


Lab2 – report


<commit history>

support run example code for calculate_delay

 HelloHe110 committed 3 weeks ago

The first commit is in the first week of the lab, and the modified parts are all about the *calculate_delay* method, and as we know right now, the method is actually wrong. Here is what I do: (1) for every 'Tx', I record the current time, and for every 'Rx', I update the overall delay time of packet with this sequence number. Finally, with those stored delay time, I can calculate the average packet end to end delay time! Sadly, if we take a deeper look to the simulation process, we will figure out that there are actually many packet with same sequence number, which shows that I mis-update the recorded send-time of the packet! This is the main issue of this commit, and will later be corrected!

Task1: Topology Configuration

 HelloHe110 committed 2 weeks ago

adf3523  

for the second commit, I mainly focus on task 1 – setting up the topology for the ground-station(GS) as both source and destination to (6.06692, 73.0213) according to the spec. And thanks to the hint from TA, we know that the x-y-z coordinates can be called by `pos_tx = users.Get(0)->GetObject<MobilityModel>()->GetPosition();`, and this is the way to get both the coordinates of GS and SAT! For the convenience of further processing in MATLAB bf / no-bf pathloss calculation. And the methodology of writing the file is through ofstream, which is a normal way to write out file in C++. In order to better the readability of the code, I grasp the write file process in to a lambda function `auto write_txt = [] (Vector pos_tx, Vector pos_rx, Vector pos_sat1) {`. The last thing is the new xyz_positions.txt which store the information of the x-y-z coordinates of GS and SAT!

support task1~5

 HelloHe110 committed last week

08801a9  

In this commit, the basic structure of this lab was set up! The *txPowerDbm*, *noisePowerDbm* and *bandwidthHz* are all defined as what being mentioned in the spec. And, I got the *rxPowerDbm* by *CreateObject < LeoPropagationLossModel >*, which is further considered no suitable...

```
Ptr<MobilityModel> txMobility = users.Get(0)->GetObject<MobilityModel>(); // U
```

```
Ptr<MobilityModel> rxMobility = satellites.Get(1)->GetObject<MobilityModel>();
```

```
double rxPowerDbm = propagationLossModel->DoCalcRxPower(txPowerDbm, txMobility, rxMobility);
```

After *rxPowerDbm*, we could head in to the data rate calculation by Shannon Capacity.

```
double snrDb = rxPowerDbm - noisePowerDbm;
double snrRatio = std::pow(10.0, snrDb / 10.0);

double shannonCapacity = bandwidthHz * std::log2(1 + snrRatio);
```

After we got the value of *shannonCapacity*, we can therefore update the new *DataRate* of GS to *shannonCapacity*; furthermore, I set the *DataRate* of SAT to 1Gbps as required. Let's move on other files, the *examples/pathloss.txt* is there for storing the calculated result of *pathloss* from MATLAB code, and *model/leo - propagation - loss - model.cc* and *.h* are also changed as the requirement in spec.

```
double rxc = txPowerDbm - m_atmosphericLoss - pathLoss - m_linkMargin;
```

update support for report & error fixed

 HelloHe110 committed now

0071525  

Due to the fact that the methodology of calculate-delay being modified, the first change in this commitment is to update the *func EchoTxRx* by setting up the constraint for not overwrite the send-time if there exist an earlier time while the *Rx* part remain unchanged.

```
if (context.find("/Tx") != std::string::npos && sendTime[seq] == (Time)0) {
    sendTime[seq] = now; // 記錄發送時間
}
```

The second part is to remove the rounding bias in MATLAB by sending the x y z in numerical value instead of scientific notation.

```
outfile << " " << std::to_string(pos_tx.x) << " " << std::to_string(pos_tx.y) << " " << std::to_string(pos_tx.z) << "\n";
```

Also, I noticed that we can't directly create a object for calculating the *rxPower* since there are some extra variables like *m_atmosphericLoss* set during the simulation?! If we create a new object directly, those variables would be the default value, which is honestly wrong!

```
- Ptr<LeoPropagationLossModel> propagationLossModel = CreateObject<LeoPropagationLossModel>();
+ // Ptr<LeoPropagationLossModel> propagationLossModel = CreateObject<LeoPropagationLossModel>();
+ Ptr<NetDevice> dev = utNet.Get(SAT_Idx);
+ Ptr<LeoMockNetDevice> mockDev = DynamicCast<LeoMockNetDevice>(dev);
+ Ptr<LeoMockChannel> channel = DynamicCast<LeoMockChannel>(mockDev->GetChannel());
+ Ptr<LeoPropagationLossModel> propagationLossModel = DynamicCast<LeoPropagationLossModel>(channel->GetPropagationLoss());
```

And there are also some modifications in order to fit the need of generating the output of result. Overall they are based on the formula!

```
double euclidean_dis = sqrt((pos_tx.x - pos_sat.x)*(pos_tx.x - pos_sat.x) + (pos_tx.y - pos_sat.y)*(pos_tx.y - pos_sat.y) + (pos_tx.z - pos_sat.z)*(pos_tx.z - pos_sat.z));

double snrDb = rxPowerDbm - noisePowerDbm;
double snrRatio = std::pow(10.0, snrDb / 10.0);

double shannonCapacity = bandwidthHz * std::log2(1 + snrRatio);

// HERE
// printf("\n===== w/o bf - Results =====\n");
printf("\n===== w/ bf - Results =====\n");
printf("Q1: Euclidean Dis: %.6f m\n", euclidean_dis);
printf("Q2: PathLoss: %.6f dBm\n", readPathloss());
printf("Q3: RxPower: %.6f dBm\n", rxPowerDbm);
printf("Q4: SNR: %.6f dB\n", snrDb);
printf("Q5: DataRate: %.6f Mbps\n", shannonCapacity / 1e6);
```

<further commit>

If there exist further commit, it'll be only about the basic change like uploading the report/result file, neither core idea of the code nor the concept will be modify!