```
D:\Python\Python\setroute\python.exe "D:\Python\Pycharm\setroute\PyCharm Community Edition 2021.2.3\plugins\python-ce\helpers\pydev\pydevconsole.py" --
    mode=client --port=27039
 3
    import sys; print('Python %s on %s' % (sys.version, sys.platform))
    sys.path.extend(['E:\\1 ] _ _ \\3 | 0 _ _ | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\\  | 0 | \\1 | 0 | \\\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | 
    6
    PyDev console: starting.
 8 Python 3.9.7 (tags/v3.9.7:1016ef3, Aug 30 2021, 20:19:38) [MSC v.1929 64 bit (AMD64)] on win32
    main RO CCG.py', wdir='E:/1 0000/3 00000/1 000000/1 0000000/1 000000/1 LW 00001/4 0000/3 python_code/9 Code for
10 Backend TkAgg is interactive backend. Turning interactive mode on.
11
    Waiting 5s.....
13 Optimize the ./R 18 5.xlsx instance by CCG
14
          Master protblem status = 2, is Optimal and MP obj = 835.0
15
16
    The initial lb = -inf
                               ub = inf
17
18
    The current iteration cnt = 0
          The SP model was solved Optimal 2 and SPObj = 835.0
19
          Deterministic Sub problem Status= 2, is Optimal
20
          1b = 1517.0
                                        ub = 1517.0
21
22
          MPObj = 1517.0
                                   MP_delete_Hua_Obj = 867.0
                                                                          Hua = 650.0
                                                                                             SPObj = 835.0
                                                                                                                  Deter_SP_Obj = 650.0
24
    ub - 1b = 0.0
25
26
    Iteration cycle stopped by termination criterion 1: Because ub - 1b \le eps, the iteration stop, and ext{cnt} = 0
      i: 0.0 l_i: 4.0 p_i: 15.0 al_i: 48.0 sol_a_i: 48.0 sol_g_i: 0.0 d_i: 59.0 sol_taoi: 48.0 sol_deltai: 62.0 sol_deltai: 62.0 sol_deltai - sol_taoi: 14.0 sol_taoP 48.0 sol_deltaP - sol_taoP: 53.0 sol_deltaP - sol_taoP: 50.0 cl_i: 3676266.0 sol_c_i: 3676266.0 sol_gp_i: 0.0 total work: 3691016.0 wasted work: 0.
27
    05594665533825917
                                                    sol_a_i: 33.0 sol_g_i: 0.0 d_i: 43.0 sol_taoi: 33.0 sol_deltai: 46.0 sol_deltai - sol_taoi: 13.0 sol_taoP:
       i: 1.0 1_i: 5.0 p_i: 2.0 aI_i: 33.0
    33.0 sol_deltaP: 38.0 sol_deltaP - sol_taoP: 5.0 cl_i: 3220010.0 sol_c_i: 3220010.0 sol_gp_i: 0.0 total work: 3427372.0 wasted work: 0.
     786522735203532
       i: 2.0 1_i: 5.0 p_i: 24.0 aI_i: 2.0
29
                                                          sol_a_i: 2.0 sol_g_i: 0.0 d_i: 16.0 sol_taoi: 2.0 sol_deltai: 20.0 sol_deltai - sol_taoi: 18.0 sol_taoP: 2
          sol deltaP: 8.0 sol deltaP - sol taoP: 6.0 cl i: 4544344.0 sol c i: 4544344.0 sol gp i: 0.0 total work: 5009236.0 wasted work: 1.
    7633323724416259
30
       i: 3.0 1_i: 5.0 p_i: 19.0 aI_i: 55.0
                                                         sol_a_i: 55.0 sol_g_i: 0.0 d_i: 68.0 sol_taoi: 55.0 sol_deltai: 72.0 sol_deltai - sol_taoi: 17.0 sol_taoP
     : 55.0 sol_deltaP: 60.0 sol_deltaP - sol_taoP: 5.0 cl_i: 4352300.0 sol_c_i: 4352300.0 sol_gp_i: 0.0 total work: 4481948.0 wasted work: 0.
    49175403195217793
                                                     sol_a_i: 31.0 sol_g_i: 0.0 d_i: 39.0 sol_taoi: 31.0 sol_deltai: 42.0 sol_deltai - sol_taoi: 11.0 sol_taoP:
       i: 4.0 1_i: 5.0 p_i: 7.0 aI_i: 31.0
31
             sol_deltaP: 33.0 sol_deltaP - sol_taoP: 2.0 cl_i: 2816559.0 sol_c_i: 2816559.0 sol_gp_i: 0.0 total work: 2900084.0 wasted work: 0.
       i: 5.0 1_i: 5.0 p_i: 29.0 aI i: 57.0
                                                        sol a i: 57.0 sol g i: 0.0 d i: 69.0 sol taoi: 57.0 sol deltai: 73.0 sol deltai - sol taoi: 16.0 sol taoP
32
      57.0 sol_deltaP: 62.0 sol_deltaP - sol_taoP: 5.0 cI_i: 4160344.0
                                                                                       sol_c_i: 4160344.0 sol_gp_i: 0.0 total work: 4218304.0 wasted work: 0.
     21984190802749162
        i: 6.0 1_i: 6.0 p_i: 0.0 aI_i: 49.0
                                                      sol a i: 49.0 sol g i: 0.0 d i: 65.0 sol taoi: 49.0 sol deltai: 70.0 sol deltai - sol taoi: 21.0 sol taoP:
             sol_deltaP: 55.0 sol_deltaP - sol_taoP: 6.0 cI_i: 5510827.0 sol_c_i: 5510827.0 sol_gp_i: 0.0 total work: 5800168.0 wasted work: 1.
    0974685560832032
                                                         sol_a_i: 57.0 sol_g_i: 0.0 d_i: 72.0 sol_taoi: 63.0 sol_deltai: 82.0 sol_deltai - sol_taoi: 19.0 sol_taoP
34
       i: 7.0 1_i: 5.0 p_i: 14.0 aI_i: 57.0
      63.0 sol_deltaP: 67.0 sol_deltaP - sol_taoP: 4.0 cl_i: 4918991.0 sol_c_i: 4918991.0 sol_gp_i: 0.0 total work: 5009236.0 wasted work: 0.
    34229870583058974
        i: 8.0 1_i: 5.0 p_i: 29.0 aI_i: 24.0
                                                         sol_a_i: 24.0 sol_g_i: 0.0 d_i: 38.0 sol_taoi: 24.0 sol_deltai: 42.0 sol_deltai - sol_taoi: 18.0 sol_taoP
      24.0 sol deltaP: 28.0 sol deltaP - sol taoP: 4.0 cl i: 4689476.0 sol c i: 4689476.0 sol gp i: 0.0 total work: 4877414.0 wasted work: 0.
     7128476278618137
36
        i: 9.0 1_i: 5.0 p_i: 7.0 al_i: 19.0 sol_a_i: 19.0 sol_g_i: 0.0 d_i: 25.0 sol_taoi: 19.0 sol_deltai: 27.0 sol_deltai: -sol_taoi: 8.0 sol_taoP:
            sol_deltaP: 21.0 sol_deltaP - sol_taoP: 2.0 cI_i: 2049802.0
                                                                                       sol_c_i: 2049802.0 sol_gp_i: 0.0 total work: 2109152.0 wasted work: 0.
    22511416910682588
        sol_a_i: 14.0 sol_g_i: 0.0 d_i: 31.0 sol_taoi: 14.0 sol_deltai: 36.0 sol_deltai - sol_taoi: 22.0
     sol_taoP: 14.0 sol_deltaP: 18.0 sol_deltaP - sol_taoP: 4.0 cl_i: 5630440.0 sol_c_i: 5630440.0 sol_gp_i: 0.0 total work: 5800168.0 wasted work
     : 0.6437772147289527
38
       i: 11.0    1_i: 4.0    p_i: 16.0    aI_i: 16.0
                                                            sol_a_i: 18.0 sol_g_i: 0.4 d_i: 33.0 sol_taoi: 18.0 sol_deltai: 40.0 sol_deltai - sol_taoi: 22.0
     sol_taoP: 18.0 sol_deltaP: 23.0 sol_deltaP - sol_taoP: 5.0 cl_i: 5685943.0 sol_c_i: 6063812.0 sol_gp_i: 0.35831367298326533 total work:
    6195634.0 wasted work: 0.5
                  1 i: 5.0 p i: 9.0 aI i: 43.0
                                                         sol_a_i: 44.0 sol_g_i: 0.125000000000001957 d_i: 64.0 sol_taoi: 44.0 sol_deltai: 68.0 sol_deltai -
       i: 12.0
     sol_taoi: 24.0 sol_taoP: 44.0 sol_deltaP: 49.0 sol_deltaP - sol_taoP: 5.0 cl_i: 6148730.0 sol_c_i: 6459278.0 sol_gp_i: 0.16827236728315456
    total work: 6591100.0 wasted work: 0.5
                                                            sol_a_i: 20.0 sol_g_i: 1.0 d_i: 25.0 sol_taoi: 20.0 sol_deltai: 37.0 sol_deltai - sol_taoi: 17.0
40
       sol_taoP: 20.0 sol_deltaP: 25.0 sol_deltaP - sol_taoP: 5.0 cl_i: 4259705.0 sol_c_i: 4786993.0 sol_gp_i: 1.0 total work: 4877414.0 wasted work
     : 0.\overline{3}4296627270106\overline{6}6
        sol_a_i: 8.0 sol_g_i: 0.14285714285714285 d_i: 22.0 sol_taoi: 8.0 sol_deltai: 20.0 sol_deltai
    sol taoi: 12.0 sol taoP: 8.0 sol deltaP: 12.0
                                                            sol deltaP - sol taoP: 4.0 cl i: 3009945.0 sol c i: 3691016.0 sol gp i: 0.5166595864119798 total
    work: 3691016.0 wasted work: 0.0
       sol_a_i: 29.0 sol_g_i: 0.8571428571428571 d_i: 34.0 sol_taoi: 29.0 sol_deltai: 43.0 sol_deltai -
    sol_taoi: 14.0 sol_taoP: 29.0 sol_deltaP: 35.0 sol_deltaP - sol_taoP: 6.0 cl_i: 3554496.0 sol_c_i: 5272880.0 sol_gp_i: 0.8147274354811792
    total work: 5536524.0 wasted work: 1.0
                                                          sol_a_i: 4.0 sol_g_i: 0.6666666666666666666666666666666 d_i: 10.0 sol_taoi: 4.0 sol_deltai: 14.0 sol_deltai - sol_taoi:
       10.0
             sol_taoP: 4.0 sol_deltaP: 6.0 sol_deltaP - sol_taoP: 2.0 cI_i: 2501602.0
                                                                                                    sol c i: 3132757.2499999995 sol gp i: 0.4787935625312919 total
     work: 3295550.0 wasted work: 0.6174718559876214
                                                            sol a i: 50.27499999999736 sol g i: 0.808333333333333 d d i: 64.0 sol taoi: 51.0 sol deltai: 73.0
        i: 17.0    1_i: 5.0    p_i: 24.0    aI_i: 43.0
        sol_deltai - sol_taoi: 22.0 sol_taoP: 51.0 sol_deltaP: 57.0 sol_deltaP - sol_taoP: 6.0 cl_i: 5719528.0 sol_c_i: 7118388.0 sol_gp_i: 0.
     663233375309129 total work: 7118388.0 wasted work: 0.0
```

unknown

45 Time: 1552.0000	00
46 1 me. 1332.0000	
46 47 48 49	
48	
49	