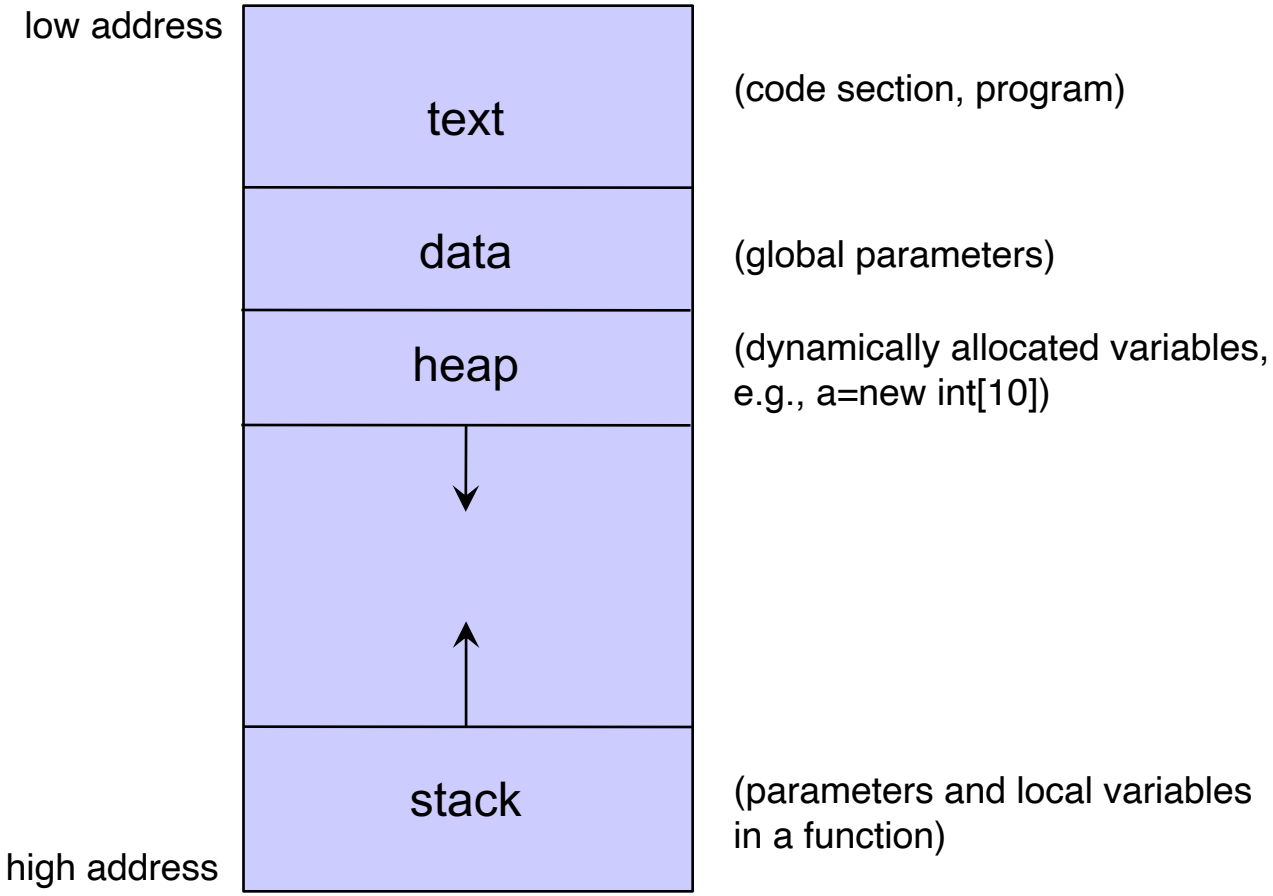
Week 8

Part 7: Memory Organization

- Bind Code and Data to Memory
  - address binding, logical versus physical address space
- Contiguous Allocation
  - fixed vs. dynamic partitioning, fragmentation
- Paging
  - address translation, page table implementation, shared pages, two-level page-table, inverted page table
- Segmentation
  - address translation

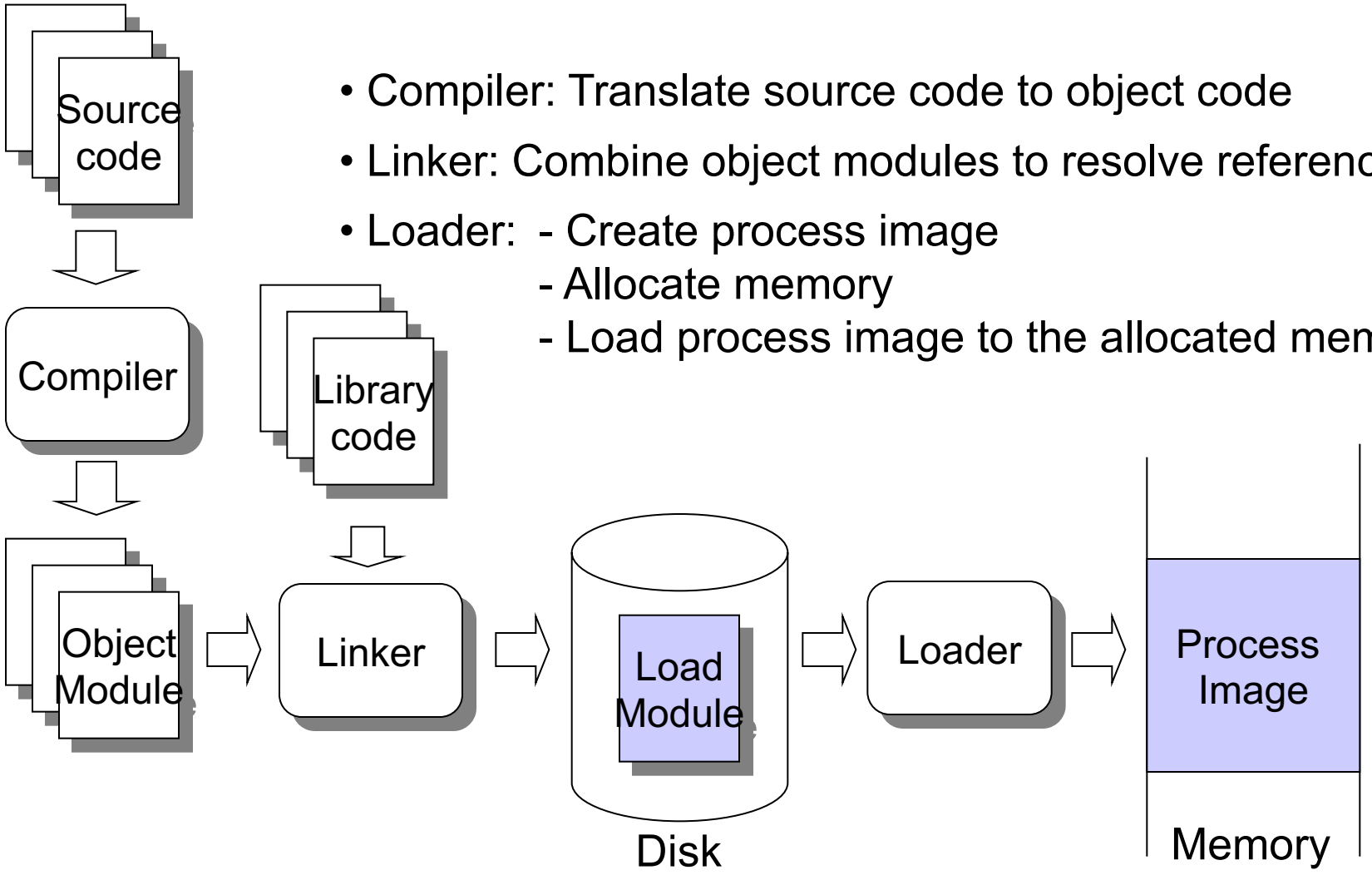
Bind Code and Data to Memory

- To run a program, a process image must be created and loaded into memory

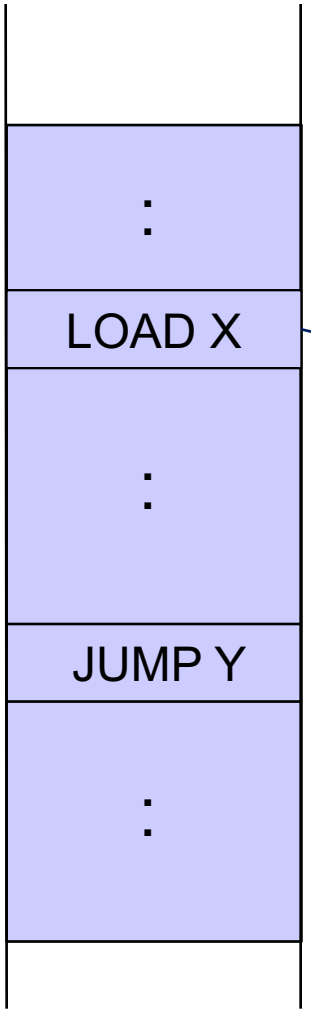


Binding of Code and Data to Memory (Cont.)

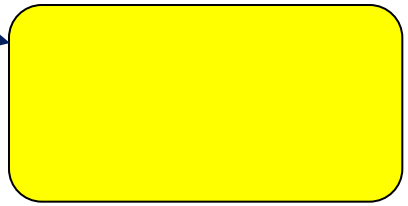
- Compiler: Translate source code to object code
- Linker: Combine object modules to resolve references
- Loader: - Create process image
  - Allocate memory
  - Load process image to the allocated memory



Binding of Code and Data to Memory (Cont.)



- Instruction needs to be fetched from memory



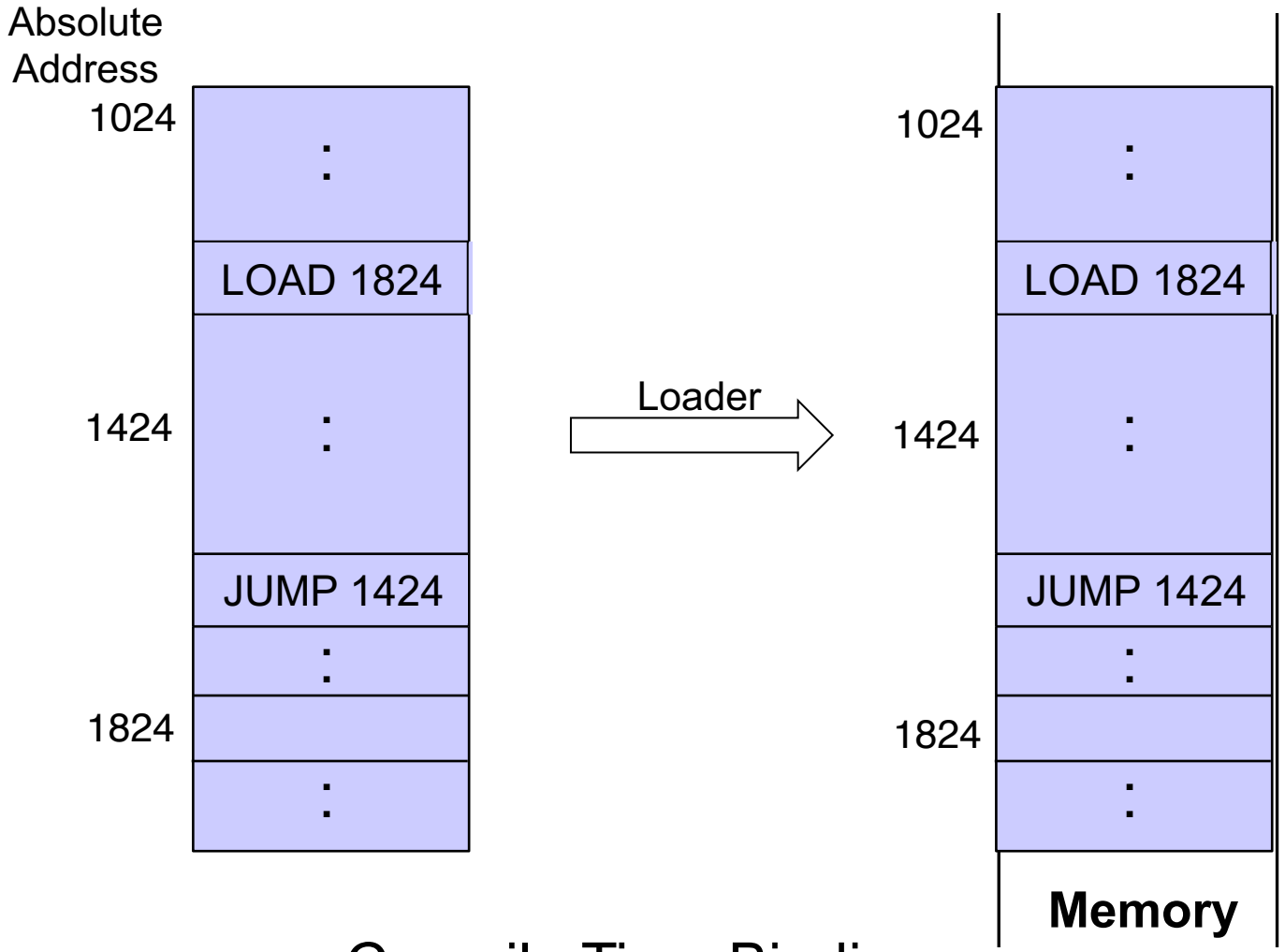
- Execute an instruction may again require to access memory
- Can address X be used to load data?

Binding of Code and Data to Memory (Cont.)

Address binding of instructions and data to memory addresses can happen at three different stages.

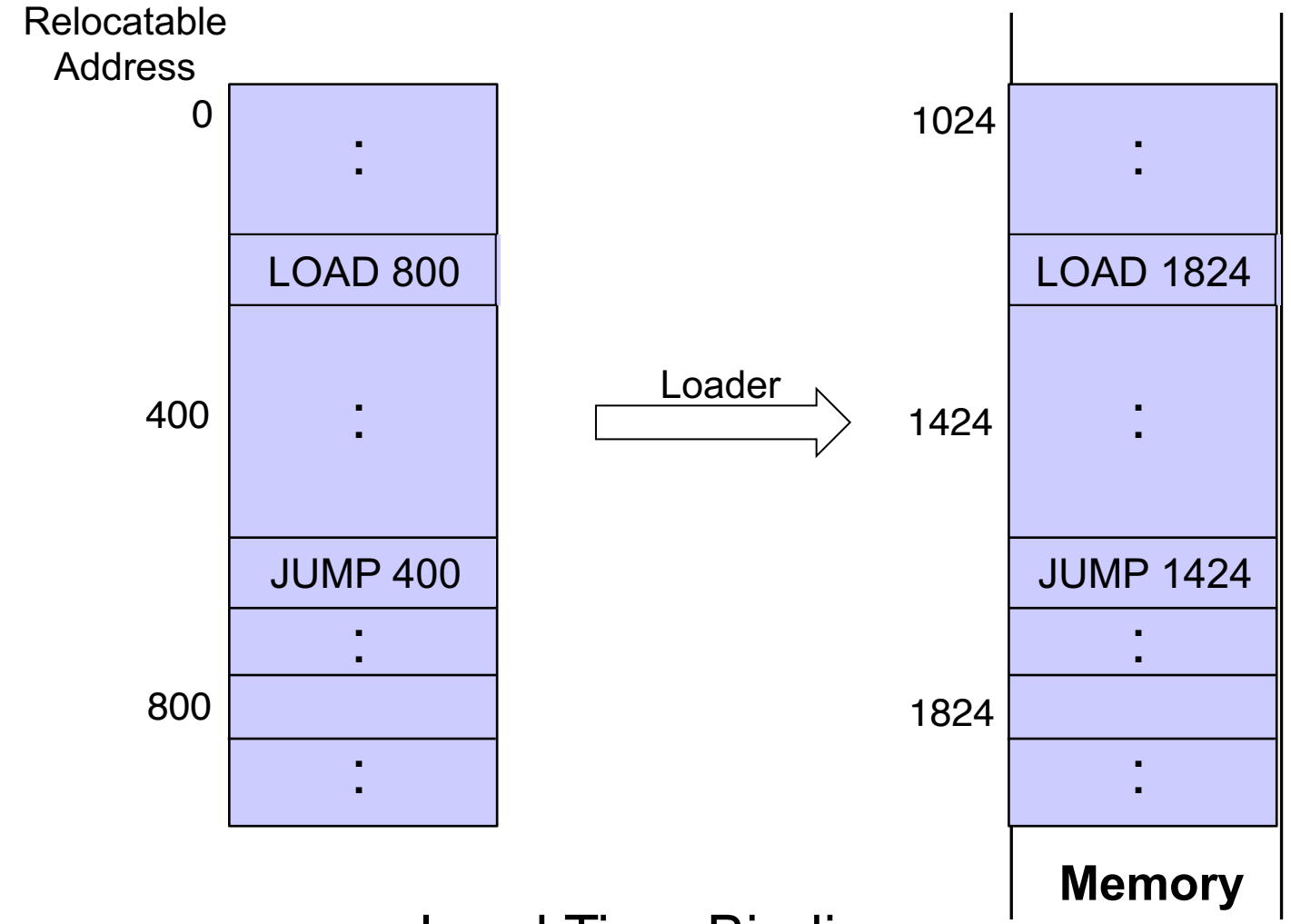
- **Compile time**: If memory location known a priori, *absolute code* can be generated; must recompile code if starting location changes.
- **Load time**: Compiler generates *relocatable code*. Binding is performed by the loader.
- **Execution time**: If the process can be moved during its execution from one memory segment to another, binding is delayed until run time.

Binding of Code and Data to Memory (Cont.)



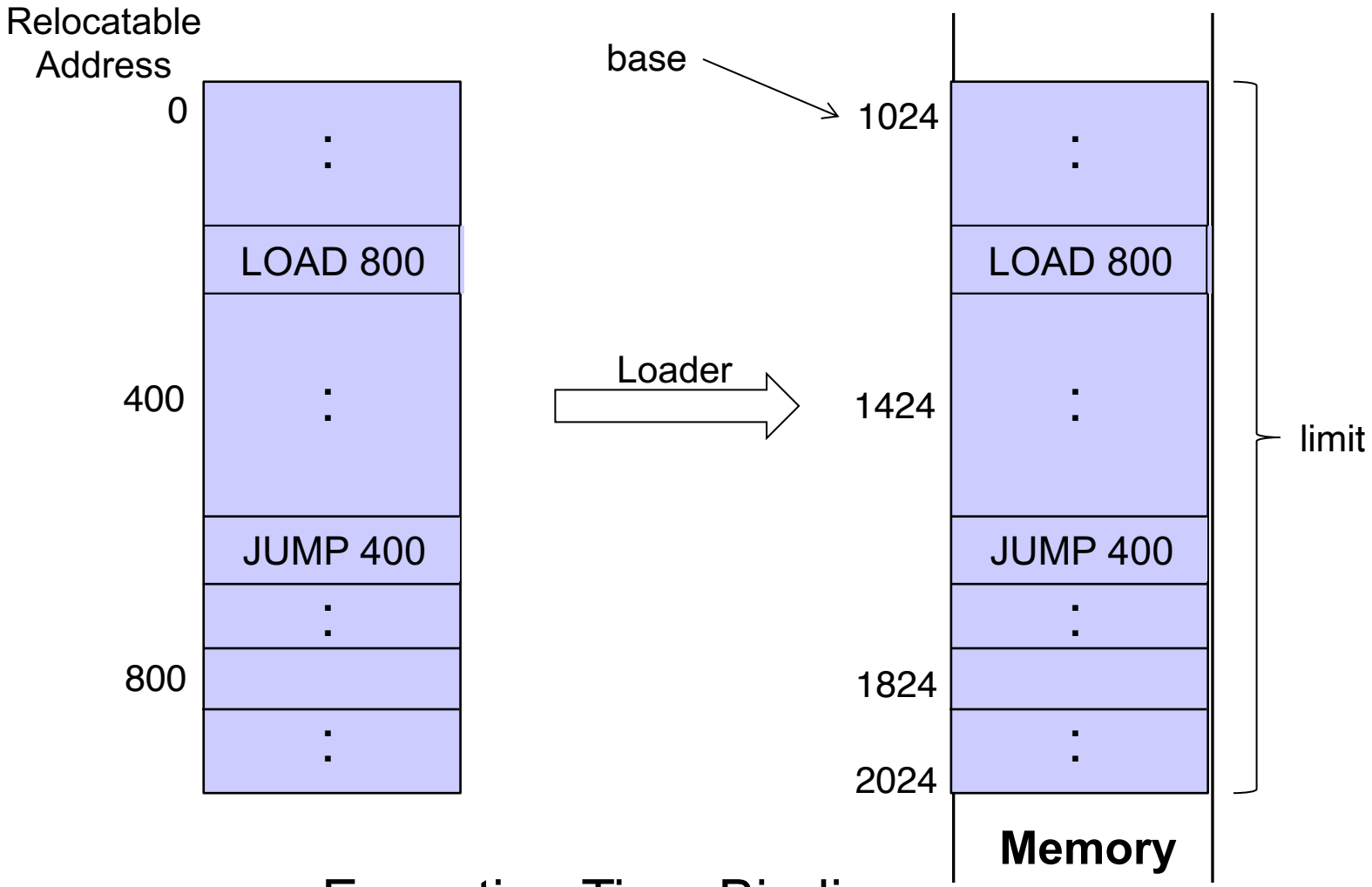
Compile Time Binding

Binding of Code and Data to Memory (Cont.)



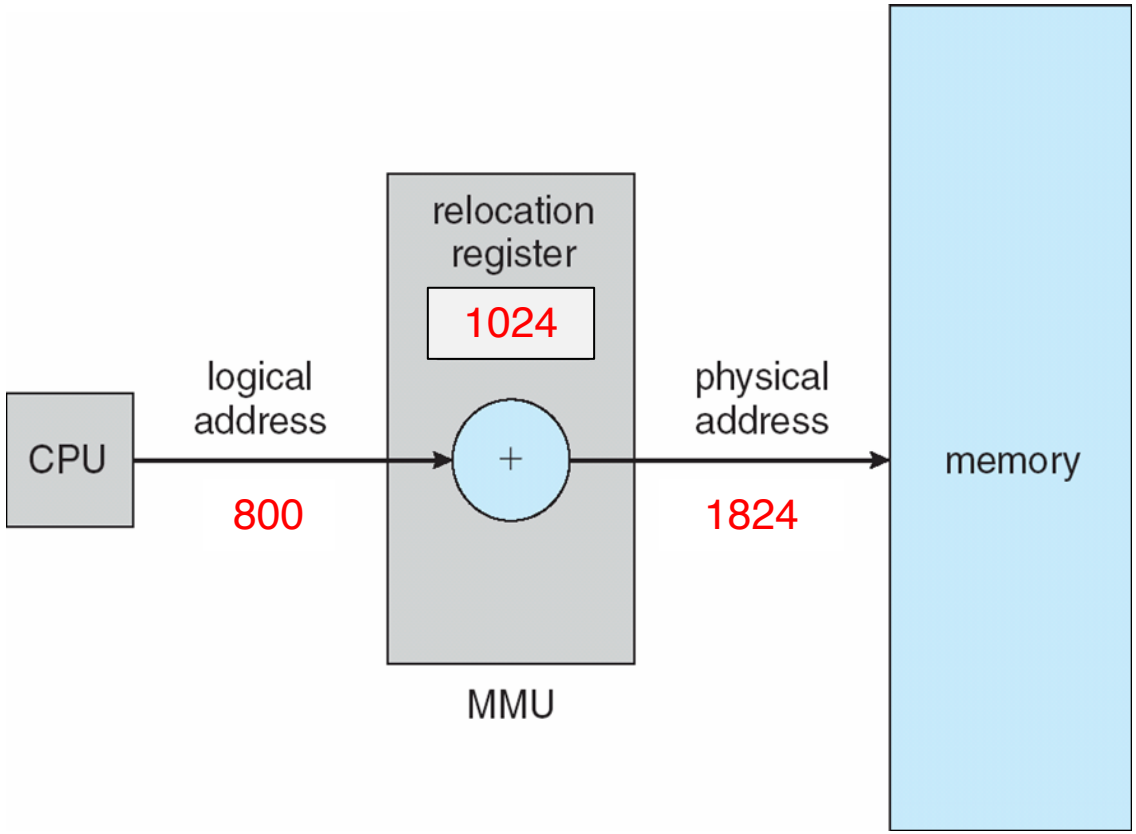
Load Time Binding

Binding of Code and Data to Memory (Cont.)



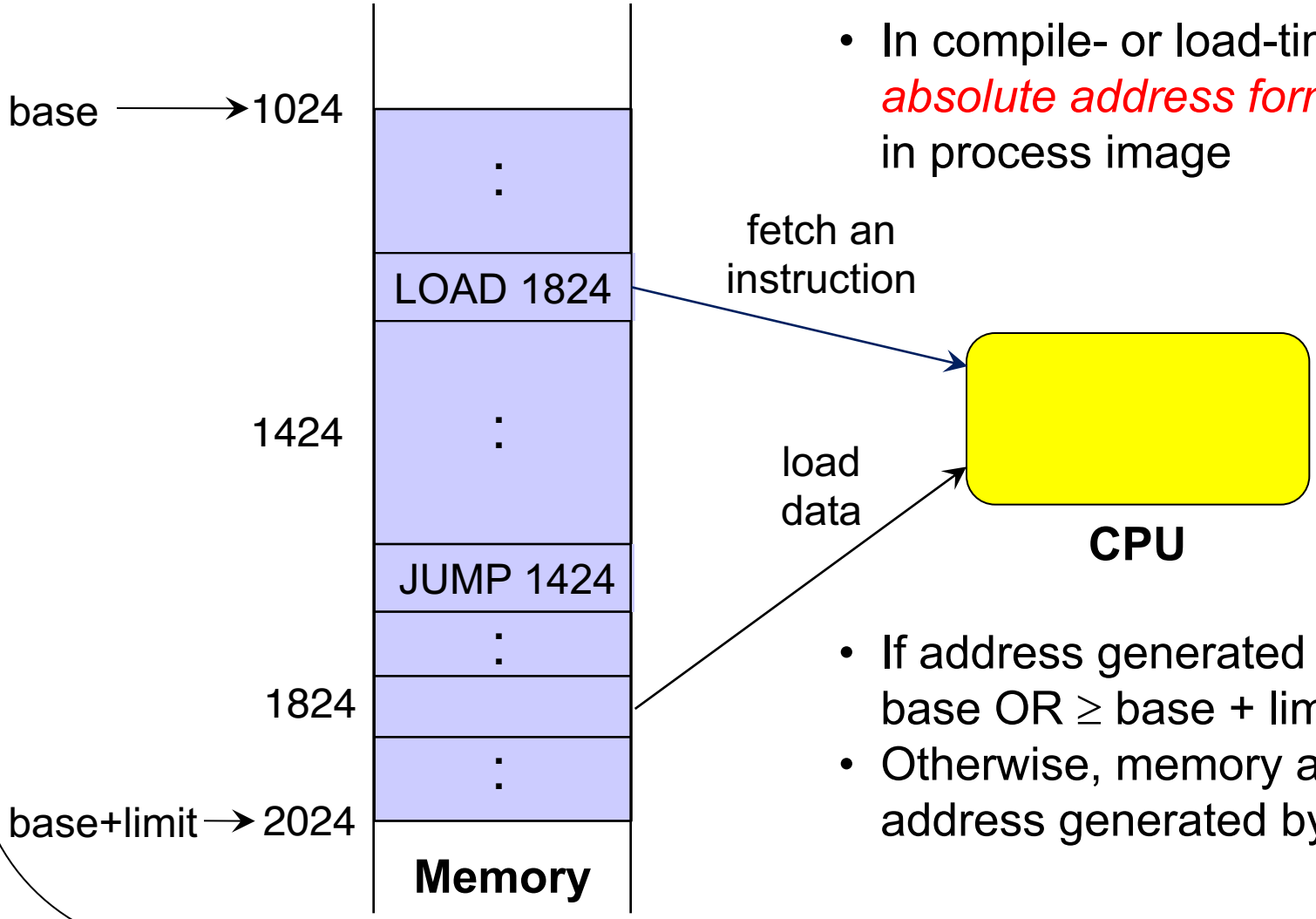
Execution Time Binding

Binding of Code and Data to Memory (Cont.)



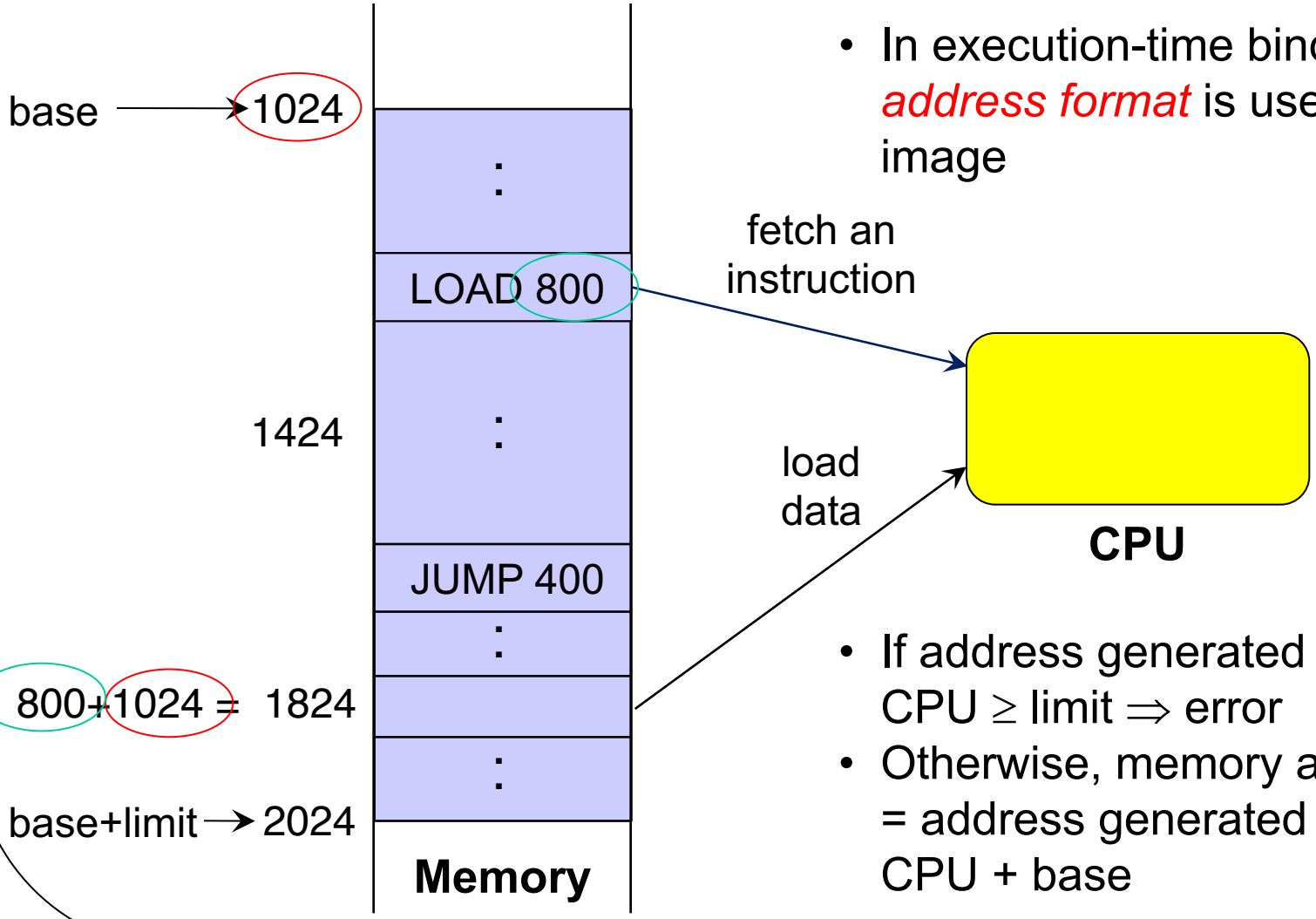
Execution Time Binding

Binding of Code and Data to Memory (Cont.)



- In compile- or load-time binding, *absolute address format* is used in process image
- If address generated by CPU < base OR ≥ base + limit ⇒ error
- Otherwise, memory address = address generated by CPU

Binding of Code and Data to Memory (Cont.)



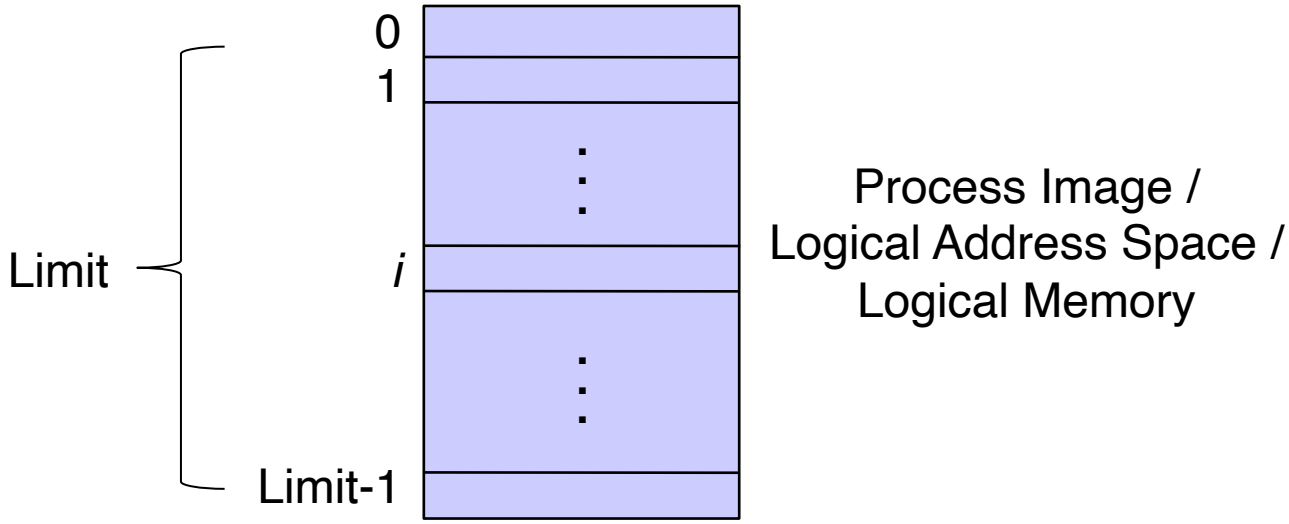
- In execution-time binding, *relative address format* is used in process image
- If address generated by CPU ≥ limit ⇒ error
- Otherwise, memory address = address generated by CPU + base

Logical vs. Physical Address Space

- *Address Space* – all addresses accessible by a process
- *Logical address* – address used in the code, generated by the CPU when executing an instruction.
- *Physical address* – address used to access physical memory, seen by the memory unit.

Logical vs. Physical Address Space

- Logical address space can be viewed as a linear, or one-dimensional, continuous address space consisting of a sequence of bytes
- For execution time binding, logical address space always starts from 0.



How to Allocate Memory among Processes

- Two approaches:
  - *Contiguous Allocation*

    The logical address space of a process remains contiguous in physical memory
    - ✳ Fixed Partitioning
    - ✳ Dynamic Partitioning

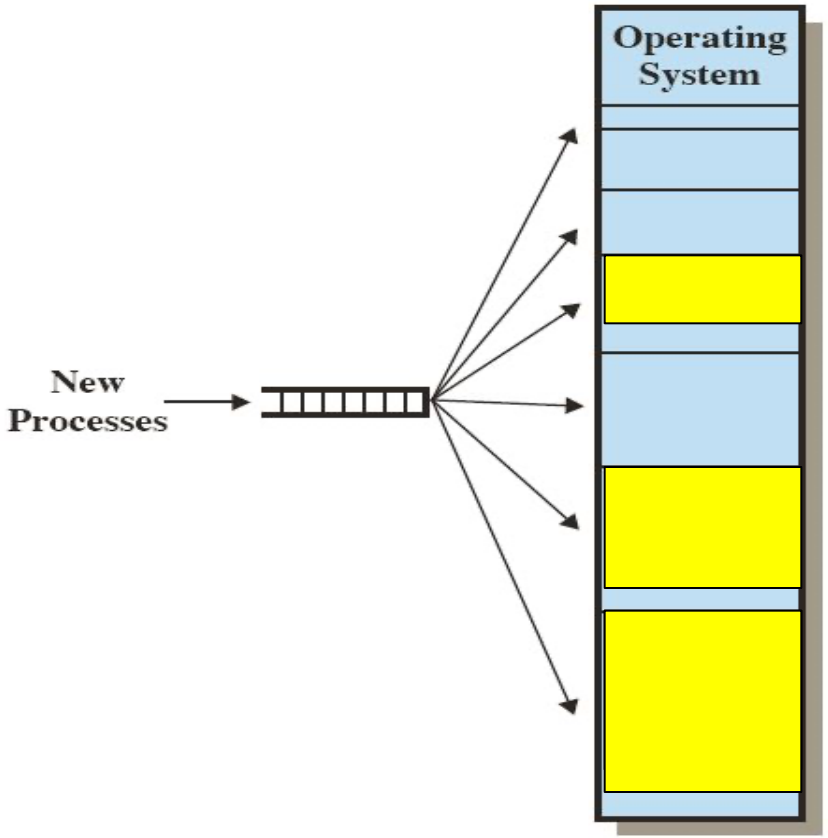
  - *Non-contiguous Allocation*

    A process logical address space is scattered over different regions in physical memory

Contiguous Allocation

- *Fixed Partitioning*

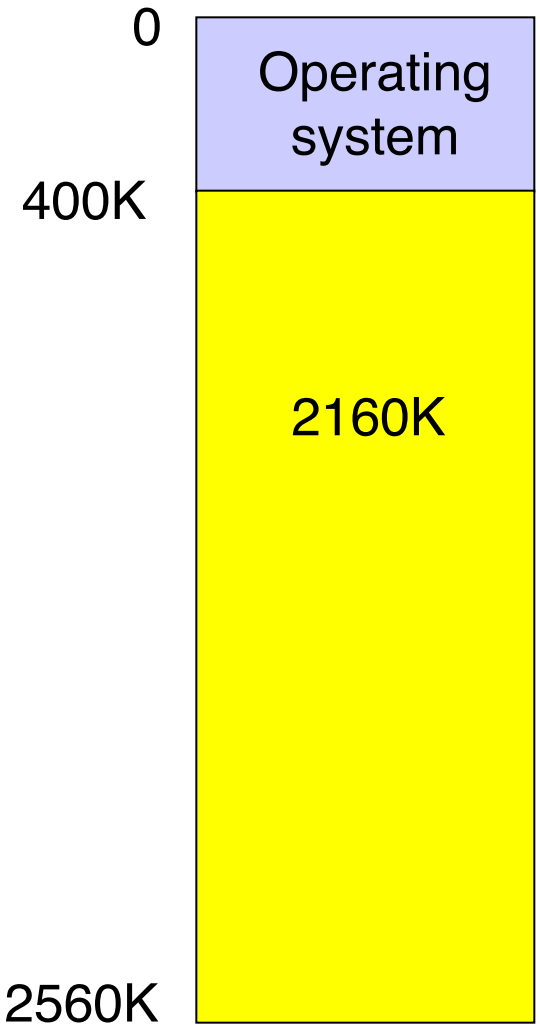
  Memory is partitioned into regions with fixed boundaries



Contiguous Allocation (Cont.)

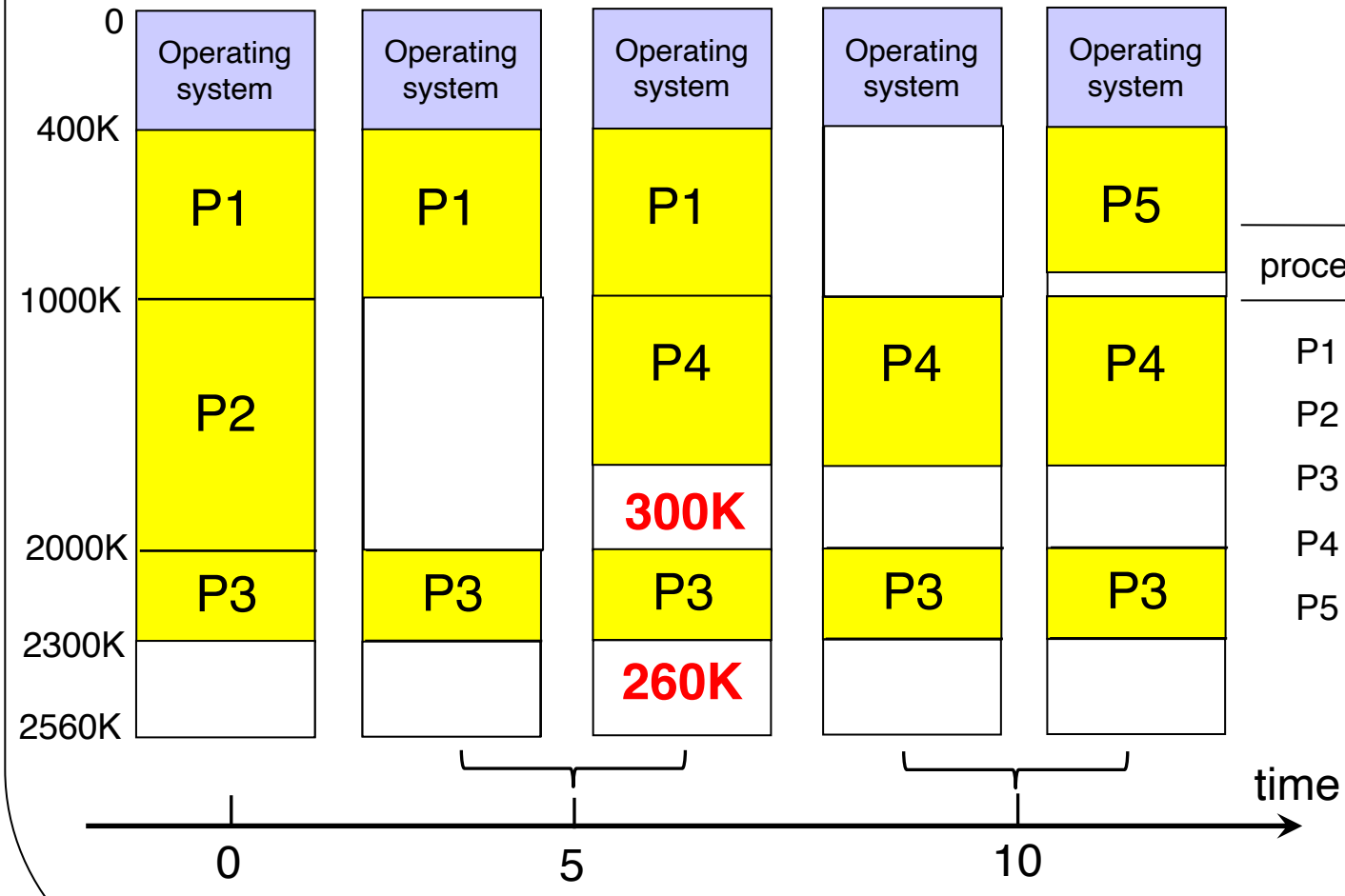
- *Dynamic Partitioning*
  - *Hole* – block of available memory; holes of various size are scattered throughout memory.
  - When a process arrives, it is allocated memory from a hole large enough to accommodate it.
  - Operating system maintains information about
    - allocated partitions
    - free partitions (hole)

Contiguous Allocation (Cont.)



Job queue		
process	memory	time
P1	600K	10
P2	1000K	5
P3	300K	20
P4	700K	8
P5	500K	15

Contiguous Allocation (Cont.)



Job queue

process	memory	time
P1	600K	10
P2	1000K	5
P3	300K	20
P4	700K	8
P5	500K	15

Dynamic Storage-Allocation Problem

How to satisfy a request of size *n* from a list of free holes.

- **First-fit**: Allocate the *first* hole that is big enough.
- **Best-fit**: Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size. Produces the smallest leftover hole.
- **Worst-fit**: Allocate the *largest* hole; must also search entire list. Produces the largest leftover hole.

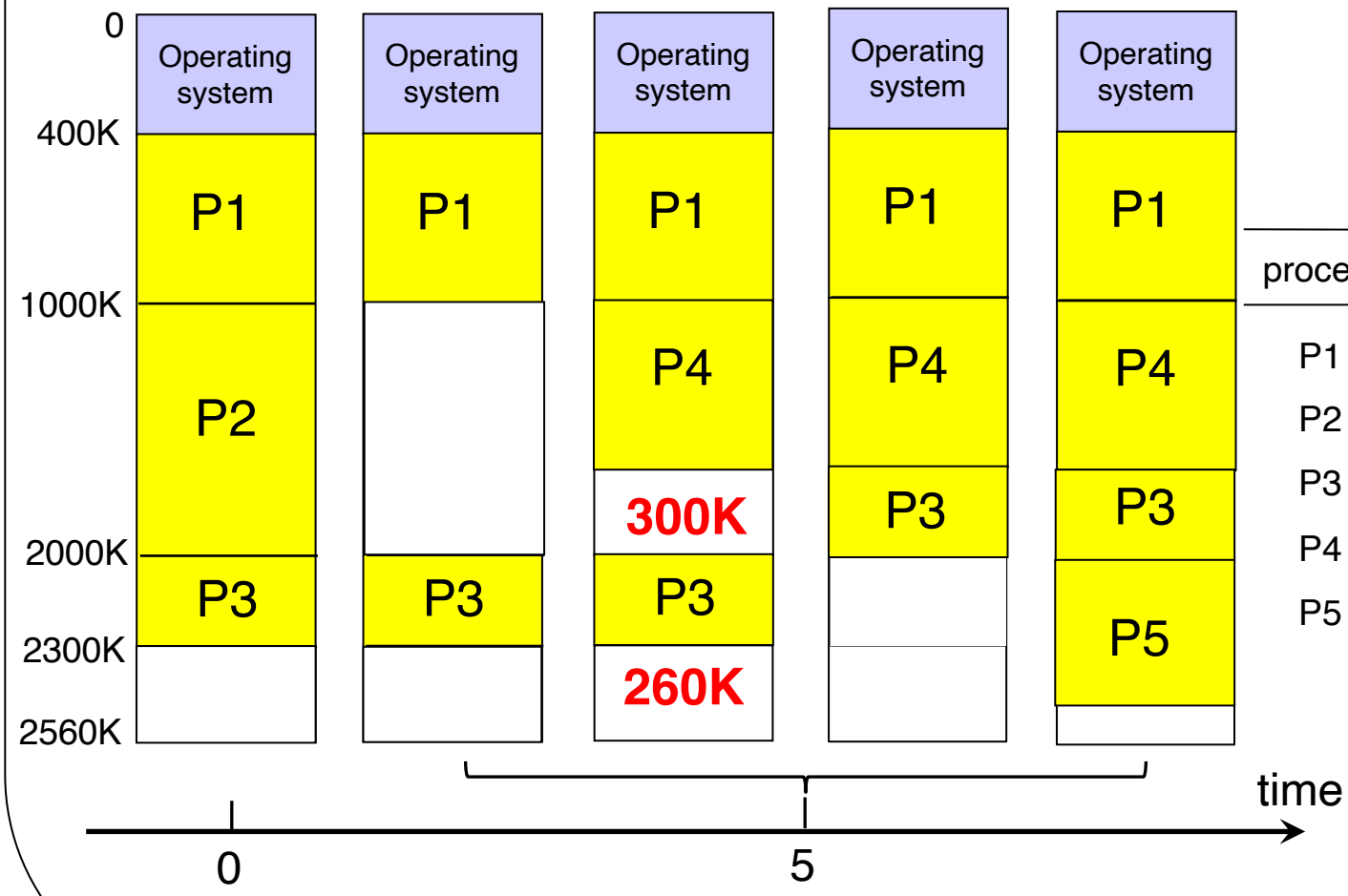
Fragmentation

- *External fragmentation*: when enough total memory space exists to satisfy a request, but it is not contiguous. Happens outside a partition.
- *Internal fragmentation*: allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used.

Fragmentation (Cont.)

- Reduce external fragmentation by *compaction*
  - Shuffle memory contents to place free memory together in one large block.
  - Compaction is possible only if re-locatable address format is used in process image and binding is done during execution-time.

Fragmentation (Cont.)



Job queue

process	memory	time
P1	600K	10
P2	1000K	5
P3	300K	20
P4	700K	8
P5	500K	15

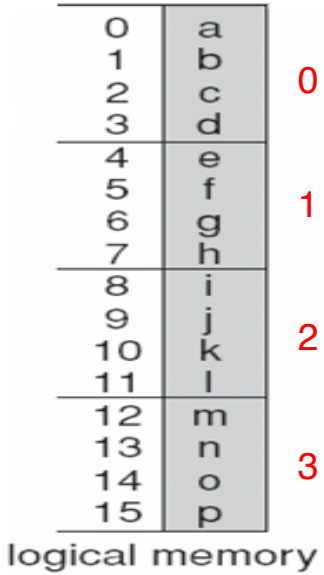
Paging

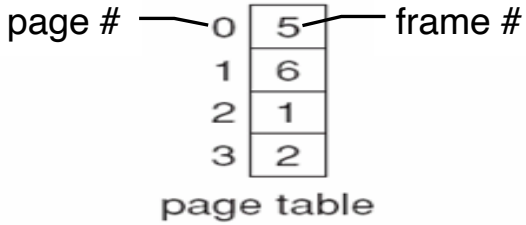
- Memory space allocated to a process can be noncontiguous; process is allocated physical memory whenever the latter is available.
- Divide physical memory into fixed-sized blocks called *frames* (size is power of 2, between 512 bytes and 8192 bytes).
- Divide logical memory into blocks of same size called *pages*.

Paging (Cont.)

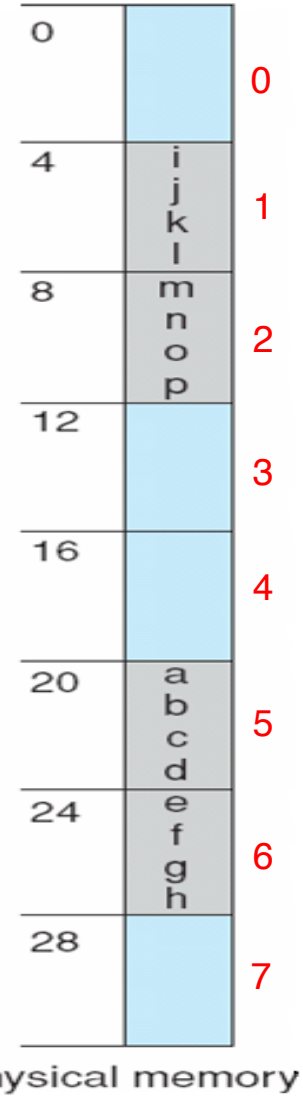
- Keep track of all free frames.
- To run a program of size n pages, need to find *n* free frames and load program.
- Set up a *page table* to translate logical to physical addresses.
- External fragmentation is eliminated
- Internal fragmentation is still possible, last page many not occupy the entire frame.

Paging (Cont.)





- To load process to memory, need to find 4 frames
- Page Table to remember the mapping



Logical address space:
4x4 = 16 bytes
4 Pages

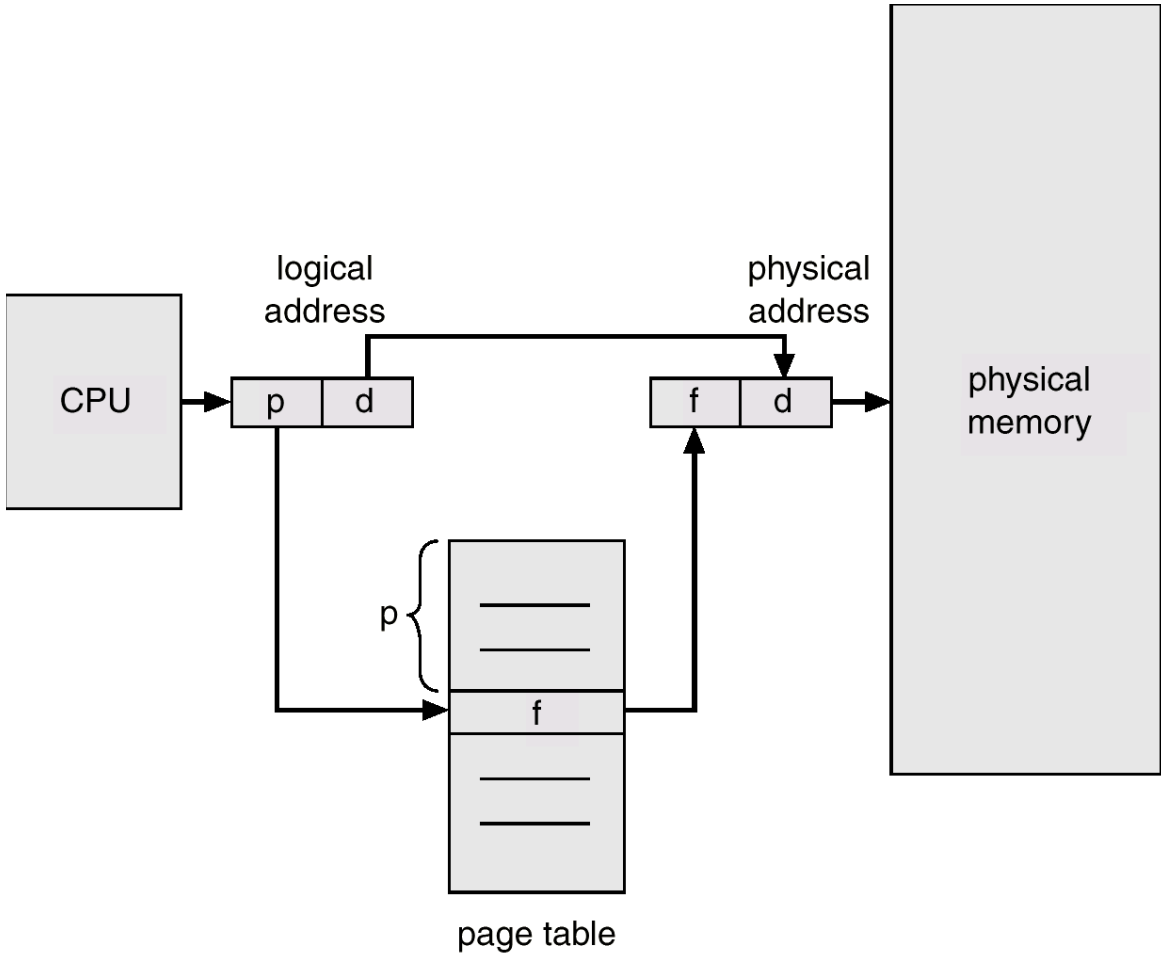
Size of Physical memory:
8x4 = 32 bytes
8 Frames

Page Size (and Frame Size): 4 bytes

Address Translation Scheme

- Logical address contains:
  - *Page number (p)* – used as an index into a *page table* entry which contains *frame number* in physical memory.
  - *Page offset (d)* – combined with frame number to define the physical memory address that is sent to the memory unit.

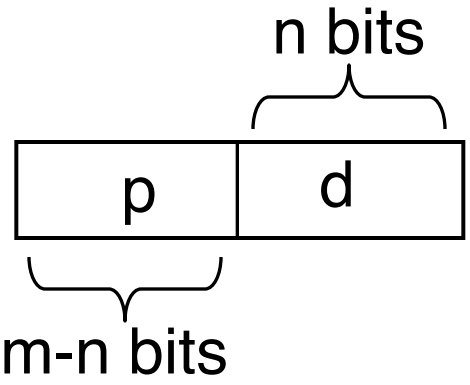
Address Translation Scheme (Cont.)



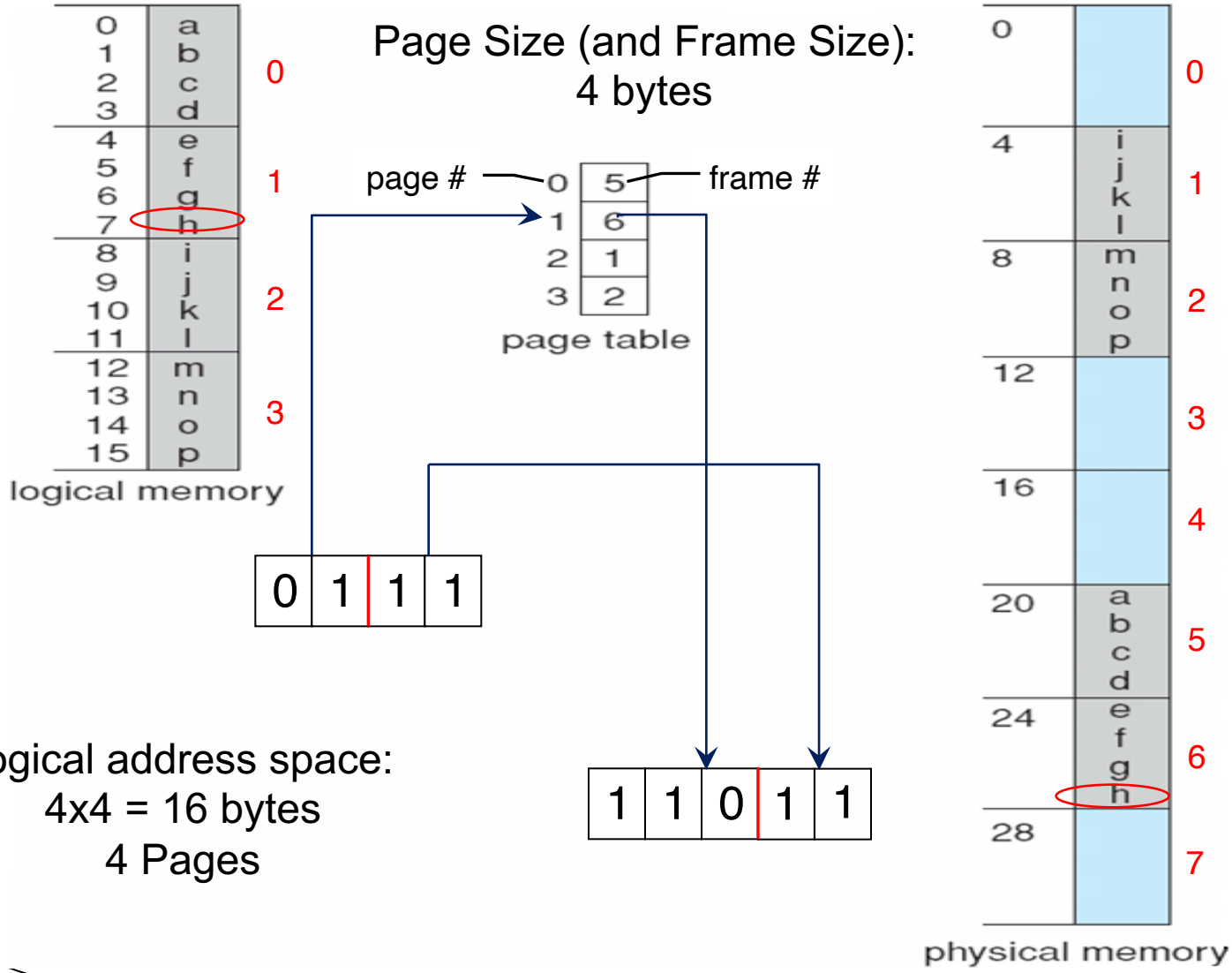
Page size: 2^n bytes

Logical address space: 2^m bytes

Number of pages: 2^{m-n}



Address Translation Scheme (Cont.)



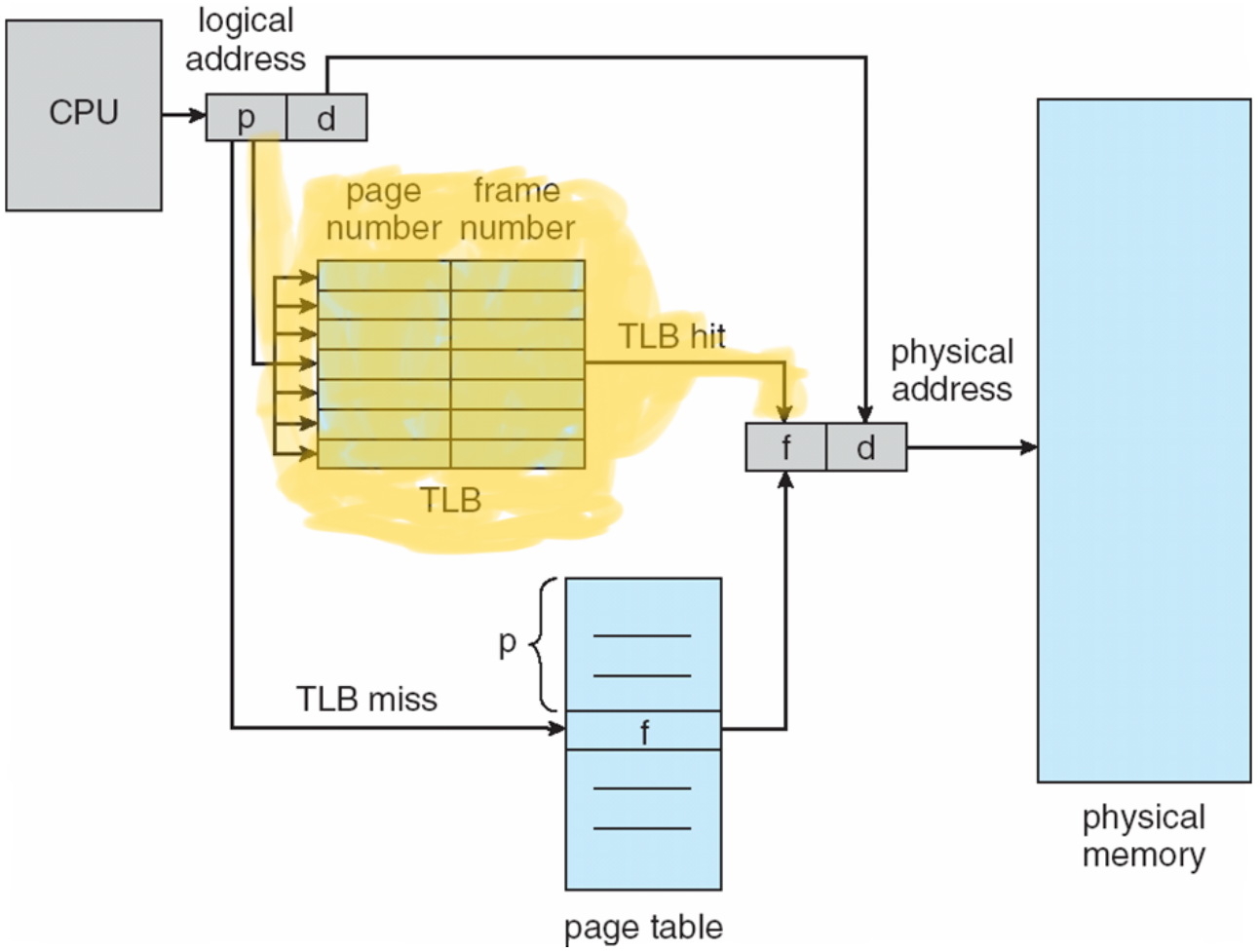
Logical address space:
4x4 = 16 bytes
4 Pages

Size of Physical memory:
8x4 = 32 bytes
8 Frames

Implementation of Page Table

- Page table is kept in physical memory.
- *Page-table base register (*PTBR) points to the page table (for each process).
- *Page-table length register* (PTLR) indicates size of the page table.
- In this scheme every data/instruction access requires two memory accesses: one for the page table and one for the data/instruction.
  - Effective memory access time = 2 μ (assuming that memory cycle time is μ time unit)
- Memory access time can be reduced by the use of a special fast-lookup hardware cache called *associative registers* or *translation look-aside buffers* (TLBs)

Paging Using TLBs



Effective Access Time

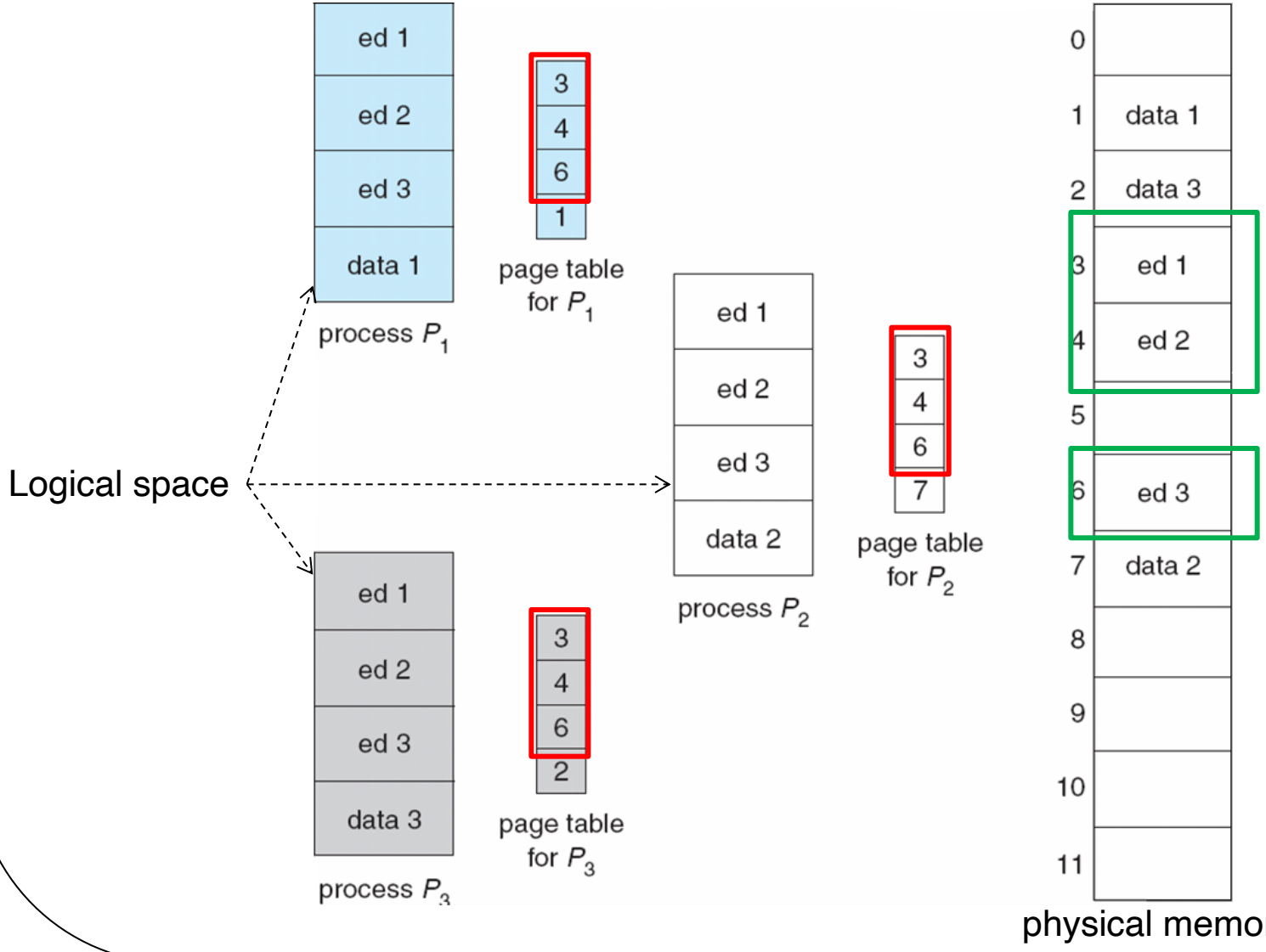
- TLBs Lookup = ε time unit
- Assume memory cycle time is μ time unit
- Hit ratio – percentage of times that a page number is found in the associative registers.
- Hit ratio = α
- Effective Access Time (EAT)

$$EAT = (\mu + \varepsilon)\,\alpha + (2\,\mu + \varepsilon)(1 - \alpha)$$

$$= (2 - \alpha)\,\mu + \varepsilon$$

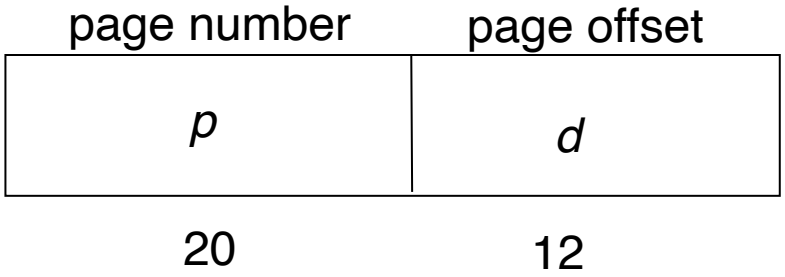
EAT = P x hit memo time + (1-P) x miss memory time

Shared Pages



Two-Level Page-Table Scheme

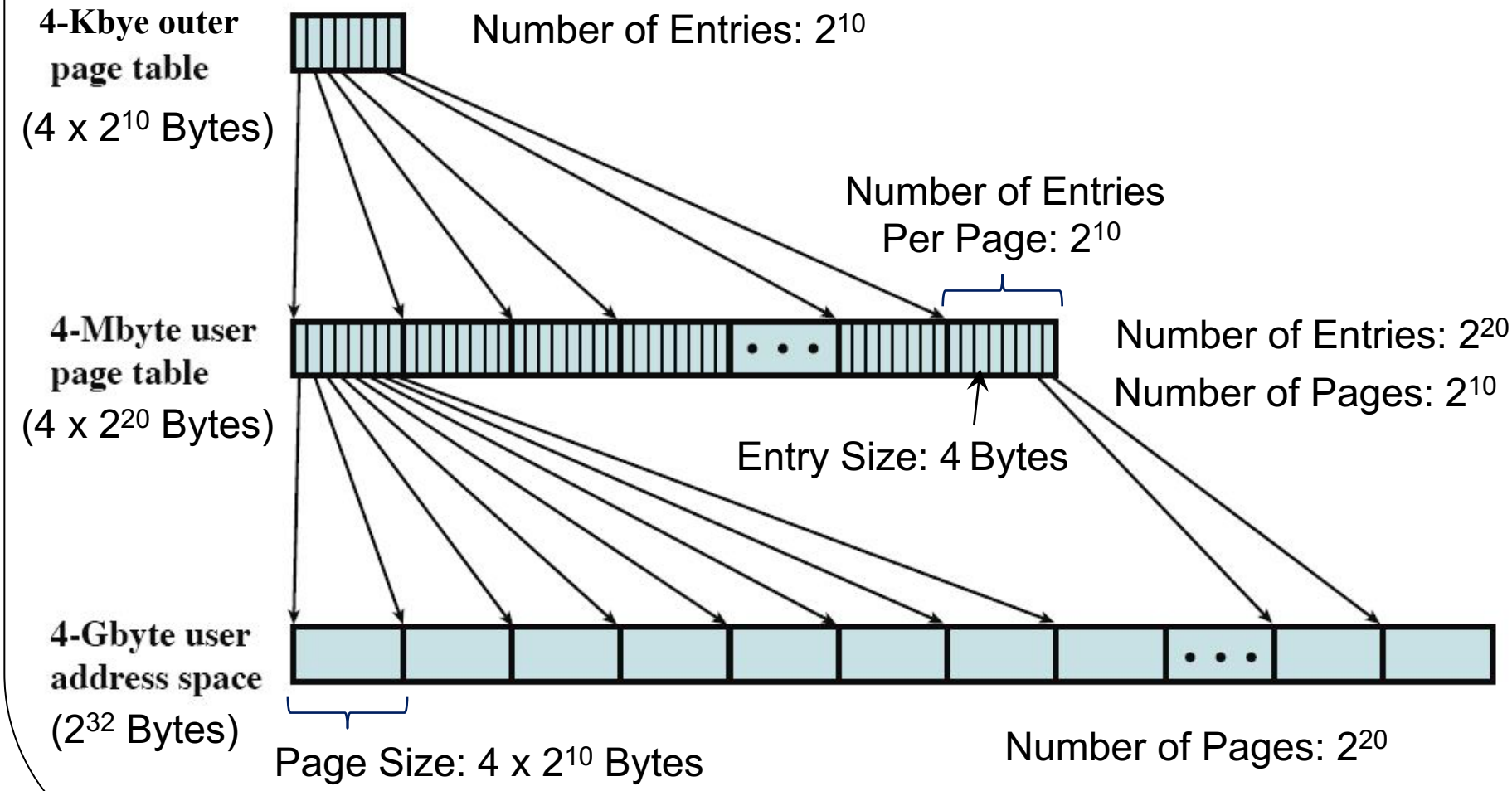
- A logical address (on 32-bit machine with 4K page size)
  - A logical address is divided into:
    - a page number consisting of 20 bits.
    - a page offset consisting of 12 bits.



  - 2^{20} entries in a page table
  - If each entry consists of 4 bytes, each page table occupies 4 megabyte of memory!

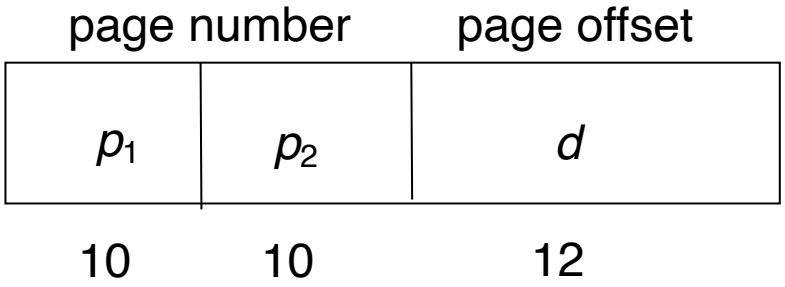
- *A large page table is divided up to be easier to allocate in physical memory, with a small increase in effective access time*

Two-Level Page-Table Scheme (Cont.)



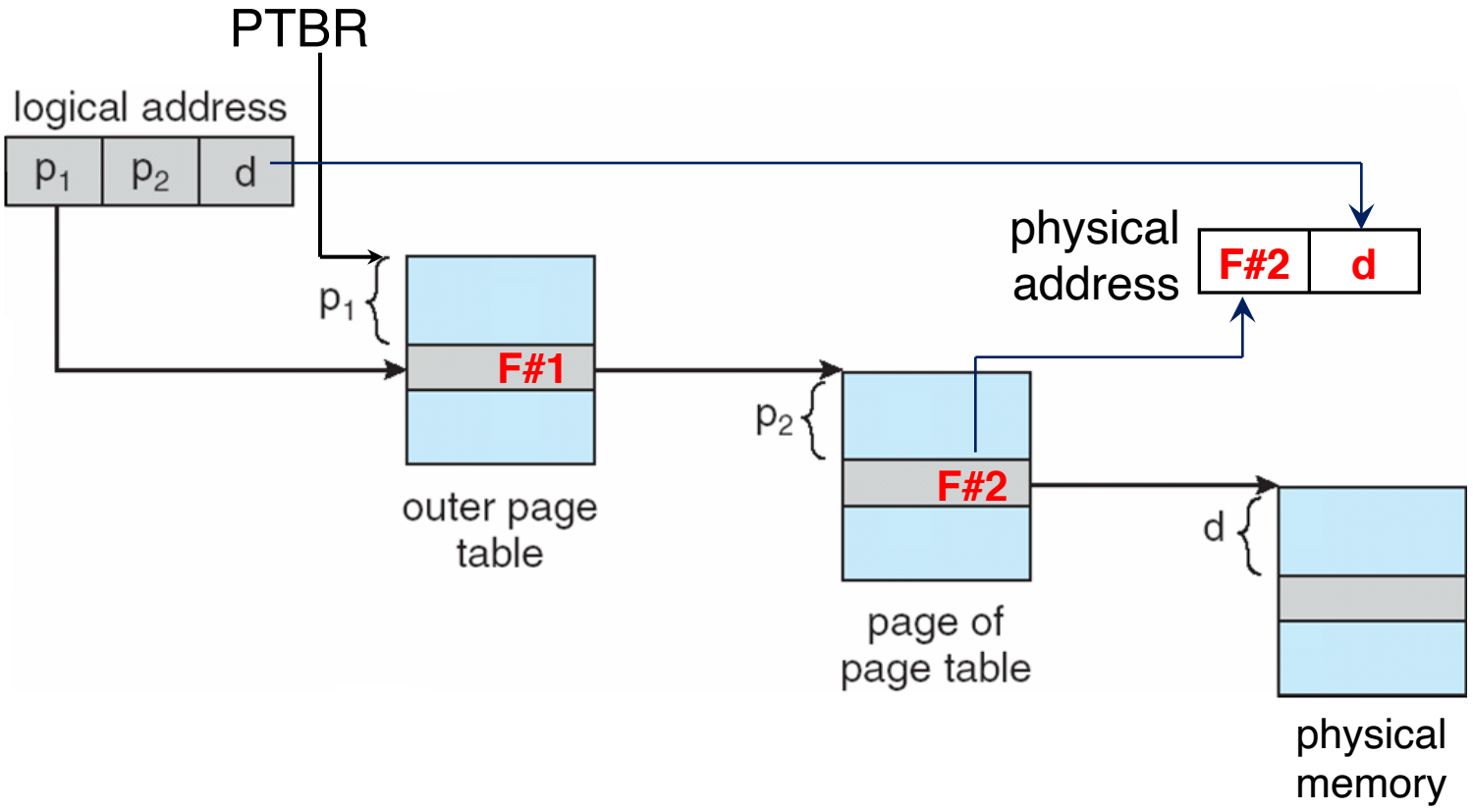
Two-Level Page-Table Scheme (Cont.)

- Since the page table is paged, the page number is further divided into:
  - p_1: an index into the outer page (second level) table
    - ✳ The outer page table contains (4 x 2^{20}) / 4K = 2^{10} number of entries -> 10 bits for p_1
  - p_2: is an index into a page of the inner (first level) page table
    - ✳ Each page in the page table contains(4 x 2^{10}) / 4 = 2^{10} number of entries -> 10 bits for p_2
- Thus, a logical address is as follows:



Two-Level Page-Table Scheme (Cont.)

- Address-translation scheme for a two-level 32-bit paging architecture

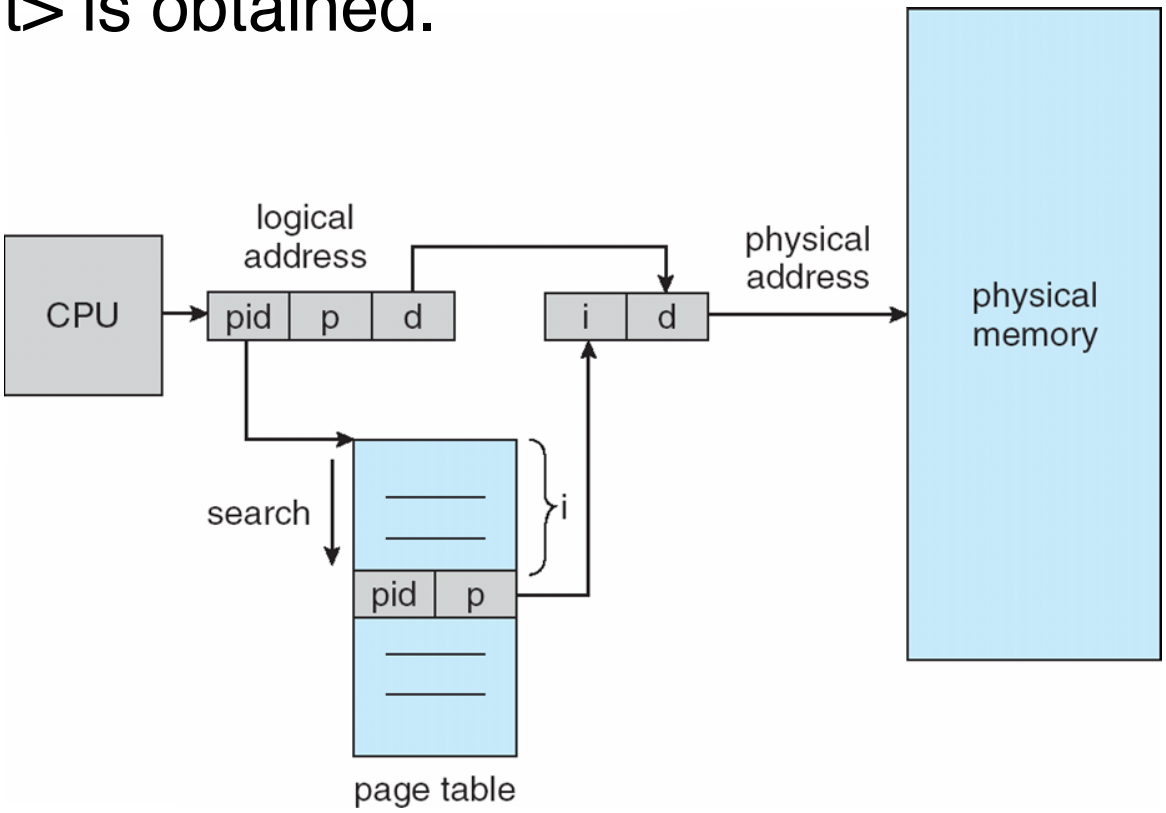


Inverted Page Table

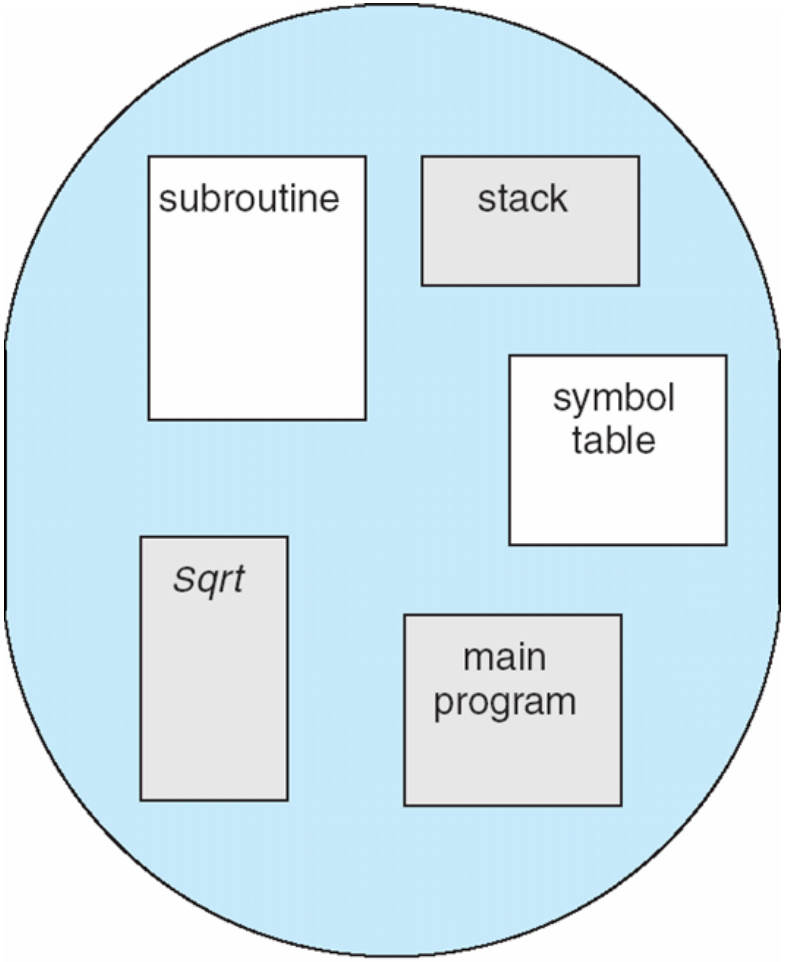
- Usually each process has its own page table. Hence the system could have many page tables, consuming substantial memory space
  - The page table size is proportional to that of the logical address space.
- **Alternative**: have a single table with one entry for each physical frame, as <process-id, page-no>. This is called an *Inverted Page Table*
- Logical address: <process-id, page-no, offset>
- Increases search time: table sorted by physical address but lookups occur on logical address

Inverted Page Table (Cont.)

- To access memory, the pair <process-id, page-no> is presented to inverted page table to find a match.
- If match is found, say at entry i, then physical addr <i, offset> is obtained.



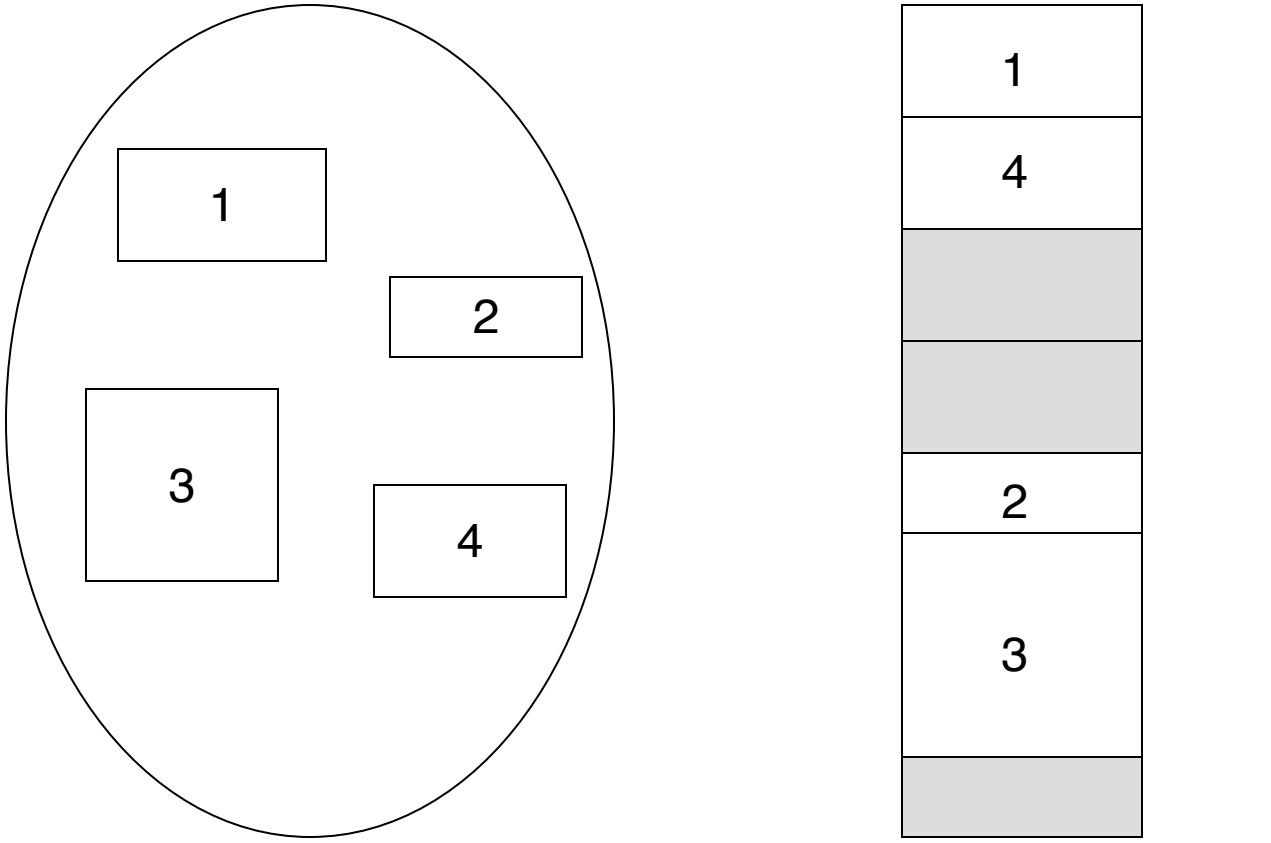
Segmentation



logical address space

- A memory-management scheme that break program up into its logical *segments* and allocating space for these segments into memory separately.
- Unlike pages, segments can be of variable size
- A process has a collection of segments.
- Like pages of a process, segments of a process may not be allocated contiguously

Segmentation (Cont.)



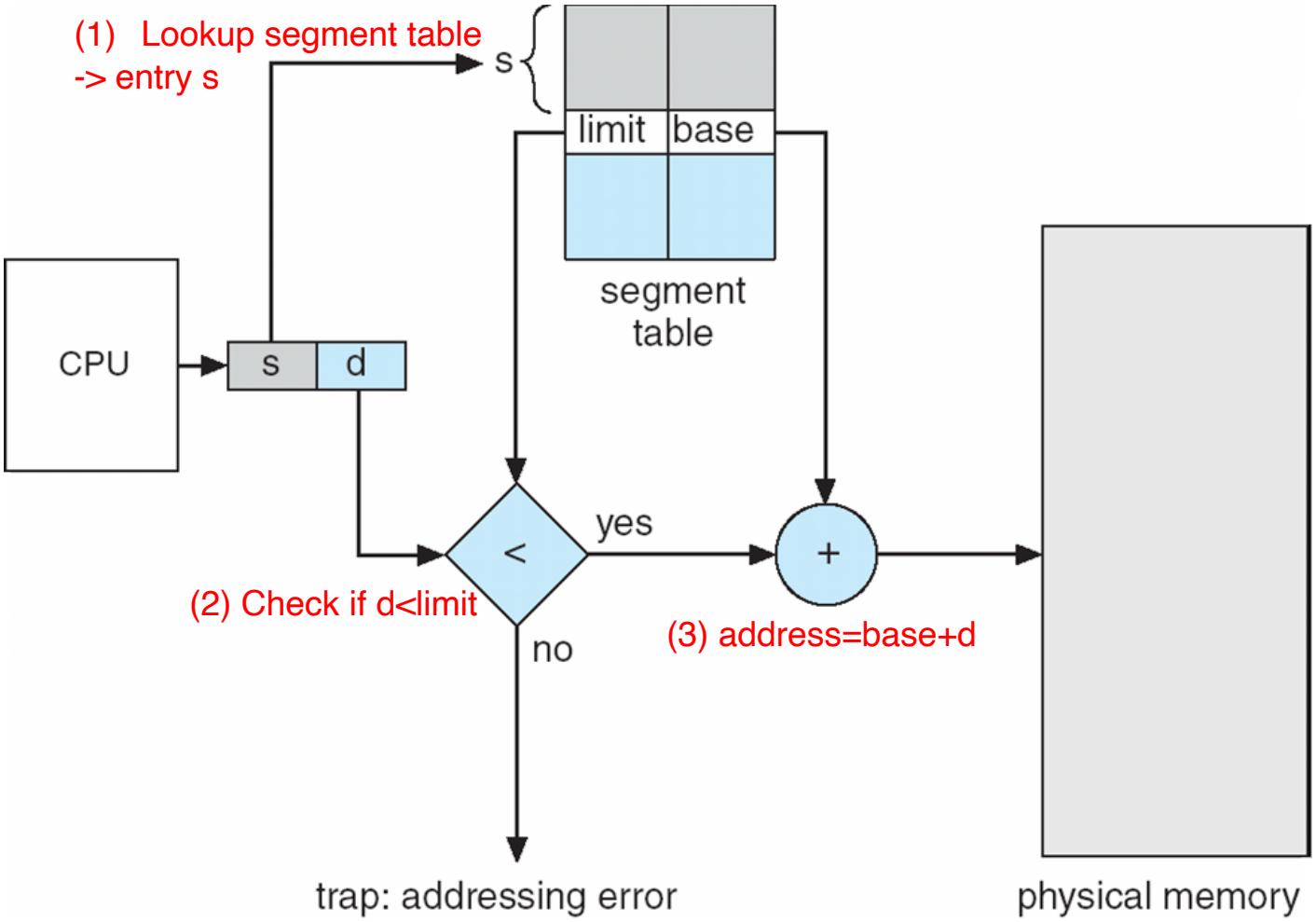
Address Translation

- Each segment has a segment no. & offset, i.e., its logical address is:

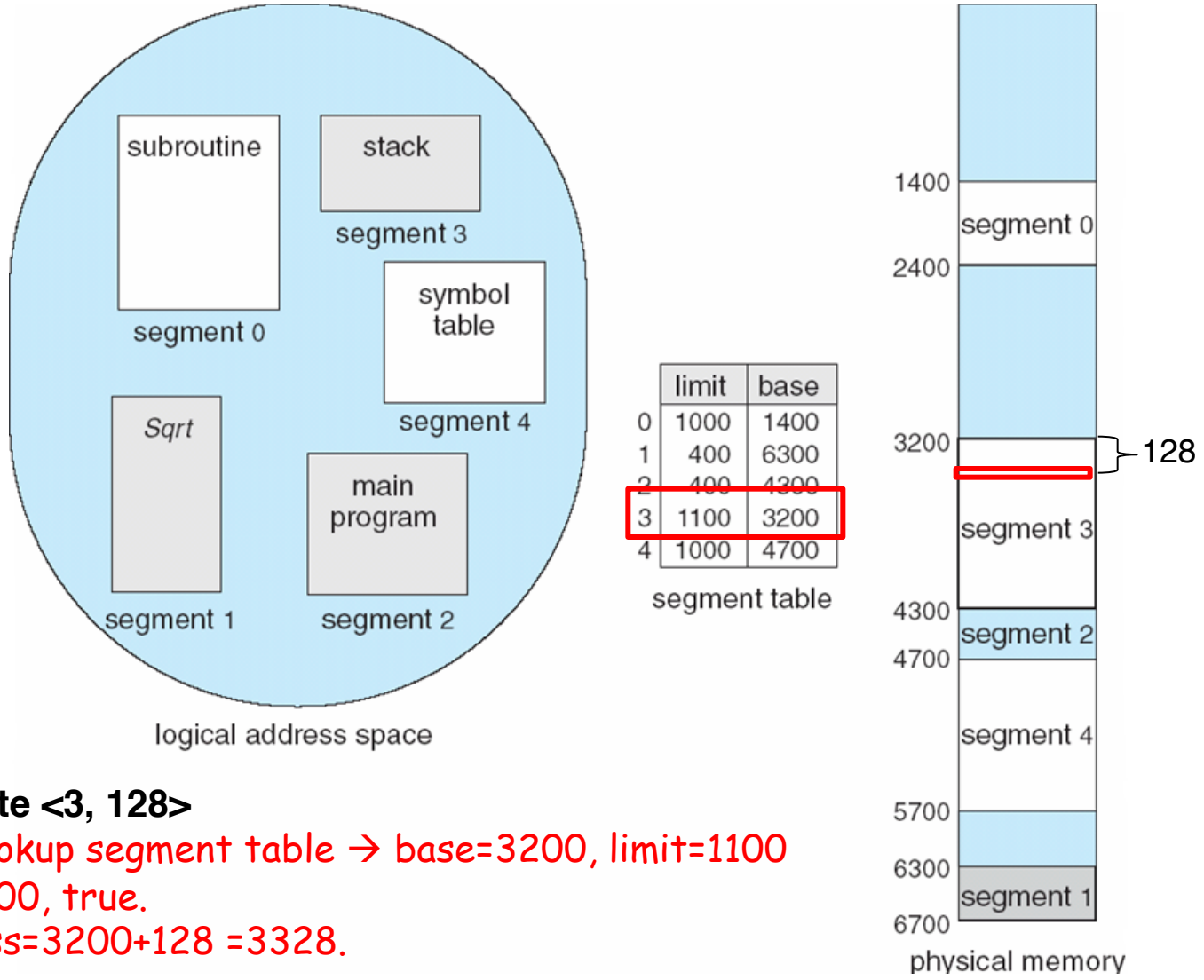
  <segment-no, offset>,

- *Segment table.* Each table entry has:
  - *base* – contains the starting physical address where the segments reside in memory.
  - *limit* – specifies the length of the segment.
- *Segment-table base register* (STBR) points to the segment table's location in memory
- *Segment-table length register* (STLR) indicates number of segments used by a program;

Address Translation (Cont.)



Address Translation (Cont.)



Q: translate <3, 128>

Ans: (1) lookup segment table → base=3200, limit=1100

(2) 128<1100, true.

(3) address=3200+128 =3328.

Fragmentation in Segmentation

- Since segments vary in length, memory allocation is a dynamic storage-allocation problem. Usually use best-fit or first-fit.
- Suffer from external fragmentation as process leaves the system, its occupied segments become holes in the memory.
- As a process leaves the system, its occupied segments become holes of varying sizes in the memory.

Summary

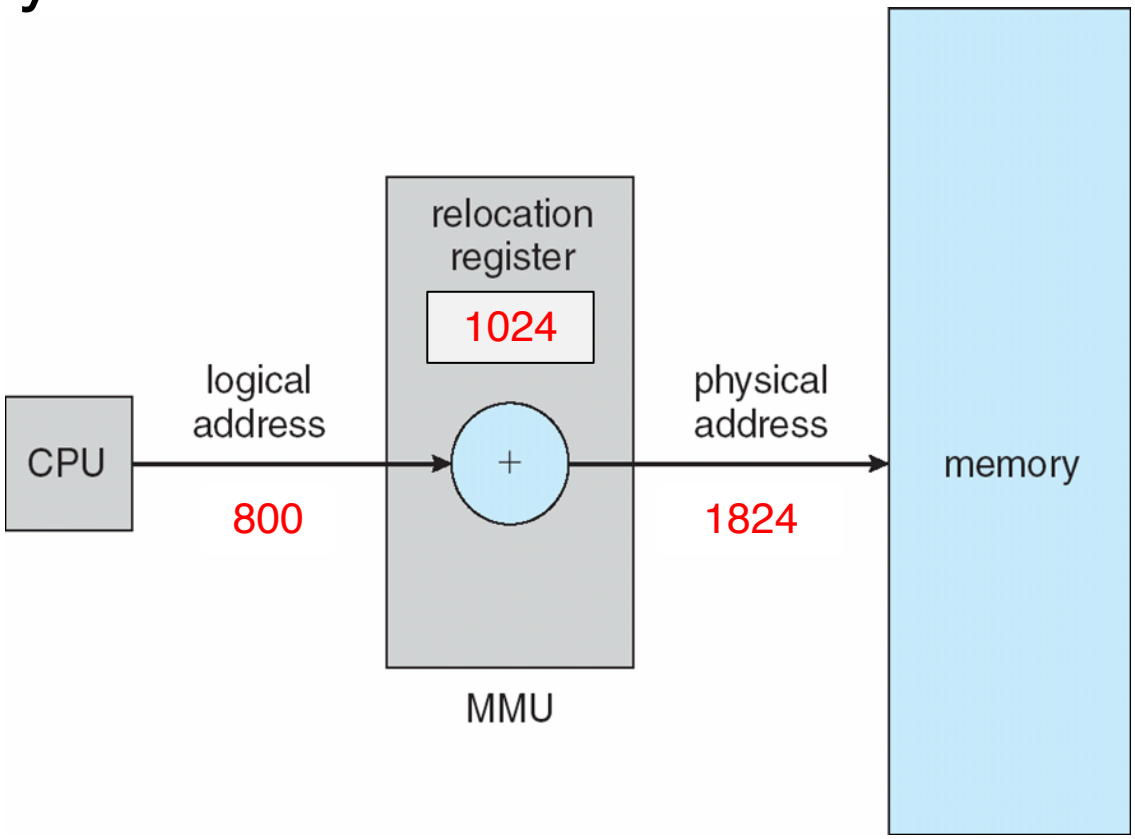
- Programs must be brought into memory for execution $\Rightarrow$ Memory Allocation
  - Contiguous Allocation
    - fix partition vs. dynamic partition
  - Non-contiguous Allocation
    - paging
  - Fragmentation Problem

Summary

- Process executes in its logical address space, but the actual code and data are stored in physical memory $\Rightarrow$ Mapping of logical address to physical address
  - Contiguous Allocation
    - relocation register
  - Paging
    - basic scheme
    - using translation look-aside buffer
    - multilevel paging
    - Inverted page table

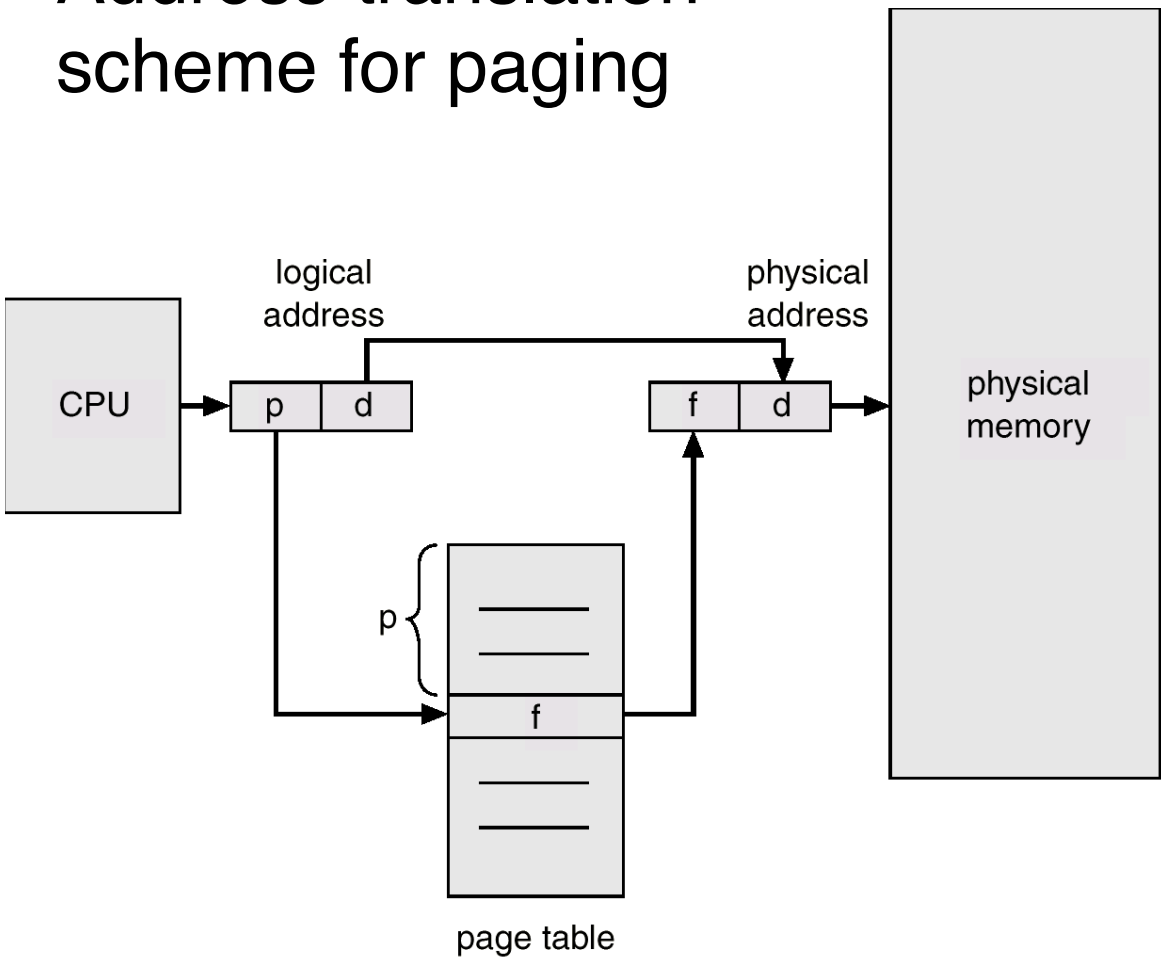
Summary

- Address-translation scheme for contiguous memory allocation



Summary

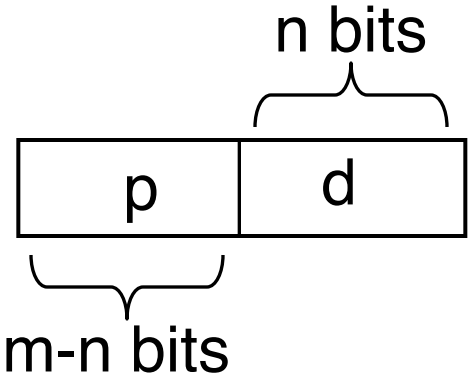
- Address-translation scheme for paging



Page size: 2^n

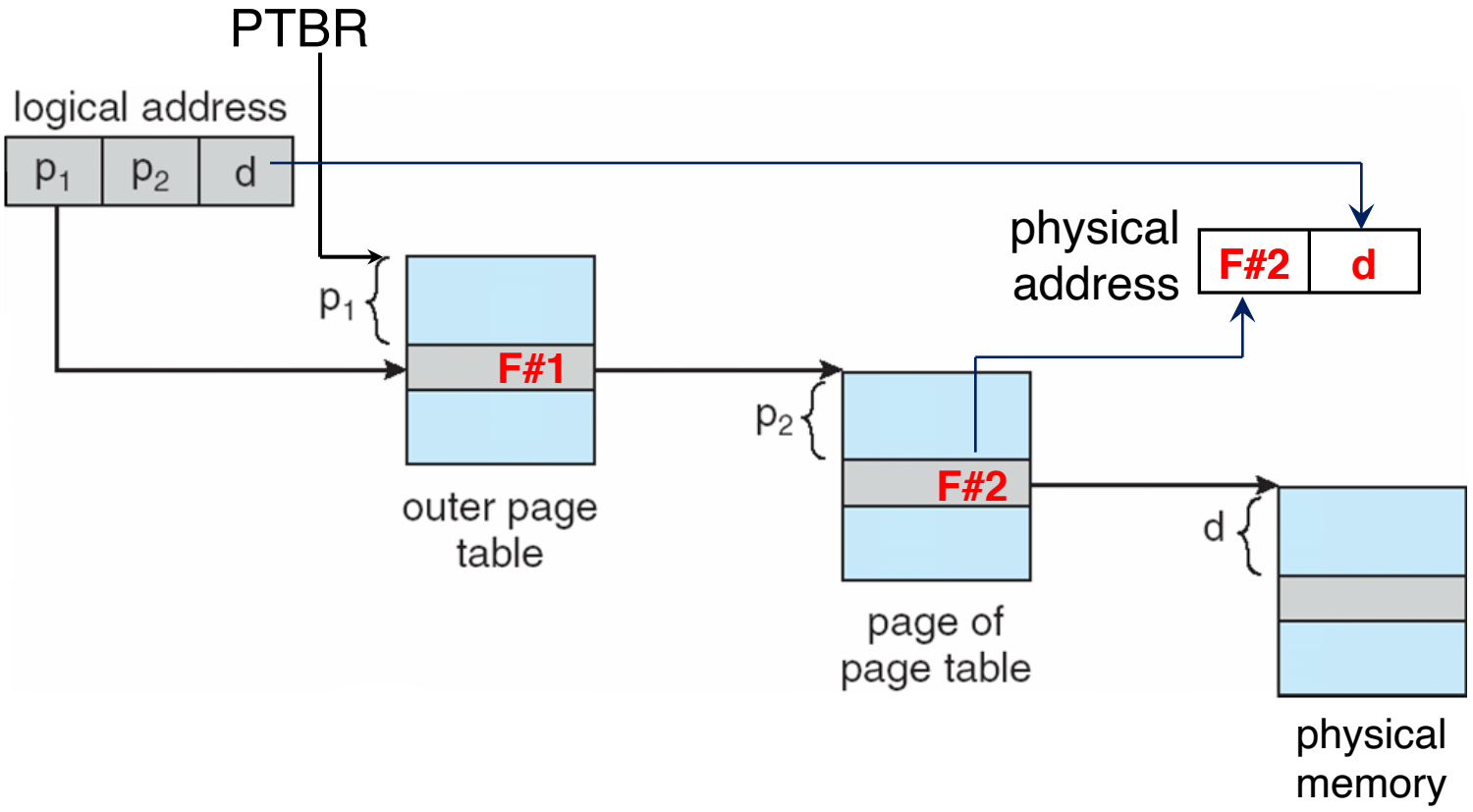
Logical address space: 2^m

Number of pages: 2^{m-n}



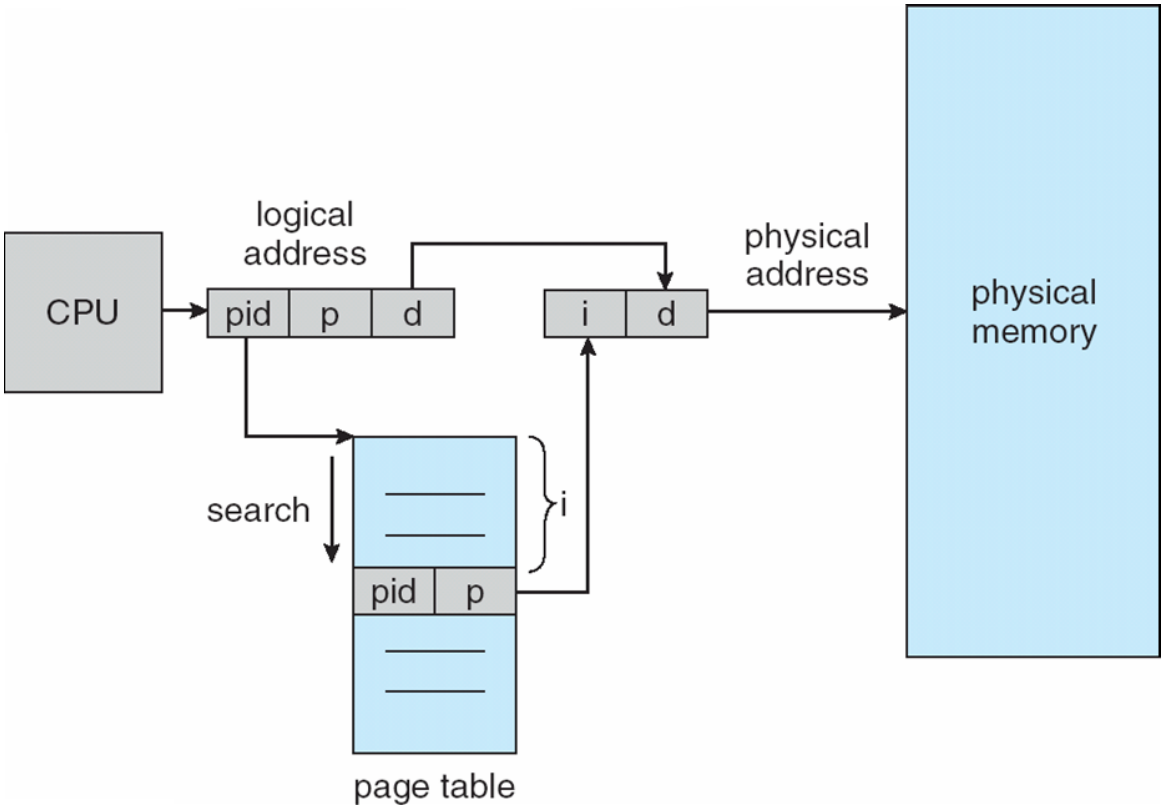
Summary

- Address-translation scheme for a two-level 32-bit paging architecture



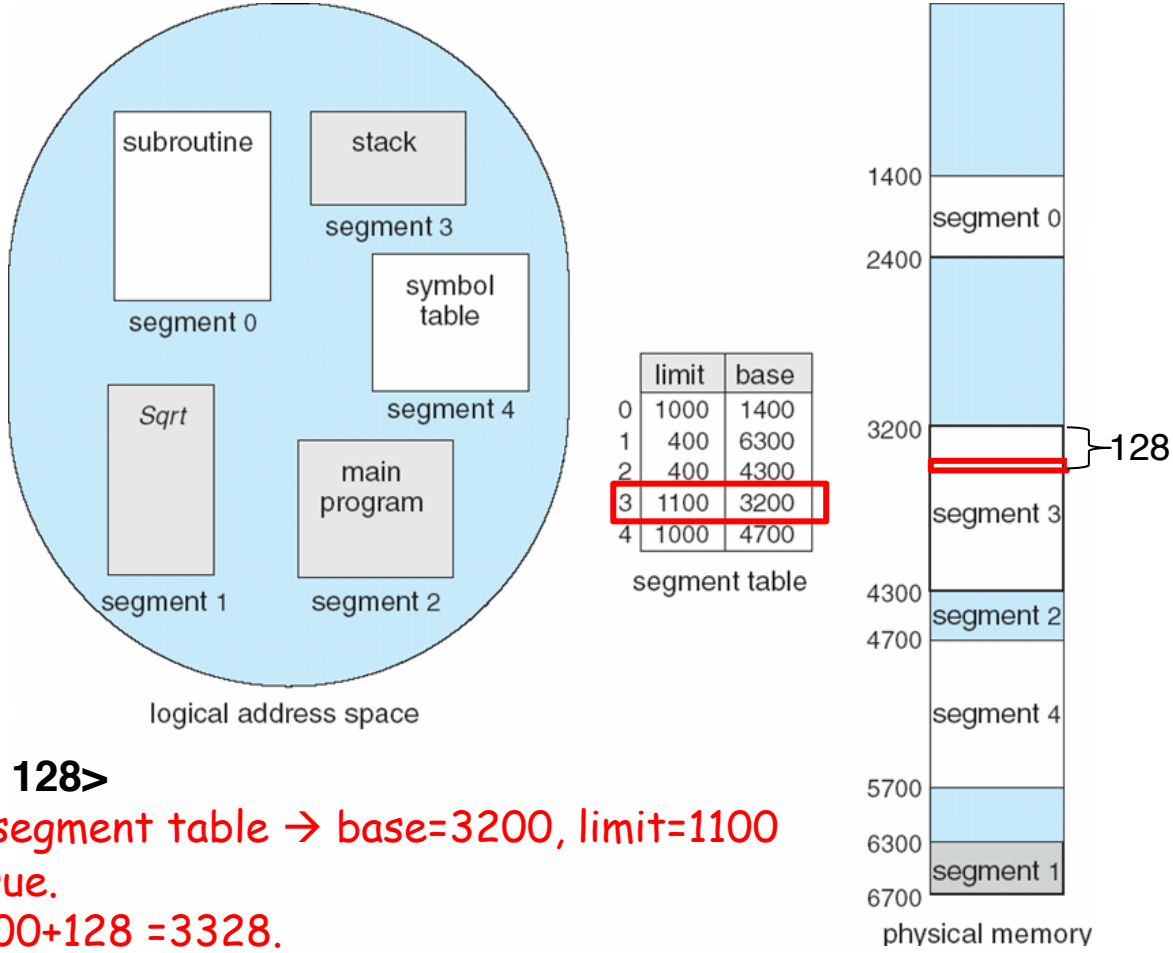
Summary

- Address translation scheme for inverted page table.



Summary

- Address translation scheme for segmentation.



Q: translate <3, 128>

Ans: (1) lookup segment table → base=3200, limit=1100

(2) 128<1100, true.

(3) address=3200+128 =3328.