



AUTOMATIC GAME SCRIPT GENERATION

By

Ahmed Abdel Samea Hassan Khalifa

A Thesis Submitted to the
Faculty of Engineering at Cairo University
in Partial Fulfillment of the
Requirements for the Degree of
MASTER OF SCIENCE
in
Computer Engineering

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GIZA, EGYPT
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Summary:

Summary

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Starting from the acknowledgements page, pages are numbered using the Roman numerals i, ii, iii etc. Starting from Chapter 1, pages must be numbered using Arabic numerals. Page numbers are at the bottom of the page, preferably centered.

Abstract

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Chapter 1: Introduction

Video Games were originally created by small groups of people in their spare time. As time passes Video Games evolved to be a huge multi-billion industry where thousands of people are working everyday to create new games. Automation doesn't play huge role in creating games so most of the work is done by humans. Hiring humans ensures producing of original high quality games but it costs a lot of money and time.

1.1 Motivation

During the early days of Video Games, games were created by a couple of people in their spare time. Most of the time was spent in programming the game, while a small portion was dedicated for graphics, sounds, and music because of the technical limitations of the devices at that time. As these limitation are no more, producing a game takes more time than before. Most of that time is spent on creating content for the game (graphics, music, sounds, levels, and ...etc)[66]; for example creating graphics for a huge main stream game may take hundreds of artist working for a year or two. That is why the production cost of a huge game may reach millions of dollars[24].

That huge production cost caused lots of Game Studios to shut their doors [16] and others became afraid of creating new game ideas. In spite of all these technological advancement, we could not reduce the cost and time for creating good game contents because creation process heavily depends on the creative aspect of the human designer. Automating this creative process is somehow difficult as there is no concrete criteria for judging creativity which raises the main question: Can technology help to reduce the time and money used in producing games?

1.2 Problem Statement

Creating content for games or any creative medium, e.g. Art, Music, Movies, and ...etc, is really a tough problem and take very long time. For example a famous popular game called *Threes* took around 14 month working on the concept itself [60]. Game market is growing fierce as there is always a demand for new games with new contents but that can not be accomplished very fast because creating new innovative games requires long time.

Games consists of lots of aspects ranging from game graphics to game rules. It is hard to generate all these aspects at the same time, so we are going to address just two of them which are Levels and Rules. Level Generation has been in industry for decades since early days of games [1] but it has always used lots of hacks and it has never been generalized. Same applies to Rule Generation except that their is a very small contribution in automatically generating rules.

Complete automation of levels and rules for all types of games seems beyond the reach at the present time, so In this work we focus on automatic generation of Puzzle Games because they are accessible by all players, they do not require much time to be played,

and do not have any boundaries on their ideas. From there, we found an urgent need to research for new ways in Level and Rule Generation for Puzzle Games.

1.3 Objectives

The aim of this work is to try to understand how our brain works in creating creative content, helping game designers and developers to think outside the box, and minimizing their time for searching for new content by providing them with good diverse seeds for levels and rules. It is not intended to create an Artificial Intelligence that can create the whole game from scratch and sell it afterwards because its too early to think that computers can do that on its own and people are not prepared yet to deal with that kind of Intelligence that can replace them at work.

1.4 Organization of the thesis

The remainder of this thesis is organized as follows. In Chapter 2, we explain further the background needed to understand Procedural Content Generation in Video Games, conducted by Chapter 3 explaining any previous work done in that area. In Chapter 4, we show different methodologies and techniques we are using to reach our objectives followed by our results from applying these techniques in Chapter 5. Finally, Chapter 6 presents our conclusion and future work.

Chapter 2: Background

This chapter presents required background information needed to understand this thesis. It starts with explaining Puzzle Genre in Video Games, followed by description of Procedural Content Generation and a special case called Search Based PCG. It is conducted by describing Video Game Description Language and why it is important. Finally, it explains General Video Game Playing and its relation to this research.

2.1 Puzzle Genre in Video Games

In 1950 a small group of academic people started developing Video Games on the main frames of their schools. This has continued to till the 1970s when Video Games reached Main Stream industry. In 1980s lots of technicals problems were solved which brought new types of Video Games. Game Genres were invented to differentiate between different game types so players can refer to their favorite games by genres, for example there is Adventure genre like Legend of Zelda, Fighting genre like Street Fighter, Platformer genre like Super Mario Bros, Shooter genre like Space Invaders, Puzzle Genre like Bomberman and ...etc. In 2000s people started to go toward being mobile and making games for cellular phones and one of the most important genres on these mobile devices is Puzzle Genre[23].

Puzzle Genre is a style of Video Games that emphasize solving puzzles, it always focuses on logical or conceptual challenges. Puzzle games can be described using the following aspects:

- **Graphics:** How the game looks like.
- **Inputs:** How input is given to the game.
- **Rules:** How the game behaves to events.
- **Levels:** How objects are placed.
- **Win Condition:** How to end the game.

2.2 Procedural Content Generation

Procedural Content Generation (PCG) means generating game content using a computer. It was first developed due to technical limitations (small disk space) and the need to provide a huge amount of content. *Akalabeth* was the first game using PCG, the game starts asking the player to provide it with a lucky number that is used as a seed to a random number generator which generates everything in the game from the player statistics to dungeon maps. Due to that the game has a very small footprint around 22 Kb so it does not need to be loaded from lots of disks [1]. Although technical difficulties become history and storage is no longer a problem, PCG is still one of the hot topics in Video Games Industry and Research. PCG helps us reduce development time and cost, be creative, and understand the process of creating game content. PCG can be used to generate different game aspects for example Textures, Sounds, Music, Levels, Rules, and ...etc. In this thesis we will focus only on the Levels and Rules Generation which is the core aspect for any Puzzle Game.

2.2.1 Level Generation

Levels are different combination of game objects. These combinations control the game flow and difficulty. For example in Super Mario, as the game advances the levels become longer and include more enemies and gaps. Level Generation has been in industry since dawn of games in order to decrease the game size, but it is now used to introduce huge amount of levels that humans can not generate manually in reasonable time. Level Generation has always been done for a specific game using lots of hacks to improve the output result. These hacks cause the output levels to follow certain guidelines which may cause elimination of huge amounts of possible levels but on the other hand these guidelines ensure that the output levels are all playable (can reach goal of the game) and satisfactory by all players [19].

2.2.2 Rule Generation

Rules are what governs game behavior. Based on them you can know how the game will be played; for example what to collect, what to avoid, how to kill enemies ...etc. Rules are very different from one game genre to another, for example in Board Games (e.g. Monopoly) all rules are applied after player plays his turn, while in Platformer Games (e.g. Super Mario) the rules are applied with every time step (not depending on the player movement). Due to that huge difference between rules in different genres, Rule Generation is one of the most difficult contents to generate. That is why we need to find a way to represent and describe rules. The only way to represent all different genres is using Coding Languages because Coding is the only common thing between all games. Generating new Rules using Coding Languages may take years because Coding Languages are used to create any computer related software such as plug-ins, programs, viruses, games and ...etc. Still some researchers managed to use it but it will need more guidance due to the huge search space of Coding Languages [9]. A better solution is to use a description language for the rules that is more specific for a certain genre which we are going to discuss in Section 2.4 [62].

2.3 Search Based PCG

There are many approaches to generate content in Video Games. The search based approach is one famous technique that has been used a lot in recent research. The search based approach can be divided into three main parts Search Algorithm, Content Representation, and Evaluation Function [63].

2.3.1 Search Algorithm

This is the *Engine* for generating game content. There are different searching algorithm for example Simulated Annealing, Hill Climbing, and Genetic Algorithm (GA) . GA is a search algorithm based on Darwin Theory "*Survival for the Fittest*". GA uses techniques inspired from natural evolution such as selection, crossover and mutation in order to find solution to large space optimization problems [20].

2.3.2 Content Representation

There are several ways for modeling different aspect of the game content during the generation process. The way of representing the content can affects a lot on the output of the generation. For example levels may be represented as:[63]

- 2D matrix where each value represent a tile location in the level.
- Sequence of position of objects in level.
- Sequence of level Patterns.
- Level properties such as Number of Objects in map, Number of Players and ...etc.
- Random number seed.

2.3.3 Evaluation Function

Without Evaluation Function the Search Algorithm will be blind. The evaluation function leads the Search Algorithm to find better content in the solution space. The evaluation Function can be either one of the following:[63]

- **Direct evaluation function:** which utilizes some understanding about the generated content and evaluates it accordingly.
- **Simulation-based evaluation function:** Use Artificial Intelligence agent to test the generated content and based on his behavior it estimates its quality.
- **Interactive evaluation function:** Evaluate generated content based on the interaction with human.

2.4 Puzzle Script as Video Game Description Language

Referring to Section 2.2.2 we can not generate game rules without having a methodology to describe it. Video Game Description Language (VGDL) was originally invented to help on the work for General Video Game Playing (discussed later in Section 2.5) at Stanford University which will be discussed in the following section. The idea behind VGDL was to provide a simple description language that can be used to describe simple 2D games. Researchers insist that any VGDL language must have the following aspects:[15]

- **Human Readable:** It must be easy for human user to understand games written with it and formulate new one.
- **Unambiguous and Easy to parse:** It must be easy to parse using a computer that is why it must be clear.
- **Searchable:** The games formulated using it can be drawn in form of tree so its easy to use Search Algorithm (discussed in Section 2.3.1) to find new games.
- **Expressive:** It can be used to express more than one game.
- **Extensible:** It can be extended to add more game types and dynamics.
- **Viable for Random Generation:** Each component of the language have 'sensible defaults' so its easier to search for new values for certain components without worrying about other ones.

Puzzle Script (PS) is a VGDL created by Stephan Lavelle to help game designers and developers to create puzzle games [38]. Games generated by PS are time stepped games

similar to Sokoban game; Sokoban is an old Japanese puzzle game where your goal is to push some crates towards certain locations[51]. PS file starts with some meta data like game name, author name, and website then it is divided into 7 sections objects, legend, sounds, collision layers, rules, win conditions, and levels. Figure 2.2 shows an example of the PS file for Sokoban game. It is refereed to it in the next sections.

2.4.1 Objects

It is the first section of the PS file and it contains a list for all the object names and colors being used in the game for example in Figure 2.2 we had Background, Target, Wall, Player, and Crate associated with a color.

2.4.2 Legend

It is a table of one letter abbreviation and one or more group of objects for example in Figure 2.2 the Wall is assigned "#" symbol and Crate and Target together are assigned "@" symbol.

2.4.3 Sounds

It consists of group of game events associated with a certain number. PS engine use these numbers as parameter to BFXR to generate sounds in runtime[5] for example in Figure 2.2 Move event for Crate object is assigned to value 36772507.

2.4.4 Collision Layers

It defines which objects can not exists at same location during running the game, Objects on the same line can not exist together. Each line is considered a new layer, for example in Figure 2.2 Player, Crate, and Wall can not exists at same location as they are assigned to the same layer.

2.4.5 Rules

Its a set of production rules that govern how the game will be played. Production rules have the following formate

$$\text{Tuple} \dots \text{Tuple} \rightarrow \text{Tuple} \dots \text{Tuple}$$

where the number of tuples on the right must be equal to number of tuples on the left, and each tuple must be in the following format

$$[\text{Objects} \mid \dots \mid \text{Objects}]$$

Each tuple has a group of Objects separated by "|" symbol which means that these objects are beside each other for example [Player | Crate] means there is a Player and Crate object beside each other. The number of "|" in both left and right side of each tuple must be equal. Objects must be written in the following format

$$\text{Direction Object} \dots \text{Direction Object}$$

Object must be selected from the Objects section and must be from different collision layer for example [Player Target] means Player and Target exists on same tile. Last thing is the Direction, it must be one of the following ">", "<", "^", and "v". The first one means in same as the moving direction, the second one means opposite to moving direction, while the third means 90° from the moving direction, and the final one is -90° from the moving direction. Let's take a real example on the rule, for example in Figure 2.2 the rule is

[> Player | Crate] -> [> Player | > Crate]

means if there is a Player and Crate beside each other, and the Player moves towards the Crate, then both the Player and the Crate will move in the same direction.

2.4.6 Win Conditions

It identifies when the level should end. It consists of 2 objects separated by on keyword. For example in Figure 2.2 "all Target on Crate" means that the level ends when all Targets are on same location with Crates. The possible keywords that can be used are "all", "some", and "no". "all" means every single object must be at same location, while "some" means at least one object at same location, but "no" means that the two objects must not be at same location.

2.4.7 Levels

They are 2D matrices showing the current configuration for each game level using the abbreviations found in the Legends section. Each level is separated from the next level by a new line. In Figure 2.2 you can see 3 designed Sokoban levels. By replacing each symbol by the corresponding object from the Legend section then the color from Objects section, so you will get the following levels in Figure 2.1.

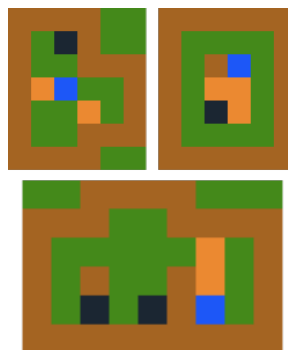


Figure 2.1: Puzzle Script Levels

```

1 title My Game
2 author Stephen Lavelle
3 homepage www.puzzlescript.net
4
5 =====
6 OBJECTS
7 =====
8
9 Background
10 GREEN
11
12 Target
13 DarkBlue
14
15 Wall
16 BROWN
17
18 Player
19 Blue
20
21 Crate
22 Orange
23
24 =====
25 LEGEND
26 =====
27
28 . = Background
29 # = Wall
30 P = Player
31 * = Crate
32 @ = Crate and Target
33 O = Target
34
35 =====
36 SOUNDS
37 =====
38
39 Crate MOVE 36772507
40 endlevel 83744503
41 startgame 92244503
42
43 =====
44 COLLISIONLAYERS
45 =====
46
47 Background
48 Target
49 Player, Wall, Crate
50
51 =====
52 RULES
53 =====
54
55 [ > Player | Crate ] -> [ > Player | > Crate ]
56
57 =====
58
59 WINCONDITIONS
60 =====
61
62 All Target on Crate
63
64 =====
65
66 LEVELS
67 =====
68
69 #####
70 #.O#..
71 #..###
72 #@P..#
73 #..*..#
74 #...###
75 #####
76
77 #####
78 #...#
79 #.#P.#
80 #.*@.#
81 #.O@.#
82 #...#
83 #####
84
85 ..####...
86 ###.####
87 #.....*..#
88 #.#..*..#
89 #.O.O#P.#
90 #####
91
92

```

Figure 2.2: Puzzle Script File

2.5 General Video Game Playing

General Video Game Playing (GVGP) is an area in Artificial Intelligence (AI) where people try to develop an intelligent agent that is able to play more than one game. Most of Game Playing Agents are not general players, they are designed for a certain game like Chess, Poker, Backgammon, or ...etc. At the beginning the AI is supported with game rules in form of VGDL Section 2.4 with current game state and possible actions and the agent should choose the next action. After several play-outs the agent should learn how to maximize his score or reach goal and avoid death. Researchers used different methods to try to create general AI using Monte Carlo Tree Search, Neural Networks, and Reinforcement Learning methods. GVGP is very important for PCG specially for rule and level creation because in order to generate good random level or rule, it is better to test it out using a GVGP Agent to have a better judgment on how the random content will be played.[27]

Chapter 3: Literature Review

This chapter will provide a review of the past work on Procedural Content Generation. It will highlight different efforts towards generating levels and rules for games.

3.1 Level Generation

This section will present some of the work related to Level Generation. Most of the previous work did not talk a lot about generating levels for Puzzle Games. It focused more on Platformer and Arcade Games. The work found about Puzzle Games was limited toward specific games such as Sokoban[57, 31], Cut The Rope[46], and Fruit Dating[37]. Even the generic work on Puzzle Games needs prior human understanding of the game rules[43, 42].

Generating levels for Puzzle Games seems interesting but it has lots of problems. Some of these problems are the main reason for not having enough previous work.

- All levels must be solvable (have at least one solution).
- Most of the level objects should be used (adding unused items may be considered as a bad level design).
- Puzzle Games ideas have no restriction. For example some games have continuous space where game actions depend on player's skills and perfect timing (Angry Birds[2], Cut the Rope[10], and Where's my Water?[67]) while other games have discrete space where game actions depend on the best sequence of actions regardless of the time taken (Fruit Dating[18], Sokoban[51], and HueBrix[25]).

3.1.1 Puzzle Level Generation

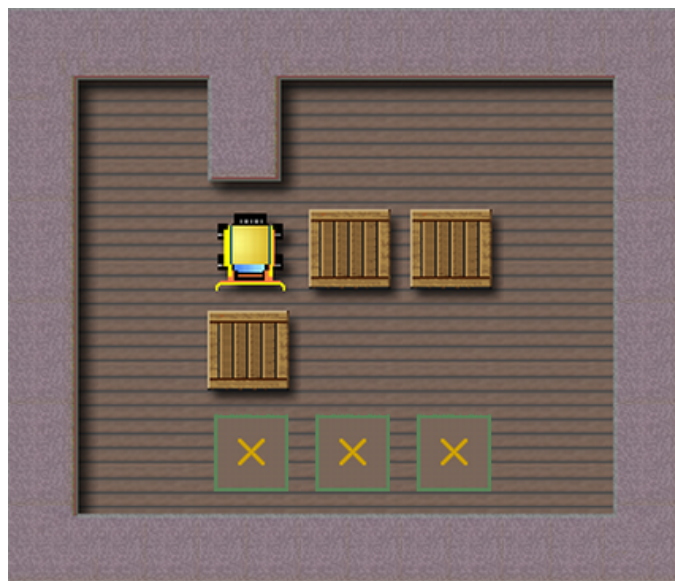


Figure 3.1: Screenshot from Sokoban

As there is nothing before like this work, this section will show all previous work that can be slightly related to our problem. One of the earliest research in Puzzle Games was

by Murase et al.[31]. Murase et al. work focused on generating well designed solvable levels for Sokoban[51]. Sokoban is an old Japanese puzzle game where your goal is to push some crates towards certain locations as shown in Figure 3.1. Their work consists of 3 stages:

- **Generate:** Responsible for generating Level Layouts. Level Layouts is generated by placing predefined templates at random positions. Goal locations and crates are placed afterwards at random positions such that each goal location is reachable from the player location and each crate is reachable from a unique goal location.
- **Check:** Responsible for checking for playability. The system uses Breadth First Search (BFS) to check for solution. All unsolvable levels are removed in this step.
- **Evaluate:** Responsible for selecting best generated levels. The system removes all levels that have a solution that is very short, contains less than four direction changes, or does not contain any detours.

Results show that for every 500 generated levels only 14 are considered as good levels. These good levels are characterized by having a short solution sequence due to the usage of BFS.

Taylor and Parberry[57] followed Yoshio Murase et al.[31] work to improve generated level quality. Their system consists of 4 stages:

- **Generating empty room:** Responsible in generating Level Layouts like Yoshio Murase et al.[31] work. After generating the layouts, the system discards any level that is not completely connected, has huge empty space, or has number of empty floors less than the planned number of boxes and goals.
- **Placing goals:** Responsible for finding best suitable goal locations. The system use a brute force algorithm to try every possible combination for goal locations.
- **Finding the farthest state:** Responsible for placing crates at farthest location from its goal location. This process is done using a similar algorithm to BFS. The algorithm expands all the reachable locations from a goal location and returns the farthest location. The farthest location is calculated using a box line metric heuristic which calculates the number of unrepeatd moves required to reach that location.
- **Evaluating generated levels:** Responsible for evaluating the generated levels. Evaluation is done using some heuristic functions. For example: number of box pushes in the solution, number of levels found at same solution depth, number of box lines, number of boxes, and ...etc.

The generated levels are not suffering from the problem of short level sequences presented in Yoshio Murase et al.[31] work. As the target number of crates increases, the generation process takes more time but delivers much more interesting and difficult levels.

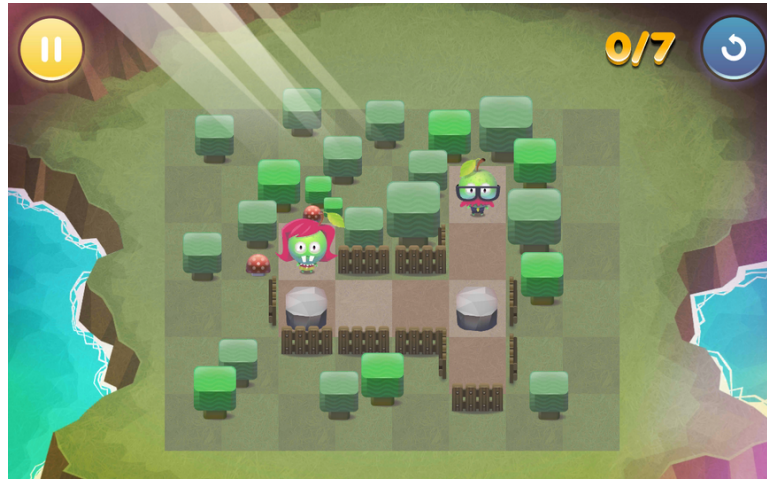


Figure 3.2: Screenshot from Fruit Dating

Rychnovsky[37] work focused on generating levels for his new game Fruit Dating. As shown in Figure 3.2, Fruit Dating is a puzzle game where the player need to move all similar fruits beside each other. The game is played by swiping in one of the four direction (up, down, left, right). Swiping in any direction causes all objects to move towards that direction. Rychnovsky developed a level editor that can be used to generate new levels or test playability of certain level. Generating new levels is done using the following steps:

- **Generating level structure:** The system generates level structures based on 2 steps. First step is generating external walls. External walls are generated at any random location connected to the border with short random length. Second step is generating inner walls. Inner walls are generated at any free location with free 3x3 locations.
- **Placing game objects:** The system generates fruits at random locations based on predefined weights. Every empty location is assigned a score using these weights. Locations with highest scores are selected. Other game objects use the same strategy but using different weights.
- **Checking for a solution:** The system use an algorithm similar to BFS to find the solution of the generated level. If no solution found, the level is discarded.

The technique doesn't take more than couple of minutes to generate a level. The main problem is there is no way to influence difficulty in the generated levels.

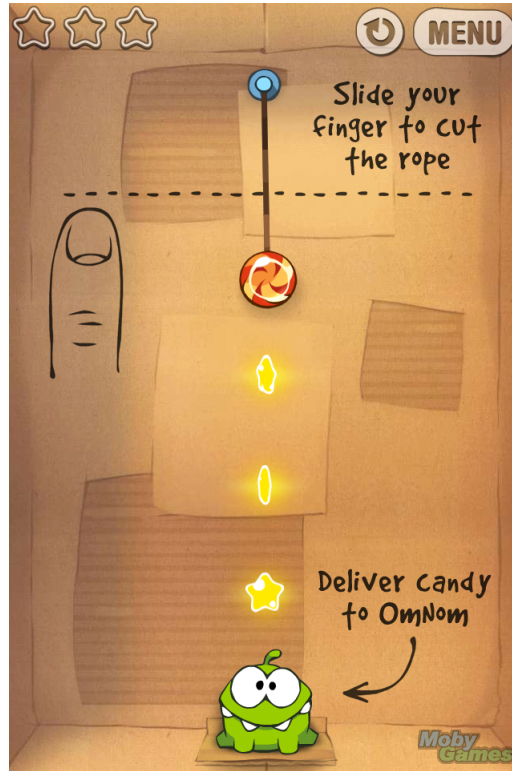


Figure 3.3: Screenshot from Cut The Rope

Shaker et al.[42] worked on generating levels for physics based puzzle games. They applied their technique on Cut The Rope (CTR) . As shown in Figure 3.3, CTR goal is to cut some ropes to free the attached candy to reach OmNom (a frog monster fixed at certain position on the screen). As game progress more game objects are introduced. These objects help in changing the movement direction of the candy to redirect it towards OmNom. Shaker et al. used Grammar Evolution (GE) technique to generate levels for CTR. GE is a result of combining an evolutionary algorithm like GA with a grammar representation. The grammar is designed to ensure that every game object appears at least one time. The fitness function used to rate the generated levels depends on some heuristic measures based on prior knowledge about the game. For example: Candy should be placed higher than the OmNom, OmNom must be placed below the lowest rope, and ...etc. Since using heuristics does not ensure playability, each generated level is played 10 time using a random player. The fitness score is reduced by a large number if no solution was found. Shaker et al. generated 100 playable levels and analyzed them according to some metrics such as frequency, density, and ...etc.

Shaker et al.[46] conducted their research on CTR to improve generated level quality. They replaced the random player with an intelligent one. Two types of automated players are developed. The first one takes an action based on the current properties of all objects in the level. While the second one takes an action based on the reachability between every level objects and the candy at every time step based on the candy's current position, velocity, and direction. The generated levels are far more diverse because the random player discards some potential levels in the search space.

Shaker et al.[43] introduced a new generation technique named Progressive Approach. Progressive Approach can be used on any kind of games to reduce the generation time. Progressive Approach is divided into two main steps:

- **Time-line Generation:** GE is used to evolve a time-line of game events.
- **Time-line Simulation:** Evolved time-lines are simulated using an intelligent agent. The agent utilize prior knowledge about the game to map the time-line to a possible level layout. Based on the agent result and some desirable heuristics, each time-line is assigned a fitness score.

Shaker et al. tested the new technique on CTR and compared its results with their previous work[46]. The results indicates a huge decrease in generation time, as it changed from 82 seconds towards 9.79 seconds. Although Progressive Approach is much faster and better from previous, it is difficult to determine the level difficulty before simulation. Also the quality of the levels depends on the intelligent agent used in the mapping process.

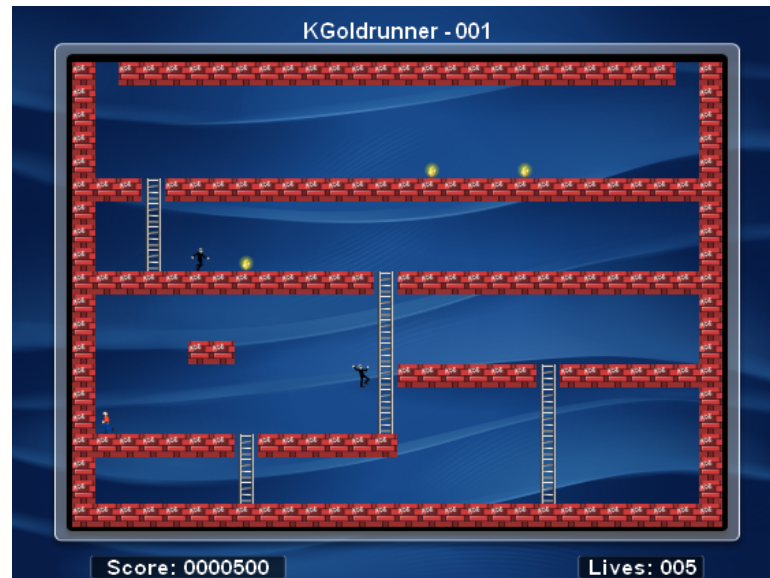


Figure 3.4: Screenshot from KGoldRunner

Williams-King et al.[68] work focused on generating levels for their game KGoldRunner. KGoldRunner is just a port for the famous game Lode Runner[30]. As shown in Figure 3.4, the goal is to collect all gold chunks without getting killed. Player can move left, move right, climb a ladder, move across a bar, or dig the floor. The game contains enemies who changes the position of the gold chunks. After collecting all gold chunks a hidden ladder appear which lead the player to the end of the level. Williams-King et al. used GA to generate random levels. Generated levels are evaluated using fitness function based on some prior knowledge about the game. For example: checking level connectivity using BFS between starting point and all gold coins. High score levels are simulated using an automated player that tries to collect all gold chunks using 20 different paths. The number of solvable paths indicates the level difficulty. As the number of generations increase more time is required but more levels are likely to be solvable.



Figure 3.5: Screenshot from Refraction

Smith et al.[47] worked on generating puzzle levels for Refraction. Refraction is an educational game created by Center for Games Science at the University of Washington. Refraction teaches children concepts in math through a puzzle game. As shown in Figure 3.5, the goal is to make every alien spaceship fully powered by directing a laser beam towards them. Each ship needs a fraction of the laser to operate. Player should use tools like Benders (change the direction of laser by 90°), Splitters (divide laser power by number of outputs from it), and ...etc to achieve that goal. Smith et al. divided his generator into 3 main components:

- **Mission Generation:** Responsible for generating a general outline showing level solutions.
- **Level Embedder:** Responsible for translating the general outline to a geometric layout.
- **Puzzle Solver:** Responsible for testing generated level for solution.

These components are implemented into two different ways (Algorithmic approach and Answer Set Programming (ASP)). Results shows that ASP is faster than Algorithmic approach specially in Puzzle Solver module, while Algorithmic approach produces more diverse levels than ASP.

3.1.2 Other Level Generation

This section is going to focus on Level Generation for non Puzzle Games. The previous work in that field focused on different game genres but a lot of work was done in Platformer genre. Showing some of the work will help in understanding the current research direction towards Level Generation.

Constructive approach in PCG has been used in commercial games for long time. It had been used in generating textures, trees, sound effects, and levels. Ismail and Nijman[39] used an Agent Based PCG to generate levels for their commercial game Nuclear Throne.

The system spawns an agent at a random position on the map. This agent starts moving into a random direction with a certain probability to change direction. New agents are spawned based on a certain probability. The agents continue moving till the number of dug floors reached 110 or reaching a dead end. Coxon[33] used perlin noise and cellular automata algorithm to generate a huge map for his commercial game Lenna's Inception. The game map is divided into small rooms. Perlin noise is used to assign a certain terrain type for each room. Cellular automata algorithm is used to craft the details for each room while ensuring reachability between entrances and exits.

Search algorithms (specially GA) has been used a lot in level generation specially in academia. Sorenson and Pasquier[53] worked on improving GA to adapt with level generation for any game. The new technique divides the population into Feasible and Infeasible. Each population is evolved on its own using crossover and mutation. Chromosomes can transfer from Feasible to Infeasible population and vice versa. The Feasible population uses a fitness function that measures the challenge presented in the game. The Infeasible population uses a fitness function that measures the distance towards the Feasible population. These techniques were tested over two different games The Legend of Zelda and Super Mario Bros. The results shows promising levels generated for both games which is an indication for the possibility of using this technique as a generic framework.

Preuss et al.[36] used 3 different search techniques to generate diverse game maps for Strategy Games. They used Restart Evolution Strategies, Novelty Search, and Niching Evolutionary Algorithm then compared their results in the end. The fitness function used in evaluation consists of 3 metrics:

- **Tile Based Distance:** measures diversity between each two maps.
- **Objective-based Distance:** measures the quality and playability of the map according to some heuristics for Strategy Games.
- **Visual Impression Distance:** measures how good the map look using 20 different heuristic measures.

Niching Evolutionary Algorithm generated the bested results in diversity and quality measurement, followed by Restart Evolution Strategies which is almost the same, while Novelty Search was the worst of them in both quality and diversity.

Liapis et al.[28] improved Novelty Search Algorithm to generate better and diverse maps for strategy games than previous work[36]. The improved algorithm borrowed an idea from Sorenson and Pasquier work[53] by dividing the population into Feasible, Infeasible populations. The Feasible population uses a fitness function that measures the distance between chromosomes to ensure diversity. The Infeasible population was tested using two different fitness functions. The first one is same like the feasible population, while the second one uses the distance toward feasibility like Sorenson and Pasquier work[53]. The results prove that the second fitness generates more feasible solutions but less diverse compared to the first one.

Baghdadi et al.[3] used GA to evolve levels for the commercial game Spelunky[54]. Spelunky entire map is divided into 4x4 rooms. Levels are represented as a group of

integers. These integers represents positions for start room, exit room, room connections, number of enemies, and ...etc. Each level is mapped to a layout before evaluation. Mapping process consists of 3 main steps:

- Generating internal structure for each room using an Agent Based PCG.
- Adding some corridors to ensure connection between rooms.
- Distributing monsters, ladders, and bombs equally across the level.

Levels are evaluated using a fitness function consisting of two heuristics measures. The first heuristic ensures level playability by measuring connectivity between mandatory rooms, placement of starting room, and ...etc. Second heuristic measures level difficulty by measuring path length, number of enemies, and ...etc. The results shows that the introduced technique is able to generate a good designed levels for Spelunky with a certain difficulty.

Smith et al.[49] generated levels for Super Mario Bros (SMB) using Rhythms. Rhythms are a sequence of action user during SMB to finish the current level. Rhythms is a way to express the pace of playing a level. The generator is divided into 2 main parts:

- **Rhythm Generation:** Responsible for generating a sequence of actions required to finish the level.
- **Rhythm to Geometry Generation:** Responsible for translating the generated Rhythm into a corresponding level layout.

The generated level is tested against some critic measures provided by the human designer. These critic measures helps in enhancing the quality and ensuring the playability of the generated levels. The results shows the importance of including the pace of playing in generating platformer levels.

Sorenson and Pasquier[52] used GA to generate SMB levels based on previous studies about GameFlow[56, 7, 55]. GameFlow studies measure the player enjoyment as the amount of challenge facing the player. The studies recommend keeping the challenge level at an optimal rate (too much challenge cause frustration, too little challenge cause boredom). Based on that fact, The study modeled the challenge level as the player's Anxiety. Sorenson and Pasquier used anxiety curve as a fitness function to evaluate the generated levels. The rate of change of anxiety curve is modeled using the following equation:

$$\frac{df}{dt} = m * \frac{da}{dt}$$

Where m can be +1 or -1. The value of m is +ve all the time till a certain threshold. If this threshold is exceeded, m value become -ve causing the curve to decrease till reach another threshold where it starts increasing again. They compared their results with the original SMB levels. The anxiety curved of the generated levels are not similar to anxiety curve of the original SMB where anxiety curve drops instantly after reaching high value. This analysis proves that anxiety curves show a promising direction of using GameFlow as a measurement.

Shaker et al.[45] used GE to generate levels for SMB. The level is represented using context free grammar that represents the level as a group of chunks where each chunk can be any game object. GE tries to increase the number of chunks appearing in the level while minimizing the number of conflicts between them. The results of the generator is compared with two other generators. The results shows that level characteristics depends on the generation technique.

Some commercial games generate levels by combining a group of hand crafted game chunks to ensure the high quality of the level. Yu and Hull[59] divided Spelunky map into 4x4 rooms. Each room is chosen from a set of predefined rooms ensuring the existence of a path between start and end points. The generator modifies each selected room by adding some new blocks without blocking any movement path. Enemies and items are added after selecting the layout. Also Mcmillen[58] used a similar technique for his commercial game *The Binding of Isaac*. Due to the huge success of these games, that technique grows popular in academia.

Dahlskog and Togelius[11, 12, 14, 13] published several papers on generating levels for SMB game utilizing the patterns found in the original game. They started[11] by analyzing all original levels from SMB and detecting all repeated patterns. Repeated patterns are divided into 5 main categories (Enemies, Gaps, Valleys, Multiple Paths, and Stairs). Each category is divided into multiple configurations called Meso Patterns, for example Enemies pattern can appear as an Enemy (single enemy), 2-Horde (two enemies together), 3-Horde (three enemies together), 4-Horde (four enemies together), and a Roof (Enemies underneath hanging platform). The level generator generates levels by randomly choosing a group of these patterns and generating a geometry corresponding to them. Levels generated by that technique have the same feeling like original SMB levels. They conducted their research[12, 14] to improve the quality of the generated levels by using these analyzed patterns as an evaluation function. Levels are generated from concatenating a group of vertical slices called Micro Patterns. Micro Patterns are generated from original levels in SMB. GA is used to improve the generated levels using a fitness function that reward levels which contains more Meso Patterns. The generated levels are more similar to the original levels of SMB and more diverse. They conducted their research[13] to improve the quality of the generation by introducing Macro Patterns. Macro Patterns are a group of Meso Patterns after each other which can be used to identify the level of difficulty. SMB levels were analyzed and Macro Patterns are extracted from it. Macro Patterns from SMB is used as fitness function for GA. The results takes more time to generate but they have the same flow of SMB levels.

Shaker and Abou-Zleikha[44] used Non-Negative Matrix Factorization (NMF) technique to capture the patterns of level design of SMB. NMF can be used on any game if it has a huge amount of levels to learn the pattern from them. They used 5 different PCG techniques to generate 5000 levels for SMB (1000 level from each technique). NMF method factorize these levels into two new matrices:

- **Pattern Matrix:** captures the patterns found in each vertical slice of SMB.
- **Weight Matrix:** captures the percentage of each pattern to appear in the current level.

Pattern Matrix can be used to generate same levels like any of the input generators if its original weight vector is used. Shaker and Abou-Zleikha generated levels using free weights and compared them with all the results from the five generators. The results shows that NMF explores more of the search space than all the five generators, but They don't know if the whole space provides a good player experience.

Snodgrass and Ontanon[50] used Markov Chain Model to generate levels for SMB. Markov Chain Model is another way to learn about the design patterns from original SMB levels. The technique can be used on different game genres if there is a huge amount of highly designed levels. They tested the technique with different input parameters and evaluated the generated levels using human players. The results of the best input configuration only generate 44% playable levels.

3.2 Rule Generation

This section will show the latest research and the different techniques used to generate rules for different game genres. Most of the work in this section target generating Arcade games[61, 8, 40, 48, 64]. Arcade games are the most popular in research because they are easier to generate (simple rules), they provide a huge diversity in mechanics, and there is a huge research happening in GVGP for Arcade Games[27]. Other work tries to generate Board Games[6], Card Games[17], and Platformer Games[9] but as far as we know no one tried to generate Puzzle Games except for the work by Lim and Harrell[29].

3.2.1 Puzzle Rule Generation

Puzzle rule generation was infamous till 2014., when Lim and Harrel[29] published their work on generating new rules for PuzzleScript games. They use GA to find other possible rules that can solve a certain level for a certain game. For example what are the rules that can solve Sokoban level shown in Figure 3.6? Lim and Harrel used GA to generate rules. They divided the fitness function into 3 parts:

- **Rule Heuristics:** measures some logical constrains that should be found in rules. For example player should be on the left hand side of at least one rule, all movements in a certain rule should be in the same direction, and ...etc.
- **Validity:** checks for runtime errors in the generated rules.
- **Feasibility:** checks if the level is solvable using an automated player.

After running GA for 50 generations on the level shown in Figure 3.6, the system discovered new rules such as Crate Pulling, Morphing, and Spawning. The discovered rules are not new for human designer but they show promising direction in generating rules for Puzzle Games.

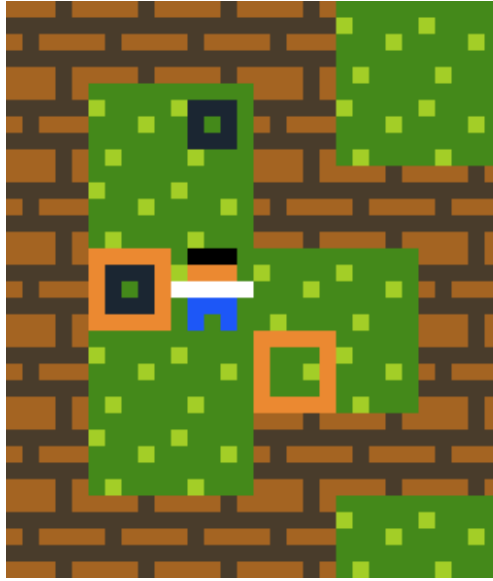


Figure 3.6: First level of Sokoban

3.2.2 Other Rule Generation

Although Rule Generation is the hardest content to be generated, a computer software written by Browne and Marie invented a board game called Yavalath. Yavalath is listed in the top 100 abstract board games of all time[69]. Browne and Maire software[6] used standard evolutionary approach to evolve game rules written in GDL for Combinatorial Games. Combinatorial Games are games that have finite number of states, deterministic (no randomness), discrete (one step at a time), perfect information (everything is visible), and involve two or more players. Evolved games fitness were measured by automated players for several plays (payouts). Based on the results of the payouts a score is given for each game based on 57 different heuristic metrics. The best scored games were tested by human players where each tester assign a score for these games. Comparing human scores with the system scores shows a correlation between both of them.

Jose et al.[17] used Genetic Programming (GP) to generate rules for card games using GDL specified for card games. The generated games are tested using automated players for several payouts. Based on the results of these payouts, games are assigned a fitness score. The system removes all games that never been finished in at least one of the payouts, results in draw for more than 20% of the payouts, or have more than 10 stages for one round. Other games are evaluated based on the difference between the number of wins of the best player to the worst player, the average number of turns required to finish the game, and the average number of turns with no actions. The resulted games are well formed and can be played by humans but at the same time they are boring and not interesting as most of them can be won using simple strategy.

Togelius and Schmidhuber[61] worked on generating rules for simple arcade games. Games are encoded in the form of collision and score matrices and a list of object behaviors. The collision matrix shows the result of colliding any two game objects. For example *red, white, kill, none* means If a red object collides with a white object, the

red object will be killed while nothing will happen to the white object. Score matrix is defined in the same way but with values of +1, 0, -1. The list of object behaviors shows how different objects behave in the game (random movement, clockwise movement, still, and ...etc). All generated games terminate when $score \geq score_{max}$ or when $time \geq time_{max}$. Togelius and Schmidhuber used hillclimbing algorithm to generate game rules. Each iteration new game is generated and evaluated using a fitness function. The current game will be replaced with the new game if the new game scores better. The fitness function is based on the idea of learning progress which is inspired by Koster's Theory of Fun[26] and Schmidhuber's theory of curiosity[41]. A game is considered as a good game according to how much it can be learned. Based on that idea Evolutionary Strategies algorithm is used to evolve a neural network to play the generated games. Neural Networks output is used as a fitness score. That approach needs very long time to run that is why the best generated games are just playable games but not interesting.

Cook and Colton[8] took a new approach in generating full Arcade Games. They divided the game into 3 main elements:

- **Map:** is a 2D matrix showing passable and impassable tiles in the levels.
- **Layout:** is a list of position for every object on the map.
- **Rules:** govern how game works and they are represented in the same way in Togelius and Schmidhuber work[61].

Each game element is evolved using GA to maximize its own fitness score. For example map fitness measures the reachability of each tile, layout fitness checks for the distance between different objects, and rules fitness checks for game playability. All game elements communicate with each other through central game object. After each generation every game element updates the central game object with the best scored output. The system is very easy to add/remove game elements but some game elements can finish evolution early which minimize communications between different elements. Most of the generated games are not interesting although some of them have some similarity with the famous game PacMan.

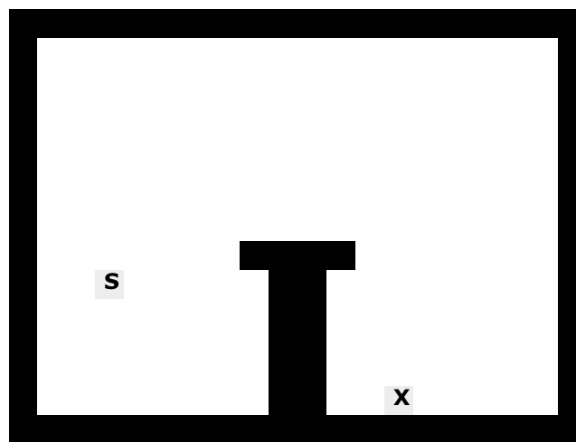


Figure 3.7: The challenge level for the Toggleable function

All discussed techniques so far based on having a specific GDL that governs the generation of rules. Cook et al.[9] decided to generate new game rule for his platformer

game (A Puzzling Present) by analyzing and generating actual game code. They use code reflection ability to get all data members from the player class. Cook et al. used GP to evolve a new Toggleable function that helps an automated player to overcome a challenge level. A Toggleable function is any function where its effect can be reversed. Toggleable function is applied to one of the player data members. Cook et al. used the challenge level presented in Figure 3.7 to test the Toggleable function. The challenge level is designed to ensure no possible solution using platformer rules (moving and jumping). After the algorithm finds a Toggleable function, the system starts generating levels using GA. Levels are rated based on 3 simulation run to ensure certain characteristics.

- **First Simulation:** Check for a solution without using the new Toggleable function.
- **Second Simulation:** Check for a solution using the new Toggleable function.
- **Third Simulation:** Check for level difficulty based on the solution length.

Some of the best evolved Toggleable functions are Gravity Inversion, Teleportation, and Bouncing. The mechanics and levels are rated using human users. Human users rated Gravity Inversion and Bouncing higher than Teleportation as they are more understandable.

Farbs released a game called *ROM CHECK FAIL*[40]. ROM CHECK FAIL is a game which changes the rules applied on each object every few seconds. The new rules are selected from a pool of handcrafted rules. Some of rules controls player movements, enemy movements, object collisions, or ...etc. For example the player can be Link from The Legend of Zelda where he can move in all direction or a Spaceship from Space Invaders where he can only move left and right and shoot upwards. Although the game seems unfamiliar and weird, it has made a huge impact on the gaming scene.

Smith and Mateas[48] went for another direction in generating new games. Instead of generating a game then test it against set of constrains and/or evaluation function. They decided to limit the generative space for not exploring these parts to minimize the processing time. They used ASP to generate games with required aspects and constraining the unplayable parts in the generative space. For example putting a constraint for only winning if all white objects are killed, Ensures ASP not exploring other games having a different winning condition. Smith and Mateas tested their theory with Arcade games by creating a game called Variation Forever[65] which is inspired by ROM CHECK FAIL[40]. Games are described using the same way like Togelius and Schmidhuber[61]. Results show promising direction in using ASP for limiting the generative space.

3.3 General Video Game Playing

In this section we are going to present the latest work in GVGP either as standalone research or as a part of level or rule generation algorithms. Most of the discussed work with level generation either use BFS algorithm[31] or a tailored AI specially for a certain game[46]. For most of Level Generation work a tailored AI performs better than using a general one as tailored AI is designed with previous knowledge about the game. Utilizing this knowledge helps the automated player to find the solution quickly.

That is not the case with Rule Generation. Rule Generation searches for new unseen games where automated player is used to test its playability. Tailored AI will not work as there is no prior knowledge. Most of work done in Rule Generation used some kind of Search Algorithm (variants of BFS) to find the solution except for Togelius and Schmidhuber[61] work. They used an evolutionary Neural Network to measure learning progress through the evolved game. Browne and Maire[6] used Min-Max trees with Alpha Beta Pruning for automating game plays. They utilize the current game description to provide estimates for each board configuration. Jose et al.[17] used two types of automated players. The first one is random player which chooses random actions to model weak players, while the second is based on Monte Carlo Tree Search (MCTS) algorithm to model professional player. Cook et al.[9] used a normal BFS technique to search for a result for the challenge level. Lim and Harrel[29] compared BFS algorithm to solve generated games with Best First Search (BestFS) algorithm. BestFS is similar to A* algorithm where it sorts the explored nodes based on a heuristic function. The system utilize the knowledge about the goal condition and tries to minimize the distance between goal objects. The system also minimizes the distance between the player object and goal objects based on the fact that the player is the main object affecting the game world. Results show that BestFS finds solution faster than BFS but with slightly longer moves.

Most of GVGP research is done on Arcade games from ATARI 2600. One of the first work on that direction was the work done by Bellemare et al.[4]. They developed a system called Arcade Learning Environment (ALE) which contains lots of different arcade games from ATARI 2600. They tested their system against two different AI approaches:

- **Learning techniques:** Reinforcement learning algorithm called *Sarsa*(λ) is tested using different types of features. Features ranged from using screen pixel colors to using the 1024 bit of Atari RAM.
- **Planning techniques:** Normal BFS and BFS with Upper Confidence Bounds Applied to Trees (UCT) are tested.

Results show that both approaches performed better than the average normal player. Although Planning techniques outperformed Learning techniques, it took more time to decide each action.

Hausknecht et al.[22] evolved a NN to play ATARI 2600 games. The system consists of 3 main steps

- **Visual Processing:** The system processes the game screen and detect all moving objects and group them into classes based on velocity information.
- **Self-Identification:** The system identifies which class is the player. The player object is identified by calculating the entropy over velocities for each class. The class with the highest entropy is considered the player.
- **Perform Action:** The system chooses its next action based on the positions of every object.

Their system outperformed three other reinforcement learning techniques based on their performance in playing two Atari 2600 games (Freeway and Asterix).

Perez et al.[34, 35] summarized the techniques and the results from General Video Game AI Competition (GVG-AI) [21]. GVG-AI is a competition that takes place every year for creating a General Player that can play some unseen ATARI 2600 games. Lots of techniques and methods used in the entries for the competition. Some of the techniques are based on learning methods while others on general heuristics. Heuristic methods produced better results than most of learning methods in the competition. The best algorithm is an Open Loop Expectimax Tree Search, followed by an algorithm named JinJerry Algorithm which is a variant of MCTS, then some variants of BFS. The first learning algorithm to appear in table of results is at the sixth place. The learning algorithm is a reinforcement learning technique called Q-Learning Algorithm which models the world in a form of Markov Decision Process.

Nielsen et al.[32] tested different AI techniques over ATARI 2600 games. They used different AI technique varies from MCTS to DoNothing. AI techniques are tested against 20 handcrafted games, 200 mutated version, and 80 random games. Based on the results, most intelligent techniques performed better on handcrafted games than other games. On the other hand, the DoNothing algorithm perform very bad on handcrafted games than other games. These results strengthen the idea of the need of an intelligent player to judge procedural generated games.

Chapter 4: Methodology

This chapter describes our approach for generating Puzzle Script levels using different methodologies. Based on the output we conducted our research for generating Puzzle Script rules. This chapter is divided mainly into two parts Level Generation conducted by Rule Generation.

4.1 Level Generation

General Level Generation is not an easy task specially if the main rules can differ from one game. Most of previous work in Puzzle Level Generation (refer to Chapter 3) was limited for generating levels for a specific game, while the rest just suggest a general technique to be used that is based on designing a game specific fitness function. In this work, we suggest some global metrics for Puzzle Games that can help in generating levels with minimum prior knowledge.

Our approach relies heavily on the current game rules and objects, and a minimum amount of prior knowledge about Puzzle Script language. Figure 4.1 shows a high level block diagram of the system. The following subsections will describe each block in details.

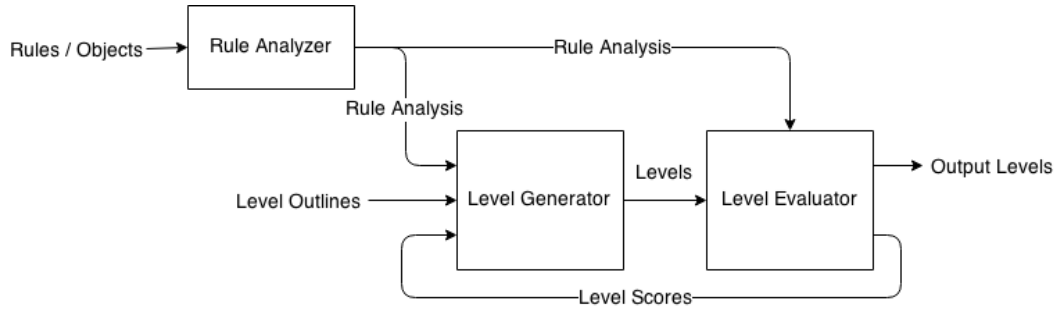


Figure 4.1: High level system block diagram

The system starts by analyzing the current game rules using the Rule Analyzer module. Rule Analyzer module utilize some basic information about Puzzle Script rules to understand the importance of each game object and its basic functionality.

The output of the Rule Analyzer and the Level Outlines are fed to Level Generator module. Level Generator is responsible for generating initial level layouts. It utilizes the output of the Rule Analyzer to insert every game objects at a suitable position in the Level Outlines. Level Generator uses two different approaches: Constructive Approach and Genetic Approach. Constructive Approach is faster in generation but produce less diverse levels, while Genetic Approach requires more time but give access to a vast majority of levels.

The generated levels are subjected to a Level Evaluator module. Level Evaluator uses an automated player to play the generated levels. Based on the result of each play, Level Evaluator gives a score for the level based on six different heuristic measures. These

measures make sure the resulting level is playable and not trivial.

In case of Constructive Approach, the system selects the best scored levels to output them, while Genetic Approach, the system enhances the output levels using GA operators.

4.1.1 Rule Analyzer

Rule Analyzer is the first module in the system. It analyzes game rules and extract some useful information about each object. The extracted information is fed to Level Generator and Level Evaluator modules. Each object is assigned:

- **Type:** Each object is assigned a type according to its presence on the Puzzle Script file. There are 4 different types:
 - **Rule Object:** Any object that appears in a rule is defined as a rule object. Rule objects are essential for rules to be applied.
 - **Player Object:** It is defined by name "player" in the Puzzle Script. It is the main game entity. It can move freely without any restriction. Any level must have at least 1 player object to be playable. It must be a Rule Object as well.
 - **Winning Object:** They are two object types appearing in the winning condition. At least one of them must be a Rule Object or a Player Object.
 - **Solid Object:** All objects that doesn't appear in rules but on same collision layer with at least one Rule Object.
- **Subtype:** By more analysis on Rule Objects and its presence within rules, each Rule Object is assigned a Subtype:
 - **Critical Object:** If an object presented in a rule with a Player Object and presented with a Winning Object in the same or different rule, it is considered a Critical Object.
 - **Normal Object:** It same like Critical Object but only connected to one of them.
 - **Useless Object:** It is an object that is neither connected to a Player Object nor a Winning Object.
- **Priority:** It reflects the number of times an object appeared in the game rules.
- **Minimum Number:** The maximum number of times any object appeared in a single rule. For example consider the following group of rules:

[> Player | Crate] -> [> Player | > Crate]

[> Crate | Crate] -> [> Crate | > Crate]

The Crate object appeared in both rules. The first rule the Crate object appeared once, while the second rule it appeared twice. That means the minimum number of Crates is 2.

- **Behaviors:** Every object can have one or more behavior. Behavior are analyzed from the difference between left hand side and right hand side of each rule. There are 4 kinds of behaviors:

- **Move:** If an object on the left hand side have different movement action associated with it compared to right hand side, this object has Move behavior. For example, In the following rule Crate moves when player approach it.

$$[> \text{Player} \mid \text{Crate}] \rightarrow [> \text{Player} \mid > \text{Crate}]$$

- **Teleport:** An object is considered to have Teleport behavior if its place in the rule change from left hand side to the right hand side. For example, In the following rule Crate change position with player when it approach it.

$$[> \text{Player} \mid \text{Crate}] \rightarrow [\text{Crate} \mid \text{Player}]$$

- **Create:** If the number of a certain object on left hand side is less than number of objects on right hand side, then this object have Create behavior. For example, In the following rule, the Crate object is created when Player moves to an empty tile.

$$[> \text{Player} \mid \quad] \rightarrow [\text{Crate} \mid \text{Player}]$$

- **Destroy:** If the number of certain object on the right hand side is less than number of objects on left hand side, then this object have Destroy behavior. For example, In the following rule, the 3 Crates are destroyed when they are aligned vertically or horizontally.

$$[\text{Crate} \mid \text{Crate} \mid \text{Crate}] \rightarrow [\quad \mid \quad \mid \quad]$$

- **Relations:** Each object have a list of Relations which contains all objects that appeared in any rule as that object exists. For example, In the following rules, Crate has relations with Player and Lava, Player has a relation with Crate, and Lava has a relation with Crate.

$$[> \text{Player} \mid \text{Crate}] \rightarrow [> \text{Player} \mid > \text{Crate}]$$

$$[> \text{Crate} \mid \text{Lava}] \rightarrow [\quad \mid \quad]$$

A special Relations list for left hand side only is also create at the same time.

4.1.2 Level Generator

Level Generator is responsible for formalizing a level with best possible way to ship it for evaluation. Two approach were used to generate levels.

4.1.2.1 Constructive Approach

Constructive Approach uses information from Rule Analyzer to modify the Level Outlines. In this approach, several levels are generated using an algorithm and the best levels are

selected. A pseudo code for the algorithm is presented in Algorithm 1.

Algorithm 1: Pseudo Algorithm for Constructive Approach
<p>Data: levelOutline, ruleAnalysis, coverPercentage</p> <p>Result: modified level outline</p> <p>numberObjects = Get the number of objects for each object type;</p> <p>levelOutline = Insert Solid Objects in the level outline;</p> <p>levelOutline = Insert Winning Objects in the level outline;</p> <p>levelOutline = Insert Player Object in the level outline;</p> <p>levelOutline = Insert Critical Objects in the level outline;</p> <p>levelOutline = Insert Rule Objects in the level outline;</p> <p>return levelOutline;</p>

The algorithm is consist of two main part. The first part is responsible for determining the amount of objects that should be presented in the current level layout. The second part consists of 5 steps and is responsible for adding the game objects in an intelligent way to the current level.

Algorithm 2 shows the process of calculating the amount of objects. The algorithm starts by determining the percentage that every type should cover from the total number of objects. Each object type must contribute by a percentage equal to the minimum number of objects needed to make all the rules valid. A cover percentage is calculated based on number of critical objects and winning objects. The value of cover percentage is smaller as the percentage of both of critical object and winning object increase and vice versa. Critical Object and Winning Object are the main game objects, without them game may not be playable at all. The increase in there number cause level to be more difficult and more complex. Having small cover percentage when they share huge part of objects, makes sure the game is not very complex.

Algorithm 2: Get the number of objects**Data:** levelOutline, ruleAnalysis**Result:** Number of Objects for each type

```
percentages[Winning Object] = Minimum Number[Winning Object 1] + Minimum
Number[Winning Object 2];
```

```
if Player Object is a Winning Object then
```

```
    | percentages[Winning Object] = 2;
```

```
end
```

```
percentages[Solid Object] = Number of the different kinds of Solid Objects;
```

```
percentages[Critical Object] = Summation of Minimum number of all Critical
Objects;
```

```
percentages[Rule Object] = Summation of Minimum number of all rule Objects;
```

```
Divide all percentages by summation of all of them;
```

```
coverPercentage = 1 - percentages[Winning Object] - percentages[Critical Object];
```

```
totalNumber = coverPercentage * total free area in levelOutline;
```

```
numberObjects = totalNumber * weights * percentages;
```

```
numberObjects[Player] = 1;
```

```
return numberObjects;
```

The following algorithm all responsible for inserting objects based on numbers from previous part. Most of the Insertion Algorithms needs to find the most suitable empty locations to insert the new Object on it. The most suitable location is based on the object going to be inserted. If the object has a Move behavior, it should be inserted at spots with the most free locations around it. Otherwise any random free location is okay.

Algorithm 3 shows the insertion algorithm for Solid Objects. This algorithm is the first step to modify the level outline. The algorithm just insert random solid objects at a random empty space in the level outline. The algorithm is repeated for several times based on the number calculated from previous step. The same idea is used for inserting Player Object in Algorithm 5 but only one object is inserted.

Algorithm 3: Insert Solid Objects Algorithm**Data:** levelOutline, ruleAnalysis, numberObjects**Result:** modified level outlines

```
while numberObjects[Solid Object] > 0 do
```

```
    | object = get random solid object;
```

```
    | location = Get Suitable Empty Location;
```

```
    | levelOutline[location] = object;
```

```
    | numberObjects[Solid Object] -= 1;
```

```
end
```

```
return levelOutline;
```

Before inserting the Player to the level, Winning Objects should be inserted. Algorithm 4 is responsible for inserting Winning Objects into the level outline. The algorithm generate an equal amount of Winning Objects except if any of the Winning Objects have

Create behavior. The amount of generate Winning Objects must be multiple of minimum number of these objects to ensure that all rules can be applied. The first winning object is inserted at a suitable empty location, while the other is inserted at the farthest suitable empty location. If the Winning Rule is No then the second object must be inserted at same location of the first object.

Algorithm 4: Insert Winning Objects Algorithm

Data: levelOutline, ruleAnalysis, numberObjects
Result: modified level outlines

```

if Winning Objects have Create behavior then
    | minObject1 = Minimum Number(Winning Object 1);
    | minObject2 = Minimum Number(Winning Object 2);
else
    | minObject1 = Max(Minimum Number(Winning Object 1), Minimum
    | Number(Winning Object 2));
    | minObject2 = minObject1;
end

while numberObjects[Winning Object] > 0 do
    | location = Get Suitable Empty Location for Winning Object 1;
    | for 1 to minObject1 do
    | | levelOutline[location] = Winning Object 1;
    | | numberObjects[Winning Object] -= 1;
    | end
    | if Winning Rule != No then
    | | location = Get the farthest suitable empty location for Winning Object 2;
    | end
    | for 1 to minObject2 do
    | | levelOutline[location] = Winning Object 1;
    | | numberObjects[Winning Object] -= 1;
    | end
    | end
end

return levelOutline;

```

Algorithm 5: Insert Player Object Algorithm

Data: levelOutline, ruleAnalysis, numberObjects
Result: modified level outlines

```

location = GetSuitableEmptyLocation(Player Object, levelOutline, ruleAnalysis);
levelOutline[location] = Player Object;

return levelOutline;

```

Algorithm 6 is responsible for inserting Critical Objects to the level. Critical Objects are one of the most important objects in the game. As they are connected with both Player and Winning Objects. In some games, the game level won't be solvable without Critical Objects. For example, the following rules are from game called DestroyGame. The game

goal is to destroy all Gem objects from the level. Gems can be destroyed if it is aligned with 2 other boxes. Boxes can be pushed by the player.

[> Player | Crate] -> [> Player | > Crate]

[Crate | Gem | Crate] -> [| |]

From these rules Crate is a critical object and is the responsible for destroying the Gem. If there is no Crates in the level, the game will be unplayable. For that reason the algorithm ensures inserting Minimum Number of all critical objects. The algorithm adds more random critical objects according to the number required afterwards. Each critical appears based on its Priority feature.

Algorithm 6: Insert Critical Objects Algorithm

Data: levelOutline, ruleAnalysis, numberObjects

Result: modified level outlines

```

foreach object in Critical Objects do
    for 1 to Minimum Number of object do
        location = Get suitable empty location;
        levelOutline[location] = object;
        numberObjects[Critical Object] -= 1;
    end
end

while numberObjects[Critical Object] > 0 do
    object = choose random critical object based on its Priority;
    for 1 to Minimum Number of object do
        location = Get suitable empty location;
        levelOutline[location] = object;
        numberObjects[Critical Object] -= 1;
    end
end

return levelOutline;

```

Same is done with Rule Objects in Algorithm 7. As random Rule Objects are inserted to the map based on its priority feature.

Algorithm 7: Insert Rule Objects Algorithm**Data:** levelOutline, ruleAnalysis, numberObjects**Result:** modified level outlines

```
while numberObjects[Rule Object > 0] do
    object = choose random rule object based on its priority;
    for 1 to Minimum Number of object do
        location = Get suitable empty location;
        levelOutline[location] = object;
        numberObjects[Critical Object] -= 1;
    end
end
return levelOutline;
```

4.1.2.2 Genetic Approach

The second approach used to generate levels for Puzzle Script games. This method uses GA to evolve levels outlines to playable levels. The following points will determine how GA is used to evolve level outlines. Elitism is used to ensure the best levels are sustained.

Chromosome Representation: GA represents the levels as 2D matrix. The value at each location represents the objects at that location.

Genetic Operators: Crossover and Mutation are used to ensure better levels in the following generations. One point crossover used where a point (x, y) is selected from the first chromosome and all previous rows (having smaller x) are swapped with the second chromosome. Mutation is different from crossover as it changes any random selected tile using any of the following:

- **Creating an object:** where a random object is selected to replace any empty tile in the level.
- **Deleting an object:** where a random object from the level is selected to be deleted.
- **Changing the position of an object:** where a random empty tile is swapped with non empty one.

The mutation operation happens by subjecting the level to these 3 methods using different probabilities. Creating and deleting an object is subjected to the lowest probabilities compared to changing the position of an object.

Initial Population: Three different techniques used to test the effect of different Initial Population on the generation process. These techniques are:

- **Random Initialization:** The population is initialized as a mutated versions of the empty level outline. This technique takes very long time to find a good designed level as it search in the whole space.
- **Constructive Initialization:** The population is initialized using constructive approach algorithm. Using the algorithm tighten the search space so it will not take very long time to find a better level.

- **Mixed Approach:** The population is initialized as a mixture between Random Initialization and Constructive Initialization. A portion of the population is created using the Constructive Approach Algorithm and some mutated versions from its output, while the other portion is the same like Random Initialization. Using that algorithm ensure more diversity than previous two runs.

More details about the results of each algorithm will be discussed in the upcoming Chapter 5.

4.1.3 Level Evaluator

Level Evaluator is responsible for evaluating the generated levels. Evaluating Puzzle Games are based on some heuristic measures. Heuristic measures are based on global knowledge about Puzzle Script games. The first idea was to ensure game playability. That is achieved by using an automated player which we are gonna discuss it later. Figure 4.2 shows several levels designed for Sokoban game where all are playable but some of them are more interesting than other. The first level is very easy level which can be solve with one move. The second level need more moves which is more interesting than the first level but it is just straight forward toward the solution. The last level is not easy to solve need some prior thinking and trying some moves which is more interesting than previous two.

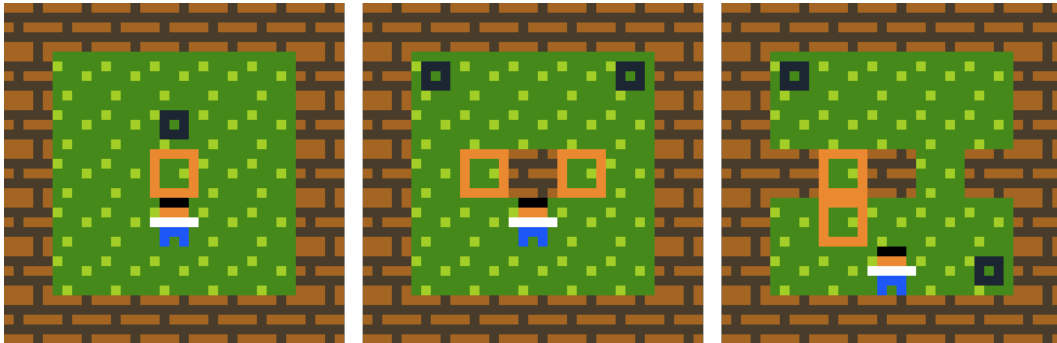


Figure 4.2: Examples on different levels for Sokoban game

The above example proves that playability is not enough to judge puzzle levels. Some other metrics must be used to ensure the solution have more moves with some thinking ahead. Six heuristics measures are applied on the output of the automated player to capture this feature.

4.1.3.1 Automated Player

Our Level Evaluator uses a modified version of the BestFS Algorithm as automated player. BestFS Algorithm was introduced in Lim et al.[29] work. BestFS is similar to BFS algorithm but instead of exploring states sequentially, it sorts them according to fitness function. This causes the algorithm to explore the more important nodes first helping it to reach the solution faster. As explained in Chapter 3, Lim et al. algorithm uses two metrics to evaluate each game state:

- **Distance between winning objects:** BestFS tries to either increase or decrease the distance between the winning objects according to the winning rule. The "No" rule is the only rule that need to increase the distance, while the others need to decrease it. Figure 4.3 shows an example from Sokoban, where the distance between crates and targets is highlighted.
- **Distance between player and winning objects:** BestFS always tries to minimize the distance between the player and the winning objects. In order to affect the distance between the winning objects, player should come near toward them. Figure 4.4 shows same level from Sokoban, where the distance between player and winning objects (crates and targets) is highlighted.

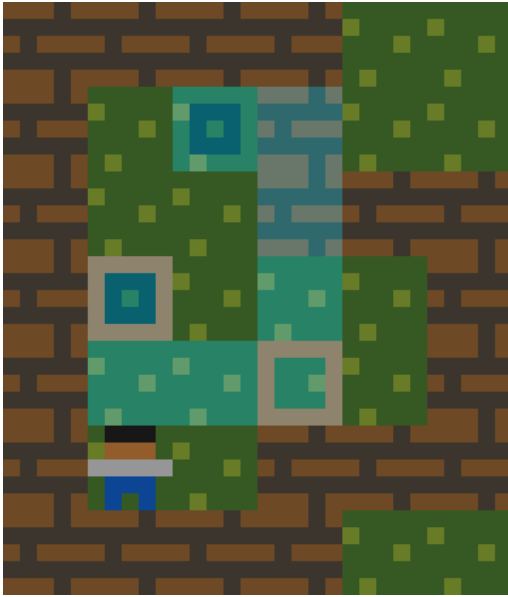


Figure 4.3: Example of distance between winning objects metric

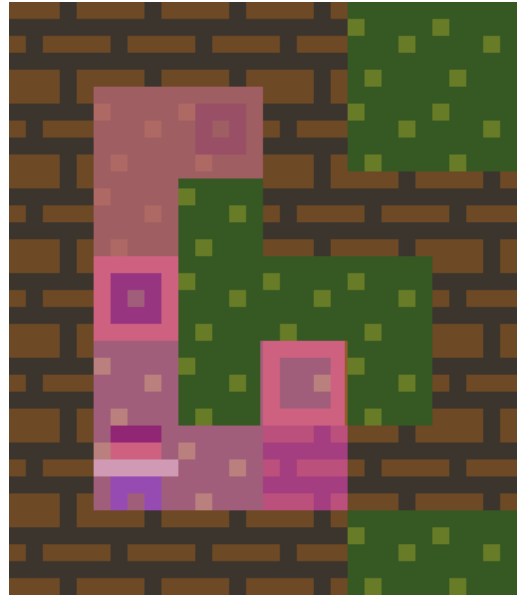


Figure 4.4: Example of distance between player and winning objects metric

That metric works fine for all games where player is not one of the winning objects. In that case, the two metrics behaves in the same way so the player always try to move towards goal regardless of other game objects. For example, Figure 4.5 shows a level from a game called LavaGame. LavaGame is a puzzle game where the goal is to make the player reaches the exit. The path to the exit is usually stuck by lava which can be destroyed by pushing a crate over it. According to the metrics, the player will try to move nearer to the exit by either going left. These movement will not help him to reach the goal, so the player will start wandering aimlessly trying to stumble about a sequence help him reach the goal.

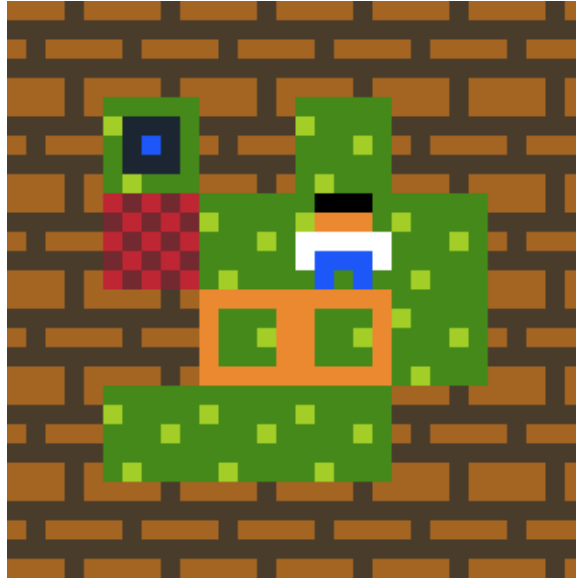


Figure 4.5: Example level from LavaGame showing the problem in the old metrics

Player's aim is to move crates towards lava to unblock his path towards the exit. This aim is somehow explained in the game rules, so by further analysis the game rules we can know which objects need to be closer. Returning to our example about LavaGame, the game rules are stated in the following order:

$$[> \text{Player} \mid \text{Crate}] \rightarrow [> \text{Player} \mid > \text{Crate}]$$

$$[> \text{Crate} \mid \text{Lava}] \rightarrow [\mid]$$

The first rule says if there is a player and crate beside each other and the player moves toward it, the crate will also move. The second rule says if there is a crate and lava beside each other and the crate moves toward it, both crate and lava will be destroyed. In any proper game, rules must be applied before achieving the winning condition. Based on that fact, the distance between objects on the left hand side of the rules must be decreased. The new heuristic is the distance between objects in the left hand side of the rules. The relation between objects in the left hand side of the rules is captured by the Rule Analyzer module.

The three metrics are weighted with respect to each other and used as a new function to evaluate each game state. The weights are chosen by experimentation to ensure best results. The automated player returns four different values that are analyzed and used in the Heuristic measures in the next section. These four values are:

- The score for the best reached state so far. The score is calculated using the first metric (Distance between winning objects). The score value is in range between [0, 1], where the score is equal 1 when a solution is found.
- The sequence of movements to reach the best state. The automated player saves up all the movement happens to reach each state.
- The number of states explored while searching for the solutions. The automated player increment a variable whenever it explore a new state.
- The number of rules that the game engine applied to reach the best state. The game engine increment a variable whenever any of the game rules is applied.

The modified BestFS find solution faster than before. More details will be expressed in Chapter 5.

4.1.3.2 Heuristic Measures

Heuristic Measure are calculated using a weighted function of six attributes. The function is described as the following:

$$F_{score} = 0.3 * P_{score} + 0.2 * L_{score} + 0.15 * N_{score} + 0.12 * B_{score} + 0.12 * R_{score} + 0.11 * E_{score}$$

where P_{score} is Playing Score, L_{score} is Solution Length Score, N_{score} is Object Number Score, B_{score} is Box Line Score, R_{score} is Applied Rule Score, and E_{score} is Exploration Score. The weights for each attribute are measured experimentally to reflect the importance of some features with respect to the others.

- **Playing Score (P_{score}):** Playing score is used to ensure playability of the level. Instead of using a boolean value for playable or not. Score is assigned a value for how much you are near the solution. Automated player is used to play the game and return a value from $[0, 1]$ where 0 means there is no objects at all, while 1 which means the agent reached the solution. Making the domain more continuous helps in measuring the percentage of the level playability. Instead of using it as a constraint to be satisfied.

Based on the work by Nielsen et al.[32] which proved that Do Nothing player is an important measure for good designed games. A score is calculated for the initial level state and subtracted from the result of the automated player. The heuristic measure can be expressed by the following equation:

$$P_{total} = P_{score} - N_{score}$$

where P_{score} is the automated player score and N_{score} is the Do Nothing player score.

- **Solution Length Score (L_{score}):** Figure 4.2 shows that interesting levels usually have more steps than trivial ones. The first idea was to use the length of best movement sequence the automated player has reached and compare it with a required value. This idea will not work as expected because solution length depends on the size of the level. For example, Figure 4.6 shows different levels from Sokoban and the corresponding solution length. Its obvious that the seconds level have longer solution length than the first one because it have huger area.

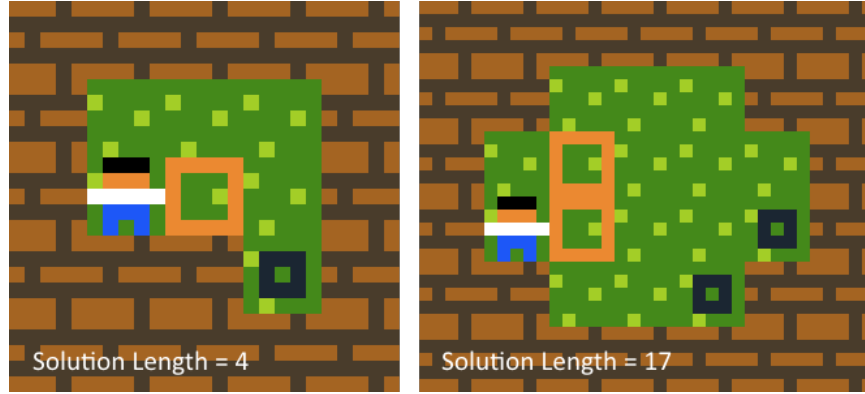


Figure 4.6: Examples of two sokoban levels with different area and solution lengths

From the previous example we can conclude that the solution length depends on the level area. Instead of using the solution length as the metric we used the ratio between the solution length and the level area. A mapping function is need to convert that number to a value in the range $[0, 1]$. We analyzed 40 hand crafted levels with different area from 5 different games. A histogram is plotted on the collected values of the ratio between the solution length and the level area.

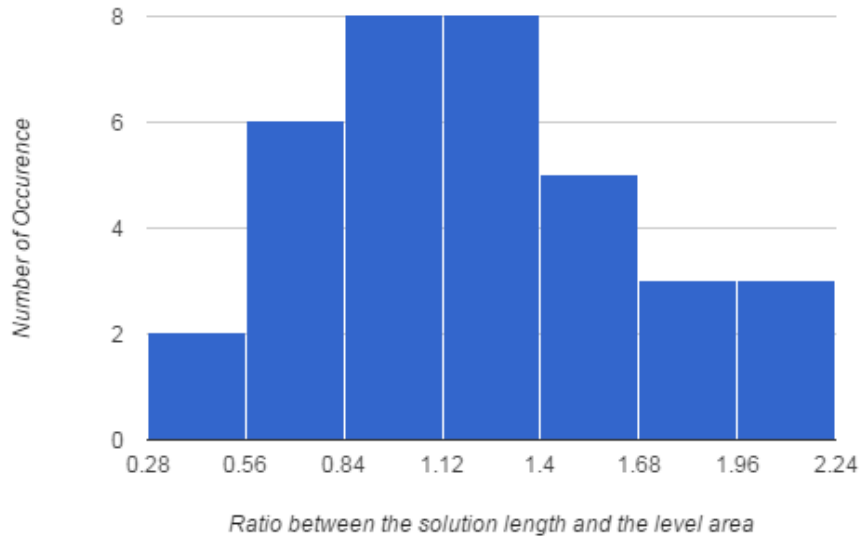


Figure 4.7: Histogram for the ratio between the solution length and the level area

The histogram in Figure 4.7 seems to follow a Normal Distribution with $\mu = 1.221$ and $\sigma = 0.461$. Based on that, the Solution Length Score is expressed by the following equation:

$$L_{score} = Normal\left(\frac{L}{A}, 1.221, 0.461\right)$$

where $Normal(ratio, \mu, \sigma)$ is a normal distribution, L is the solution length score, and A is the level area.

- **Object Number Score (N_{score}):** It is divided into 3 parts:
 - **Number of Rule Objects:** In a good designed level, most of the rule objects should appear in the level to ensure there is a possibility of applying each rule. The minimum number of times the object should appear in the level must be greater than or equal his minimum number property from Rule Analyzer.
 - **Number of Players:** The game should have only one player. If the level have any other value, this part pf the score will be zero.
 - **Number of Winning Objects:** The number of the winning objects should be equal, unless one of the winning objects have "Create" behavior. Based on the previous condition, the score is set either to one or zero.

Object Number Score is calculated using the following equation:

$$N_{score} = 0.4 * N_{rule} + 0.3 * N_{player} + 0.3 * N_{winning}$$

where N_{rule} is the Number of Rule Objects, N_{player} is the Number of Players, and $N_{winning}$ is the Number of Winning Objects.

- **Box Line Score (B_{score}):** It is similar to Taylor and Parberry[57] metric used to find the farthest state. This metric calculates the number of unrepeated moves found in the solution and divide it by total length of the solution. The following equation represents the metric:

$$B_{score} = \frac{L_{unique}}{L}$$

where L_{unique} is the number of unrepeated moves in the solution and L is the solution length.

- **Applied Rule Score (R_{score}):** Good level design involves applying game rules number of times to solve a level. The ratio between number of applied rules and solution length should be used for indicting good level design. Exaggerating in applying the rules results in boring level. Same can be said for very low amount of applying. Figure 4.8 shows two levels from Sokoban with different solution. The left level needs to apply Sokoban rule one time to solve the level, while the right needs to apply Sokoban rule with every step.

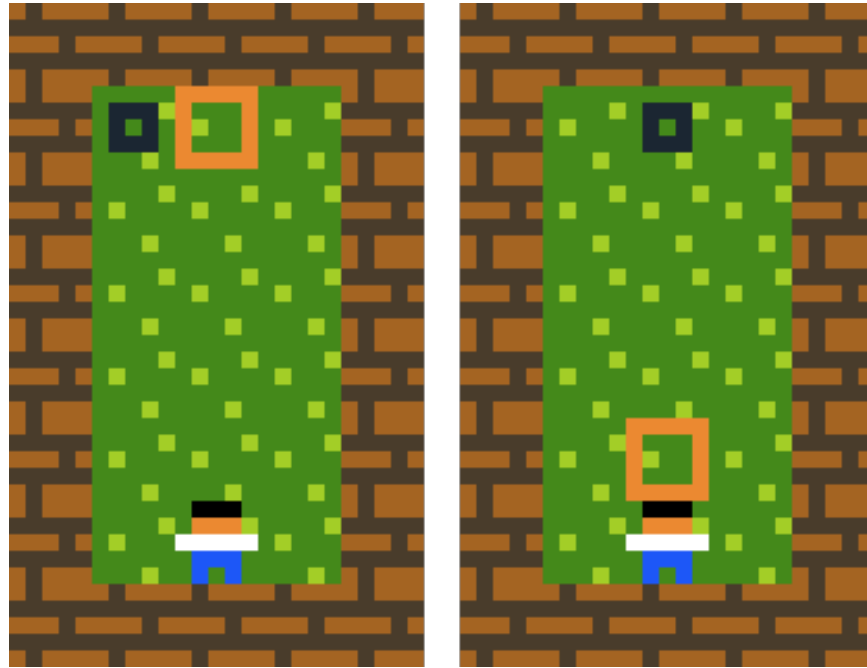


Figure 4.8: Example for two boring levels from Sokoban

To get the calculate the best ratio, We analyzed 40 hand crafted levels with different area from 5 different games. A histogram is plotted on the collected values of the ratio between the number of rules applied and the solution length.

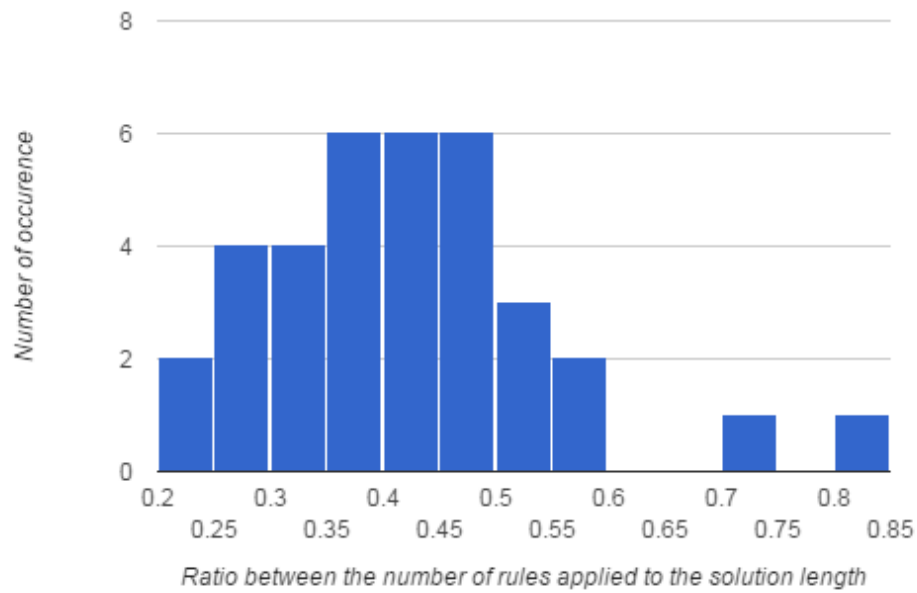


Figure 4.9: Histogram for the number of rules applied to the solution length

The histogram in Figure 4.9 seems to follow Normal Distribution with $\mu = 0.417$ and

$\sigma = 0.128$. Based on that the Applied Rule Score can be expressed by the following equation:

$$R_{score} = Normal(\frac{R_{applied}}{L}, 0.417, 0.128)$$

where $Normal(ration, \mu, \sigma)$ is a normal distribution, $R_{applied}$ is the number of applied rules, and L is the solution length.

- Exploration Score (E_{score}):** As the number of explored states increase before reaching goal state this means the level solution is not obvious with the general heuristic. This does not mean exploring huge space without finding a solution is better than exploring small number of states with solution. The following equation express this idea:

$$E_{score} = \begin{cases} 0.75 + \frac{N_{explored}}{N_{max}} & \text{solution exists} \\ 0.5 & \text{no solution and } N_{explored} = N_{max} \\ 0 & \text{no solution and } N_{explored} < N_{max} \end{cases}$$

where $N_{explored}$ is the number of explored states and N_{max} is the maximum number of states the automated player can explore.

4.2 Rule Generation

4.2.1 Chromosome Representation

4.2.2 Fitness Function

Table 4.2

Table 4.1 demonstrates

Table 4.1: Example table for demonstration

Table 4.3.

xxxx	1233	cccc
uuuuu	2323	gggggg

Table 4.2: Example table for demonstration

Table 4.3: Another example wide table for demonstration

[illegible]

Chapter 5: Results and Evaluation

In this research, the common industrial problem of As extension to this work, the following points are recommended for the future work;

5.1 Data Description

5.2 Level Generation Problem

5.3 Rule Generation Problem

Chapter 6: Conclusion

In this research, the common industrial problem of As extension to this work, the following points are recommended for the future work;

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