

```
1 "E:\1 \0000\3 \0000\1 \0000\1 \0000\1 \0000\1_LW_\0000\4 \0000\3 python_code\1 exzample\2 \0000\9 Code for
this paper\Scripts\python.exe" "D:\Python\Pycharm\setroute\PyCharm Community Edition 2021.2.3\plugins\python-ce\helpers\pydev\pydevconsole.py" --mode=
client --port=28322
2
3 import sys; print('Python %s on %s' % (sys.version, sys.platform))
4 sys.path.extend(['E:\1 \0000\3 \0000\1 \0000\1 \0000\1 \0000\1_LW_\0000\4 \0000\3 python_code\9 Code for this
paper', 'E:/1 \0000/3 \0000/1 \0000/1 \0000\1 \0000\1_LW_\0000/4 \0000/3 python_code/9 Code for this paper'])
5
6 PyDev console: starting.
7
8 Python 3.9.7 (tags/v3.9.7:1016ef3, Aug 30 2021, 20:19:38) [MSC v.1929 64 bit (AMD64)] on win32
9 >>> runfile('E:/1 \0000/3 \0000\1 \0000\1 \0000\1 \0000\1_LW_\0000/4 \0000\3 python_code/9 Code for this paper/
main_RO_CCG_ExtendedByMe.py', wdir='E:/1 \0000/3 \0000\1 \0000\1 \0000\1 \0000\1_LW_\0000/4 \0000/3
python_code/9 Code for this paper')
10 Backend TkAgg is interactive backend. Turning interactive mode on.
11 Waiting 5s.....
12
13 Optimize the ./R_6_1.xlsx instance by ECCG
14
15 Master problem status = 2 , is Optimal and MP obj = 203.0
16 The initial lb = -inf ub = inf
17
18 The current iteration cnt = 0
19 The SP model was solved Optimal 2 and SPObj = 203.0
20 Deterministic Sub problem Status= 2 , is Optimal
21 Master problem status = 2 , is Optimal
22 lb = 336.0 ub = 336.0
23 MPObj = 336.0 MP_delete_Hua_Obj = 212.0 Hua = 124.0 SPObj = 203.0 Deter_SP_Obj = 124.0
24
25 ub - lb = 0.0
26
27 Iteration cycle stopped by termination criterion 1: Because ub - lb <= eps, the iteration stop, and cnt = 0
28 i: 0.0 l_i: 5.0 p_i: 20.0 al_i: 2.0 sol_a_i: 2.0 sol_g_i: 0.0 d_i: 11.0 sol_taoi: 2.0 sol_deltai: 11.0 sol_deltai - sol_taoi: 9.0 sol_taoP: 2
.0 sol_deltaP: 4.0 sol_deltaP - sol_taoP: 2.0 cl_i: 2292581.0 sol_c_i: 2292581.0 sol_gp_i: 0.0 total work: 2636440.0 wasted work: 1.
3042549802005734
29 i: 1.0 l_i: 6.0 p_i: 14.0 al_i: 7.0 sol_a_i: 7.0 sol_g_i: 0.0 d_i: 27.0 sol_taoi: 7.0 sol_deltai: 27.0 sol_deltai - sol_taoi: 20.0 sol_taoP: 7
.0 sol_deltaP: 11.0 sol_deltaP - sol_taoP: 4.0 cl_i: 5270879.0 sol_c_i: 5270879.0 sol_gp_i: 0.0 total work: 5272880.0 wasted work: 0.
007589780158091973
30 i: 2.0 l_i: 7.0 p_i: 7.0 al_i: 2.0 sol_a_i: 2.0 sol_g_i: 0.0 d_i: 15.0 sol_taoi: 2.0 sol_deltai: 15.0 sol_deltai - sol_taoi: 13.0 sol_taoP: 2.0
sol_deltaP: 6.0 sol_deltaP - sol_taoP: 4.0 cl_i: 3408100.0 sol_c_i: 3408100.0 sol_gp_i: 0.0 total work: 3427372.0 wasted work: 0.
07309857231721564
31 i: 3.0 l_i: 4.0 p_i: 20.0 al_i: 22.0 sol_a_i: 22.0 sol_g_i: 0.0 d_i: 50.0 sol_taoi: 22.0 sol_deltai: 50.0 sol_deltai - sol_taoi: 28.0 sol_taoP:
22.0 sol_deltaP: 27.0 sol_deltaP - sol_taoP: 5.0 cl_i: 7366651.0 sol_c_i: 7366651.0 sol_gp_i: 0.0 total work: 7382032.0 wasted work: 0.
05834003428866198
32 i: 4.0 l_i: 5.0 p_i: 0.0 al_i: 23.0 sol_a_i: 24.0 sol_g_i: 0.2 d_i: 62.0 sol_taoi: 24.0 sol_deltai: 43.0 sol_deltai - sol_taoi: 19.0 sol_taoP:
24.0 sol_deltaP: 30.0 sol_deltaP - sol_taoP: 6.0 cl_i: 4857867.0 sol_c_i: 5536523.800000001 sol_gp_i: 0.4290234811589375 total work:
5536524.0 wasted work: 7.585987136249713e-07
33 i: 5.0 l_i: 6.0 p_i: 5.0 al_i: 30.0 sol_a_i: 38.0 sol_g_i: 1.0 d_i: 70.0 sol_taoi: 38.0 sol_deltai: 66.0 sol_deltai - sol_taoi: 28.0 sol_taoP:
38.0 sol_deltaP: 46.0 sol_deltaP - sol_taoP: 8.0 cl_i: 7318466.0 sol_c_i: 7928256.0 sol_gp_i: 0.7709765188410624 total work: 8172964.0
wasted work: 0.928175873526422
34 Time: 29.000000
35
36
37
38
```