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1 D:\Python\Python\setroute\python.exe "D:\Python\Pycharm\setroute\PyCharm Community Edition 2021.2.3\plugins\python-ce\helpers\pydev\pydevconsole.py" --
mode=client --port=52141
2
3 import sys; print('Python %s on %s' % (sys.version, sys.platform))
4 sys.path.extend(['E:/1 /3 / /1 / / /1 / / /1 /_ /1_LW_ /1/4 / /3 python_code/9 Code for this
paper', 'E:/1 /3 / /1 / / /1 / / /1 /_ /1_LW_ /1/4 / /3 python_code/9 Code for this paper'])
5
6 PyDev console: starting.
7
8 Python 3.9.7 (tags/v3.9.7:1016ef3, Aug 30 2021, 20:19:38) [MSC v.1929 64 bit (AMD64)] on win32
9 >>> runfile('E:/1 /3 / /1 / / /1 / / /1 /_ /1_LW_ /1/4 / /3 python_code/9 Code for this paper/
main_ECCG_deterministic.py', wdir='E:/1 /3 / /1 / / /1 / / /1 /_ /1_LW_ /1/4 / /3 python_code/
9 Code for this paper')
10 Backend TkAgg is interactive backend. Turning interactive mode on.
11 Waiting 5s.....
12
13 Optimize the ./R_8_4.xlsx instance by ECCG for deterministic model
14
15 Set parameter MIPGap to value 0.01
16 Master problem status = 2 , is Optimal and MP obj = 372.0
17 The initial lb = -inf ub = inf
18
19 The current iteration cnt = 0
20 The SP model was solved Optimal 2 and SPObj = 372.0
21 Deterministic Sub problem Status= 2 , is Optimal
22 Master problem status = 2 , is Optimal
23 lb = 657.0 ub = 657.0
24 MPObj = 657.0 MP_delete_Hua_Obj = 372.0 Hua = 285.0 SPObj = 372.0 MP_SP_Obj = 285.0 Deter_SP_Obj = 285.0
25
26 ub - lb = 0.0
27
28 Iteration cycle stopped by termination criterion 1: Because ub - lb <= eps, the iteration stop, and cnt = 0
29 i: 0.0 l_i: 5.0 p_i: 29.0 al_i: 35.0 sol_a_i: 35.0 sol_g_i: 0.0 d_i: 55.0 sol_taoi: 35.0 sol_deltai: 55.0 sol_deltai - sol_taoi: 20.0 sol_taoP
: 35.0 sol_deltaP: 41.0 sol_deltaP - sol_taoP: 6.0 cl_i: 5034915.0 sol_c_i: 5034915.0 sol_gp_i: 0.0 total work: 5141058.0 wasted work: 0.
40259971780127746
30 i: 1.0 l_i: 7.0 p_i: 16.0 al_i: 35.0 sol_a_i: 35.0 sol_g_i: 0.0 d_i: 46.0 sol_taoi: 35.0 sol_deltai: 46.0 sol_deltai - sol_taoi: 11.0 sol_taoP
: 35.0 sol_deltaP: 40.0 sol_deltaP - sol_taoP: 5.0 cl_i: 2775624.0 sol_c_i: 2775624.0 sol_gp_i: 0.0 total work: 2900084.0 wasted work: 0.
4720759812474397
31 i: 2.0 l_i: 6.0 p_i: 28.0 al_i: 5.0 sol_a_i: 5.0 sol_g_i: 0.0 d_i: 14.0 sol_taoi: 5.0 sol_deltai: 14.0 sol_deltai - sol_taoi: 9.0 sol_taoP: 5
.0 sol_deltaP: 7.0 sol_deltaP - sol_taoP: 2.0 cl_i: 2161001.0 sol_c_i: 2161001.0 sol_gp_i: 0.0 total work: 2636440.0 wasted work: 1.
8033370757536678
32 i: 3.0 l_i: 6.0 p_i: 23.0 al_i: 36.0 sol_a_i: 36.0 sol_g_i: 0.0 d_i: 46.0 sol_taoi: 36.0 sol_deltai: 46.0 sol_deltai - sol_taoi: 10.0 sol_taoP
: 36.0 sol_deltaP: 38.0 sol_deltaP - sol_taoP: 2.0 cl_i: 2554319.0 sol_c_i: 2554319.0 sol_gp_i: 0.0 total work: 2636440.0 wasted work: 0.
31148442596835124
33 i: 4.0 l_i: 6.0 p_i: 7.0 al_i: 10.0 sol_a_i: 10.0 sol_g_i: 0.0 d_i: 34.0 sol_taoi: 10.0 sol_deltai: 34.0 sol_deltai - sol_taoi: 24.0 sol_taoP:
10.0 sol_deltaP: 14.0 sol_deltaP - sol_taoP: 4.0 cl_i: 6132769.0 sol_c_i: 6132769.0 sol_gp_i: 0.0 total work: 7382032.0 wasted work: 4.
738446541548452
34 i: 5.0 l_i: 7.0 p_i: 22.0 al_i: 65.0 sol_a_i: 65.0 sol_g_i: 0.0 d_i: 80.0 sol_taoi: 65.0 sol_deltai: 75.0 sol_deltai - sol_taoi: 10.0 sol_taoP:
: 65.0 sol_deltaP: 67.0 sol_deltaP - sol_taoP: 2.0 cl_i: 2503846.0 sol_c_i: 2503846.0 sol_gp_i: 0.0 total work: 2636440.0 wasted work: 0.
5029281910455008
35 i: 6.0 l_i: 6.0 p_i: 7.0 al_i: 47.0 sol_a_i: 47.0 sol_g_i: 0.0 d_i: 68.0 sol_taoi: 47.0 sol_deltai: 60.0 sol_deltai - sol_taoi: 13.0 sol_taoP:
47.0 sol_deltaP: 49.0 sol_deltaP - sol_taoP: 2.0 cl_i: 3334365.0 sol_c_i: 3334365.0 sol_gp_i: 0.0 total work: 3691016.0 wasted work: 1.
3527749541047775
36 i: 7.0 l_i: 7.0 p_i: 0.0 al_i: 24.0 sol_a_i: 24.0 sol_g_i: 0.0 d_i: 52.0 sol_taoi: 24.0 sol_deltai: 42.0 sol_deltai - sol_taoi: 18.0 sol_taoP:
24.0 sol_deltaP: 29.0 sol_deltaP - sol_taoP: 5.0 cl_i: 4617655.0 sol_c_i: 4617655.0 sol_gp_i: 0.0 total work: 5272880.0 wasted work: 2.
4852642199329398
37 Time: 34.000000
38
39
40
41

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