```
D:\Python\Python\setroute\python.exe "D:\Python\Pycharm\setroute\PyCharm Community Edition 2021.2.3\plugins\python-ce\helpers\pydev\pydevconsole.py" --
     mode=client --port=52068
 2
 3
     import sys; print('Python %s on %s' % (sys.version, sys.platform))
     6
     PyDev console: starting.
 8 Python 3.9.7 (tags/v3.9.7:1016ef3, Aug 30 2021, 20:19:38) [MSC v.1929 64 bit (AMD64)] on win32
     main_ECCG_deterministic.py', wdir='E:/1 0000/3 00000/1 0000000/1 0000000/1 000000/1 LW_00001/4 0000/3 python_code/
10 Backend TkAgg is interactive backend. Turning interactive mode on.
11
     Waiting 5s.....
     Optimize the ./R 9 4.xlsx instance by ECCG for deterministic model
13
14
15
     Set parameter MIPGap to value 0.01
            Master protblem status = 2, is Optimal and MP obj = 412.0
16
     The initial lb = -inf
                                     ub = inf
17
18
19
     The current iteration cnt = 0
20
            The SP model was solved Optimal 2 and SPObj = 412.0
            Deterministic Sub problem Status= 2, is Optimal
21
22
            Master protblem status = 2, is Optimal
                                           ub = 720.0
            MPObj = 720.0 MP_delete_Hua_Obj = 412.0
24
                                                                                  Hua = 308.0
                                                                                                         SPObi = 412.0
                                                                                                                                MP SP Obj = 308.0
                                                                                                                                                                      Deter SP Obj = 308.0
25
26
     ub - 1b = 0.0
27
28 Iteration cycle stopped by termination criterion 1: Because ub - lb \le eps, the iteration stop, and cnt = 0
                                                              sol_a_i: 54.0 sol_g_i: 0.0 d_i: 70.0 sol_taoi: 54.0 sol_deltai: 70.0 sol_deltai - sol_taoi: 16.0 sol taoP:
29
         i: 0.0 1_i: 6.0 p_i: 7.0 aI_i: 54.0
               sol_deltaP: 58.0 sol_deltaP - sol_taoP: 4.0 cI_i: 4202886.0 sol_c_i: 4202886.0 sol_gp_i: 0.0 total work: 5272880.0 wasted work: 4.
     0584803750512055
         i: 1.0 1_i: 6.0 p_i: 23.0 aI_i: 31.0
                                                                sol_a_i: 31.0 sol_g_i: 0.0 d_i: 46.0 sol_taoi: 31.0 sol_deltai: 46.0 sol_deltai - sol_taoi: 15.0 sol_taoP
30
       31.0 sol deltaP: 34.0 sol deltaP - sol taoP: 3.0 cI i: 3814820.0
                                                                                                     sol c i: 3814820.0 sol gp i: 0.0 total work: 3822838.0 wasted work: 0.
     03041222254251946
     i: 2.0 <u>l</u> i: 6.0 <u>p</u> i: 7.0 a<u>l</u> i: 30.0 <u>sol_a i</u>: 30.0 sol_g i: 0.0 30.0 <u>sol_deltaP</u>: 37.0 <u>sol_deltaP</u> - sol_taoP: 7.0 c<u>l_i</u>: 4748430.0
                                                               sol_a_i: 30.0 sol_g_i: 0.0 d_i: 49.0 sol_taoi: 30.0 sol_deltai: 49.0 sol_deltai - sol_taoi: 19.0 sol_taoP:
                                                                                                      sol_c_i: 4748430.0 sol_gp_i: 0.0 total work: 4877414.0 wasted work: 0.
     4892354842135607
         i: 3.0 l_i: 5.0 p_i: 0.0 al_i: 3.0 sol_a_i: 3.0 sol_g_i: 0.0 d_i: 13.0 sol_taoi: 3.0 sol_deltai: 13.0 sol_de
32
                                                               sol_a_i: 3.0 sol_g_i: 0.0 d_i: 13.0 sol_taoi: 3.0 sol_deltai: 13.0 sol_deltai - sol_taoi: 10.0 sol_taoP: 3.0
     6804630486565216
                                                                  sol a i: 28.0 sol g i: 0.0 d i: 36.0 sol taoi: 28.0 sol deltai: 36.0 sol deltai - sol taoi: 8.0 sol taoP
         i: 4.0 1_i: 6.0 p_i: 17.0 aI_i: 28.0
       28.0 sol_deltaP: 30.0 sol_deltaP - sol_taoP: 2.0 cl_i: 2051977.0 sol_c_i: 2051977.0 sol_gp_i: 0.0 total work: 2636440.0 wasted work: 2.
     2168644080654216
         i: 5.0 1_i: 6.0 p_i: 5.0 aI_i: 5.0
                                                                sol_a_i: 5.0 sol_g_i: 0.0 d_i: 19.0 sol_taoi: 5.0 sol_deltai: 18.0 sol_deltai - sol_taoi: 13.0 sol_taoP: 5.0
         sol_deltaP: 10.0
                                 sol deltaP - sol_taoP: 5.0 cl_i: 3343960.0 sol_c_i: 3343960.0 sol_gp_i: 0.0 total work: 3427372.0 wasted work: 0.
     3163811806830423
                                                                   sol a i: 65.0 sol g i: 0.0 d i: 83.0 sol taoi: 65.0 sol deltai: 78.0 sol deltai - sol taoi: 13.0 sol taoP
         i: 6.0 1 i: 6.0 p i: 13.0 aI i: 65.0
       65.0 sol_deltaP: 68.0 sol_deltaP - sol_taoP: 3.0 cl_i: 3237418.0 sol_c_i: 3237418.0 sol_gp_i: 0.0 total work: 4481948.0 wasted work: 4.
     7204943029236395
         i: 7.0 1_i: 7.0 p_i: 0.0 aI_i: 31.0
                                                                sol_a_i: 31.0 sol_g_i: 0.0 d_i: 63.0 sol_taoi: 31.0 sol_deltai: 57.0 sol_deltai - sol_taoi: 26.0 sol_taoP:
36
               sol_deltaP: 39.0 sol_deltaP - sol_taoP: 8.0 cI_i: 6664913.0 sol_c_i: 6664913.0 sol_gp_i: 0.0 total work: 6854744.0 wasted work: 0.
     7200277647130221
         i: 8.0 1 i: 4.0 p i: 13.0 aI i: 20.0
                                                                  sol a i: 20.0 sol g i: 0.0 d i: 48.0 sol taoi: 20.0 sol deltai: 45.0 sol deltai - sol taoi: 25.0 sol taoP
37
       20.0 sol_deltaP: 25.0 sol_deltaP - sol_taoP: 5.0 cl_i: 6574605.0 sol_c_i: 6574605.0 sol_gp_i: 0.0 total work: 6591100.0 wasted work: 0.
     0625654291392939
    Time: 58.000000
39
40
41
42
```