

Micro Homework 10

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Question 1. What is the practical consequence of the possibility that the RHC becomes infeasible?

Question 2. How can the risk of infeasibility be avoided in practice?

Question 3. What is the significance of banded matrices when solving QP problems?

Question 4. How can the number of control signal values to be determined in an RHC be reduced, without limiting the control horizon?

Q1) That we can't find a control sequence, the optimization problem doesn't have a solution. Then we lose ability to control.

Q2) Use soft constraints, expand terminal states x_f , increase prediction horizon.

If we still hit it we can find alternative solutions:

E.g. take previous control signal, PID, ad hoc.

Q3) Reduce memory usage and computational complexity.

Q4) Piecewise constant control signal.

E.g. $u_1 = u_0$, $u_3 = u_2$, $u_5 = u_4$.

Hence we keep control horizon but reduce number of control signals.