PSUEDOCODE:

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BEGIN
  INITIALIZE libraries and constants
  SET WiFi credentials
  SET Telegram credentials

  INITIALIZE hardware components
    SET LED pin, buzzer pin, ultrasonic sensor pins, servo pin
    SET LCD display
    SET MPU6050 sensor
    INITIALIZE servo

  SETUP function
    BEGIN serial communication
    INITIALIZE I2C communication for MPU6050
    IF MPU6050 fails to initialize THEN
      PRINT error message
      HALT
    END IF

    INITIALIZE WiFi connection
    WHILE WiFi is not connected
      PRINT dots
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    DELAY
  END WHILE
  PRINT WiFi connected message

  TEST connection to Telegram server
  IF connection to Telegram server fails THEN
    PRINT error message
    RETURN
  ELSE
    PRINT connection successful
  END IF

  TEST sending initial message via Telegram
  IF message sent THEN
    PRINT success message
  ELSE
    PRINT failure message
  END IF
END SETUP

FUNCTION moveToAngle(angle)
  MOVE servo to specified angle
  DELAY
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END FUNCTION

FUNCTION readUltrasonicDistance(triggerPin, echoPin)
  SEND trigger pulse
  READ echo pulse duration
  CALCULATE distance from duration
  RETURN distance
END FUNCTION

LOOP function
  READ acceleration, gyroscope, and temperature data from MPU6050
  MOVE servo to initial position (0 degrees)

  PRINT sensor data to serial monitor

  CALCULATE acceleration magnitude
  PRINT acceleration magnitude

  READ distance from ultrasonic sensor
  PRINT distance to serial monitor
  DISPLAY distance on LCD

  IF distance between 20 and 30 cm THEN
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  DISPLAY "Vehicle Ahead" on LCD
  ACTIVATE buzzer in a pattern
  CLEAR LCD
END IF

IF distance between 10 and 20 cm THEN
  DISPLAY "Alert" and "Applying Brakes" on LCD
  MOVE servo to braking position (180 degrees)
  ACTIVATE buzzer in a pattern
  CLEAR LCD
END IF

IF acceleration magnitude indicates sudden jerk THEN
  IF distance less than 10 cm THEN
    DISPLAY "Accident Alert" and "Sending SOS" on LCD
    MOVE servo to braking position (180 degrees)
    ACTIVATE LED and buzzer for a duration
    SEND accident alert message via Telegram
    IF message sent THEN
      PRINT success message
    ELSE
      PRINT failure message
    END IF
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      END IF
    END IF

    BLINK LED to indicate system is running
  END LOOP
END
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