

# Contents

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- **ADC**
- **DAC**

## INTERFACING TO ADC AND SENSORS

### ADC Devices

- ❑ ADCs (analog-to-digital converters) are among the most widely used devices for data acquisition
  - A physical quantity, like temperature, pressure, humidity, and velocity, etc., is converted to electrical (voltage, current) signals using a device called a *transducer*, or *sensor*
- ❑ We need an analog-to-digital converter to translate the analog signals to digital numbers, so microcontroller can read them

## INTERFACING TO ADC AND SENSORS

### ADC804 Chip

- ❑ ADC804 IC is an analog-to-digital converter
  - It works with +5 volts and has a resolution of 8 bits
  - *Conversion time* is another major factor in judging an ADC
    - Conversion time is defined as the time it takes the ADC to convert the analog input to a digital (binary) number
    - In ADC804 conversion time varies depending on the clocking signals applied to CLK R and CLK IN pins, but it cannot be faster than 110  $\mu$ s

# INTERFACING TO ADC AND SENSORS

## ADC804 Chip (cont')

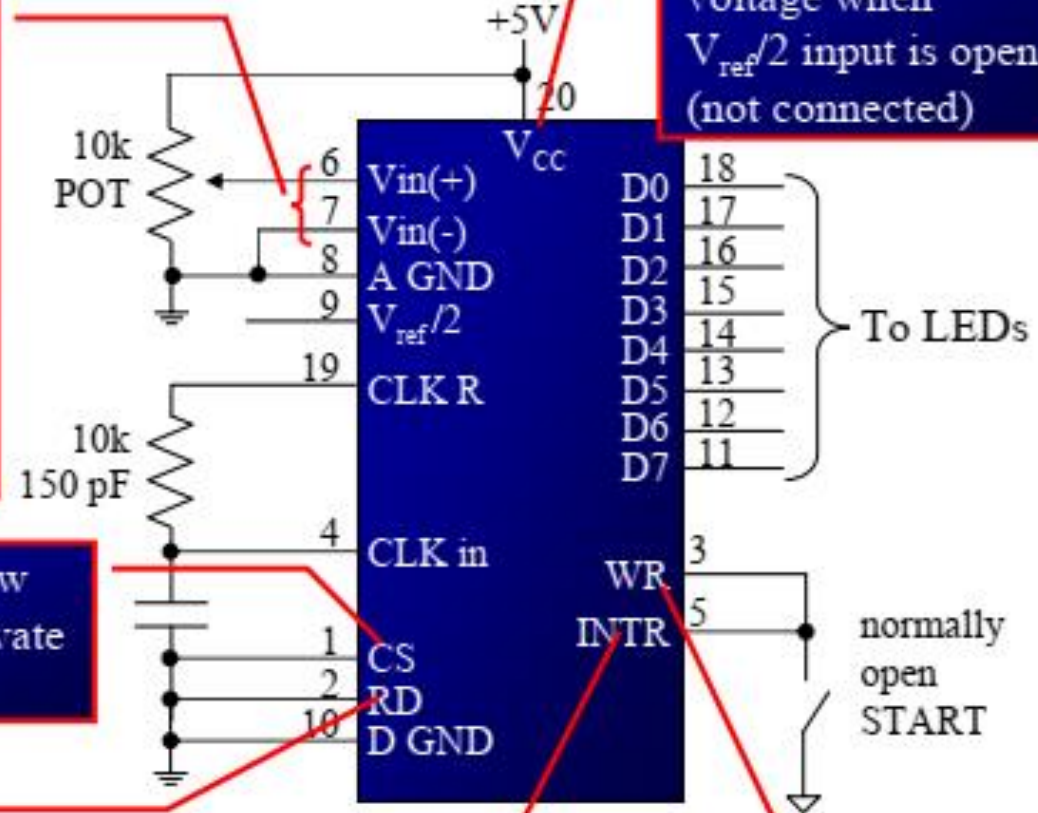
Differential analog inputs where  $V_{in} = V_{in}(+) - V_{in}(-)$   
 $V_{in}(-)$  is connected to ground and  $V_{in}(+)$  is used as the analog input to be converted

CS is an active low input used to activate ADC804

“output enable”  
a high-to-low RD pulse is used to get the 8-bit converted data out of ADC804

“end of conversion”  
When the conversion is finished, it goes low to signal the CPU that the converted data is ready to be picked up

“start conversion”  
When WR makes a low-to-high transition, ADC804 starts converting the analog input value of  $V_{in}$  to an 8-bit digital number



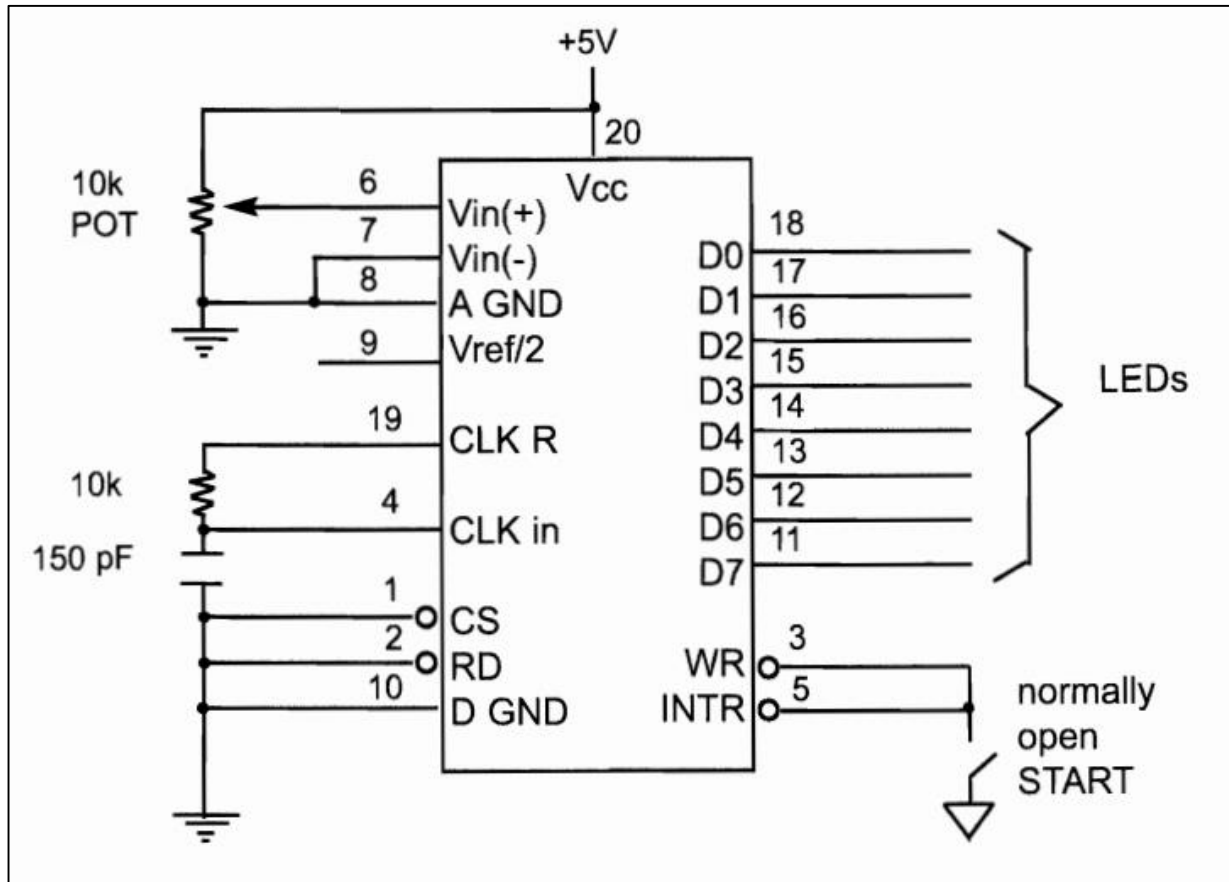
+5V power supply  
or a reference  
voltage when  
 $V_{ref}/2$  input is open  
(not connected)

## □ CLK IN and CLK R

- CLK IN is an input pin connected to an external clock source
- To use the internal clock generator (also called self-clocking), CLK IN and CLK R pins are connected to a capacitor and a resistor, and the clock frequency is determined by

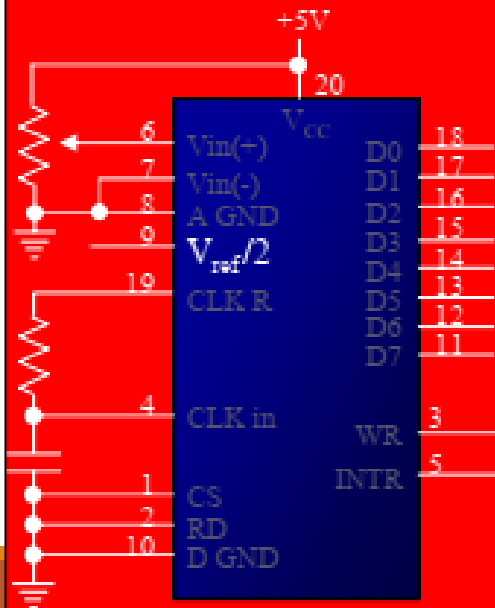
$$f = \frac{1}{1.1RC}$$

- Typical values are  $R = 10K$  ohms and  $C = 150$  pF
- We get  $f = 606$  kHz and the conversion time is  $110 \mu s$



# INTERFACING TO ADC AND SENSORS

## ADC804 Chip (cont')



### □ V<sub>ref</sub>/2

➤ It is used for the reference voltage

- If this pin is open (not connected), the analog input voltage is in the range of 0 to 5 volts (the same as the V<sub>cc</sub> pin)
- If the analog input range needs to be 0 to 4 volts, V<sub>ref</sub>/2 is connected to 2 volts

### V<sub>ref</sub>/2 Relation to V<sub>in</sub> Range

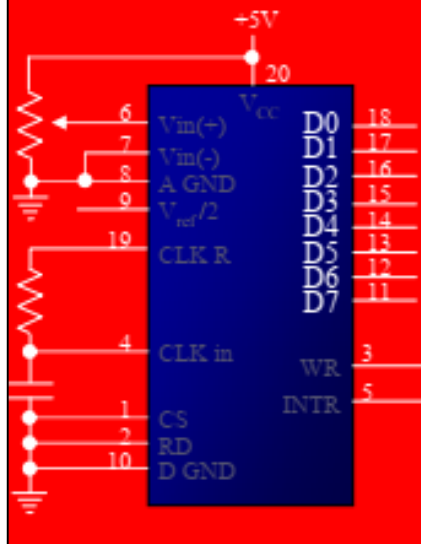
V <sub>ref</sub> /2(v)	V <sub>in</sub> (V)	Step Size ( mV)
Not connected*	0 to 5	5/256=19.53
2.0	0 to 4	4/255=15.62
1.5	0 to 3	3/256=11.71
1.28	0 to 2.56	2.56/256=10
1.0	0 to 2	2/256=7.81
0.5	0 to 1	1/256=3.90

Step size is the smallest change can be discerned by an ADC



## INTERFACING TO ADC AND SENSORS

### ADC804 Chip (cont')



#### □ D0-D7

- The digital data output pins
- These are tri-state buffered
  - The converted data is accessed only when CS = 0 and RD is forced low
- To calculate the output voltage, use the following formula

$$D_{out} = \frac{V_{in}}{step\ size}$$

- $D_{out}$  = digital data output (in decimal),
- $V_{in}$  = analog voltage, and
- $step\ size$  (resolution) is the smallest change

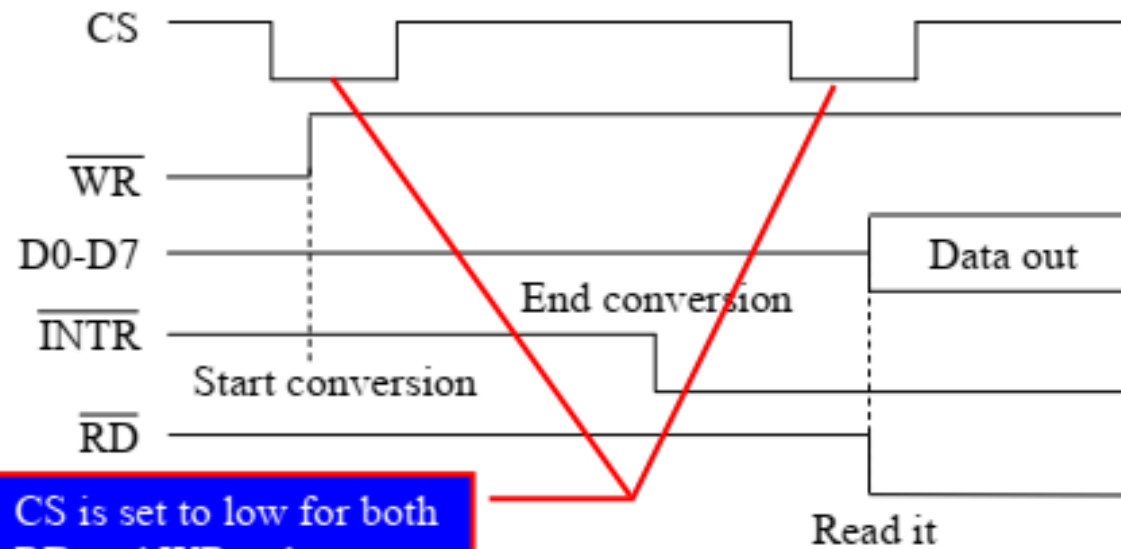
#### □ Analog ground and digital ground

- Analog ground is connected to the ground of the analog  $V_{in}$
- Digital ground is connected to the ground of the  $V_{cc}$  pin

## INTERFACING TO ADC AND SENSORS

### ADC804 Chip (cont')

- ❑ The following steps must be followed for data conversion by the ADC804 chip
  - Make CS = 0 and send a low-to-high pulse to pin WR to start conversion
  - Keep monitoring the INTR pin
    - If INTR is low, the conversion is finished
    - If the INTR is high, keep polling until it goes low
  - After the INTR has become low, we make CS = 0 and send a high-to-low pulse to the RD pin to get the data out of the ADC804



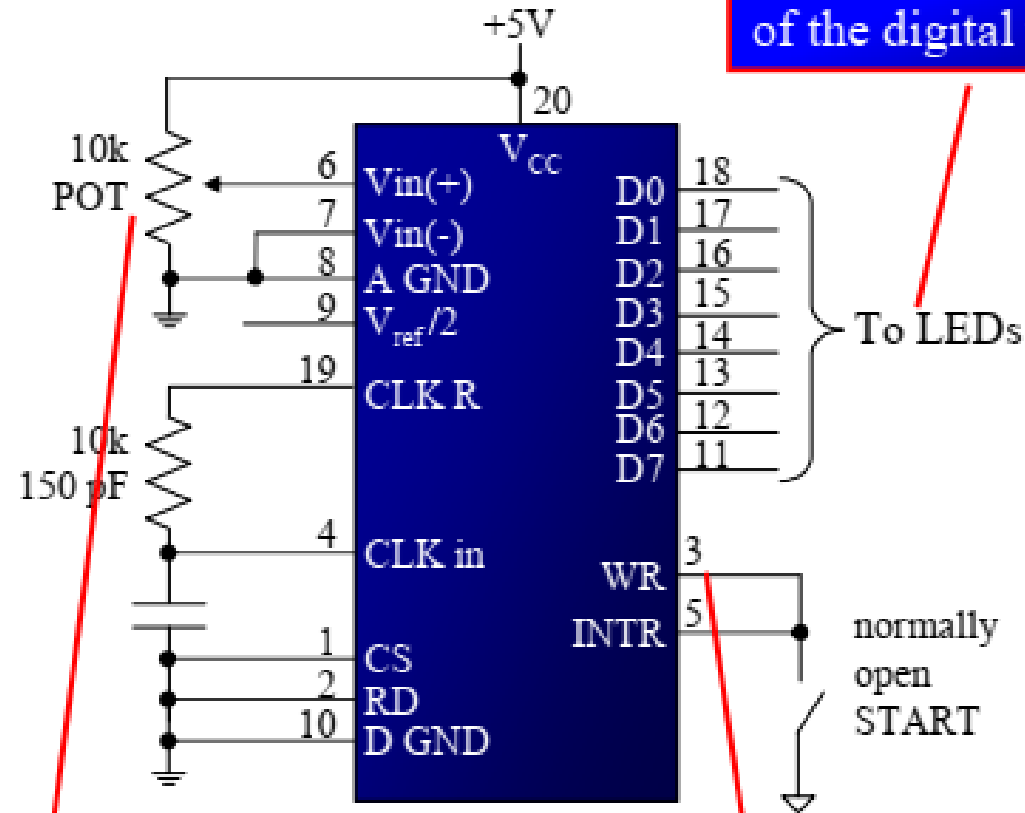
CS is set to low for both  
RD and WR pulses



# INTERFACING TO ADC AND SENSORS

## Testing ADC804

### ADC804 Free Running Test Mode



The binary outputs are monitored on the LED of the digital trainer

a potentiometer used to apply a 0-to-5 V analog voltage to input  $V_{in}(+)$  of the 804 ADC

The CS input is grounded and the WR input is connected to the INTR output

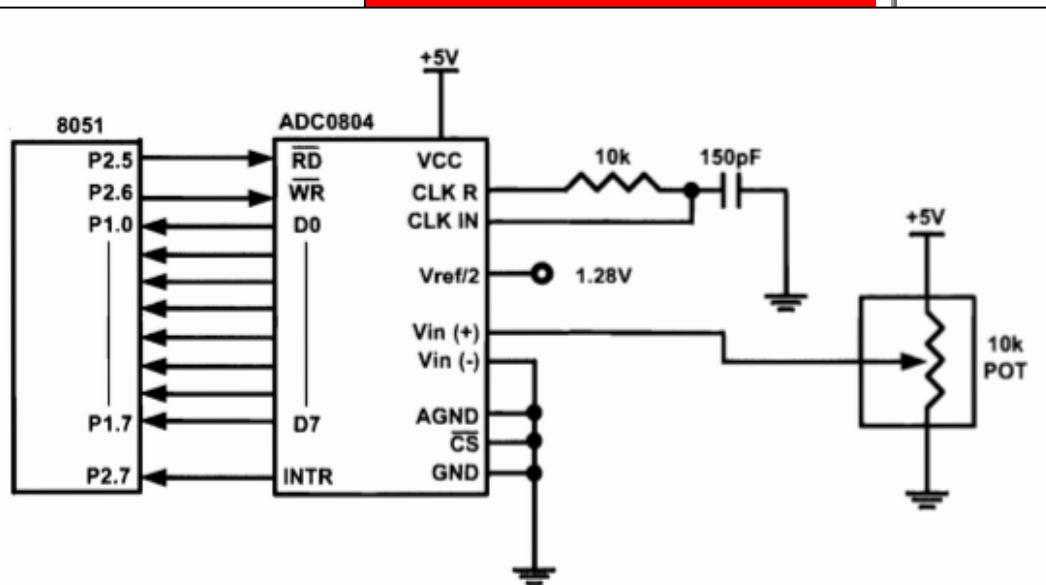
# INTERFACING TO ADC AND SENSORS

## Testing ADC804 (cont')

Examine the ADC804 connection to the 8051 in Figure 12-7. Write a program to monitor the INTR pin and bring an analog input into register A. Then call a hex-to ASCII conversion and data display subroutines. Do this continuously.

```
;p2.6=WR (start conversion needs to L-to-H pulse)
;p2.7 When low, end-of-conversion)
;p2.5=RD (a H-to-L will read the data from ADC chip)
;p1.0 - P1.7= D0 - D7 of the ADC804
;

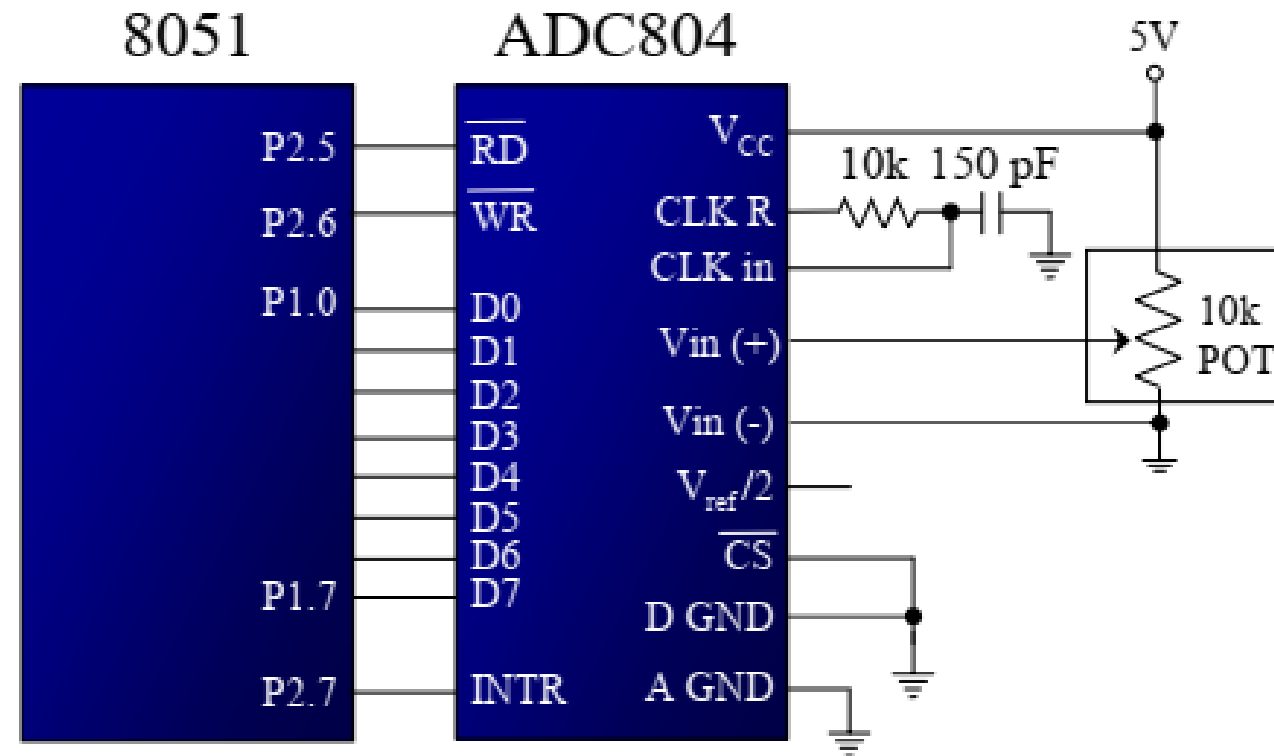
MOV     P1,#0FFH      ;make P1 = input
BACK:   CLR     P2.6    ;WR = 0
        SETB    P2.6    ;WR = 1 L-to-H to start conversion
HERE:   JB      P2.7,HERE ;wait for end of conversion
        CLR     P2.5    ;conversion finished, enable RD
        MOV     A,P1     ;read the data
        ACALL   CONVERSION ;hex-to-ASCII conversion
        ACALL   DATA_DISPLAY;display the data
        SETB    p2.5     ;make RD=1 for next round
        SJMP    BACK
```



# INTERFACING TO ADC AND SENSORS

## Testing ADC804 (cont')

### 8051 Connection to ADC804 with Self-Clocking



# ADC804 Clock from 8051 XTAL2

The frequency of crystal is too high, we use two D flip-flops to divide the frequency by 4

## INTERFACING TO ADC AND SENSORS

### Interfacing Temperature Sensor

- ❑ A *thermistor* responds to temperature change by changing resistance, but its response is not linear
- ❑ The complexity associated with writing software for such nonlinear devices has led many manufacturers to market the linear temperature sensor

Temperature (C)	Tf (K ohms)
0	29.490
25	10.000
50	3.893
75	1.700
100	0.817

From William Kleitz, digital Electronics

## INTERFACING TO ADC AND SENSORS

### LM34 and LM35 Temperature Sensors

- ❑ The sensors of the LM34/LM35 series are precision integrated-circuit temperature sensors whose output voltage is linearly proportional to the Fahrenheit/Celsius temperature
  - The LM34/LM35 requires no external calibration since it is inherently calibrated
  - It outputs 10 mV for each degree of Fahrenheit/Celsius temperature



## INTERFACING TO ADC AND SENSORS

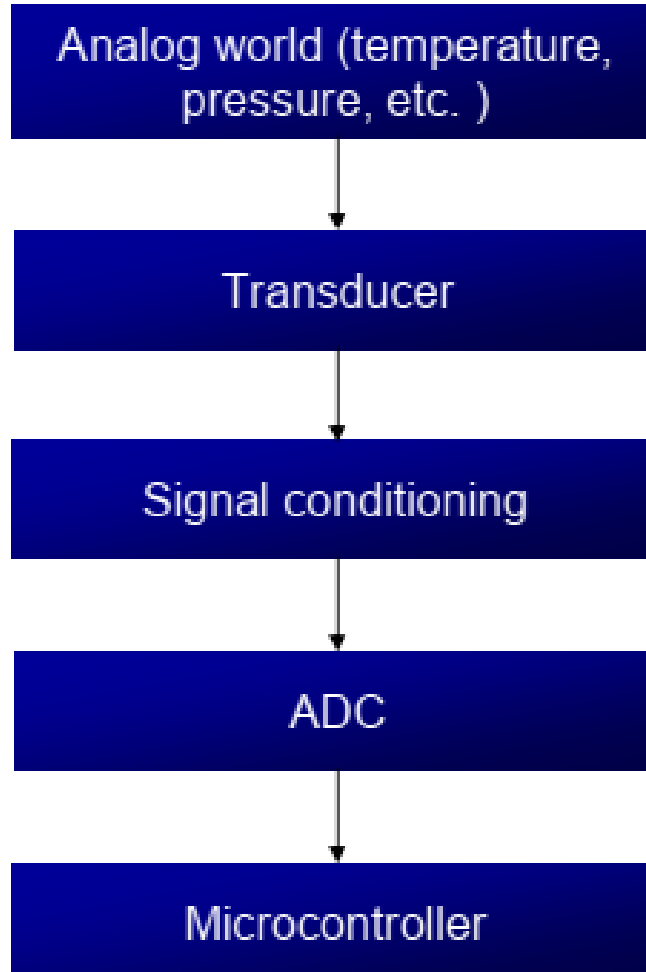
### Signal Conditioning and Interfacing LM35

- ❑ *Signal conditioning* is a widely used term in the world of data acquisition
  - It is the conversion of the signals (voltage, current, charge, capacitance, and resistance) produced by transducers to voltage, which is sent to the input of an A-to-D converter
- ❑ Signal conditioning can be a current-to-voltage conversion or a signal amplification
  - The thermistor changes resistance with temperature, while the change of resistance must be translated into voltage in order to be of any use to an ADC

# INTERFACING TO ADC AND SENSORS

Signal  
Conditioning  
and  
Interfacing  
LM35  
(cont')

## Getting Data From the Analog World



## INTERFACING TO ADC AND SENSORS

### Signal Conditioning and Interfacing LM35 (cont')

#### Example:

Look at the case of connecting an LM35 to an ADC804. Since the ADC804 has 8-bit resolution with a maximum of 256 steps and the LM35 (or LM34) produces 10 mV for every degree of temperature change, we can condition  $V_{in}$  of the ADC804 to produce a  $V_{out}$  of 2560 mV full-scale output. Therefore, in order to produce the full-scale  $V_{out}$  of 2.56 V for the ADC804, We need to set  $V_{ref}/2 = 1.28$ . This makes  $V_{out}$  of the ADC804 correspond directly to the temperature as monitored by the LM35.

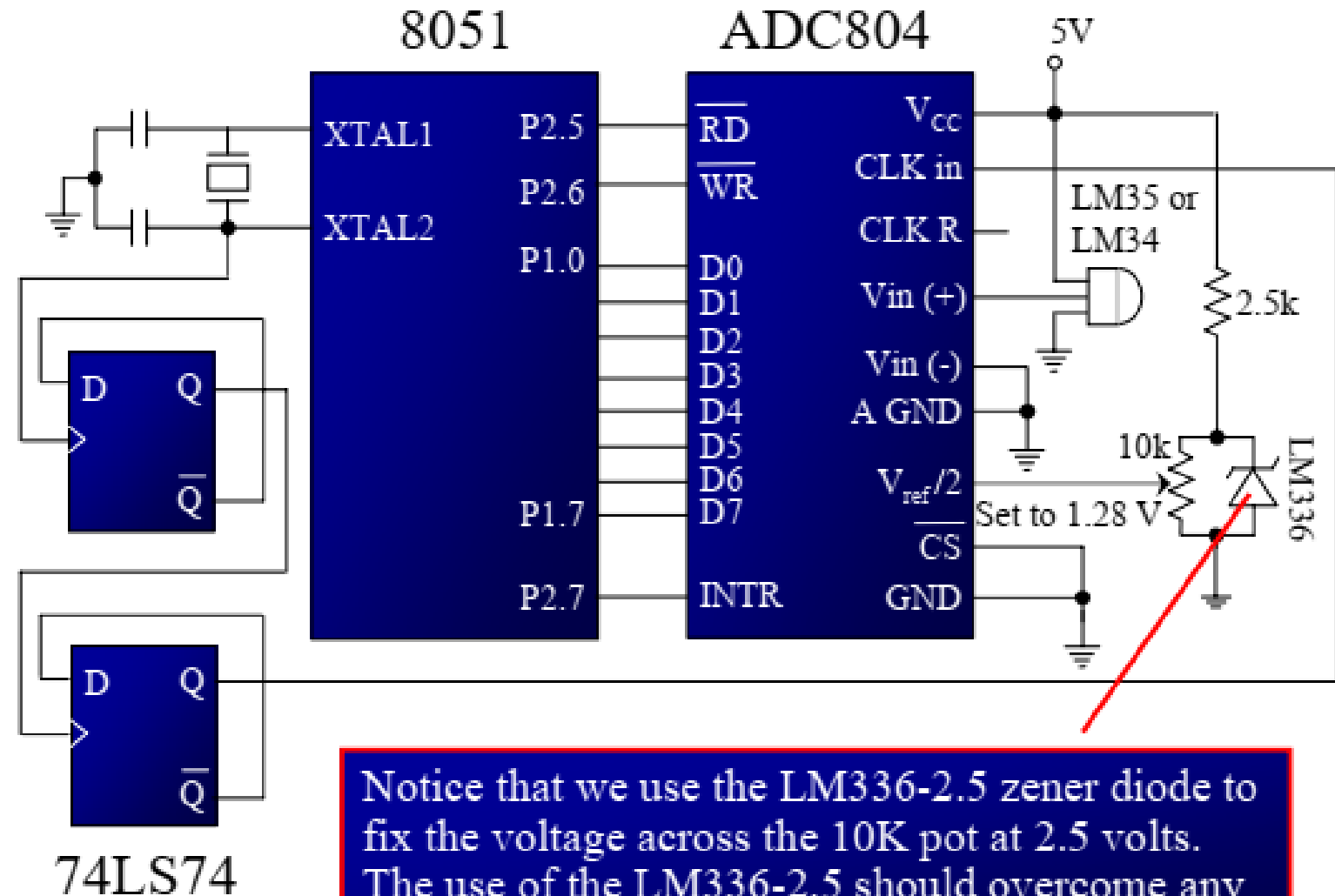
#### Temperature vs. $V_{out}$ of the ADC804

Temp. (C)	$V_{in}$ (mV)	$V_{out}$ (D7 – D0)
0	0	0000 0000
1	10	0000 0001
2	20	0000 0010
3	30	0000 0011
10	100	0000 1010
30	300	0001 1110

# INTERFACING TO ADC AND SENSORS

Signal  
Conditioning  
and  
Interfacing  
LM35  
(cont')

## 8051 Connection to ADC804 and Temperature Sensor



Notice that we use the LM336-2.5 zener diode to fix the voltage across the 10K pot at 2.5 volts. The use of the LM336-2.5 should overcome any fluctuations in the power supply

### Example 13-1

For a given ADC0848, we have  $V_{\text{ref}} = 2.56 \text{ V}$ . Calculate the D0 - D7 output if the analog input is: (a) 1.7 V, and (b) 2.1 V.

**Solution:**

Since the step size is  $2.56/256 = 10 \text{ mV}$ , we have the following.

(a)  $D_{\text{out}} = 1.7 \text{ V}/10 \text{ mV} = 170$  in decimal, which gives us 10101011 in binary for D7 - D0.

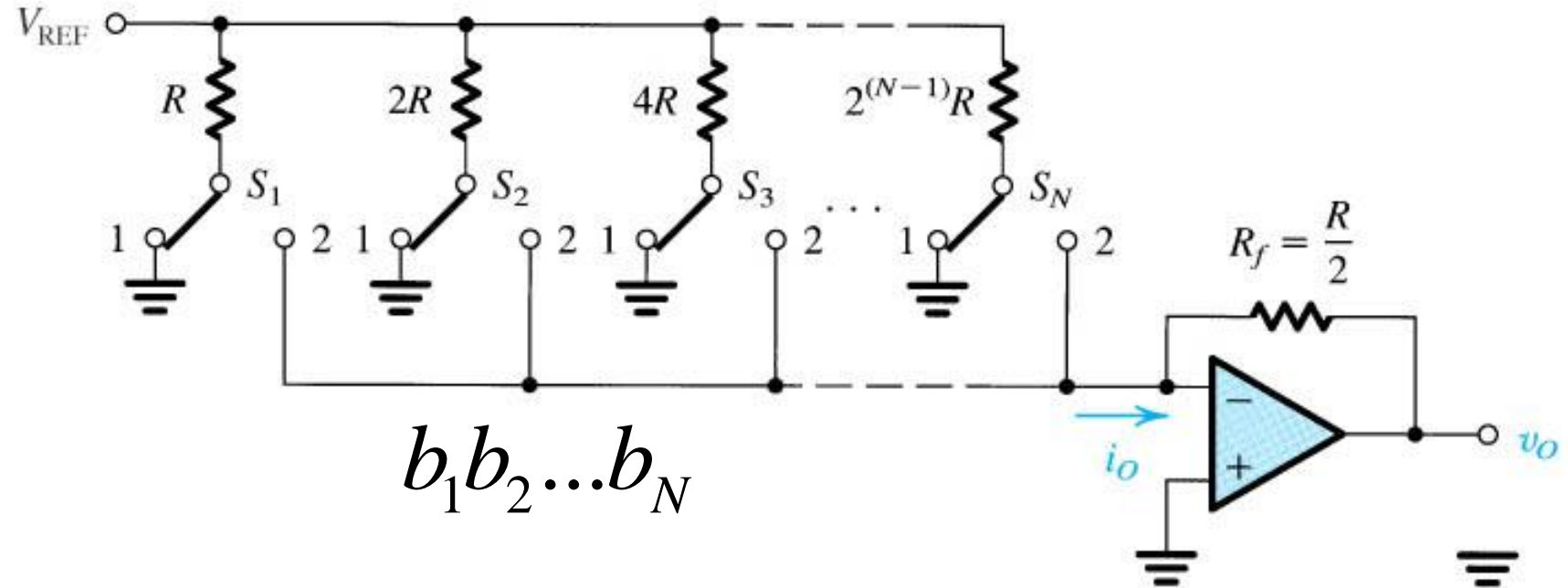
(b)  $D_{\text{out}} = 2.1 \text{ V}/10 \text{ mV} = 210$  in decimal, which gives us 11010010 in binary for D7 - D0.

# DAC Interfacing



# D/A Converter Circuits

- Binary-weighted registers



$$i_o = \frac{V_{\text{REF}}}{R} b_1 + \frac{V_{\text{REF}}}{2R} b_2 + \dots + \frac{V_{\text{REF}}}{2^{N-1}R} b_N$$

$$v_o = -i_o R_f$$

$$I_{out} = I_{ref} \left( \frac{D7}{2} + \frac{D6}{4} + \frac{D5}{8} + \frac{D4}{16} + \frac{D3}{32} + \frac{D2}{64} + \frac{D1}{128} + \frac{D0}{256} \right)$$

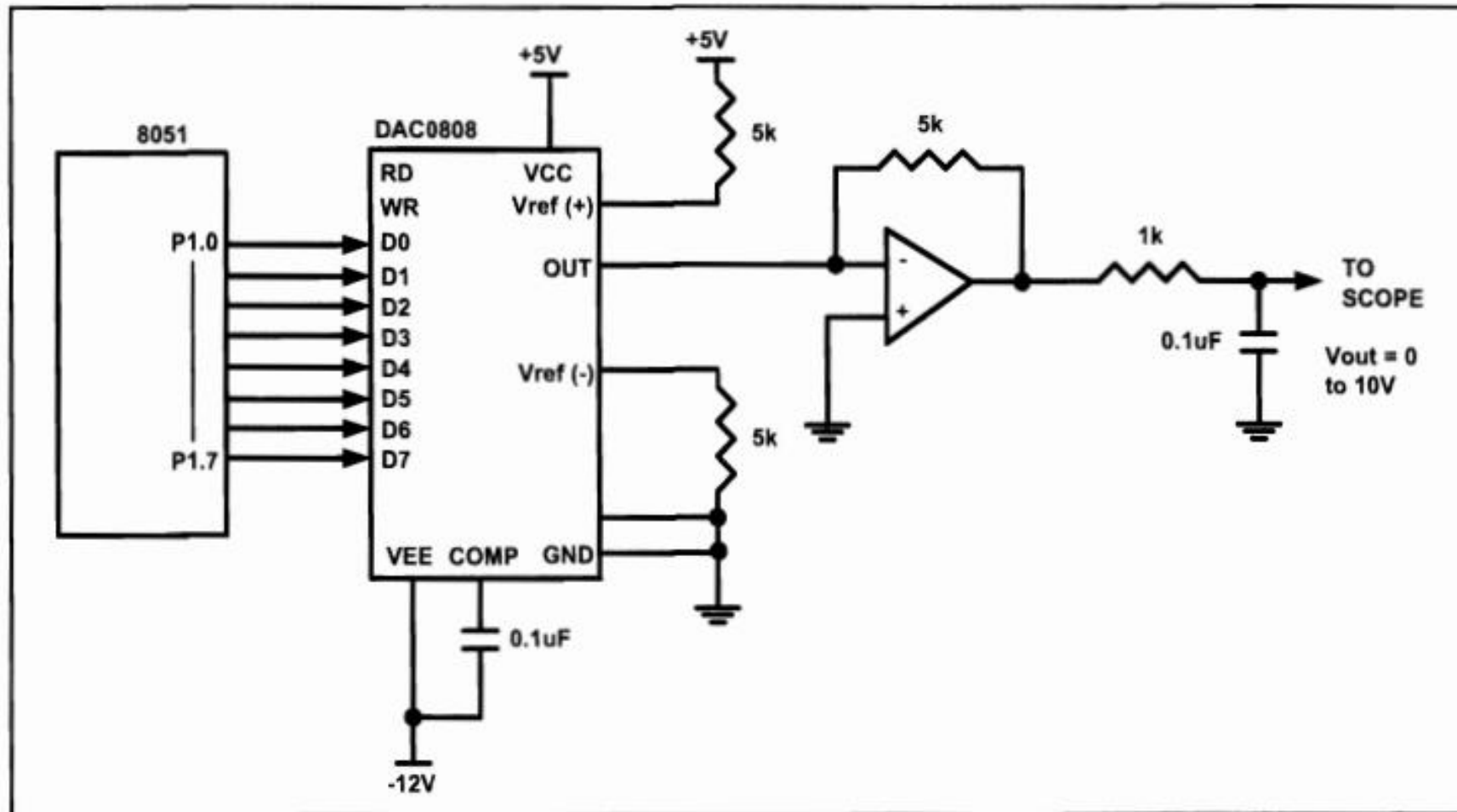


Figure 13-18. 8051 Connection to DAC808

## Example:

In order to generate a stair-step ramp, set up the circuit in Figure 13-18 and connect the output to an oscilloscope. Then write a program to send data to the DAC to generate a stair-step ramp.

## Solution:

```
                CLR      A
AGAIN:          MOV      P1,A      ;send data to DAC
                INC      A        ;count from 0 to FFH
                ACALL    DELAY     ;let DAC recover
                SJMP     AGAIN
```

**Table: Angle vs. Voltage Magnitude for Sine Wave**

Angle $\theta$ (degrees)	Sin $\theta$	$V_{out}$ (Voltage Magnitude) $5\text{ V} + (5\text{ V} \times \sin \theta)$	Values Sent to DAC (decimal) (Voltage Mag. $\times 25.6$ )
0	0	5	128
30	0.5	7.5	192
60	0.866	9.33	238
90	1.0	10	255
120	0.866	9.33	238
150	0.5	7.5	192
180	0	5	128
210	-0.5	2.5	64
240	-0.866	0.669	17
270	-1.0	0	0
300	-0.866	0.669	17
330	-0.5	2.5	64
360	0	5	128

### Example 13-5

Verify the values given for the following angles: (a)  $30^\circ$  (b)  $60^\circ$ .

**Solution:**

$$(a) V_{\text{out}} = 5 \text{ V} + (5 \text{ V} \times \sin q) = 5 \text{ V} + 5 \times \sin 30^\circ = 5 \text{ V} + 5 \times 0.5 = 7.5 \text{ V}$$

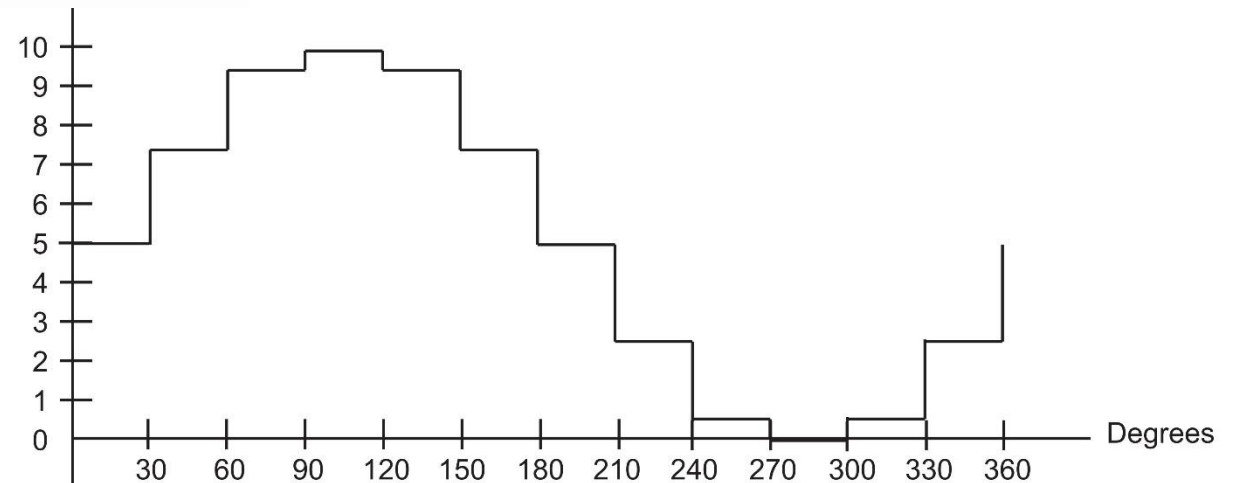
$$\text{DAC input values} = 7.5 \text{ V} \times 25.6 = 192 \text{ (decimal)}$$

$$(b) V_{\text{out}} = 5 \text{ V} + (5 \text{ V} \times \sin q) = 5 \text{ V} + 5 \times \sin 60^\circ = 5 \text{ V} + 5 \times 0.866 = 9.33 \text{ V}$$

$$\text{DAC input values} = 9.33 \text{ V} \times 25.6 = 238 \text{ (decimal)}$$

## Figure: Angle vs. Voltage Magnitude for Sine Wave

```
AGAIN:    MOV DPTR,#TABLE
          MOV R2,#COUNT
BACK:     CLR A
          MOVC A,@A+DPTR
          MOV P1,A
          INC DPTR
          DJNZ R2,BACK
          SJMP AGAIN
          ORG 300
TABLE:    DB 128,192,238,255,238,192 ;see Table 13-7
          DB 128,64,17,0,17,64,128
```





**Thank You**