ The algorithm does not change anything
- Thus statement 2 is proved
- Statement 3 follows because of the choice of  $u$  minimizing  $d[u]$
- Where did we use non-negativity?