

SC2001/ CX2101: Algorithm Design and Analysis

Week 11

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Another example of the longest path problem not satisfying the principle of optimality

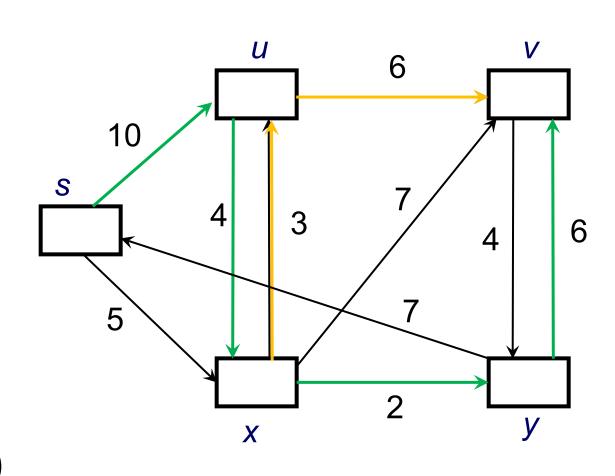
The longest path from s to v is

$$s -> u -> x -> y -> v$$

The longest path from x to v?

Why?

Note, the longest path means the longest simple path (path with no cycle)



The solution to the problem of the longest path from s to v includes the solutions of 2 subproblems: from s to x and from x to v.

U

X

3

10

S

6

The longest path for the subproblem from x to v passes through a vertex which appears in the path from s to x

Summary: Greedy vs DP

A greedy strategy for coin change problem

Example: Making Change

Problem: A country has coins with denominations

$$1 = d_1 < d_2 < \cdots < d_k$$
.

You want to make change for n cents, using the smallest number of coins.

Example: U.S. coins

$$d_1 = 1$$
 $d_2 = 5$ $d_3 = 10$ $d_4 = 25$

Change for 37 cents - 1 quarter, 1 dime, 2 pennies.

What is the algorithm?

A greedy strategy for coin change problem

```
c = 0;
While (n> 0) {
   c++;
   n = n - value of the highest valued coin that is <= n;
}
Return c;  // O(n)</pre>
```

An even faster version of the greedy approach is

```
1. a_1 = \lfloor n/d_k \rfloor, n = n - a_1 * d_k

2. a_2 = \lfloor n/d_{k-1} \rfloor, n = n - a_2 * d_{k-1}

3. ...

// O(k), or O(1) if k is a known constant
```

A greedy strategy for coin change problem

Works for many cases, e.g. to change for 37 cents,

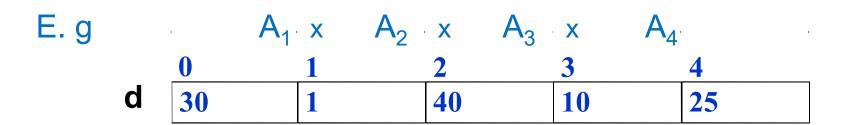
$$d_1 = 1$$
 $d_2 = 5$ $d_3 = 10$ $d_4 = 25$

The answer is optimal: one 25¢, one 10¢, two 1¢

 but fails for cases like d ={1, 10, 25} and we want to change 30 cents

A Greedy Method for chain matrix multiplication

1. use an array to record the dimensions.

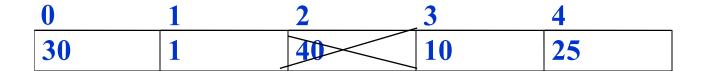


2. choose the multiplication of two matrices whose cost is the minimum at each step:

First, min(30x1x40, 1x40x10, 40x10x25) \Rightarrow 1x40x10 is the minimum. So A₂x A₃ first:

0	1	2	3	4
30	1	40	10	25

A Greedy Method for chain matrix multiplication



Second, min(30x1x10, 1x10x25) \Rightarrow 1x10x25 is the minimum. So $(A_2x A_3)x A_4$

0	1	2	_3	4
30	1	40	10>	25

Last: 30x1x25: $A_1((A_2x A_3)x A_4)$

Total: 1x40x10 + 1x10x25 + 30x1x25 = 1400

Works in most cases except some sequences of 3 matrices (i.e. 2 matrix multiplications) e.g.

 $A_1x A_2x A_3 : 10x1x10x15 \Rightarrow 10x1x10 + 10x10x15$

Another Greedy Method for chain matrix multiplication

1. use an array to record the dimensions.

E.g
$$A_1 \times A_2 \times A_3 \times A_4$$

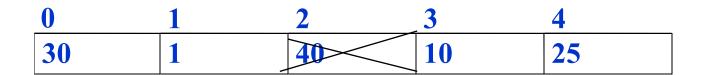
0 1 2 3 4
d 30 1 40 10 25

2. choose the multiplication of two matrices whose resulting matrix has minimum dimension at each step:

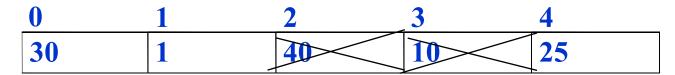
First, min(30x40, 1x10, 40x25) \Rightarrow 1x10 is the minimum. So A₂x A₃ first:

0	1	2	_3	4
30	1	40	10	25

Another Greedy Method for chain matrix multiplication



Second, min(30x10, 1x25) \Rightarrow 1x25 is the minimum. So (A₂x A₃)x A₄



Last: 30x25: $A_1((A_2x A_3)x A_4)$

Total: 1x40x10 + 1x10x25 + 30x1x25 = 1400

Works in most cases but not for this (question in the tutorial T4Q5)

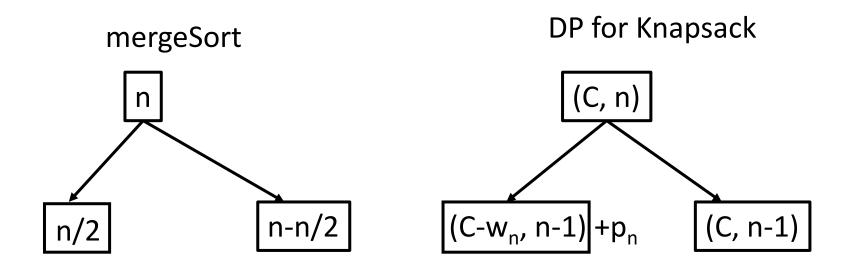
 $A_1x A_2x A_3x A_4 : A_1x (A_2x (A_3x A_4)) \Rightarrow 2680 (1680 by DP)$

Summary: Greedy vs DP

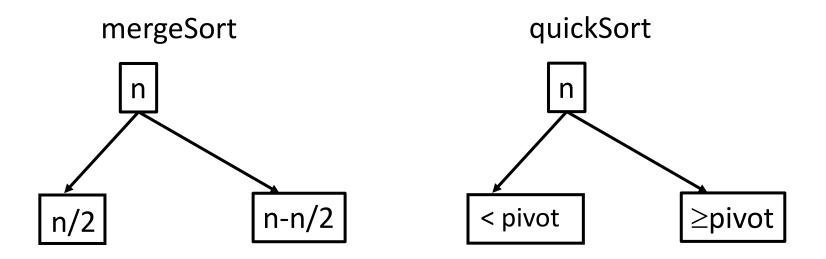
- DP is an optimization technique
- Both build solutions through a sequence of individual steps
- Both make a selection out of a collection of choices at each step
- At each step, the greedy method computes its locally optimal choice one after another and never revises any choices made – optimal solution not guaranteed, but many problems do get the optimal solution
- At each step, DP computes its solution by trying all choices before it arrives at the optimal choice

- Greedy heuristic algorithms are often used to solve problems because of its simplicity.
- Typically, DP algorithms are more expensive than greedy algorithms
- So DP is used only when no greedy strategy can be found to deliver the optimal solution

 Both techniques divide their problems into subproblems, find subsolutions to the subproblems, and synthesize larger solutions from smaller ones.

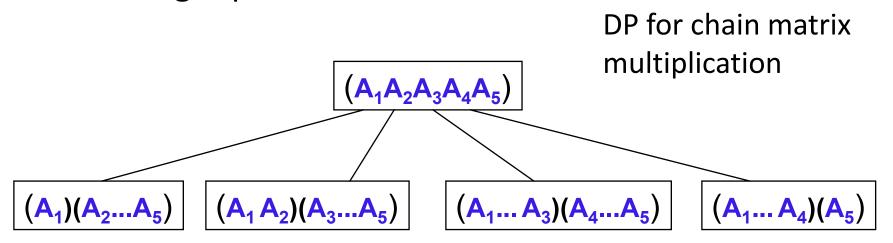


 Divide and Conquer divides a problem at prespecified deterministic points (e.g., always in the middle), combine the subsolutions to obtain the solution to a larger problem



Divide at deterministic point

 For optimization problems, DP divides a problem at every possible split points rather than at a prespecified points. After trying all split points, it determines which split point is optimal. The subsolution at the split point is part of the solution to a larger problem



Divide at all possible split point