

# ISE 426

## Optimization models and applications

Lecture 18 — November 4, 2014

- ▶ The Traveling Salesperson Problem (TSP)
- ▶ The Quadratic Assignment Problem (QAP)
- ▶ Piecewise linear functions

# The Traveling Salesperson Problem (TSP)

A salesperson has to visit  $n$  cities and then return home.

- ▶ She/he would like to spend as little as possible time/gas.
- ▶ Any pair of cities  $(i, j)$  is connected by a road, and the distance between them is denoted as  $d_{ij}$ .

A very well-known Optimization problem, with applications in the VLSI (chip manufacturing) industry:

- ▶ visit  $n$  points on a printed circuit board to punch each of them with a laser.
- ⇒ minimize time spent moving the robotic arm from point to point, i.e., minimize the total distance travelled: a TSP!

Other less obvious applications: machine scheduling with set up costs (e.g. painting cars).

<http://www.math.uwaterloo.ca/tsp>

## Formulation(s)

- ▶ Let's define the set of cities  $V = \{1, 2, \dots, n\}$ .
  - ▶ **Variables:**  $x_{ij}$ , binary; 1 if  $i \rightarrow j$  in the *tour*, 0 otherwise
- $\Rightarrow n(n-1)$  variables, one for each  $(i, j) \in V^2 : i \neq j$
- ▶ **Objective function:** The total distance travelled,

$$\sum_{i \in V} \sum_{j \in V: i \neq j} d_{ij} x_{ij}$$

- ▶ **Constraints:** every city  $i$  is visited (once), that is, only one arc leaves  $i$ :

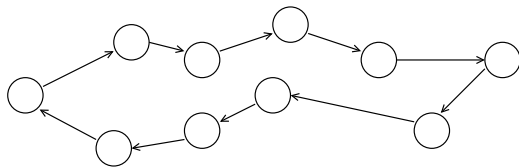
$$\sum_{j \in V: i \neq j} x_{ij} = 1 \quad \forall i \in V$$

and only one arc enters  $i$ :

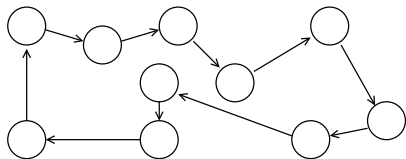
$$\sum_{j \in V: i \neq j} x_{ji} = 1 \quad \forall i \in V$$

- ▶ Is that it?

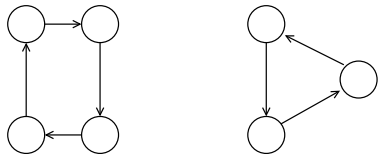
## “Feasible” solutions



OK



OK



Oops...

# Subtours

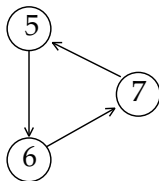
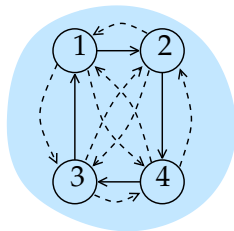
- ▶ An optimal solution to this IP model may be **infeasible!**
  - ▶ We need to ensure that no solution is a **union of subtours**
- ⇒ **Subtour elimination constraints:**

Every subset of  $m < n$  nodes cannot have  $m$  connections:

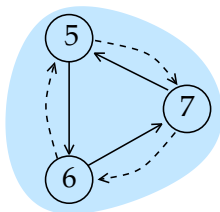
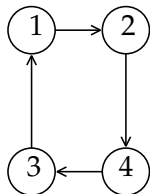
$$\sum_{i \in S, j \in S: i \neq j} x_{ij} \leq |S| - 1 \quad \forall S \subset V : S \neq \emptyset$$

- ▶ How many such constraints are there?
- ▶ As many as the (proper, non-empty) subsets of  $V$ :  $2^n - 2$
- ▶ For  $n = 30$ , that means a billion or so:  $2^{30} = 1,073,741,824$ .

## Example: eliminate a subtour



$$\begin{aligned} &x_{12} + x_{13} + x_{14} + \\ &x_{21} + x_{23} + x_{24} + \\ &x_{31} + x_{32} + x_{34} + \\ &x_{41} + x_{42} + x_{43} \leq 3 \end{aligned}$$



$$\begin{aligned} &x_{56} + x_{57} + \\ &x_{65} + x_{67} + \\ &x_{75} + x_{76} \leq 2 \end{aligned}$$

After adding these inequalities, the new solution may have subtours, but surely not these two.

# Subtours

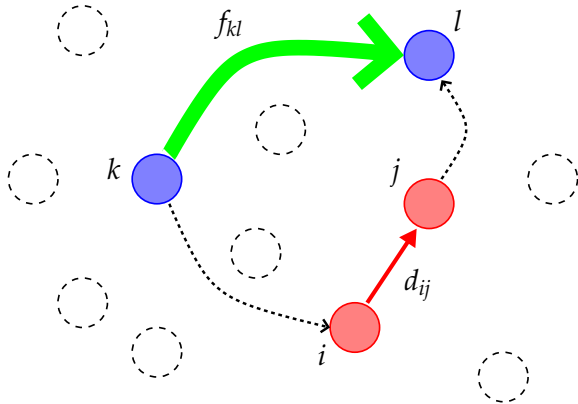
- ⇒ Do not add all of them, especially in real-world problems (where  $n$  is usually bigger than 30)
- ▶ **Iteratively** add those found to be violated:
  - repeat**
    - solve LP
    - find violated subtour elimination constraint(s)
    - add them to LP
  - until** no subtour elimination constraint is found
  - if** solution is fractional, **branch**
- ▶ This is called **Branch&Cut** (solves the  $n = 85,900$  problem)

# The Quadratic Assignment Problem (QAP)

- ▶ Consider  $n$  locations
  - ▶ and  $n$  activities (e.g. stages of an industrial process)
  - ▶ Any two locations  $i$  and  $j$  have a **distance**  $d_{ij}$
  - ▶ There is a **demand**  $f_{kl}$  between activities  $k$  and  $l$
  - ▶ Cost of satisfying each demand: proportional to
    - ▶  $f_{kl}$  and
    - ▶ the distance between the two locations assigned to  $k$  and  $l$
- ⇒ Assign each activity to a location such that the total assignment cost is minimum



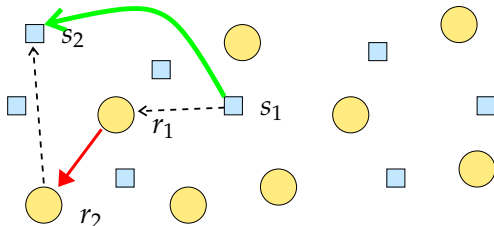
## A single demand



# QAP is a very general problem

It can be used when multiplicative costs factors are involved, for example:

- ▶ A set  $S$  of  $n$  students, a set  $R$  of  $n$  dorm rooms
- ▶ Each pair of students  $(k, l)$  has a friendship level  $f_{kl}$  (how often they visit each other).
- ▶ The distance between rooms  $i$  and  $j$  is  $d_{ij}$



⇒ formulate this problem as a QAP:

- ▶ Assign students to rooms so that the total time spent walking between dorm rooms is minimized.
- ▶ Once we solve the QAP, construct solution to our problem

# Formulation

Define  $N := \{1, 2, \dots, n\}$ .

**Variables:**  $x_{ij}$ . 1 if student  $i$  assigned to room  $j$ , 0 otherwise

**Constraints:** Each student  $i$  is assigned to **exactly** one room:

$$\sum_{j \in N} x_{ij} = 1 \quad \forall i \in N$$

Viceversa, each room  $j$  hosts **exactly** one student:

$$\sum_{i \in N} x_{ij} = 1 \quad \forall j \in N$$

# Formulation

- ▶ **Objective function:** For each pair  $(k, l)$  of students, frequency of visits  $f_{kl}$  is weighted with by distance between the rooms associated with  $k$  and  $l$
  - ▶ Suppose student  $k$  is assigned to room  $i$  (i.e.  $x_{ki} = 1$ ) and student  $l$  is assigned to room  $j$  (i.e.  $x_{lj} = 1$ )
  - ▶ The contribution to the cost: is  $f_{kl}$  multiplied by distance  $d_{ij}$ , but only if  $x_{ki} = 1 \wedge x_{lj} = 1$ , i.e.,  $x_{ki}x_{lj} = 1$  (nonlinear!).
- ⇒ The cost associated with each pair of students  $(k, l)$  is

$$(\star) \quad \sum_{i \in N} \sum_{j \in N} f_{kl} d_{ij} x_{ki} x_{lj}$$

- ▶ The overall cost is therefore the sum of  $(\star)$  on all pairs  $(k, l)$ :

$$\sum_{k \in N} \sum_{l \in N} \sum_{i \in N} \sum_{j \in N} f_{kl} d_{ij} x_{ki} x_{lj}$$

# Formulation

- ▶ The objective function is nonlinear, but we know what to do...
  - ▶ Introduce a new variable  $y_{kilj}$  defined as  $x_{ki}x_{lj}$
- ⇒  $y_{kilj}$  are binary too, and are subject to the constraints:

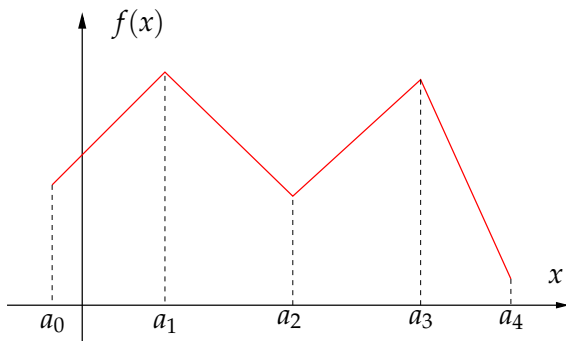
$$\begin{aligned}y_{kilj} &\leq x_{lj} \\y_{kilj} &\leq x_{ki} \\y_{kilj} &\geq x_{ki} + x_{lj} - 1\end{aligned}$$

# Formulation

$$\begin{array}{ll} \min & \sum_{k \in N} \sum_{l \in N} \sum_{i \in N} \sum_{j \in N} f_{kl} d_{ij} y_{kilj} \\ & \sum_{j \in N} x_{ij} = 1 \quad \forall i \in N \\ & \sum_{i \in N} x_{ij} = 1 \quad \forall j \in N \\ & y_{kilj} \leq x_{ki} \quad \forall (k, i, l, j) \in N^4 \\ & y_{kilj} \leq x_{lj} \quad \forall (k, i, l, j) \in N^4 \\ & y_{kilj} \geq x_{ki} + x_{lj} - 1 \quad \forall (k, i, l, j) \in N^4 \\ & y_{kilj} \in \{0, 1\} \quad \forall (k, i, l, j) \in N^4 \\ & x_{ij} \in \{0, 1\} \quad \forall (i, j) \in N^2 \end{array}$$

# Piecewise Linear functions

Consider a univariate, **piecewise linear** function  $f(x)$  made of  $n$  linear pieces.



- ▶ it can be modeled with linear constraints
- ▶ but the function is not convex, hence we need a MILP model this time

# A model for piecewise linear functions

Variable  $x$  needs to be modeled depending on the  $a_i$ 's.

- ▶ If  $a_2 \leq x \leq a_3$ , we want  $f(x)$  to be between  $f(a_2)$  and  $f(a_3)$
- ▶ If  $x = \lambda a_2 + (1 - \lambda)a_3$ , with  $0 \leq \lambda \leq 1$ , then  $f(x)$  must be  $\lambda f(a_2) + (1 - \lambda)f(a_3)$
- ▶ In general, use variables  $\lambda_i$ :  $x = \sum_{i=0}^n \lambda_i a_i$ , where
  - ▶ **only two**  $\lambda_i$ 's are non zero, **and**
  - ▶ they sum up to **one**, **and**
  - ▶ they are **consecutive**

e.g. to model  $x$  exactly at the midpoint between  $a_2$  and  $a_3$ , we need  $\lambda_2 = \lambda_3 = \frac{1}{2}$  and  $\lambda_0 = \lambda_1 = \lambda_4 = 0$



# A model for piecewise linear functions

OK, but how do we ensure the “only two” and the “consecutive” things?

⇒ with binary variables!

- ▶ Define one binary variable  $y_i$  for each linear piece:
- ▶ There is only one nonzero  $y_i$
- ▶  $y_i$  is 1 if  $x$  is between  $a_{i-1}$  and  $a_i$
- ▶ That is, we want
  - ▶ if  $\lambda_0 > 0$ , then  $y_1 = 1$
  - ▶ if  $\lambda_i > 0$  with  $i = 1, 2, \dots, n-1$ , then  $y_i = 1$  **or**  $y_{i+1} = 1$
  - ▶ if  $\lambda_n > 0$ , then  $y_n = 1$

# A model for piecewise linear functions

Introduce a new variable  $\varphi$  for  $f(x)$ . We have:

$$\begin{aligned}\varphi &= \sum_{i=0}^n \lambda_i f(a_i) \\ x &= \sum_{i=0}^n \lambda_i a_i \\ \sum_{i=0}^n \lambda_i &= 1 \\ \sum_{i=1}^n y_i &= 1 \\ \lambda_0 &\leq y_1 \\ \lambda_n &\leq y_n \\ \lambda_i &\leq y_i + y_{i+1} && \forall i = 1, 2, \dots, n-1 \\ \lambda_i &\in [0, 1] && \forall i = 0, 2, \dots, n \\ y_i &\in \{0, 1\} && \forall i = 1, 2, \dots, n\end{aligned}$$