```
D:\Python\Python\setroute\python.exe "D:\Python\Pycharm\setroute\PyCharm Community Edition 2021.2.3\plugins\python-ce\helpers\pydev\pydevconsole.py" --
      mode=client --port=22717
 3
     import sys; print('Python %s on %s' % (sys.version, sys.platform))
      sys.path.extend(['E:\\1 ] _ _ \\3 | 0 _ _ | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\1 | 0 | \\\  | 0 | \\1 | 0 | \\\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | \\  | 0 | 
      6
     PyDev console: starting.
 8 Python 3.9.7 (tags/v3.9.7:1016ef3, Aug 30 2021, 20:19:38) [MSC v.1929 64 bit (AMD64)] on win32
     main RO CCG.py', wdir='E:/1 0000/3 00000/1 000000/1 0000000/1 000000/1 LW 00001/4 0000/3 python_code/9 Code for
10 Backend TkAgg is interactive backend. Turning interactive mode on.
11
      Waiting 5s.....
13 Optimize the ./R 16 5.xlsx instance by CCG
14
             Master protblem status = 2, is Optimal and MP obj = 700.0
15
16
      The initial lb = -inf
                                         ub = inf
17
18
      The current iteration cnt = 0
              The SP model was solved Optimal 2 and SPObj = 700.0
19
20
             Deterministic Sub problem Status= 2, is Optimal
             1b = 1242.0
                                                    ub = 1242.0
21
22
              MPObj = 1242.0
                                               MP_delete_Hua_Obj = 722.0
                                                                                                  Hua = 520.0
                                                                                                                            SPObj = 700.0
                                                                                                                                                        Deter_SP_Obj = 520.0
24
     ub - 1b = 0.0
25
26 Iteration cycle stopped by termination criterion 1: Because ub - 1b \le e^2 eps, the iteration stop, and 1e^2 cm = 0
      i: 0.0 l_i: 4.0 p_i: 8.0 al_i: 21.0 sol_a i: 21.0 sol_g i: 0.0 d_i: 31.0 sol_taoi: 21.0 sol_deltai: 31.0 sol_deltai: 31.0 sol_deltai: 31.0 sol_deltai: 31.0 sol_deltai: 31.0 sol_taoi: 10.0 sol_taop: 21.0 sol_deltap: 24.0 sol_deltap - sol_taop: 3.0 cl_i: 2564346.0 sol_c_i: 2564346.0 sol_gp_i: 0.0 total work: 2768262.0 wasted work: 0.
27
      7734520793190818
          i: 1.0 1_i: 4.0 p_i: 19.0 aI_i: 37.0
                                                                           sol_a_i: 37.0 sol_g_i: 0.0 d_i: 50.0 sol_taoi: 37.0 sol_deltai: 50.0 sol_deltai - sol_taoi: 13.0 sol_taoP
        37.0 sol_deltaP: 40.0 sol_deltaP - sol_taoP: 3.0 cl_i: 3378522.0 sol_c_i: 3378522.0 sol_gp_i: 0.0 total work: 3427372.0 wasted work: 0.
      18528773649314986
          i: 2.0 1_i: 6.0 p_i: 1.0 aI_i: 47.0
                                                                     sol_a_i: 47.0 sol_g_i: 0.0 d_i: 62.0 sol_taoi: 47.0 sol_deltai: 62.0 sol_deltai - sol_taoi: 15.0 sol_taoP:
      47.0 sol deltaP: 51.0 sol_deltaP - sol_taoP: 4.0 cl_i: 3846651.0 sol_c_i: 3846651.0 sol_gp_i: 0.0 total work: 3954660.0 wasted work: 0.
      40967744382576504
30
          i: 3.0 1_i: 6.0 p_i: 6.0 aI_i: 1.0
                                                                       sol_a_i: 1.0 sol_g_i: 0.0 d_i: 18.0 sol_taoi: 1.0 sol_deltai: 18.0 sol_deltai - sol_taoi: 17.0 sol_taoP: 1.0
          sol_deltaP: 9.0 sol_deltaP - sol_taoP: 8.0 cI_i: 4246384.0
                                                                                                        sol_c_i: 4246384.0 sol_gp_i: 0.0 total work: 4481948.0 wasted work: 0.
      8934927402102836
          i: 4.0 1_i: 4.0 p_i: 19.0 aI i: 11.0
                                                                         sol_a_i: 11.0 sol_g_i: 0.0 d_i: 36.0 sol_taoi: 11.0 sol_deltai: 36.0 sol_deltai - sol_taoi: 25.0 sol_taoP
31
      : 11.0 sol_deltaP: 16.0 sol_deltaP - sol_taoP: 5.0 cl_i: 6440269.0 sol_c_i: 6440269.0 sol_gp_i: 0.0 total work: 6459278.0 wasted work: 0.
      0721010150050826\\
          i: 5.0 1_i: 6.0 p_i: 0.0 aI_i: 2.0
                                                                        sol\_a\_i: 2.0 \quad sol\_g\_i: 0.0 \quad d\_i: 19.0 \quad sol\_taoi: 2.0 \quad sol\_deltai: 19.0 \quad sol\_deltai - sol\_taoi: 17.0 \quad sol\_taoP: 2.0 \quad sol\_deltai - sol\_taoi: 17.0 \quad sol\_taoP: 2.0 \quad sol\_taoi: 19.0 \quad sol\_t
32
          sol_deltaP: 7.0 sol_deltaP - sol_taoP: 5.0 cI_i: 4398544.0 sol_c_i: 4398544.0 sol_gp_i: 0.0 total work: 4481948.0 wasted work: 0.
      31635083673438424
          i: 6.0 1_i: 7.0 p_i: 7.0 aI_i: 64.0
                                                                        sol_a_i: 64.0 sol_g_i: 0.0 d_i: 82.0 sol_taoi: 64.0 sol_deltai: 82.0 sol_deltai - sol_taoi: 18.0 sol_taoP:
      64.0 sol_deltaP: 67.0 sol_deltaP - sol_taoP: 3.0 cl_i: 4627375.0 sol_c_i: 4627375.0 sol_gp_i: 0.0 total work: 4745592.0 wasted work: 0.
      44839632231342264
         i: 7.0 1_i: 7.0 p_i: 0.0 aI_i: 37.0
                                                                      sol_a_i: 37.0 sol_g_i: 0.0 d_i: 45.0 sol_taoi: 37.0 sol_deltai: 45.0 sol_deltai - sol_taoi: 8.0 sol_taoP:
                sol_deltaP: 39.0 sol_deltaP - sol_taoP: 2.0 cI_i: 2064742.0 sol_c_i: 2064742.0 sol_gp_i: 0.0 total work: 2109152.0 wasted work: 0.
      16844684498793827
35
          i: 8.0 1_i: 5.0 p_i: 29.0 aI_i: 8.0
                                                                            sol_a_i: 8.0 sol_g_i: 0.0 d_i: 27.0 sol_taoi: 8.0 sol_deltai: 27.0 sol_deltai - sol_taoi: 19.0 sol_taoP: 8
             sol deltaP: 14.0 sol deltaP - sol taoP: 6.0 cl i: 4957402.0 sol c i: 4957402.0 sol gp i: 0.0 total work: 5141058.0 wasted work: 0.
      6966060293425983
36
          i: 9.0 1_i: 7.0 p_i: 12.0 aI_i: 4.0
                                                                          sol_a_i: 5.0 sol_g_i: 0.2 d_i: 31.0 sol_taoi: 5.0 sol_deltai: 29.0 sol_deltai - sol_taoi: 24.0 sol_taoP: 5
              sol_deltaP: 10.0 sol_deltaP - sol_taoP: 5.0 cl_i: 6090104.0 sol_c_i: 6090104.0 sol_gp_i: 0.0 total work: 6195634.0 wasted work: 0.
      40027461273535525
                                                                             sol_a_i: 52.0 sol_g_i: 0.5 d_i: 69.0 sol_taoi: 52.0 sol_deltai: 72.0 sol_deltai - sol_taoi: 20.0
37
          sol_taoP: 52.0 sol_deltaP: 59.0 sol_deltaP - sol_taoP: 7.0 cl_i: 5195384.0 sol_c_i: 5931990.0 sol_gp_i: 0.6984854576626056 total work:
      6063812.0 wasted work: 0.5
          i: 11.0 l_i: 7.0 p_i: 7.0 al_i: 27.0
38
                                                                         sol a i: 34.0 sol g i: 0.7 d i: 42.0 sol taoi: 34.0 sol deltai: 48.0 sol deltai - sol taoi: 14.0 sol taoP
        34.0 sol_deltaP: 37.0 sol_deltaP - sol_taoP: 3.0 cl_i: 3674443.0 sol_c_i: 4729019.0 sol_gp_i: 1.0 total work: 5536524.0 wasted work: 3.
      0628612826387096
          i: 12.0 1 i: 7.0 p i: 0.0 aI i: 10.0
                                                                         sol a i: 17.0 sol g i: 1.0 d i: 24.0 sol taoi: 20.0 sol deltai: 34.0 sol deltai - sol taoi: 14.0 sol taoP
        20.0 sol_deltaP: 27.0 sol_deltaP - sol_taoP: 7.0 cl_i: 3449685.0 sol_c_i: 3691016.0 sol_gp_i: 0.13076670488559247 total work: 3691016.0
      wasted work: 0.0
                                                                                40
         sol_deltai: 63
              sol deltai - sol_taoi: 25.0 sol_taoP: 38.0 sol_deltaP: 46.0 sol_deltaP - sol_taoP: 8.0 cl_i: 6370527.0 sol_c_i: 6776933.085714286 sol_gp_i: 0
      .770747837451802 total work: 6854744.0 wasted work: 0.2951362985150954
          sol_a_i: 17.0 sol_g_i: 1.0 d_i: 34.0 sol_taoi: 17.0 sol_deltai: 39.0 sol_deltai - sol_taoi: 22.0
      sol_taoP: 17.0 sol_deltaP: 22.0 sol_deltaP - sol_taoP: 5.0 cl_i: 5654254.0 sol_c_i: 6972474.0 sol_gp_i: 1.0 total work: 7118388.0 wasted work
      : 0.5534508655611354
          42
      sol_taoi: 20.0 sol_taoP: 47.0 sol_deltaP: 52.0 sol_deltaP - sol_taoP: 5.0 cl_i: 5113142.0 sol_c_i: 5956802.8 sol_gp_i: 0.4 total work: 6459278.0
          wasted work: 1.9058852088422273
43 Time: 1460.000000
44
45
46
47
```