**CS2106 Introduction to Operating Systems**

**Lab 3**

**Answer Book**

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**Part 1**

Question 1.1 (1 mark)

All the “<some number> I am child X” appears before most of the numbers as each child process blocks when it calls “usleep(250000);” which allows a child process created later to print its “<some number> I am child X”. Also, “fflush(stdout);” is called before “usleep(250000);” which causes the 1 number from “printf("%d ", j);” stored in the output buffer of stdout (stream) to be flushed (need since printing without ‘\n’) so all the “<some number> I am child X” appears before most of the numbers instead of all of the numbers.

This suggests that the time quantum is longer than the total time needed to call “printf("I am child %d\n", i);”, “printf("%d ", j);” and “fflush(stdout);” in succession.

The interleaving happens due to the combination of “printf("%d ", j);”, “fflush(stdout);” and “usleep(250000);” called in succession which causes a number to be printed to the screen from each child process before it blocks and gives up the CPU due to usleep.

The operating system’s scheduling affects the interleaved order of output.

Question 1.2 (1 mark)

The lock variable is not atomic, meaning any operation involving the lock variable can be interrupted. Hence trying to use it as a synchronization mechanism will fail and a race condition will still occur.

Question 1.3 (1 mark)

Step 1:

I created the shared variable “turn” and initialized it to 0 at the start of main().

Step 2.1:

I added “while(turn[0] != i);” above “break;” in the loop used to create processes.

Step 2.3:

I added “turn[0] = turn[0] + 1;” as the last statement to execute in the if-block for “pid == 0”.

Extra Step:

I added code to detach and free the shared variable “turn” as the last statements to execute in the else-block for “pid == 0”.

Turn variables might be less efficient of multi-core systems due to busy waiting occurring on each core from checking the turn variable every frame, wasting CPU cycles per core which could have been used to make progress in other computations.

Question 1.4 (1 mark)

sem\_init params (from left to right):

1st param (pass in address of the semaphore to initialize)

2nd param (pass in 0 for semaphore shared between threads of a process or non-0 for semaphore shared between processes)

3rd param (pass in value to initialize semaphore with)

sem\_wait param:

1st param (pass in address of semaphore, value of semaphore is decremented if it is non-0 and call blocks if value of semaphore is 0 until it becomes non-0 or a signal handler interrupts the call)

sem\_post param:

1st param (pass in address of semaphore, value of semaphore is incremented, resulting value is non-0 if no threads or processes were blocked waiting for semaphore to be unlocked or 0 if a thread or process was unblocked and allowed to return from sem\_wait)

Question 1.5 (1 mark)

Since the semaphore is not part of shared memory, when the child process calls sem\_wait, it will block indefinitely as the semaphore has the value of 0 on initialization. Since the parent process calls wait and the child process never exits, the parent process will also be blocked indefinitely, causing the program to hang.

Question 1.6 (1 mark)

To start, code to declare and initialize (value of 0 for all semaphores) an array of semaphores and an array of shmIds was added at the start of main() before the loop where the child processes were created.

During the creation of the child processes, in the if-block for “(pid = fork()) == 0”, the line “sem\_wait(semaphoreArr[i]);” was added before “break;” for all child processes to block since at this point, all the semaphores have the value of 0.

In the else-block of “pid == 0”, the line “sem\_post(semaphoreArr[i]);” was added before “wait(NULL);” in the for loop to unlock the semaphore for each child sequentially then the “wait(NULL);” is left there for the parent process to wait for the child process that is currently running to finish executing before unlocking the semaphore for the next child.

Finally, also in the else-block of “pid == 0”, code for destroying all semaphores, detaching all shared memories and freeing all shared memories was added after the aforementioned loop.

More processes will mean more shared memory usage with more semaphores since it is currently 1 semaphore per process, leading to a large overhead. Also, more processes cannot be added dynamically now due to the fixed-sized array of semaphores and shmIds used. Therefore, current implementation has poor overall scalability.

To rectify this, I would probably modify the code such that all processes will use 1 shared semaphore instead through shared memory.

**Part 2**

Question 2.1 (1 mark)

static int processTotalCount; //nproc

static int processCurrCountShmId; static int\* processCurrCountPtr; //count

static int mutexShmId; static sem\_t\* mutexPtr;

static int turnstile0ShmId; static sem\_t\* turnstile0Ptr;

static int turnstile1ShmId; static sem\_t\* turnstile1Ptr;

void init\_barrier(int num\_proc) {

processTotalCount = num\_proc; //Init processTotalCount (not updated by processes so not shm)

///Init processCurrCount (shm as shared between processes)

processCurrCountShmId = shmget(IPC\_PRIVATE, sizeof(int), IPC\_CREAT | 0600);

processCurrCountPtr = shmat(processCurrCountShmId, NULL, 0);

\*processCurrCountPtr = 0; //Init to 0

///Init mutex (for operations involving processCurrCountPtr)

mutexShmId = shmget(IPC\_PRIVATE, sizeof(sem\_t), IPC\_CREAT | 0600);

mutexPtr = (sem\_t\*)shmat(mutexShmId, NULL, 0);

sem\_init(mutexPtr, 1, 1); //Init to 1 (need to let 1 process through for operations involving processCurrCountPtr so init to 1)

///Init turnstile0 (for reusable barrier)

turnstile0ShmId = shmget(IPC\_PRIVATE, sizeof(sem\_t), IPC\_CREAT | 0600);

turnstile0Ptr = (sem\_t\*)shmat(turnstile0ShmId, NULL, 0);

sem\_init(turnstile0Ptr, 1, 0); //Init to 0 (need all processes to block on this semaphore before last process arrives so init to 0)

///Init turnstile1 (for reusable barrier)

turnstile1ShmId = shmget(IPC\_PRIVATE, sizeof(sem\_t), IPC\_CREAT | 0600);

turnstile1Ptr = (sem\_t\*)shmat(turnstile1ShmId, NULL, 0);

sem\_init(turnstile1Ptr, 1, 1); //Init to 1 (last process will wait on this semaphore so must init to 1 so it becomes 0 when waited then all other processes will block on it)

}

Question 2.2 (1 mark)

**Part 3**

Question 3.1 (1 mark)

Question 3.2 (1 mark)

Question 3.3 (1 mark)

**TOTAL:** \_\_\_\_\_\_ / 11