```
D:\Python\Python\setroute\python.exe "D:\Python\Pycharm\setroute\PyCharm Community Edition 2021.2.3\plugins\python-ce\helpers\pydev\pydevconsole.py" --
       mode=client --port=26421
  2
 3
      import sys; print('Python %s on %s' % (sys.version, sys.platform))
       sys.path.extend(['E:\\1 \\] \\\3 python_code\\9 Code for this
       6
      PyDev console: starting.
 8 Python 3.9.7 (tags/v3.9.7:1016ef3, Aug 30 2021, 20:19:38) [MSC v.1929 64 bit (AMD64)] on win32
      main_RO_CCG_ExtendedByMe.py', wdir='E:/1 0000/3 00000/1 0000000/1 0000000/1 0000000/1 LW_0001/4 0000/3
       python code/9 Code for this paper')
10 Backend TkAgg is interactive backend. Turning interactive mode on.
11
       Waiting 5s.....
       Optimize the ./R 12 4.xlsx instance by ECCG
13
14
15
               Master protblem status = 2, is Optimal and MP obj = 466.0
16
       The initial lb = -inf
                                                ub = inf
17
18
       The current iteration cnt = 0
19
                The SP model was solved Optimal 2 and SPObj = 466.0
20
               Deterministic Sub problem Status= 2, is Optimal
21
               Master protblem status = 2, is Optimal
               1b = 839.0
22
                                                       ub = 839.0
                MPObj = 839.0
23
                                              MP delete Hua Obj = 490.0
                                                                                                             Hua = 349.0
                                                                                                                                           SPObj = 466.0
                                                                                                                                                                             Deter SP Obj = 349.0
24
25
       ub - 1b = 0.0
26
27
      Iteration cycle stopped by termination criterion 1: Because ub - lb \le eps, the iteration stop, and cnt = 0
            i: 0.0 1_i: 6.0 p_i: 8.0 a1_i: 1.0 sol_a_i: 1.0 sol_g_i: 0.0 d_i: 33.0 sol_taoi: 1.0 sol_deltai: 30.0 sol_deltai - sol_taoi: 29.0 sol_taoP: 1.0
            sol_deltaP: 6.0 sol_deltaP - sol_taoP: 5.0 cl_i: 7519252.0
                                                                                                                        sol_c_i: 7519252.0 sol_gp_i: 0.0 total work: 7645676.0 wasted work: 0.
       47952542064298825
                                                                                   sol\_a\_i: 5.0 \quad sol\_g\_i: 0.0 \quad d\_i: 10.0 \quad sol\_taoi: 5.0 \quad sol\_deltai: 10.0 \quad sol\_deltai - sol \quad taoi: 5.0 \quad sol \quad taoP: 5.0 \quad sol\_deltai - sol \quad taoi: 5.0 \quad taoi:
            i: 1.0 1 i: 6.0 p_i: 2.0 aI_i: 5.0
29
            sol_deltaP: 7.0 sol_deltaP - sol_taoP: 2.0 cl_i: 1180139.0 sol_c i: 1180139.0 sol_gp_i: 0.0 total work: 1318220.0 wasted work: 0.
       5237403468313332
           i: 2.0 1_i: 6.0 p_i: 14.0 aI_i: 8.0
                                                                                        sol_a_i: 8.0 sol_g_i: 0.0 d_i: 13.0 sol_taoi: 8.0 sol_deltai: 13.0 sol_deltai - sol_taoi: 5.0 sol_taoP: 8
               sol_deltaP: 9.0 sol_deltaP - sol_taoP: 1.0 cl_i: 1067541.0 sol_c_i: 1067541.0 sol_gp_i: 0.0 total work: 1318220.0 wasted work: 0.
       9508238382060658
            i: 3.0 1_i: 5.0 p_i: 23.0 aI_i: 10.0
                                                                                        sol_a_i: 10.0 sol_g_i: 0.0 d_i: 16.0 sol_taoi: 10.0 sol_deltai: 17.0 sol_deltai - sol_taoi: 7.0 sol_taoP
31
          10.0 sol deltaP: 12.0 sol deltaP - sol taoP: 2.0 cI i: 1774663.0 sol c i: 1774663.0 sol gp i: 0.0 total work: 1977330.0 wasted work: 0.
       7687146303348454
            i: 4.0 1_i: 5.0 p_i: 14.0 aI_i: 17.0
                                                                                        sol_a_i: 17.0 sol_g_i: 0.0 d_i: 42.0 sol_taoi: 17.0 sol_deltai: 43.0 sol_deltai - sol_taoi: 26.0 sol_taoP
          17.0 sol_deltaP: 23.0 sol_deltaP - sol_taoP: 6.0 cl_i: 6675547.0 sol_c_i: 6675547.0 sol_gp_i: 0.0 total work: 6854744.0 wasted work: 0.
       679693070959324
                                                                                        sol\_a\_i: 24.0 \quad sol\_g\_i: 0.0 \quad d\_i: 45.0 \quad sol\_taoi: 24.0 \quad sol\_deltai: 42.0 \quad sol\_deltai - sol\_taoi: 18.0 \quad sol\_taoP
33
            i: 5.0 1_i: 6.0 p_i: 19.0 aI_i: 24.0
          24.0 sol_deltaP: 27.0 sol_deltaP - sol_taoP: 3.0 cI_i: 4610200.0 sol_c_i: 4610200.0 sol_gp_i: 0.0 total work: 4613770.0 wasted work: 0.
       013540987088649845
                                                                                        sol_a_i: 27.0 sol_g_i: 0.6 d_i: 31.0 sol_taoi: 27.0 sol_deltai: 32.0 sol_deltai - sol taoi: 5.0 sol taoP
            i: 6.0 \ l\_i: 7.0 \ p\_i: 25.0 \ aI\_i: 24.0
34
          27.0 sol deltaP: 28.0 sol deltaP - sol taoP: 1.0 cl i: 1202972.0 sol c i: 1273048.7000000002 sol gp i: 0.04430007889426657 total work:
       1318220.0 wasted work: 0.1713344510021082
       i: 7.0 l_i: 7.0 p_i: -0.0 al_i: 26.0 sol_a_i: 30.8 sol_g_i: 0.6 d_i: 45.0 sol_taoi: 31.0 sol_deltai: 50.0 sol_deltai - sol_taoi: 19.0 sol_ 31.0 sol_deltai - sol_taoi: 39.0 sol_deltai - sol_taoi: 19.0 sol_c_i: 5800168.0 sol_gp_i: 0.7893191197220494 total work: 5800168.0
                                                                                      sol a i: 30.8 sol g i: 0.6 d i: 45.0 sol taoi: 31.0 sol deltai: 50.0 sol deltai - sol taoi: 19.0 sol taoP
35
       wasted work: 0.0
                                                                                  sol a i: 31.0 sol g i: 0.0 d i: 45.0 sol taoi: 31.0 sol deltai: 36.0 sol deltai - sol taoi: 5.0 sol taoP:
            i: 8.0 1 i: 5.0 p i: 9.0 aI i: 31.0
       31.0 sol_deltaP: 33.0 sol_deltaP - sol_taoP: 2.0 cl_i: 1090030.0 sol_c_i: 2109152.0 sol_gp_i: 0.9663808013836841 total work: 2109152.0
       wasted work: 0.0
            i: 9.0 1_i: 7.0 p_i: 7.0 aI_i: 42.0
                                                                                    sol_a_i: 46.0 sol_g_i: 0.5714285714285714 d_i: 70.0 sol_taoi: 46.0 sol_deltai: 70.0 sol_deltai - sol_taoi:
       24.0 sol taoP: 46.0 sol deltaP: 50.0 sol_deltaP - sol_taoP: 4.0 cl_i: 6115664.0 sol_c_i: 6150981.800000004 sol_gp_i: 0.019137169819910538
            total work: 6327456.0 wasted work: 0.669365508033547
                                                                                            38
            sol deltai - sol taoi: 33.0 sol taoP: 50.0 sol deltaP: 56.0 sol deltaP - sol taoP: 6.0 cI i: 8590984.0 sol c i: 9118272.0 sol gp i: 1.0 total
       work: 9227540.0 wasted work: 0.4144528227458239
            i: 11.0 \quad 1\_i: 6.0 \quad p\_i: 20.0 \quad al\_i: 50.0 \quad sol\_a\_i: 55.0 \quad sol\_g\_i: 0.833333333333334 \quad d\_i: 66.0 \quad sol\_taoi: 55.0 \quad sol\_deltai: 64.0 \quad sol\_d
       sol_taoi: 9.0 sol_taoP: 56.0 sol_deltaP: 59.0 sol_deltaP - sol_taoP: 3.0 cI_i: 2266201.0 sol_c_i: 3295549.99999999 sol_gp_i: 0.
       7808628301800908 total work: 3822838.0 wasted work: 2.0000000000000036
      Time: 98.000000
41
42
43
44
```