

Digital Logic Design

Clocks and Sequential Circuits

- Two types of sequential circuits:

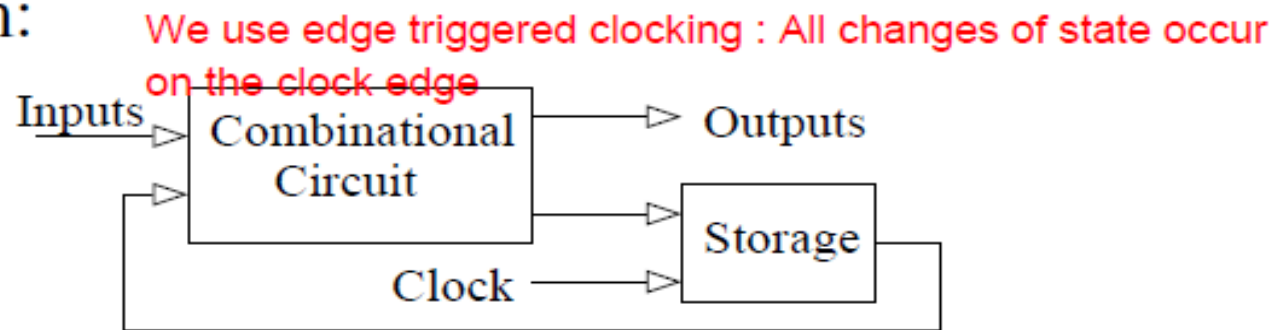
- Synchronous: has a clock

Memory changes only at discrete points in time

Clock pulse: Free running signal with a fixed cycle time:



Block diagram:



Easier to analyze, tend to be more stable

- Asynchronous: no clock

Potentially faster and less power-hungry, but harder to design and analyze

Clocks and Sequential Circuits

- Two types of sequential circuits:

- Synchronous: has a clock

Memory changes only at discrete points in time

Clock pulse: Free running signal with a fixed cycle time:



Clock Cycle: From one rising edge to another rising edge

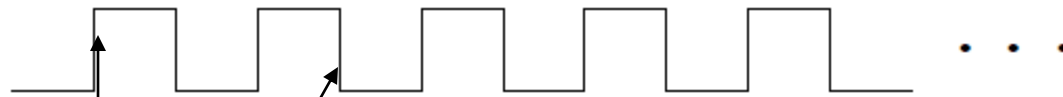
Clocks and Sequential Circuits

- Two types of sequential circuits:

- Synchronous: has a clock

Memory changes only at discrete points in time

Clock pulse: Free running signal with a fixed cycle time:



Rising Edge

Falling Edge

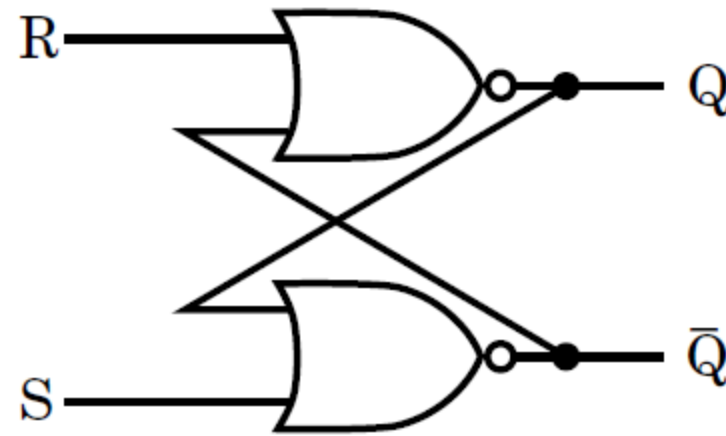
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Set/Reset Latch

SR Latch with NOR gates

- SR Latch with NOR gates

Simplist Memory Element UNLOCKED



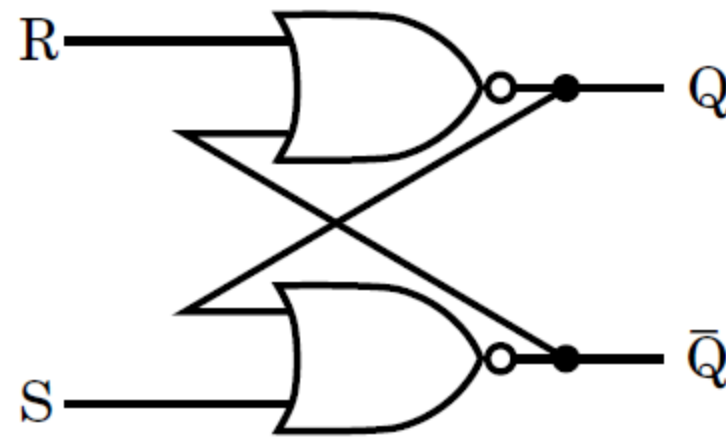
Values of Q represent stored state and its complement. This value is recycled through NOR gates and again we get the values of Q

Set/Reset Latch

SR Latch with NOR gates

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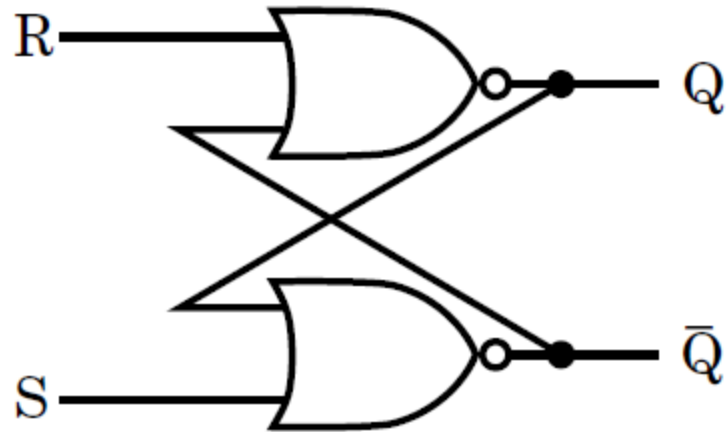
Simplist Memory Element UNLOCKED



Values of Q represent stored state and its complement. This value is recycled through NOR gates and again we get the values of Q

S, R transition	Q, \bar{Q} transition
$1, 0 \rightarrow 0, 0$	\rightarrow
$0, 1 \rightarrow 0, 0$	\rightarrow
$1, 1 \rightarrow 0, 0$	\rightarrow

Maintaining the State : Or Value of Q as a memory Bit



$$Q = 1$$

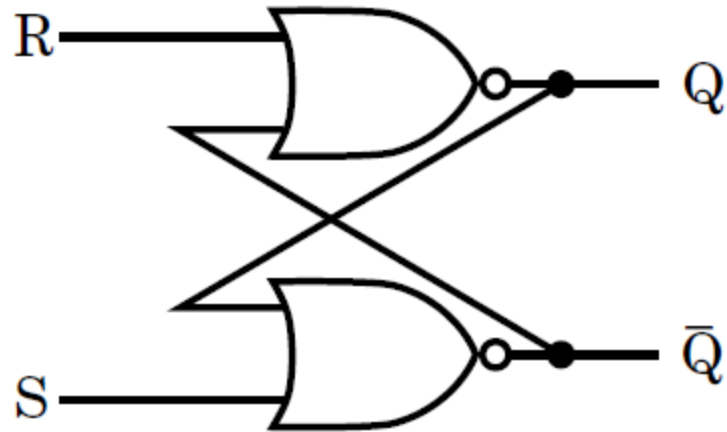
$$\overline{Q} = 0$$

S = 0 R = 0 means, Keep the value of Q as it.

NOR GATE:

A	B	Q
0	0	1
0	1	0
1	0	0
1	1	0

Maintaining the State : Or Value of Q as a memory Bit



$$Q = 1 \quad \overline{Q} = 0$$

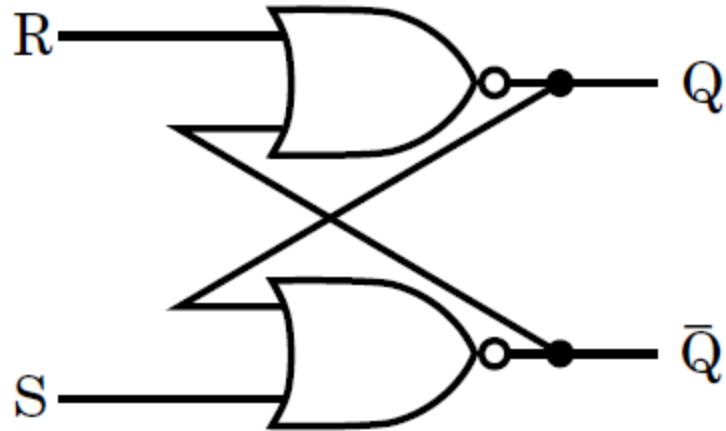
$S = 0$ $R = 0$ means, Keep the value of Q as it is.

Similarly when $Q = 0$ initially
 $S = 0$ $R = 0$ means keep $Q = 0$

NOR GATE:

A	B	Q
0	0	1
0	1	0
1	0	0
1	1	0

Set, Reset : Change value of Q



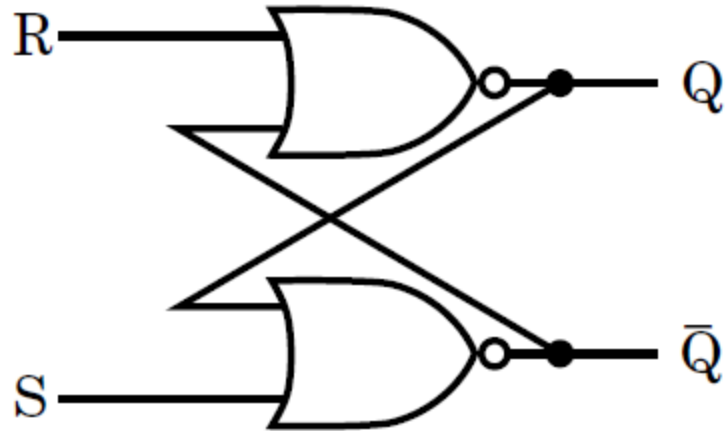
$S=1$ $R=0$ means, set Q :

$$Q = 1 \quad \bar{Q} = 0$$

NOR GATE:

A	B	Q
0	0	1
0	1	0
1	0	0
1	1	0

Set, Reset : Change value of Q



$S=1$ $R=0$ means, set Q :

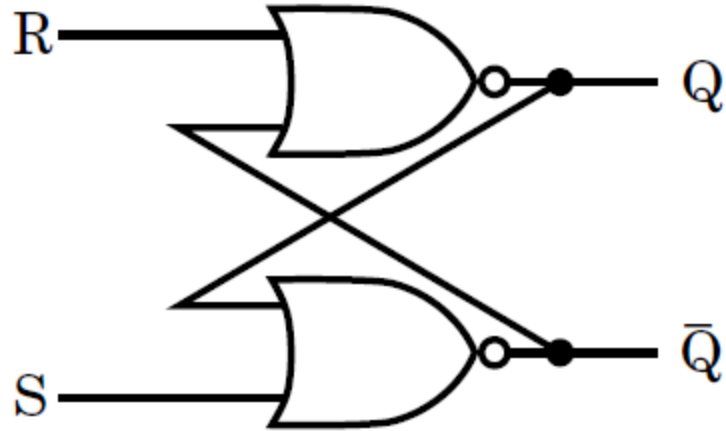
$$Q = 1 \quad \bar{Q} = 0$$

NOR GATE:

A	B	Q
0	0	1
0	1	0
1	0	0
1	1	0

Even if Q was already =1. This will work

Set, Reset : Change value of Q



$R = 1$ $S = 0$ means, **reset** Q :

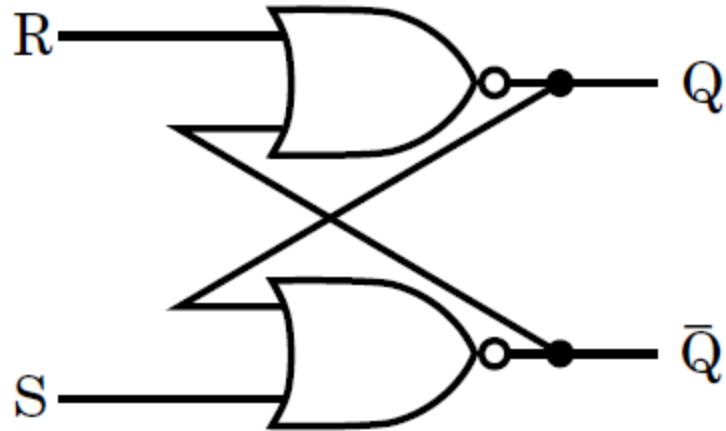
$$Q = 0 \quad \bar{Q} = 1$$

Even if Q was previously 0 or 1. This will work
Reset Q to 0

NOR GATE:

A	B	Q
0	0	1
0	1	0
1	0	0
1	1	0

Set, Reset : **Change value of Q or Store Q as it is**



NOR GATE:

A	B	Q
0	0	1
0	1	0
1	0	0
1	1	0

S, R transition	Q, \bar{Q} transition
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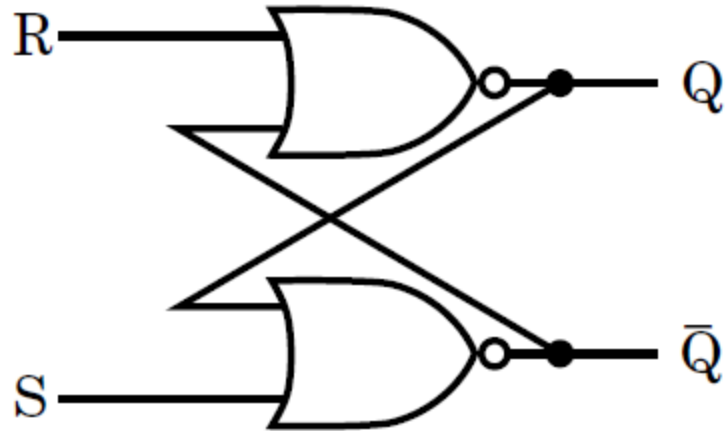
$1, 0 \rightarrow 0, 0$	$1, 0 \rightarrow 1, 0$
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$0, 1 \rightarrow 0, 0$	$0, 1 \rightarrow 0, 1$
-------------------------	-------------------------

$1, 1 \rightarrow 0, 0$	\rightarrow
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What happens here?

Set, Reset : **Change value of Q or Store Q as it is**



NOR GATE:

A	B	Q
0	0	1
0	1	0
1	0	0
1	1	0

S, R transition	Q, \bar{Q} transition
$1, 0 \rightarrow 0, 0$	$1, 0 \rightarrow 1, 0$
$0, 1 \rightarrow 0, 0$	$0, 1 \rightarrow 0, 1$
$1, 1 \rightarrow 0, 0$	\rightarrow

What Happens when $S=1$ and $R=1$

A) $Q=1$ and $\bar{Q} = 1$ then $Q=0, \bar{Q}=1$

B) $Q=0$ and $\bar{Q} = 0$, then $Q=1, \bar{Q}=1$ oscillates

C) $Q=0$ and $\bar{Q} = 1$

D) $Q=1$ and $\bar{Q} = 0$

E) NOR Gates explode

Improvement on SR Latch : D Latch, D Flip Flop:

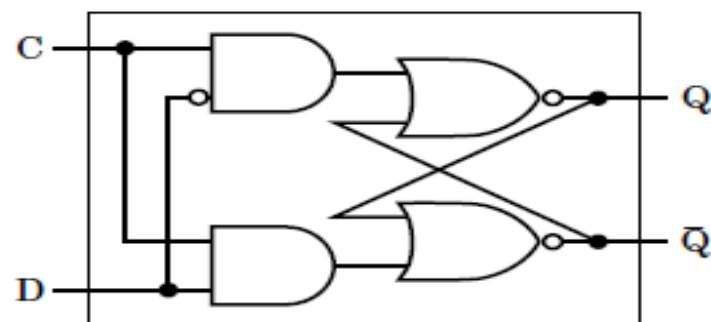
Using a **CLOCK** pulse to control when the State of a Memory Bit is changed.

When Clock pulse is asserted- data updates (Set,Reset) is allowed.

Otherwise Latch stays in a $S=0, R=0$ State

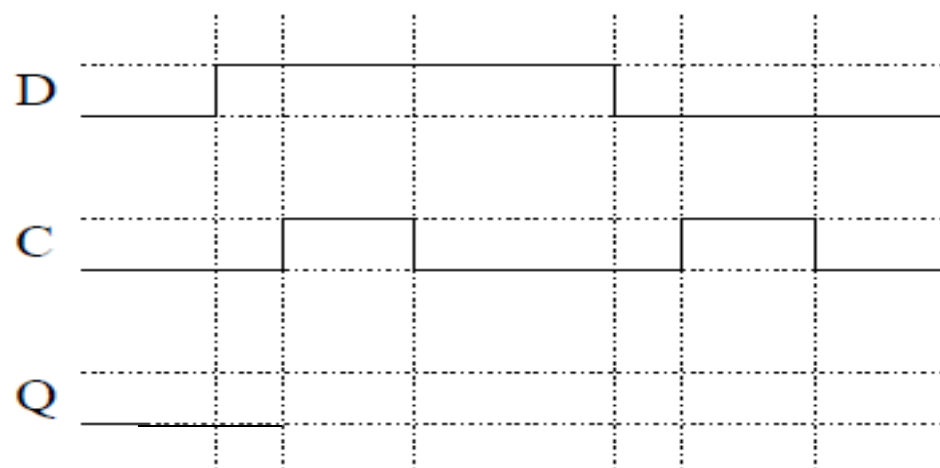
Course Notes

The D Latch

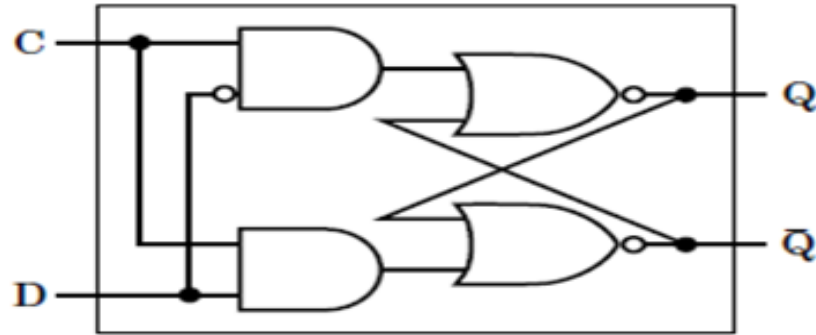


C	D	Next state of Q
0	X	No change
1	0	$Q = 0$ (Reset)
1	1	$Q = 1$ (Set)

Graphical example:

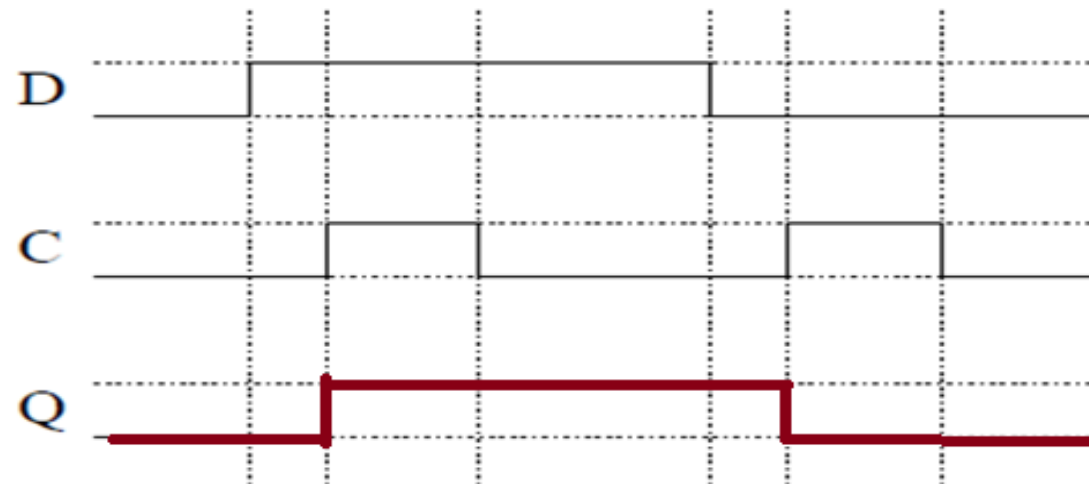


The D Latch



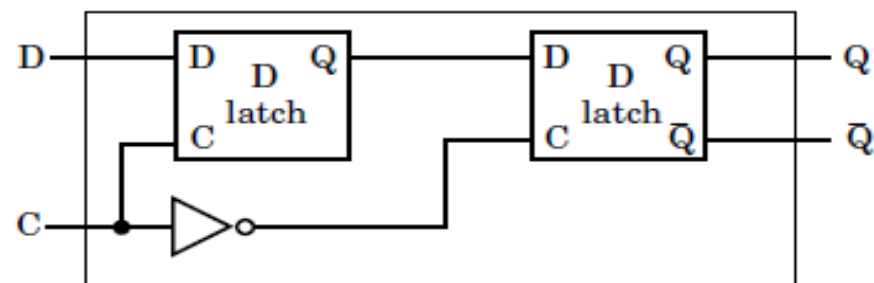
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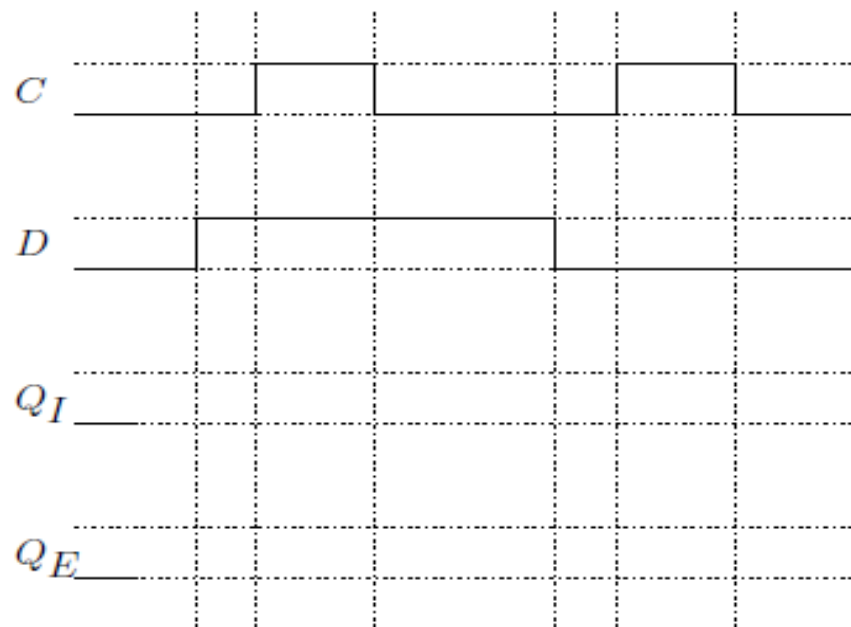


The D Flip-Flop

- We want state to be affected only at discrete points in time; a master-slave design achieves this.

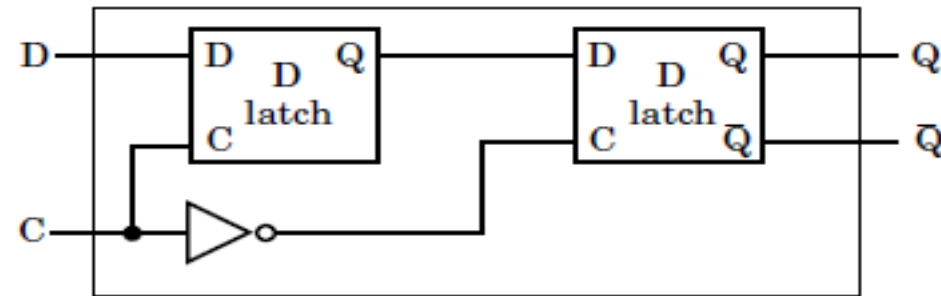


- Graphical example:

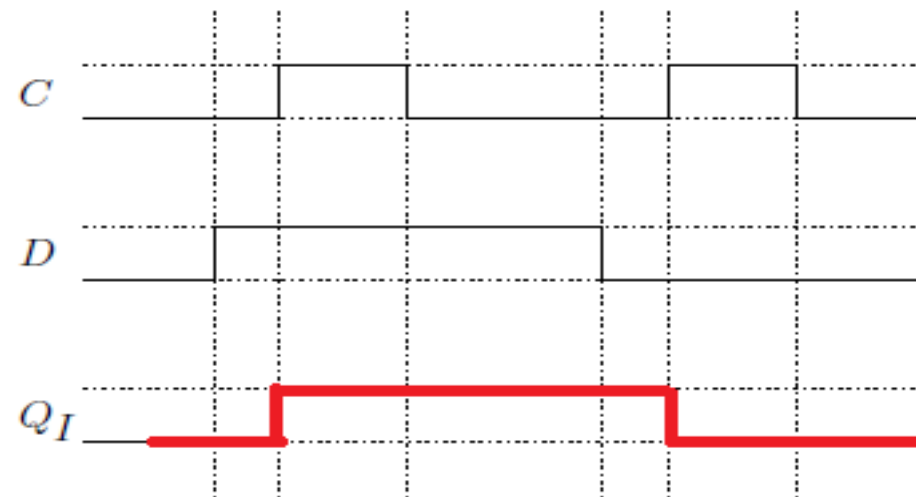


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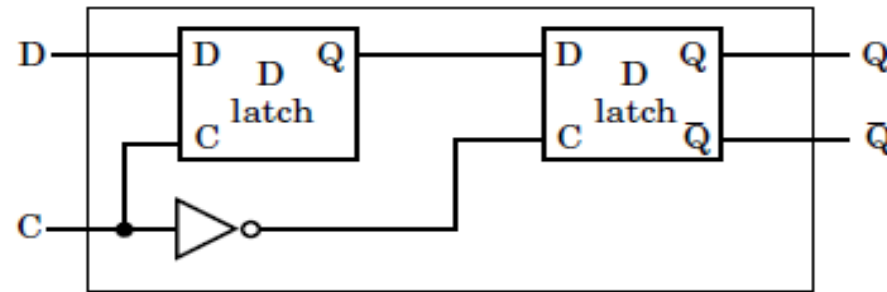


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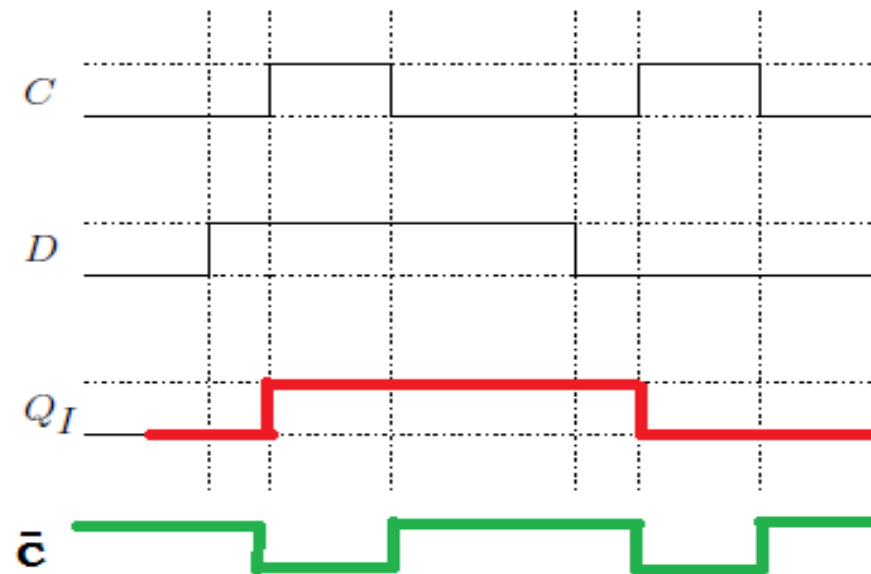


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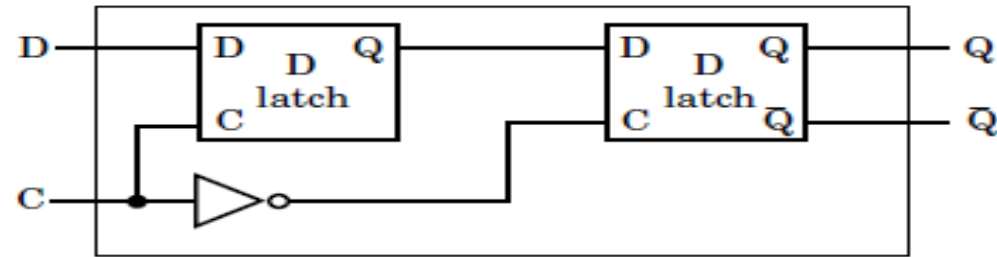


- Graphical example:

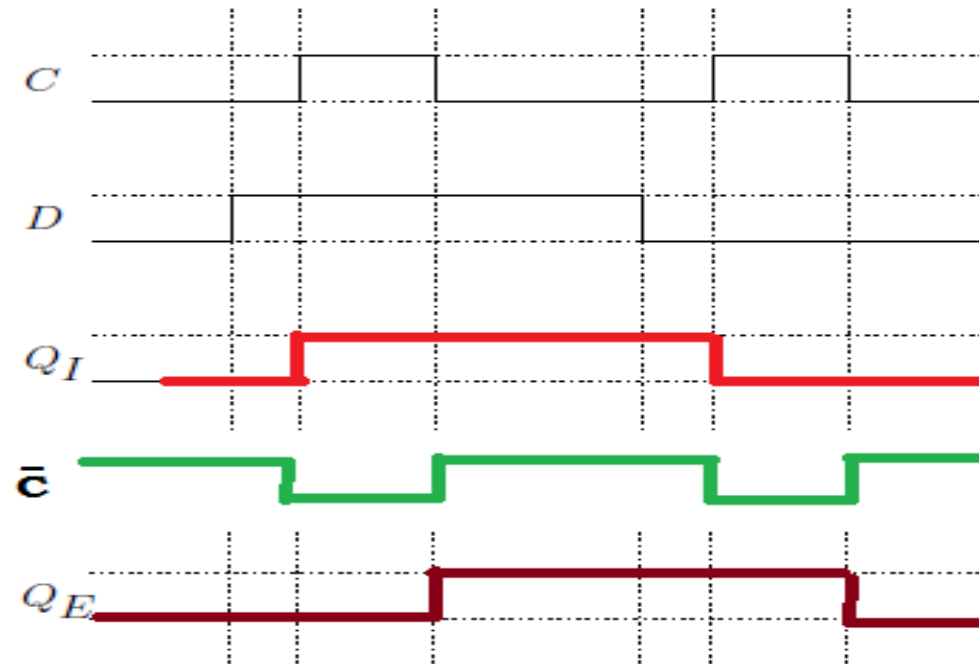


The D Flip-Flop

- We want state to be affected only at discrete points in time; a master-slave design achieves this.



- Graphical example:



Implementing Boolean Functions: ROMs



- Can think of ROM as table of 2^n m -bit words
- Can think of ROM as implementing m one-bit functions of n variables
- Internally, consists of a decoder plus an OR gate for each output
- Types of ROM: PROM, EPROM, EEPROM
- PLAs - simplified ROM
Less hardware, but less flexible

**Electrically Erasable Programmable
Read Only Memory**

RAM (Random Access Memory) this is memory that can be accessed very easily. The data is organized in such a way as to allow programs to access the data very efficiently. Main memory, easy access by CPU. Fast. Volatile storage. 'Save your work'

ROM (Read Only Memory) is memory that cannot be changed. It can only be read –Audio CD is a good example of a ROM. Cannot be changed. Computer ROM retains its contents even when system is off. Non Volatile

RAM usually can be written to and read from many times. **ROM** can only be written once, but it can be read many times.

Hard Drives: Made up of several rigid metal, glass or ceramic disks

PLA/ ROM

We saw Truth Tables
implement logic functions:

Functions of the form

* Product of sums

* Layer of AND Gates
followed by Layer of OR
Gates

ROM/PLA:

Internally AND Gates followed by OR Gates

Every input and its complement are available

