



The background features a 3x3 grid of colored squares. The top row contains light blue, pink, and light blue squares. The middle row contains light green, light green, and light gray squares. The bottom row contains light orange, light beige, and light purple squares. A yellow path with circular nodes connects five squares: (1,2), (2,3), (3,1), (3,2), and (3,3). The text "Lotta 101" and "Milling Action" is centered over the grid.

Lotta 101

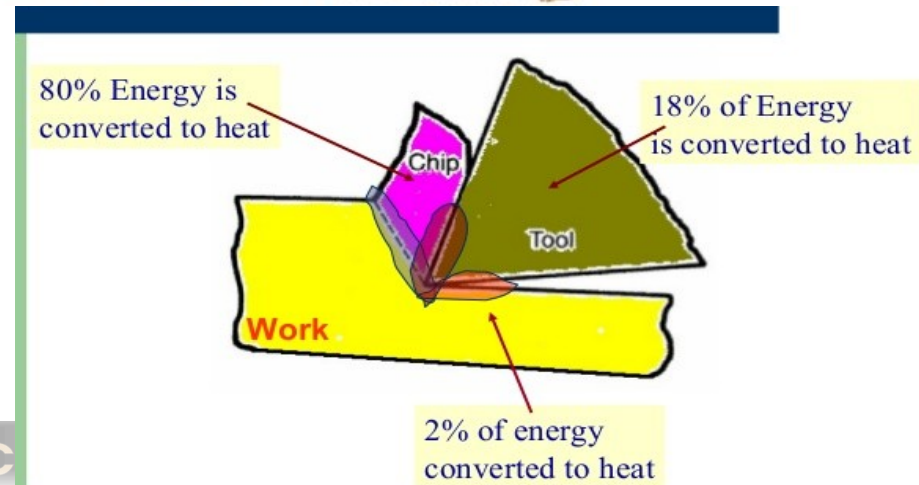
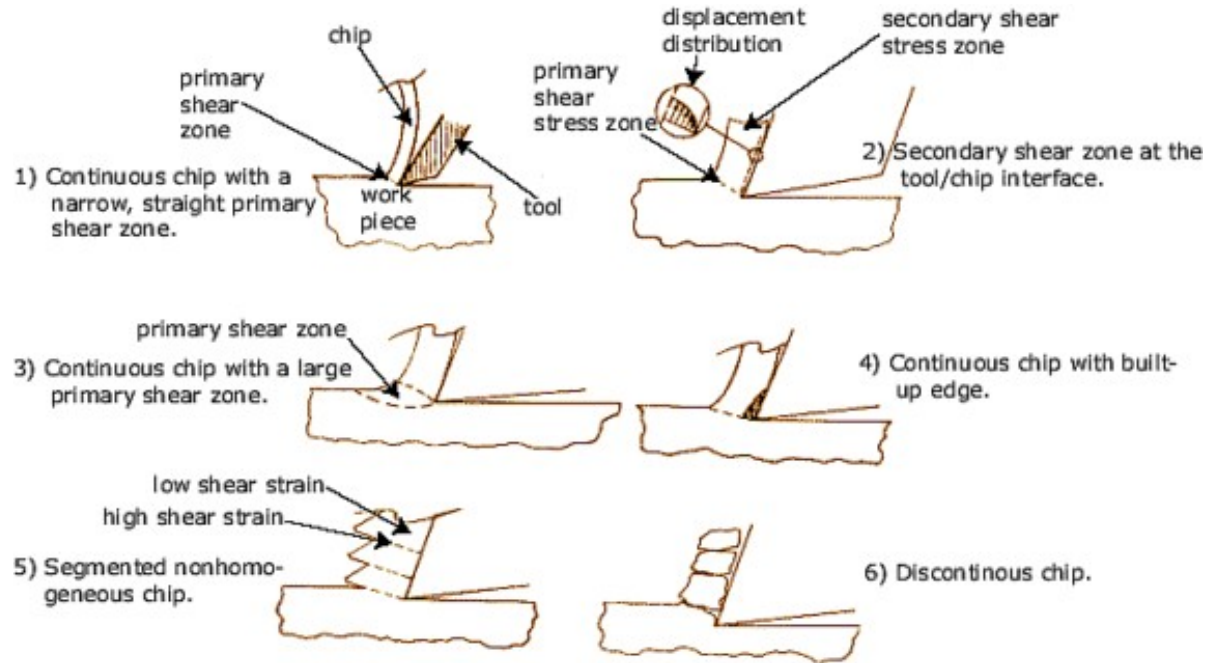
Milling Action



Chip formation

<https://www.youtube.com/watch.v=mRuSYQ5Npek>

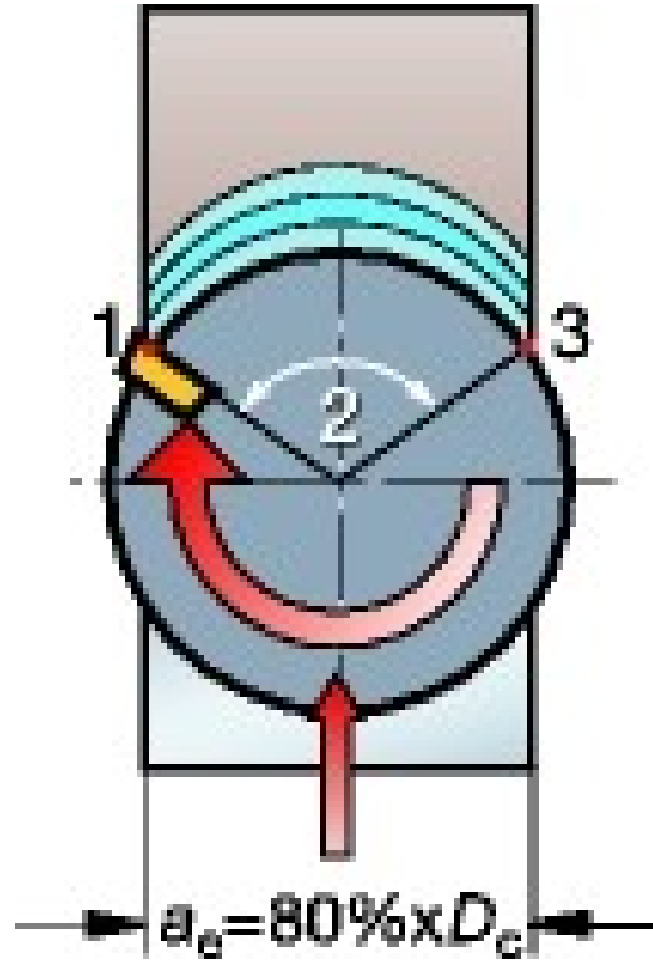
- The tool creates a chip by plastic deformation in the so called primary shear zone
 - The material heats until it softens
- The aim is a continuous solid chip with smooth tool side
 - The primary shear zone in front of the blade heats up resulting in plastic deformation
 - Ideal chip color is from straw colored to blue (steel)





Successive phases of cutting and chip formation

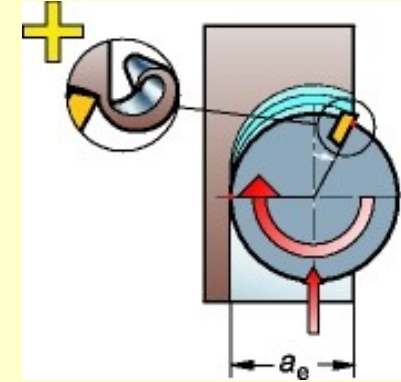
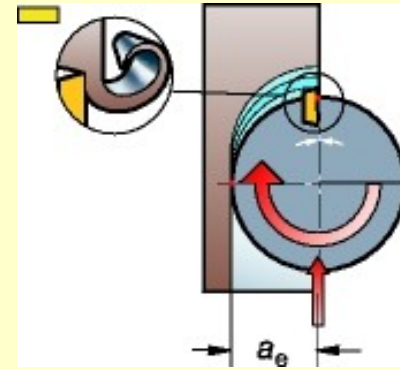
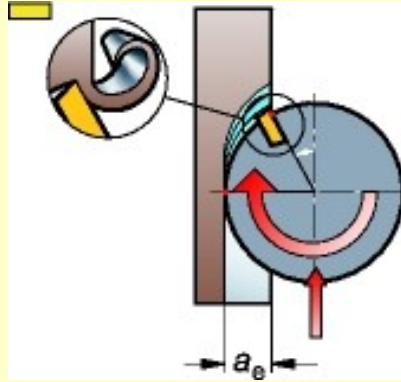
- 1. Initial contact
- 2. Actual cutting
- 3. Exit



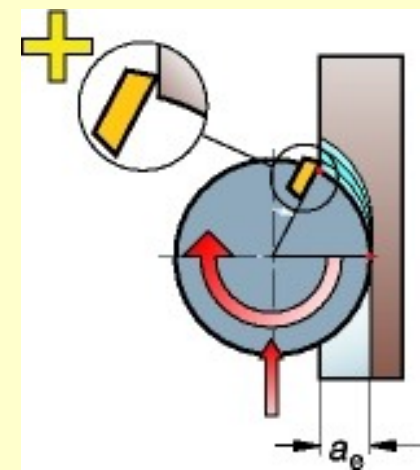
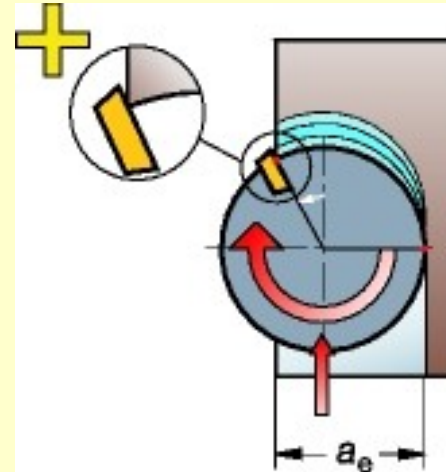
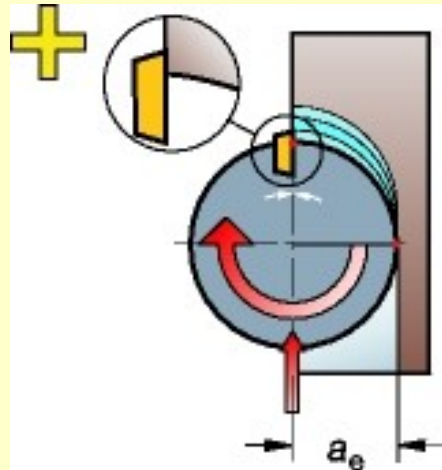


Cutting Directions

Conventional cut
(older machines with
manual leadscrews
[backlash!])



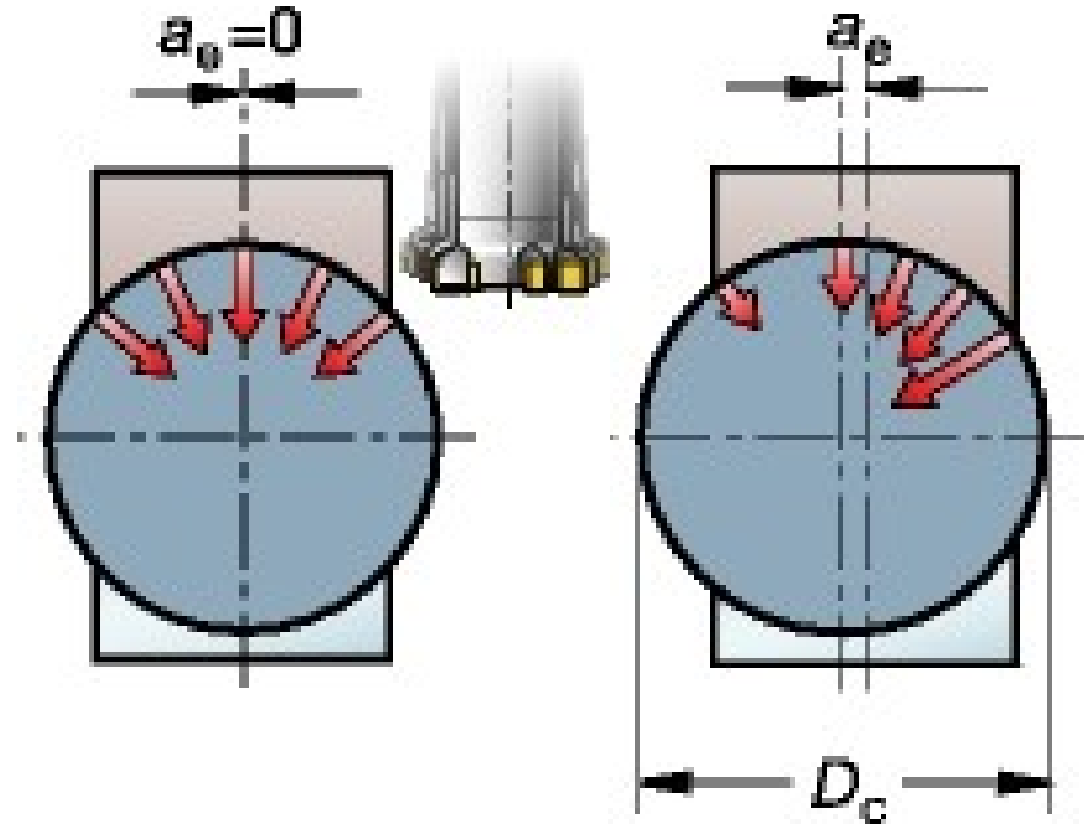
Climbing cut
(preferred for machines
with ballscrews;
*always use for
carbide tools*)





Desirable Tool Position Relative to Workpiece

- The chip should thin out at exit
- The tool should track left of centerline (in direction of motion)
 - Cutting force is more stable – less risk of resonant vibration
- The tool should be 20-50% wider than the workpiece





Milling terms - Speeds

- Cutting speed v_c (m/min)
 - Nominal cutting speed at tool outer radius. This is the speed at which the cutting edge moves through material.
- Effective cutting speed (m/min)
 - Actual cutting speed at the effective radius D_{cap}

$$v_c = \frac{D_{cap} * \pi * n}{1000}$$

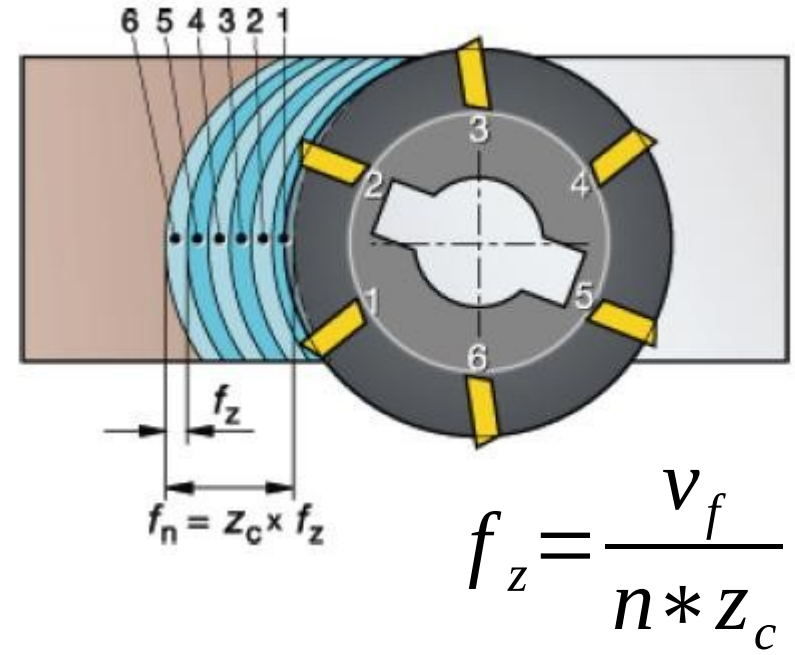
- Spindle speed n = RPM





Milling terms - Feeds

- Feed per tool flute f_z (mm/flute)
 - The distance the tool advances for each individual cut of a flute (one factor that determines chip thickness)
- Feed per revolution f_n (mm/rev)
 - The distance the tool advances per one complete revolution (in tapping, this is programmed)
- Feed per minute (mm/min)
 - The distance the tool advances in one minute (with normal milling, this is programmed)





Phases of a milling job

- 1. Roughing
 - Coarse milling that removes lots of material quickly
 - Get the workpiece close to final shape
 - No special requirements for surface quality
 - Tool selected to achieve fast material removal with reasonable accuracy
- 3. Finishing
 - Light final passes that achieve the desired dimensions precisely
 - Tool selected to produce precise dimensions and optimal surface quality

Esityksen tuotti



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