

Feb-25-2019 Compensation Function for ADC

$$f(x) + g(x) = ax + b \quad \dots (1)$$

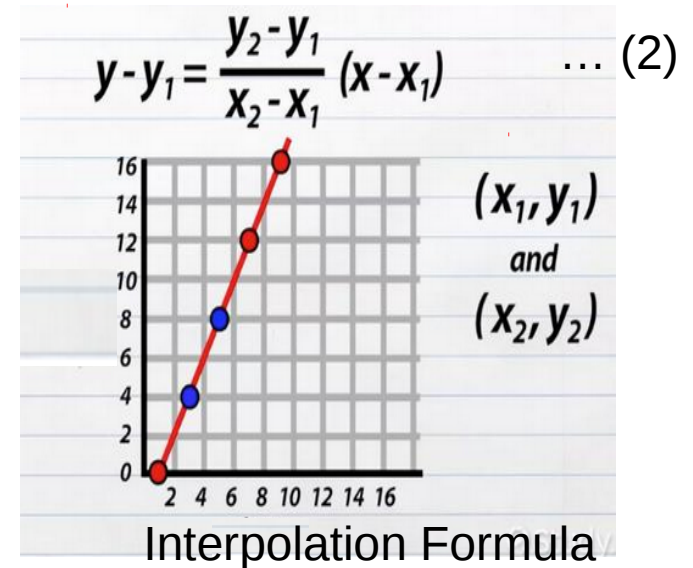
Where $ax + b$ is the ideal linear characteristics of the ADC, $f(x)$ is the actual ADC function (piece wise linear), and $g(x)$ is the compensation function to be designed. Note $b = 0$, and a is a slope for the ADC, for 10 bits ADC, $a = 1024/3.3$, $f(x)$ is from the ADC data characteristic curve and $g(x)$ is the compensation function to be designed.

So $f(x) + g(x) = ax$ and

Based on equation (2), we can write $f(x)$ as

$$f(x) = px + q \quad \dots (3)$$

p and q can be found from the actual experiment. Substitute eqn(3) back to (1),



we have

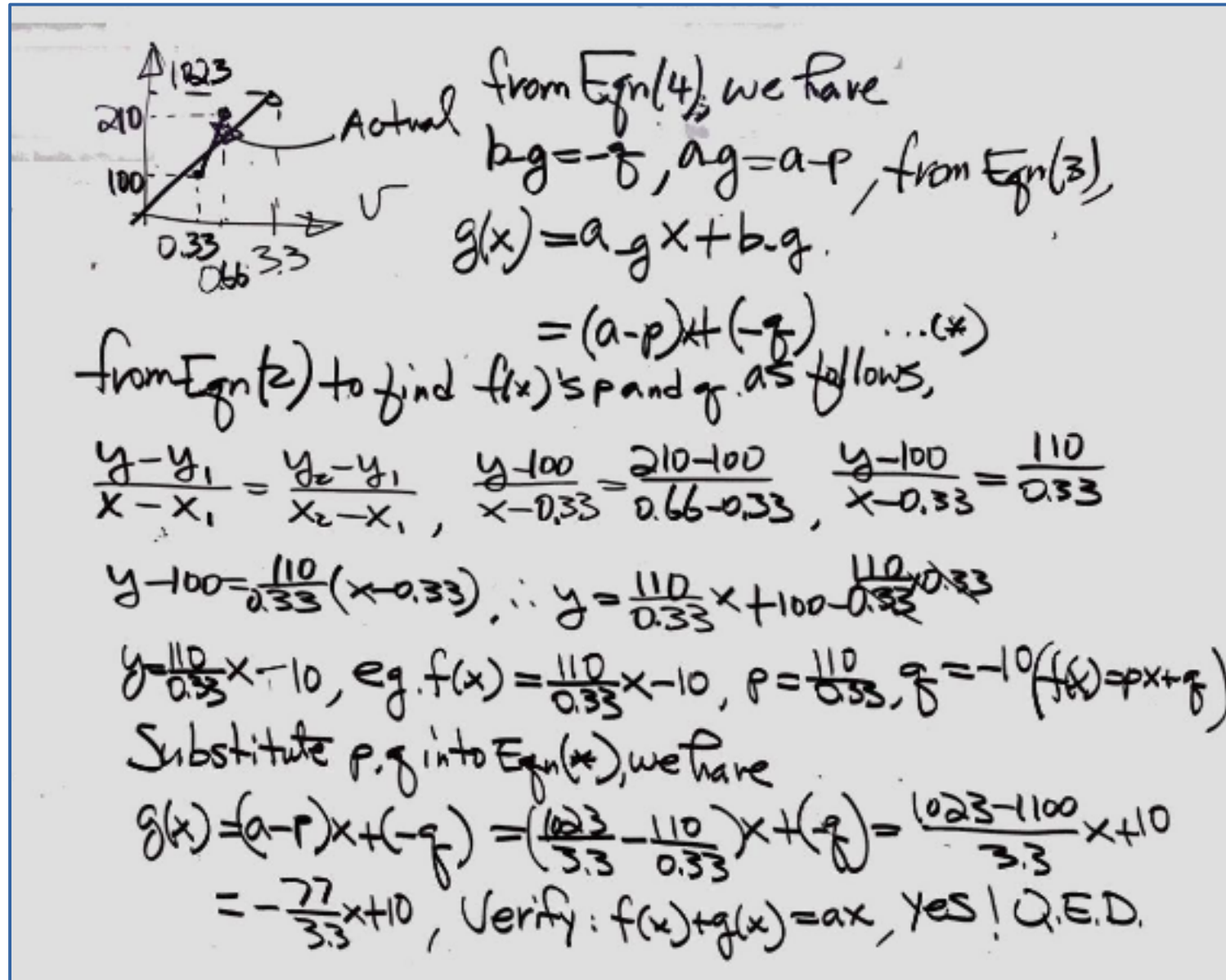
$$px + q + g(x) = ax$$

$$px + q + a_g x + b_g = ax$$

Therefore:

$$b_g = -q; a_g = (a - p) \quad \dots (4)$$

Feb-25-2019 ADC Compensation Example



A/D Converter

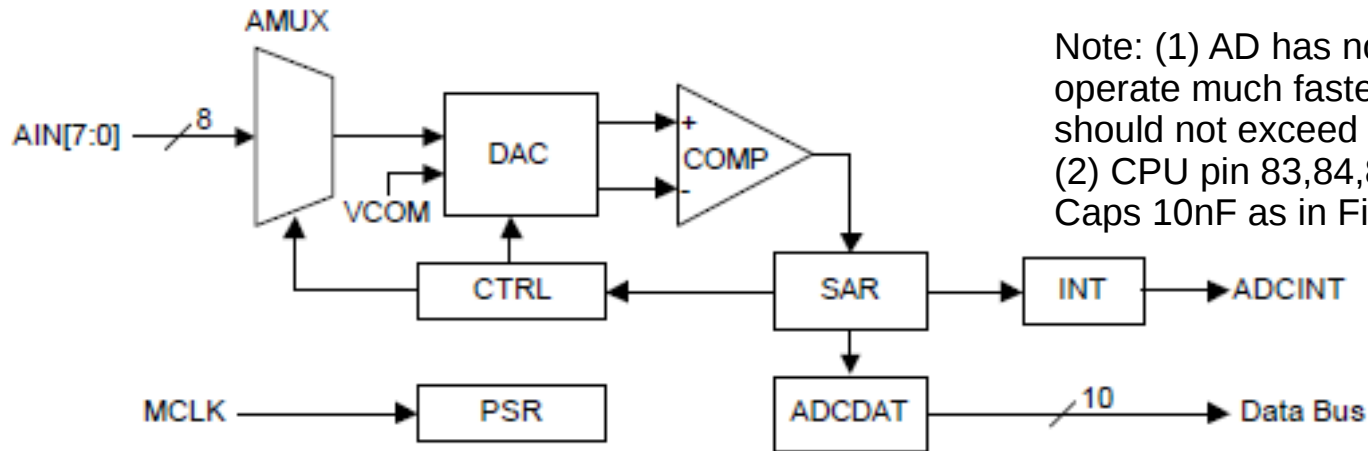


Fig 1

Note: (1) AD has no built-in S/H circuit. Even it can operate much faster, but without S/H, the sampling speed should not exceed 100 Hz;
 (2) CPU pin 83,84,85 must have external compensation Caps 10nF as in Fig 2;

(3) Problem 1 of the ADC: ADCCON's ADC state flag off by 1 right after the conversion starts and right before the conversion ends;

PSR	Prescaler register: define sample speed	
ADCCON	ADC control register	
ADCDAT	ADC data register	
SAR	Successive approximation register	

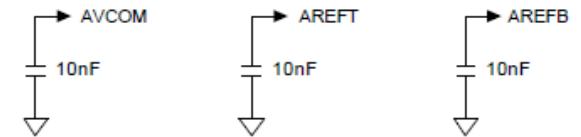


Fig 2

(4) Problem 2 of the ADC: No S/H therefore ADC error can be large, need to reduce the output impedance of the analog signal source.

$$f_{Conv} = \frac{CLK_{CPU}}{2 * (N_{PSR} + 1)} \quad \dots(1) \quad T_{Conv} = \frac{1}{f_{Conv}} \quad \dots(2)$$

Example: For a given signal, we have $f_{Sampling} = 98.2 \text{ KHz}$, find N_{PSR} to realize this AD design requirement. Ans: $N_{PSR} = 20$

ADC Theoretical Background

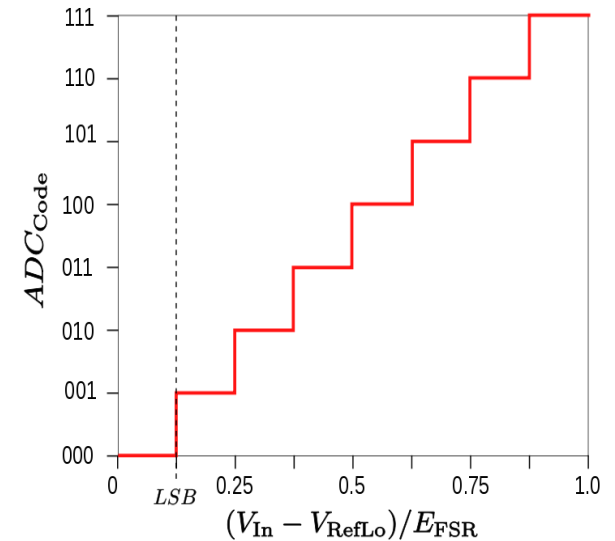
ADC voltage resolution Q calculation

$$Q = \frac{E_{FSR}}{N}$$

Where $E_{FSR} = V_{R,High} - V_{R,Low}$

and

$$N = 2^x$$



http://en.wikipedia.org/wiki/File:ADC_voltage_resolution.svg

Fig 3

Example 1

- * Coding scheme as in figure 3
- * Full scale measurement range = 0 to 10 volts
- * ADC resolution is 12 bits: $2^{12} = 4096$ quantization levels (codes)
- * ADC voltage resolution, $Q = (10V - 0V) / 4096 = 10V / 4096 \approx 0.00244 V \approx 2.44 mV$.

DFT (FFT: fast Fourier Transform) based AD conversion validation.

ADC Characterization

Today's Topics:

1° Introduction to ADC. (CPU Datasheet)

2° Data Validation.

Reference: CPU ADC Chapter (392)
for ARM11 or Equivalent

Table 1 ADC Characterization

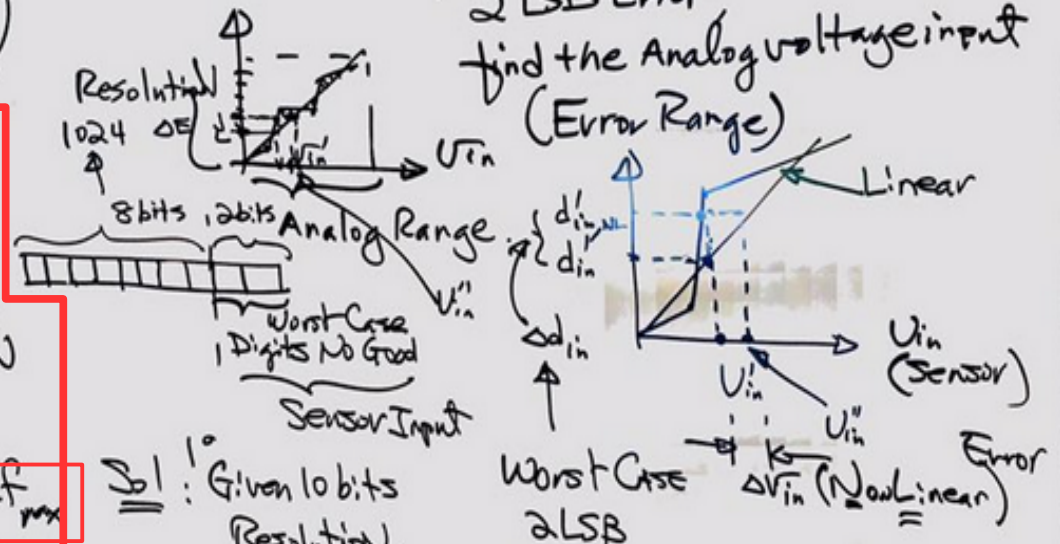
No	Description	Note
1° Resolution	10 bit (1024) 12 bit (4096)	Quantization Levels per given Resolution
2° Conversion Rate	1 MSPS	Conversion Time per Sample $f_{\text{Sampling}} \geq 2f_{\text{max}}$
3° Analog Input Range	[0, 3.3]	for Sensor I/F Design. OpAmp Preprocessing CKT.
4° Linearity (Non)	2 LSB Difference	Calculation for Sensor Input

Note:

1° Conversion Time, $T_{\text{conv}} = \frac{1}{f_{\text{Sampling}}} = 1 \times 10^{-6}$
 $\mu\text{S} = 1 \times 10^{-6}$

2° Non-Linearity

Example: Given 2 LSB Error
find the Analog voltage input (Error Range)



Sol: 1° Given 10 bits Resolution.

2° Analog Range 3.3V.

3° Therefore for LSB (1 bit): $\frac{3.3V (\text{Full Range})}{1024 (\text{Full Resolution})} \approx 3.3 \times 10^{-3} \text{ VDC}$

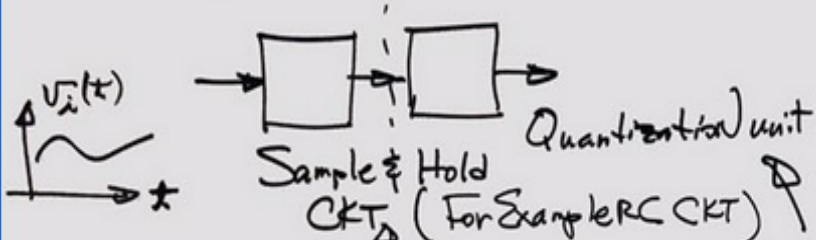
4° For Additional Bits: $2^{10} (\text{LSB}) \rightarrow 1024$

Hence $\frac{3.3V}{2^9} = 6.6 \times 10^{-3}$
 $2^9 (\text{2 bits, LSB}) \rightarrow 512 \rightarrow \text{bit Error}$
 1 Additional

Introduction To DFT For Data Validation

April 16/2018 CMPE42 2/.

ADC Hardware Aspects.



Quantization unit

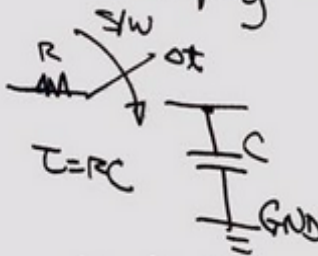
Sample & Hold CKT (For Sample RC CKT)

Nyquist Theory

$f_{\text{Sampling}} \geq 2f_{\text{Max}}$

$\Delta t = \frac{1}{f_{\text{Sampling}}}$

Signal itself



$\tau = RC$

Define D.F.T.

Analog Sensor Output $x(t)$

$x(t)$ (Vol/Current)

$x(n)$

$\Delta t = \frac{1}{f_{\text{Sampling}}}$

$f_{\text{Sampling}} = \frac{1}{\Delta t}$

$X(n) \leftrightarrow X(m)$ D.F.T. Fourier Transform.

Frequency Index: $0, 1, 2, \dots, N-1$

$m=0$. D.C.

$m = \frac{N}{2}-1$ highest Freq. Index

$X(\frac{N}{2}-1)$ highest Freq. Component

N : Total of Pts per period

$X(m) = X(m + k \cdot N)$ $k=1, 2, \dots$

N pts: ONE period.

Signal

Basis function

Compare to Taylor Expansion.

$f(x) = f(x_0) + \frac{f'(x_0)}{1!}(x-x_0) + \frac{f''(x_0)}{2!}(x-x_0)^2 + \dots$

$f(x) = c + a(x-x_0)$

$y = ax + b$

* Let's Consider Data Validation.
(To verify if $f_{\text{Sampling}} \geq 2f_{\text{Max}}$)

$X(m) = \frac{1}{N} \sum_{n=0}^{N-1} X(n) e^{-j2\pi \frac{mn}{N}}$... (I)