CS 341: Algorithms Module 8: Intractability and Undecidability

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Certificates

Certificate: Informally, a certificate for a yes-instance I is some "extra information" C which makes it easy to verify that I is a yes-instance.

Certificate Verification Algorithm: Suppose that Ver is an algorithm that verifies certificates for yes-instances. Then Ver(I,C) outputs "yes" if I is a yes-Instance and C is a valid certificate for I. If Ver(I,C) outputs "no", then either I is a no-instance, or I is a yes-instance and C is an invalid certificate.

Polynomial-time Certificate Verification Algorithm: A certificate verification algorithm Ver is a polynomial-time certificate verification algorithm if the complexity of Ver is $O(n^k)$, where k is a positive integer and n = Size(I).

The Complexity Class NP

Certificate Verification Algorithm: A certificate verification algorithm Ver is said to solve a decision problem Π provided that

- for every yes-instance I, there exists a certificate C such that Ver(I,C) outputs "yes".
- for every no-instance I and for every certificate C, Ver(I, C) outputs "no".

The Complexity Class NP denotes the set of all decision problems that have polynomial-time certificate verification algorithms solving them. We write $\Pi \in NP$ if the decision problem Π is in the complexity class NP.

Finding Certificates vs Verifying Certificates: It is not required to be able to find a certificate C for a yes-instance in polynomial time in order to say that a decision problem $\Pi \in NP$.

Important Fact: $P \subseteq NP$.

Certificate verification algorithm for subset sum.

Recall subset sum problem has as input an array of integers a_1, a_2, \ldots, a_n and an integer S (target value).

The question is whether or not there is subset of integers a_1, a_2, \ldots, a_n that sums to S.

A certificate consists of an array $B = [b_1, \dots, b_n], b_i \in \{0, 1\}.$

```
SubS-D_verifier(a,S,B) {
   for i = 1 to n do
      S = S - a[i]*b[i]
   od
   return (S==0)
}
```

The verification algorithm takes time $\Theta(n)$, so it is polynomial time in size of the instance. Thus, **SubS-D** \in *NP*.

Recall **CLIQUE-D** decision problem: given a graph G = (V, E), and an integer k, decide if graph G has a cliques of size $\geq k$. A certificate is subset $C \subseteq V$ that might be a clique of size $\geq k$.

```
CLIQUE-D_verifier(V,E,k,C) {
 m = |C|;
  if m<k return FALSE;
  for i = 1 to |C|-1 do
    for j = i+1 to |C| do
      if E[C[i],C[j]]==0
//
        edge (C[i],C[j]) is not in E
        then return FALSE;
    od
  od
 return TRUE;
```

The verification algorithm takes time $O(|V|^2)$, so it is polynomial time in size of the instance. Thus **CLIQUE-D** \in *NP*.

Certificate Verification Algorithm for Hamiltonian Cycle

A certificate consists of an *n*-tuple, $X = [x_1, ..., x_n]$, that might be a hamiltonian cycle for a given graph G = (V, E) (where n = |V|).

Algorithm 1: Hamiltonian Cycle Certificate Verification (G, X)

```
1 flag \leftarrow true

2 Used \leftarrow \{x_1\}

3 j \leftarrow 2

4 while (j \le n) and flag do

5 flag \leftarrow (x_j \notin Used) and (\{x_{j-1}, x_j\} \in E)

6 If (j = n) then flag \leftarrow flag and (\{x_n, x_1\} \in E)

7 Used \leftarrow Used \cup \{x_j\}

8 j \leftarrow j + 1

9 return (flag)
```

Polynomial Transformations

For a decision problem Π , let $\mathcal{I}(\Pi)$ denote the set of all instances of Π . Let $\mathcal{I}_{yes}(\Pi)$ and $\mathcal{I}_{no}(\Pi)$ denote the set of all yes-instances and no-instances (respectively) of Π .

Suppose that Π_1 and Π_2 are decision problems. We say that there is a polynomial transformation from Π_1 to Π_2 (denoted $\Pi_1 \leq_P \Pi_2$) if there exists a function $f: \mathcal{I}(\Pi_1) \to \mathcal{I}(\Pi_2)$ such that the following properties are satisfied:

- f(I) is computable in polynomial time (as a function of size(I), where $I \in \mathcal{I}(\Pi_1)$)
- if $I \in \mathcal{I}_{yes}(\Pi_1)$, then $f(I) \in \mathcal{I}_{yes}(\Pi_2)$
- if $I \in \mathcal{I}_{no}(\Pi_1)$, then $f(I) \in \mathcal{I}_{no}(\Pi_2)$

Polynomial Transformations (cont.)

Polynomial transformations are also known as Karp reductions or many-one reductions.

A polynomial transformation can be thought of as a (simple) special case of a polynomial-time Turing reduction, i.e., if $\Pi_1 \leq_P \Pi_2$, then $\Pi_1 \leq_P^T \Pi_2$. Given a polynomial transformation f from Π_1 to Π_2 , the corresponding Turing reduction is as follows:

- Given $I \in \mathcal{I}(\Pi_1)$, construct $f(I) \in \mathcal{I}(\Pi_2)$.
- Given an oracle for Π_2 , say A, run A(f(I)).

We transform the instance, and then make a single call to the oracle.

Very important point: We do not know whether I is a yes-instance or a no-instance of Π_1 when we transform it to an instance f(I) of Π_2 .

To prove the implication "if $I \in \mathcal{I}_{no}(\Pi_1)$, then $f(I) \in \mathcal{I}_{no}(\Pi_2)$ ", we usually prove the contrapositive statement "if $f(I) \in \mathcal{I}_{yes}(\Pi_2)$, then $I \in \mathcal{I}_{ves}(\Pi_1)$.

Two Graph Theory Decision Problems

Clique Problem

Instance: An undirected graph G = (V, E) and an integer k,

where $1 \le k \le |V|$.

Question: Does G contain a clique of size $\geq k$? (A clique is a

subset of vertices $W \subseteq V$ such that $uv \in E$ for all

 $u, v \in W, u \neq v.$

Vertex Cover Problem

Instance: An undirected graph G = (V, E) and an integer k, where $1 \le k \le |V|$.

Question: Does G contain a vertex cover of size $\leq k$? (A vertex cover is a subset of vertices $W \subseteq V$ such that $\{u,v\} \cap W \neq \emptyset$ for all edges $uv \in E$.)

Clique \leq_P Vertex-Cover

Suppose that I = (G, k) is an instance of Clique, where G = (V, E), $V = \{v_1, \ldots, v_n\}$ and $1 \le k \le n$. Construct an instance $f(I) = (H, \ell)$ of Vertex Cover, where H = (V, F), $\ell = nk$ and

$$v_i v_j \in F \Leftrightarrow v_i v_j \notin E$$
.

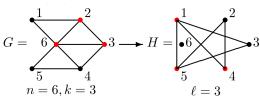
H is called the complement of G, because every edge of G is a non-edge of H and every non-edge of G is an edge of G. We have $Size(I) = n^2 + \log_2 k \in \Theta(n^2)$. Computing H takes time $\Theta(n^2)$ and computing ℓ takes time $\Theta(\log n)$, so f(I) can be computed in time $\Theta(Size(I))$, which is polynomial time.

Clique \leq_P Vertex-Cover (cont.)

Suppose I is a yes-instance of Clique. Therefore there exists a set of k vertices W such that $uv \in E$ for all $u,v \in W$. Define $W' = V \setminus W$.

Clearly $|W'|=n-k=\ell$. We claim that W' is a vertex cover of H. Suppose $uv\in F$ (so $uv\notin E$). If $\{u,v\}\cap W'\neq\emptyset$, we are done, so assume $u,v\notin W'$. Therefore $u,v\in W$. But $uv\notin E$, so W is not a clique. This is a contradiction and hence f(I) is a yes-instance of Vertex Cover.

Suppose f(I) is a yes-instance of Vertex Cover. Therefore there exists a set of $\ell = n-k$ vertices W' that is a vertex cover of H. Define $W = V \setminus W'$. Clearly |W| = k. We claim that W is a clique in $G \dots$



Properties of Polynomial-time Transformations

Theorem 1

If Π_1 and Π_2 are decision problems, $\Pi_1 \leq_P \Pi_2$ and $\Pi_2 \in P$, then $\Pi_1 \in P$.

Proof.

Suppose A is a poly-time algorithm for Π_2 , having complexity $O(m^\ell)$ on an instance of size m. Suppose f is a transformation from Π_1 to Π_2 having complexity $O(n^k)$ on an instance of size n. We solve Π_1 as follows:

- **1** Given $I \in \mathcal{I}(\Pi_1)$, construct $f(I) \in \mathcal{I}(\Pi_2)$.
- ② Run A(f(I)).

It is clear that this yields the correct answer. We need to show that these two steps can be carried out in polynomial time as a function of n = Size(I). Step (1) can be executed in time $O(n^k)$ and it yields an instance f(I) having size $m \in O(n^k)$. Step (2) takes time $O(m^\ell)$. Since $m \in O(n^k)$, the time for step (2) is $O(n^{k\ell})$, as is the total time to execute both steps.

Properties of Polynomial-time Transformations (cont.)

Theorem 2

Suppose that Π_1,Π_2 and Π_3 are decision problems. If $\Pi_1\leq_P\Pi_2$ and $\Pi_2\leq_P\Pi_3$, then $\Pi_1\leq_P\Pi_3$.

Proof

We have a polynomial transformation f from Π_1 to Π_2 , and another polynomial transformation g from Π_2 to Π_3 . We define $h=f\circ g$, i.e., h(I)=g(f(I)) for all instances I of Π_1 . (Exercise: fill in the details.)

The Complexity Class NPC

The complexity class \overline{NPC} denotes the set of all decision problems Π that satisfy the following two properties:

- Π ∈ NP
- For all $\Pi' \in NP$, $\Pi' \leq_P \Pi$.

NPC is an abbreviation for NP-complete.

Note that the definition does not imply that NP-complete problems exist!