Model Order Reduction Project Heat Diffusion

Xinyu Zeng, 1301462 Hemaditya Malla, 1282484

January 7, 2019

Contents

Problem 3	2
Problem 4	Ş
Problem 10	3
Problem 11	9

Problem 1

This system is non-linear and time-invariant. According to description, this model is isotropic. Therefor,

$$\rho(x,y)c(x,y)\frac{\partial T}{\partial t}(x,y,t) = \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \end{bmatrix} \begin{bmatrix} \kappa(x,y) & 0 \\ 0 & \kappa(x,y) \end{bmatrix} \begin{bmatrix} \frac{\partial T}{\partial x}(x,y,t) \\ \frac{\partial T}{\partial y}(x,y,t) \end{bmatrix} + u(x,y,t) \tag{1}$$

i.e.

$$\rho(x,y)c(x,y)\frac{\partial T}{\partial t}(x,y,t) = \left(\frac{\partial \kappa}{\partial x}(x,y)\frac{\partial T}{\partial x}(x,y,t) + \frac{\partial \kappa}{\partial y}(x,y)\frac{\partial T}{\partial y}(x,y,t)\right) + u(x,y,t) \tag{2}$$

non-homogeneous

Non-linear

Firstly, just consider the left side of the equation (2),

$$\rho(x_1 + x_2, y_1 + y_2)c(x_1 + x_2, y_1 + y_2)\frac{\partial T}{\partial t}(x_1 + x_2, y_1 + y_2, t)$$
(3)

Since it's unknown whether ρ and c is linear (because the part of T is only associated with t, this part could be ignored), even though they are both linear, like equation (5), it is still non-linear.

$$\rho(x_1 + x_2, y_1 + y_2)c(x_1 + x_2, y_1 + y_2) = (\rho(x_1, y_1) + \rho(x_2, y_2))(c(x_1, y_1) + c(x_2, y_2))$$
(4)

$$\rho(x_1,y_1)c(x_1,y_1) + \rho(x_1,y_1)c(x_2,y_2) + \rho(x_2,y_2)c(x_1,y_1) + \rho(x_2,y_2)c(x_2,y_2) \neq (\rho(x_1,y_1)c(x_1,y_1) + \rho(x_2,y_2))c(x_2,y_2)$$
 (5)

time-invariant

input delayed: $u_d(t) = u(t + \delta)$

$$\rho(x,y)c(x,y)\frac{\partial T}{\partial t}(x,y,t) - \left(\frac{\partial \kappa}{\partial x}(x,y)\frac{\partial T}{\partial x}(x,y,t) + \frac{\partial \kappa}{\partial y}(x,y)\frac{\partial T}{\partial y}(x,y,t)\right) = u(x,y,t+\delta) \quad (6)$$

output delayed: $T_d(t) = T(t + \delta)$

$$\rho(x,y)c(x,y)\frac{\partial T}{\partial t}(x,y,t+\delta) - (\frac{\partial \kappa}{\partial x}(x,y)\frac{\partial T}{\partial x}(x,y,t+\delta) + \frac{\partial \kappa}{\partial y}(x,y)\frac{\partial T}{\partial y}(x,y,t+\delta)) = u(x,y,t+\delta)$$
(7)

The right side of equation (6) and (7) is equal, so it is time-invariant.

homogeneous

Non-linear

When ρ and c is constant, consider the right side of equation(2),

$$\frac{\partial \kappa}{\partial x}(x_1 + x_2, y_1 + y_2) \frac{\partial T}{\partial x}(x_1 + x_2, y_1 + y_2, t) + \frac{\partial \kappa}{\partial y}(x_1 + x_2, y_1 + y_2) \frac{\partial T}{\partial y}(x_1 + x_2, y_1 + y_2, t) + u(x_1 + x_2, y_1 + y_2, t)$$
(8)

since κ is coupled with T, the first item

$$\frac{\partial \kappa}{\partial x}(x_1 + x_2) \frac{\partial T}{\partial x}(x_1 + x_2) \neq \frac{\partial \kappa}{\partial x}(x_1) \frac{\partial T}{\partial x}(x_1) + \frac{\partial \kappa}{\partial x}(x_2) \frac{\partial T}{\partial x}(x_2)$$
(9)

time-invariant

Because only u and T is associated with time that no matter the system is homogeneous or not, it is time-invariant. (Proof as equation(6) and (7))

Problem 2

Problem 3

Problem 4