

## 12.1 AdjacencyMatrix: Representing a Graph by a Matrix

An adjacency matrix is a way of representing an  $n$  vertex graph  $G = (V, E)$  by an  $n \times n$  matrix,  $\mathbf{a}$ , whose entries are boolean values.

```
int n;
boolean[][] a;
AdjacencyMatrix(int n0) {
    n = n0;
    a = new boolean[n][n];
}
```

The matrix entry  $\mathbf{a}[\mathbf{i}][\mathbf{j}]$  is defined as

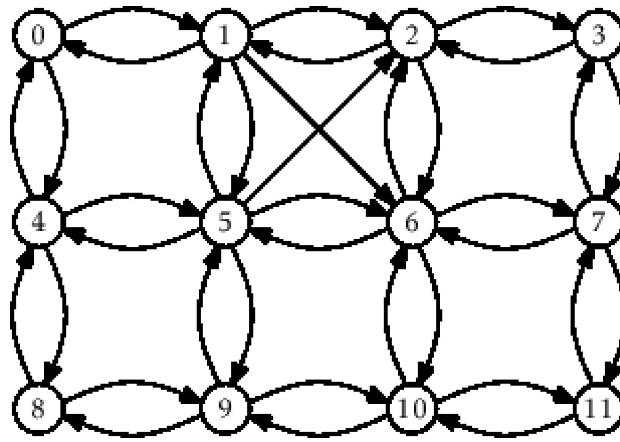
$$\mathbf{a}[\mathbf{i}][\mathbf{j}] = \begin{cases} \text{true} & \text{if } (i, j) \in E \\ \text{false} & \text{otherwise} \end{cases}$$

The adjacency matrix for the graph in [Figure 12.1](#) is shown in [Figure 12.2](#).

In this representation, the operations `addEdge(i, j)`, `removeEdge(i, j)`, and `hasEdge(i, j)` just involve setting or reading the matrix entry  $\mathbf{a}[\mathbf{i}][\mathbf{j}]$ :

```
void addEdge(int i, int j) {
    a[i][j] = true;
}
void removeEdge(int i, int j) {
    a[i][j] = false;
}
boolean hasEdge(int i, int j) {
    return a[i][j];
}
```

These operations clearly take constant time per operation.



	0	1	2	3	4	5	6	7	8	9	10	11
0	0	1	0	0	1	0	0	0	0	0	0	0
1	1	0	1	0	0	1	1	0	0	0	0	0
2	1	0	0	1	0	0	1	0	0	0	0	0
3	0	0	1	0	0	0	0	1	0	0	0	0
4	1	0	0	0	0	1	0	0	1	0	0	0
5	0	1	1	0	1	0	1	0	0	1	0	0
6	0	0	1	0	0	1	0	1	0	0	1	0
7	0	0	0	1	0	0	1	0	0	0	0	1
8	0	0	0	0	1	0	0	0	0	1	0	0
9	0	0	0	0	0	1	0	0	1	0	1	0
10	0	0	0	0	0	0	1	0	0	1	0	1
11	0	0	0	0	0	0	0	1	0	0	1	0

**Figure 12.2:** A graph and its adjacency matrix.

Where the adjacency matrix performs poorly is with the `outEdges(i)` and `inEdges(i)` operations. To implement these, we must scan all `n` entries in the corresponding row or column of `a` and gather up all the indices, `j`, where `a[i][j]`, respectively `a[j][i]`, is true.

```

List<Integer> outEdges(int i) {
    List<Integer> edges = new ArrayList<Integer>();
    for (int j = 0; j < n; j++)
        if (a[i][j]) edges.add(j);
    return edges;
}

List<Integer> inEdges(int i) {
    List<Integer> edges = new ArrayList<Integer>();
    for (int j = 0; j < n; j++)
        if (a[j][i]) edges.add(j);
}

```

```
    return edges;
}
```

These operations clearly take  $O(n)$  time per operation.

Another drawback of the adjacency matrix representation is that it is large. It stores an  $n \times n$  boolean matrix, so it requires at least  $n^2$  bits of memory. The implementation here uses a matrix of `boolean` values so it actually uses on the order of  $n^2$  bytes of memory. A more careful implementation, which packs  $w$  boolean values into each word of memory, could reduce this space usage to  $O(n^2/w)$  words of memory.

**Theorem 12..1** *The AdjacencyMatrix data structure implements the Graph interface. An AdjacencyMatrix supports the operations*

- `addEdge(i, j)`, `removeEdge(i, j)`, and `hasEdge(i, j)` in constant time per operation; and
- `inEdges(i)`, and `outEdges(i)` in  $O(n)$  time per operation.

*The space used by an AdjacencyMatrix is  $O(n^2)$ .*

Despite its high memory requirements and poor performance of the `inEdges(i)` and `outEdges(i)` operations, an AdjacencyMatrix can still be useful for some applications. In particular, when the graph  $G$  is dense, i.e., it has close to  $n^2$  edges, then a memory usage of  $n^2$  may be acceptable.

The AdjacencyMatrix data structure is also commonly used because algebraic operations on the matrix `a` can be used to efficiently compute properties of the graph  $G$ . This is a topic for a course on algorithms, but we point out one such property here: If we treat the entries of `a` as integers (1 for `true` and 0 for `false`) and multiply `a` by itself using matrix multiplication then we get the matrix `a2`. Recall, from the definition of matrix multiplication, that

$$a^2[i][j] = \sum_{k=0}^{n-1} a[i][k] \cdot a[k][j] .$$

Interpreting this sum in terms of the graph  $G$ , this formula counts the number of vertices,  $k$ , such that  $G$  contains both edges  $(i, k)$  and  $(k, j)$ . That is, it counts the number of paths from  $i$  to  $j$  (through intermediate vertices,  $k$ ) whose length is exactly two. This observation is the foundation of an algorithm that computes the shortest paths between all pairs of vertices in  $G$  using only  $O(\log n)$  matrix multiplications.

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