IBRAHIM ESSAM ABDELMONEM

Mechatronics & Robotics Engineer.

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EXPERIENCE

R&D Engineer

Avelabs

09/2018-Ongoing

♥ Cairo, Egypt

- Developer Advocate For Yonohub (A cloud-based system for Autonomous Vehicles, ADAS, and Robotics yonohub.com).
- Creating tech content for publication as articles, tutorials and showcase apps to effectively demonstrate use cases of Yonohub.
- Developing new Blocks from the state of the art ML/DL and ADAS Algorithms.
- Preparing Hardware for Local Deployment (Nvidia Jetson AGX Xavier, Raspberry Pi).
- Preparing AVS Datasets for Yonohub, e.g. KITTI, DeepDrive, ApolloScape and Comma.ai
- AV's Sensor Product Algorithms Development Engineer.
- · Creating ROS packages for the product.
- > Key Technologies: Autonomous Vehicles, ROS, ML/DL, Cloud, Embedded Boards

Bachelor Thesis and Internship

Daimler AG

1 02/2017-08/2017

♀ Sindelfingen, Germany

- Devleoping a Test Robot for Touch Devices Testing.
- Hardware (Robot Construction, Kinematics and Touch Devices)
- Software (CANoe,CAN-bus,Databases and The Test System)
- Making Tests on The Touch Devices with the Robot to analyze the state and develop improvements.
- Implementing new Algorithms and Data structures for the Robot in MATLAB.
- Programming a Graphical User Interface for the System
- Optimizing the test system to fulfill the requirements of Daimler AG.
- >_ Key Technologies: Delta Robots, MATLAB, CANoe

Suspension and Steering Team

GUC Innovators - Shell Eco Marathon Competition

1 03/16 - 02/17

♀ Cairo, Egypt

- Design and Manufacturing of Car's Steering and Chassis.
- >_ Key Technologies: SolidWorks, MATLAB

Commercial Aircraft Maintenance Internship Egypt Air

m 06/16 - 07/16

♀ Cairo, Egypt

• Training on Avionics and Jet Engines maintenance.

Junior Teaching Assistant

The German University in Cairo

10/14 - 02/15

♀ Cairo, Egypt

- Teaching CS01 Students Programming Concepts and Assisting them during the Labs.
- >_ Key Technologies: Java

EDUCATION

BSc. Mechatronics Engineering The German University in Cairo

2018

♀ Cairo

Excellent with Honors

ONLINE DEGREES



Sensors Fusion Nano Degree - Udacity Certificate — Description

- Lidar Obstacles Detection, Plane Segmentation and PointsCloud Clustering.
- Camera and Lidar Fusion.
- Radar Obstacle Detection.
- Kalman Filters.

Deep Learning Specialization - Coursera Certificate — Description

- Neural Networks and Deep Learning
- Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization
- Structuring Machine Learning Projects
- Convolutional Neural Networks
- Sequence Models

PROGRAMMING LANGUAGES

C++

Python

Java

MATLAB

Bash

FRAMEWORKS AND LIBRARIES









TECHNOLOGIES



PROJECTS

- Unscented Kalman Filter to estimate the state of multiple cars. Github
- Particles Filter C++ Implementation. Github
- Time To Collision System (TTC) based on Lidar and Camera. Github
- PointClouds Obstacles Detection, Segmentation and Clustering Github
- Jupyter-ROS (Contributor) ROS Support for jupyter notebooks Github
- Longitudinal and Lateral Control in CARLA Simulator Github Video
- Deep Reinforcement Learning DQN Agent Playing Space Invaders Github Video
- Road Semantic Segmentation Using Fully Convolutional Network (FCN) Github
- Building and Simulating TurtleBot using ROS and Raspberry Pi Github Video
- Optimal LQG Control of Wind Turbine using Kalman Filter
- Non-Linear Controller (Feedback Linearization) for 2D Plotter Robot Arm
- PID Control of Two-Wheeled Self balancing Robot . Video
- Yu-Gi-Oh Video Game in Java Github Video

HONORS & AWARDS

Academic Achievement Full Scholarship
The German University in Cairo

2013-2018

♀ Cairo, Egypt

Ranked 7th in Thanwya Amma (High School)

The Egyptian Ministry of Education

2013

♀ Cairo, Egypt

ONLINE COURSES

- State Estimation and Localization for SDC
- Introduction to Self-Driving Cars
- ROS1x: Hello (Real) World with ROS
- Electric and Conventional Vehicles
- Machine Learning with TensorFlow on GCP
- Python Parallel Programming Solutions
- Intro to FPGA Design for Embedded Systems
- Agile Software Development
- Control of Mobile Robots

LANGUAGES

- Arabic ★★★★★
- English ★★★★
- German ★★★★★