```
D:\Python\Python\setroute\python.exe "D:\Python\Pycharm\setroute\PyCharm Community Edition 2021.2.3\plugins\python-ce\helpers\pydev\pydevconsole.py" --
    mode=client --port=28303
 3
    import sys; print('Python %s on %s' % (sys.version, sys.platform))
    sys.path.extend(['E:\\1 ] _ _ \\3 | 0 _ _ | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\\  | 0 | \\1 | 0 | \\\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | 
    6
    PyDev console: starting.
 8 Python 3.9.7 (tags/v3.9.7:1016ef3, Aug 30 2021, 20:19:38) [MSC v.1929 64 bit (AMD64)] on win32
    python code/9 Code for this paper')
10 Backend TkAgg is interactive backend. Turning interactive mode on.
11
    Waiting 5s.....
    Optimize the ./R 15 3.xlsx instance by ECCG
13
14
15
          Master protblem status = 2, is Optimal and MP obj = 547.0
16
    The initial lb = -inf
                                ub = inf
17
18
    The current iteration cnt = 0
19
          The SP model was solved Optimal 2 and SPObj = 547.0
20
          Deterministic Sub problem Status= 2, is Optimal
21
          Master protblem status = 2, is Optimal
22
          1b = 1045.0
                                        ub = 1045.0
           MPObj = 1045.0
                                    MP delete Hua Obj = 577.0
23
                                                                           Hua = 468.0
                                                                                               SPObj = 547.0
                                                                                                                     Deter SP Obj = 468.0
24
25
    ub - 1b = 0.0
26
27 Iteration cycle stopped by termination criterion 1: Because ub - lb \leq eps, the iteration stop, and cnt = 0
        i: 0.0 1_i: 5.0 p_i: 0.0 a1_i: 3.0 sol_a i: 3.0 sol_g i: 0.0 d_i: 39.0 sol_taoi: 3.0 sol_deltai: 7.0 sol_deltai - sol_taoi: 4.0 sol_taoi: 3.0
28
        sol_deltaP: 4.0 sol_deltaP - sol_taoP: 1.0 cl_i: 1002244.0
                                                                                sol_c_i: 1002244.0 sol_gp_i: 0.0 total work: 1054576.0 wasted work: 0.
     19849494014656127
29
        i: 1.0 1_i: 5.0 p_i: 9.0 aI_i: 8.0
                                                       sol a i: 8.0 sol g i: 0.0 d i: 54.0 sol taoi: 8.0 sol deltai: 23.0 sol deltai - sol taoi: 15.0 sol taoP: 8.0
                             sol_deltaP - sol_taoP: 3.0 cl_i: 3867170.0 sol_c_i: 3867170.0 sol_gp_i: 0.0 total work: 4745592.0 wasted work: 3.
        sol deltaP: 11.0
    331849008511478
                                                          sol a i: 13.0 sol g i: 0.0 d i: 55.0 sol taoi: 13.0 sol deltai: 24.0 sol deltai - sol taoi: 11.0 sol taoP
       i: 2.0 1 i: 5.0 p i: 14.0 aI i: 13.0
      13.0 sol_deltaP: 15.0 sol_deltaP - sol_taoP: 2.0 cl_i: 2793468.0 sol_c_i: 2793468.0 sol_gp_i: 0.0 total work: 3163728.0 wasted work: 1.
     404393803765684
       i: 3.0 1_i: 5.0 p_i: 19.0 aI_i: 17.0
                                                          sol_a_i: 17.0 sol_g_i: 0.0 d_i: 62.0 sol_taoi: 17.0 sol_deltai: 31.0 sol_deltai - sol_taoi: 14.0 sol_taoP
31
      17.0 sol deltaP: 21.0 sol deltaP - sol taoP: 4.0 cI i: 3514829.0 sol c i: 3514829.0 sol gp i: 0.0 total work: 3954660.0 wasted work: 1.
    6682761602767369
        i: 4.0 1_i: 5.0 p_i: 24.0 aI_i: 19.0
                                                          sol_a_i: 19.0 sol_g_i: 0.0 d_i: 55.0 sol_taoi: 19.0 sol_deltai: 24.0 sol_deltai - sol_taoi: 5.0 sol_taoP
      19.0 sol_deltaP: 20.0 sol_deltaP - sol_taoP: 1.0 cl_i: 1292682.0 sol_c_i: 1292682.0 sol_gp_i: 0.0 total work: 1318220.0 wasted work: 0.
    09686547010362459
                                                          sol_a_i: 22.0 sol_g_i: 0.0 d_i: 57.0 sol_taoi: 22.0 sol_deltai: 26.0 sol_deltai - sol_taoi: 4.0 sol_taoP
        i: 5.0 l_i: 5.0 p_i: -0.0 aI_i: 22.0
33
      22.0 sol_deltaP: 23.0 sol_deltaP - sol_taoP: 1.0 cI_i: 1037494.0 sol_c_i: 1037494.0 sol_gp_i: 0.0 total work: 1054576.0 wasted work: 0.
    0647919163720775
      i: 6.0 l_i: 5.0 p_i: 24.0 al_i: 26.0 sol_a_i: 26.0 sol_g_i: 0.0 d_i: 62.0 sol_taoi: 26.0 sol_deltai: 33.0 sol_deltai - sol_taoi: 7.0 sol_deltai - sol_taoi: 26.0 sol_deltai - sol_taoi: 26.0 sol_deltai - sol_taoi: 1812852.0 sol_g_i: 1812852.0 sol_g_i: 0.0 total work: 1845508.0 wasted work: 0.
                                                         sol_a_i: 26.0 sol_g_i: 0.0 d_i: 62.0 sol_taoi: 26.0 sol_deltai: 33.0 sol_deltai - sol taoi: 7.0 sol taoP
34
     12386399842211467
        i: 7.0 l_i: 5.0 p_i: 9.0 al_i: 29.0 sol_a_i: 29.0 sol_g_i: 0.0 d_i: 82.0 sol_taoi: 29.0 sol_deltai: 41.0 sol_deltai - sol_taoi: 12.0 sol_c_i: 2983420.0 sol_c_i: 2983420.0 sol_gp_i: 0.0 total work: 3163728.0 wasted work: 0.
                                                     sol a i: 29.0 sol g i: 0.0 d i: 82.0 sol taoi: 29.0 sol deltai: 41.0 sol deltai - sol taoi: 12.0 sol taoP:
35
     6839070868292091
        i: 8.0 1 i: 5.0 p i: 14.0 aI i: 31.0
                                                          sol a i: 34.0 sol g i: 0.6 d i: 73.0 sol taoi: 34.0 sol deltai: 45.0 sol deltai - sol taoi: 11.0 sol taoP
     34.0 sol_deltaP: 38.0 sol_deltaP - sol_taoP: 4.0 cl_i: 2870420.0 sol_c_i: 3427372.0 sol_gp_i: 0.35208589360400133 total work: 3427372.0
     wasted work: 0.0
        i: 9.0 1_i: 5.0 p_i: 24.0 aI_i: 32.0
                                                          sol deltai - sol taoi: 8.0 sol_taoP: 37.0 sol_deltaP: 39.0 sol_deltaP - sol_taoP: 2.0 cl_i: 1873374.0 sol_c_i: 2767563.8666666667 sol_gp_i: 0.
     8479141063959986 total work: 2900084.0 wasted work: 0.5026480152528914
        sol_a_i: 41.0 sol_g_i: 0.5 d_i: 82.0 sol_taoi: 41.0 sol_deltai: 57.0 sol_deltai - sol_taoi: 16.0
    sol taoP: 41.0 sol deltaP: 46.0 sol deltaP - sol taoP: 5.0 cl i: 4119901.0 sol c i: 4745592.0 sol gp i: 0.5933104868686562 total work:
    4745592.0 wasted work: 0.0
        i: 11.0 \quad l\_i: 5.0 \quad p\_i: 19.0 \quad aI\_i: 38.0
                                                             sol_a_i: 40.0 sol_g_i: 0.2857142857142857 d_i: 74.0 sol_taoi: 40.0 sol_deltai: 51.0 sol_deltai -
    sol_taoi: 11.0 sol_taoP: 40.0 sol_deltaP: 43.0 sol_deltaP - sol_taoP: 3.0 cl_i: 2878192.0 sol_c_i: 3954660.0 sol_gp_i: 0.5832908879289606
    total work: 4218304.0 wasted work: 1.0
        sol_a_i: 49.0 sol_g_i: 1.0 d_i: 80.0 sol_taoi: 49.0 sol_deltai: 62.0 sol_deltai - sol_taoi: 13.0
     sol taoP: 49.0 sol deltaP: 52.0 sol deltaP - sol taoP: 3.0 cl i: 3205861.0 sol c i: 3534571.614285716 sol gp i: 0.623398625202386 total work
     : 3559194.0 wasted work: 0.09339255099408347
        sol_a_i: 49.0 sol_g_i: 0.5 d_i: 76.0 sol_taoi: 49.0 sol_deltai: 56.0 sol_deltai - sol_taoi: 7.0
    sol_taoP: 49.0 sol_deltaP: 51.0 sol_deltaP - sol_taoP: 2.0 cl_i: 1842456.0 sol_c_i: 2375499.1249999963 sol_gp_i: 0.404365830438012 total work
     : 2636440.0 wasted work: 0.9897470642229814
       i: 14.0 l_i: 5.0 p_i: 9.0 al_i: 38.0 sol_a_i: 43.0 sol_g_i: 0.5555555555555556 d_i: 79.0 sol_taoi: 43.0 sol_deltai: 52.0 sol_deltai
    sol_taoi: 9.0 sol_taoP: 43.0 sol_deltaP: 46.0 sol_deltaP - sol_taoP: 3.0 cl_i: 2171089.0 sol_c_i: 3427372.0 sol_gp_i: 0.5956341695619851
    total work: 3822838.0 wasted work: 1.5
    Time: 84.000000
44
45
46
47
```