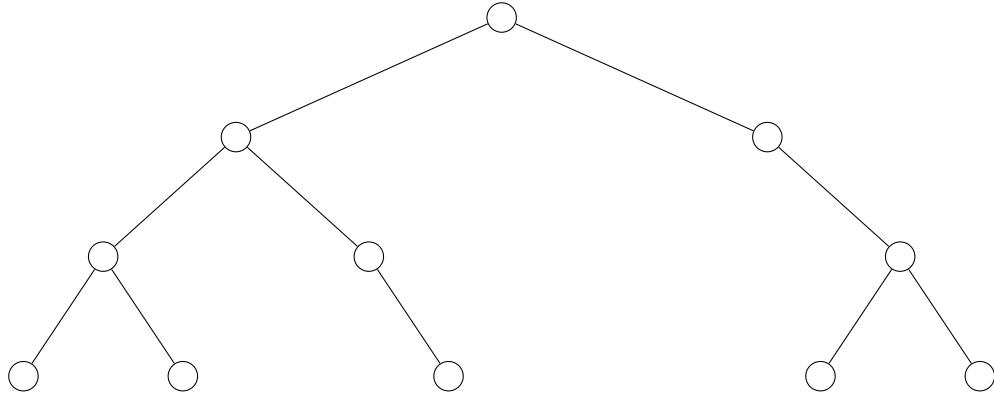


Math 239 Lecture 15

Graham Cooper

June 10th, 2015

Counting Binary Trees

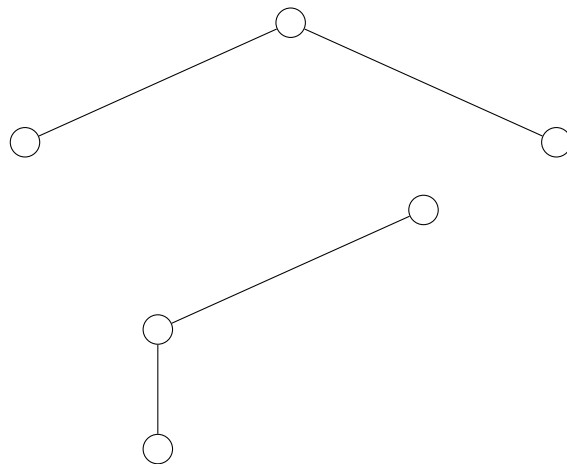


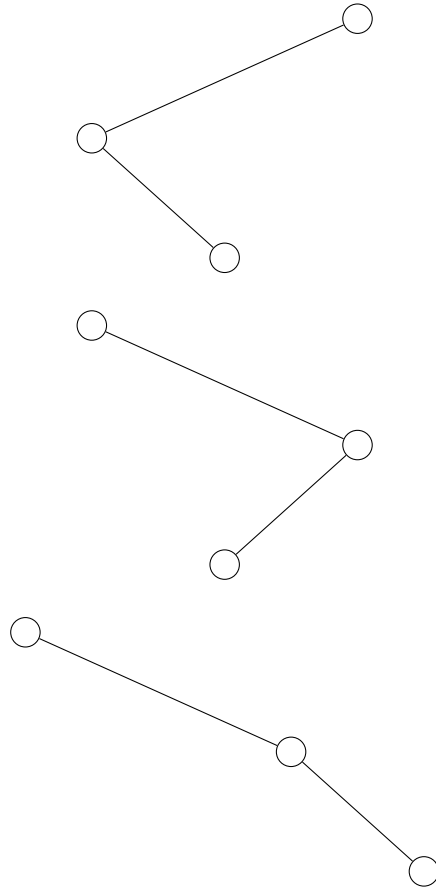
Definition: A binary tree is either:

1. an empty tree ϵ
2. a root vertex with a left branch and a right branch each of which is a binary tree

how many binary trees have n nodes?

for 3 nodes:



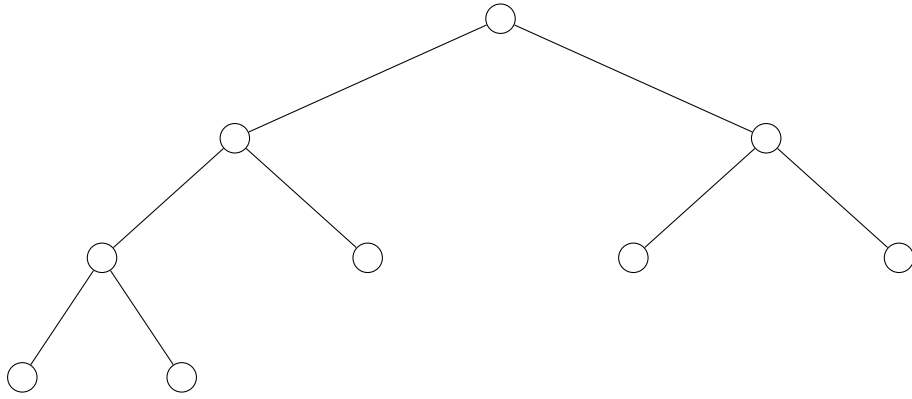


Let T be the set of all binary trees of any size. For each $t \in T$, define weight functions $w(t)$ to be the number of nodes in T . Let $T(x)$ be the generating series for T with respect to w . The answer to our question is $[x^n]t(x)$

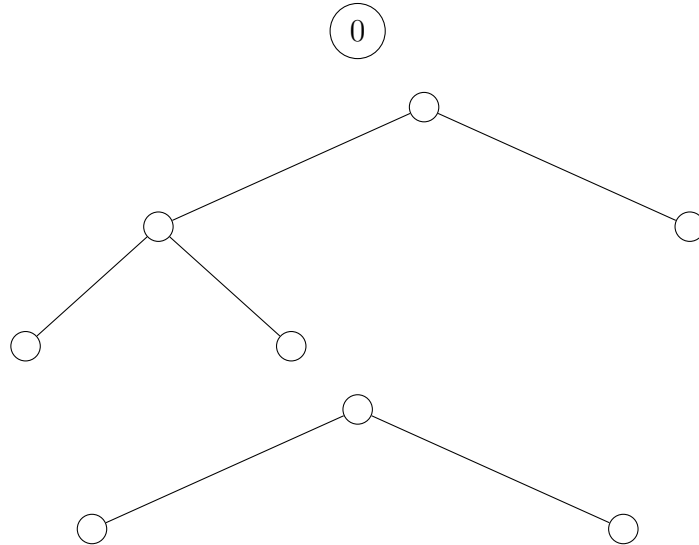
For any non-empty tree t , we can decompose it into 3 parts, root node r , the left tree t_1 , the right tree t_2 . $t_1, t_2 \in T$. This belongs to the cartesian product $r \times T \times T$

Let $S = \{\epsilon\} \cup \{r\} \times T \times T$

Then each tree $t \in T$ corresponds to one element of S in a bijection.



becomes



$$T \rightleftharpoons (r, t_1, t_2)$$

$$w(r, t_1, t_2) = 1 + w(t_1) + w(t_2) = w(t)$$

We can apply product lemma

$$\Phi_S(x) = 1 + x \cdot t(x) \cdot t(x)$$

Due to the bijection $t(x) = \Phi_S(x)$

$$\implies t(x) = 1 + xt(x)^2$$

$$\begin{aligned}
0 &= xt(X)^2 - t(x) + 1 \\
&= 4x(xt(x)^2 - t(x) + 1) \\
&= 4x^2t(x)^2 - 4xt(x) + 4x \\
&= (4x^2t(x)^2 - 4xt(x) + 1) - 1 + 4x \\
&= (2xt(x) - 1)^2 - 1 + 4x
\end{aligned}$$

so:

$$(2xt(x) - 1)^2 = 1 - 4x = ((1 - 4x)^{1/2})^2$$

from A2:

$$\begin{aligned}
2xt(x) - 1 &= +/ - (1 - 4x)^{1/2} \\
&= +/ - (1 - 2 \sum_{n \geq 0} \frac{1}{n+1} \binom{2n}{n} x^{n+1})
\end{aligned}$$

Constant term is -1 so we pick - over +, which means:

$$\begin{aligned}
2xt(x) - 1 &= -1 + 2 \sum_{n \geq 0} \frac{1}{n+1} \binom{2n}{n} x^{n+1} \\
\implies t(x) &= \sum_{n \geq 0} \frac{1}{n+1} \binom{2n}{n} x^n
\end{aligned}$$

So the number of binary trees iwth n nodes is $\frac{1}{n+1} \binom{2n}{n}$
(n = 3, $\frac{1}{4} \binom{6}{3} = \frac{1}{4} \frac{6*5*4}{3*2} = 5$)

Catalan number: $\frac{1}{n+1} \binom{2n}{n}$

Graph Theory

Definition: A graph G is a pair of sets (V, E) (or (V(G), E(G))) where V is a set of objects called vertices and E is a set of unordered pairs of V called edges.

Example: Define G = (V,E) where
V = {a,b,c,d}, E = {{a,b}, {b,c}, {c,d}, {a,d} }

Graphical Representation of G.
See notes.

In graph theory, we mainly care about the "structure" of the graphs, e.g. what are the vertices, which pairs for edges

Terminologies:

- Two vertices u, v are adjacent if $\{u, v\}$ is an edge Example above, a is adjacent to b and d but not c
- If u is adjacent to v , then u is a neighbour of v , the set of all neighbours of u is the neighbourhood, denoted by $N(u)$. Example: $N(a) = \{b, d\}$
- An edge, $e = \{u, v\}$ is incident with u and v , e joins u and v