

S . HEMANTH ADITHYA VARMA

20BCE7229 VIT-AP

ASSIGNMENT-1 IOT

```
int t= 5;
int e= 18;
//20BCE7229
void setup() {
    // put your setup code here, to run once:
    Serial.begin(115200);
    Serial.println("Hello, ESP32!");
    pinMode(t, OUTPUT); // Sets the trigPin as an Output
    pinMode(e, INPUT);
    pinMode(21,OUTPUT);
}

void loop() {

    // put your main code here, to run repeatedly:
    delay(10); // this speeds up the simulation
    digitalWrite(t,LOW);
    digitalWrite(t,HIGH);
    delayMicroseconds(10);
    digitalWrite(t,LOW);
    float dur = pulseIn(e,HIGH);
    float dis =(dur*0.0343)/2;
    Serial.print("Distance in cm: ");
    Serial.println(dis);
    if(dis<100)
    {
digitalWrite(21,HIGH);
    }
    else{
        digitalWrite(21, LOW);
    }

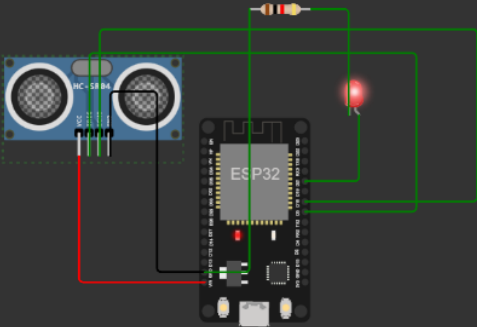
}
```

}

Simulation

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Editing Ultrasonic Distance Sensor
Distance: 93cm



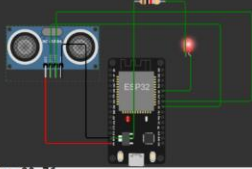
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Distance in cm: 93.76
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Simulation controls: Run, Stop, Pause

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8   pinMode(t, OUTPUT); // Sets the trigPin as an Output
9   pinMode(e, INPUT);
10  pinMode(21, OUTPUT);
11 }
12
13
14 void loop() {
15   // put your main code here, to run repeatedly:
16   delay(10); // this speeds up the simulation
17   digitalWrite(t, LOW);
18   digitalWrite(t, HIGH);
19   delayMicroseconds(10);
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23   Serial.print("Distance in cm: ");
24   Serial.println(dis);
25   if(dis<100)
26   {
27     digitalWrite(21, HIGH);
28   }
29   else{
30     digitalWrite(21, LOW);
31   }
32 }
33
```

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Editing Ultrasonic Distance Sensor
Distance: 93cm



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Simulation controls: Run, Stop, Pause