

# CSCE 2110

## Foundations of Data Structures

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### Splay Tree

# Contents

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- Splay tree
  - insertion
  - find
  - deletion
  - running time analysis
- Binary Trees

# Self adjusting Trees

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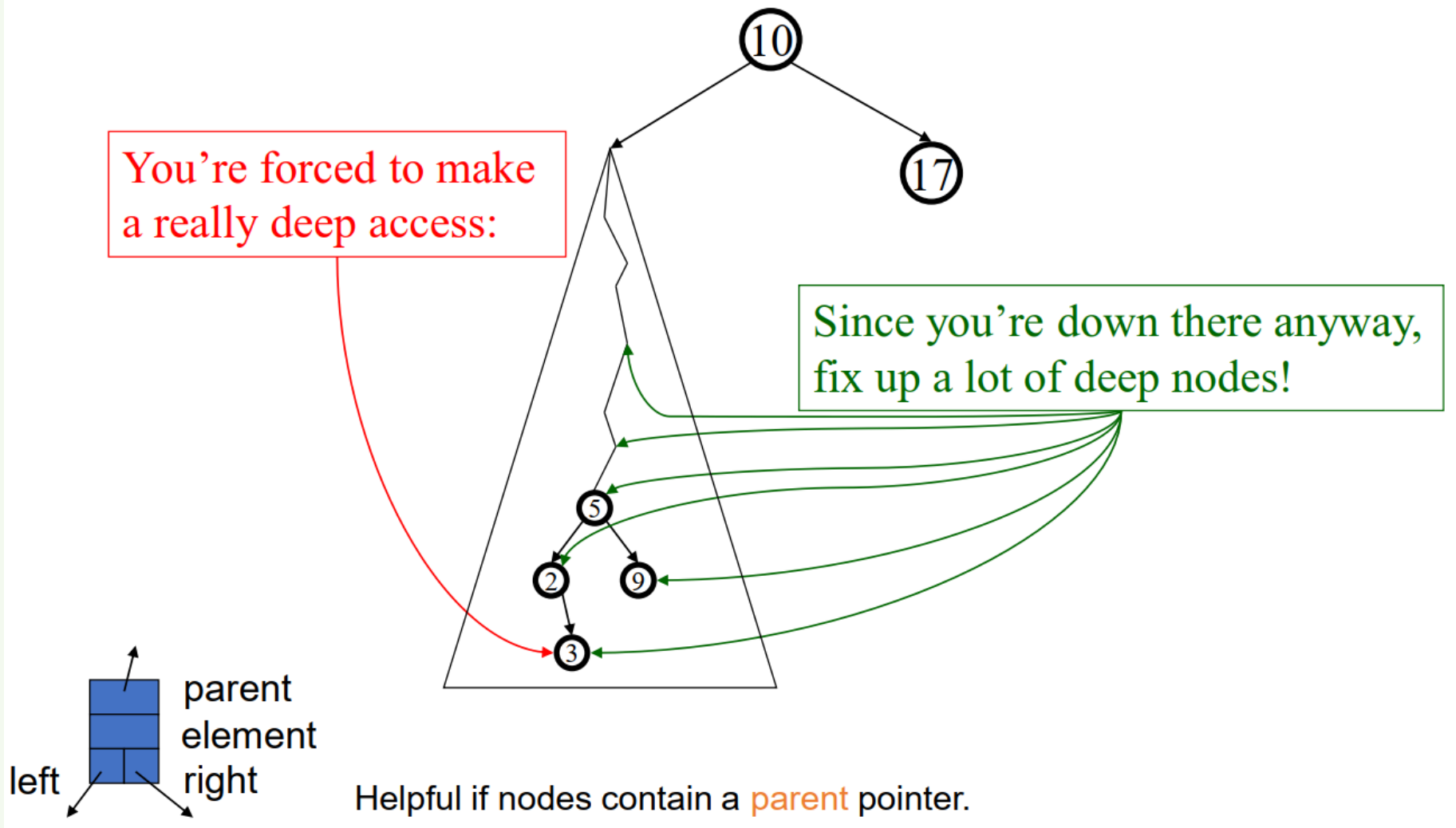
- Ordinary binary search trees have no balance conditions
  - What you get from insertion order is it
- Balanced trees like AVL trees enforce a balance condition when nodes change
  - Tree is always balanced after an insert or delete
- Self-adjusting trees get reorganized over time as nodes are accessed
  - Tree adjusts after insert, delete, or find

# Splay Trees

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- Splay trees are tree structures that:
  - Are not perfectly balanced all the time
  - Data most recently accessed is near the root. (principle of locality; 80-20 "rule")
- The procedure:
  - After node X is accessed, perform "splaying" operations to bring X to the root of the tree.
  - Do this in a way that leaves the tree more balanced as a whole

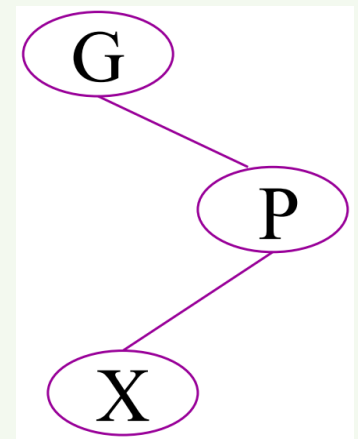
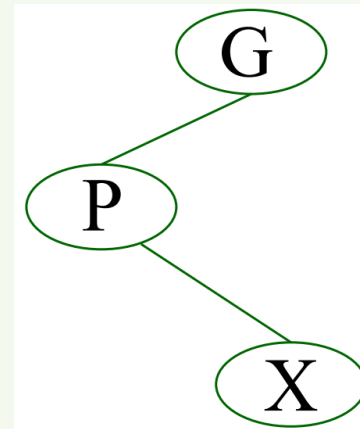
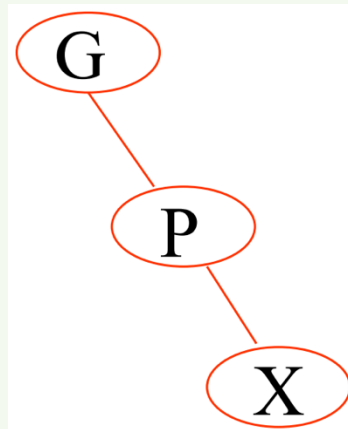
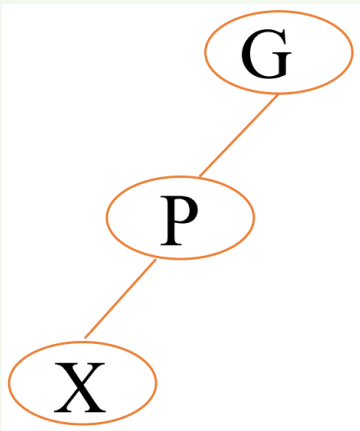
# Splay Tree Idea



# Splaying Cases

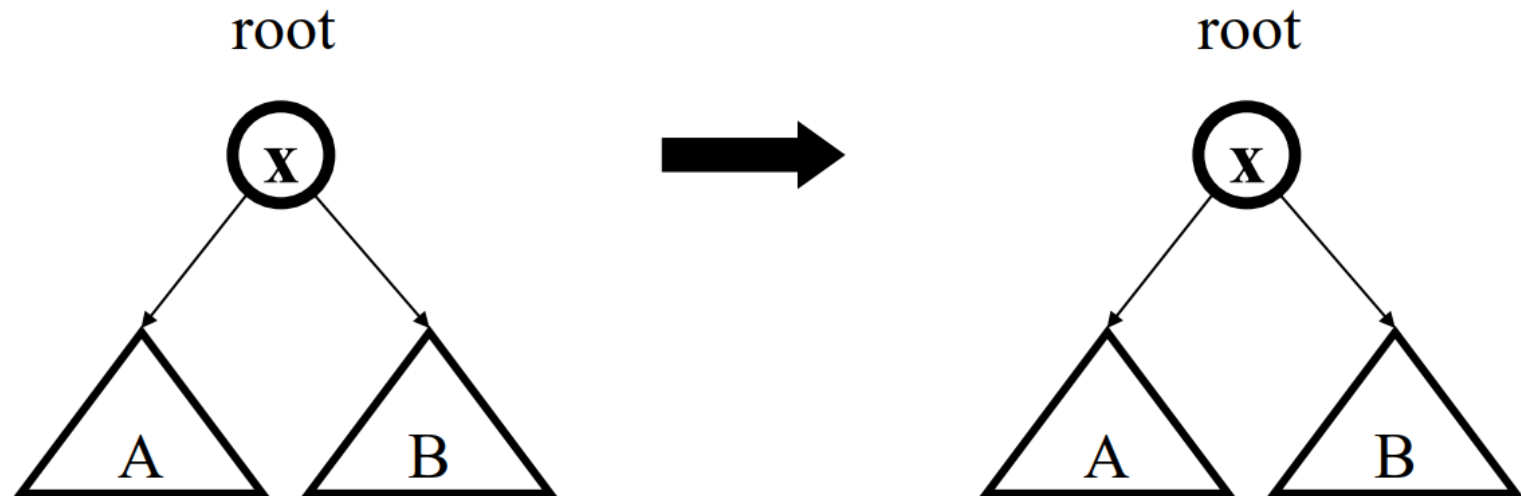
Node being accessed (x) is:

- Root
- Child of root
- Has both parent (p) and grandparent (g)
  - Zig-zig pattern:  $g \rightarrow p \rightarrow x$  is left-left or right-right
  - Zig-zag pattern:  $g \rightarrow p \rightarrow x$  is left-right or right-left



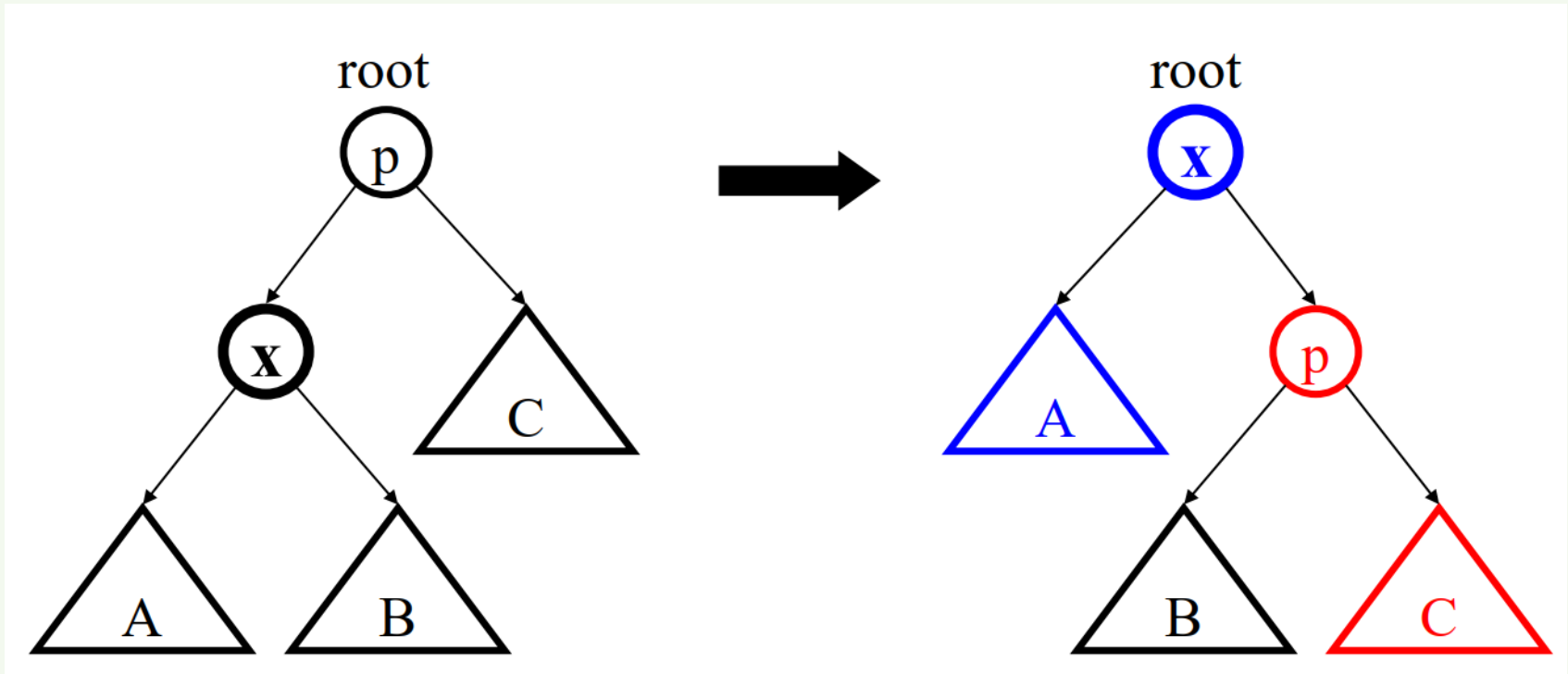
# Access Root

Do nothing (that was easy!)



# Access Child of Root

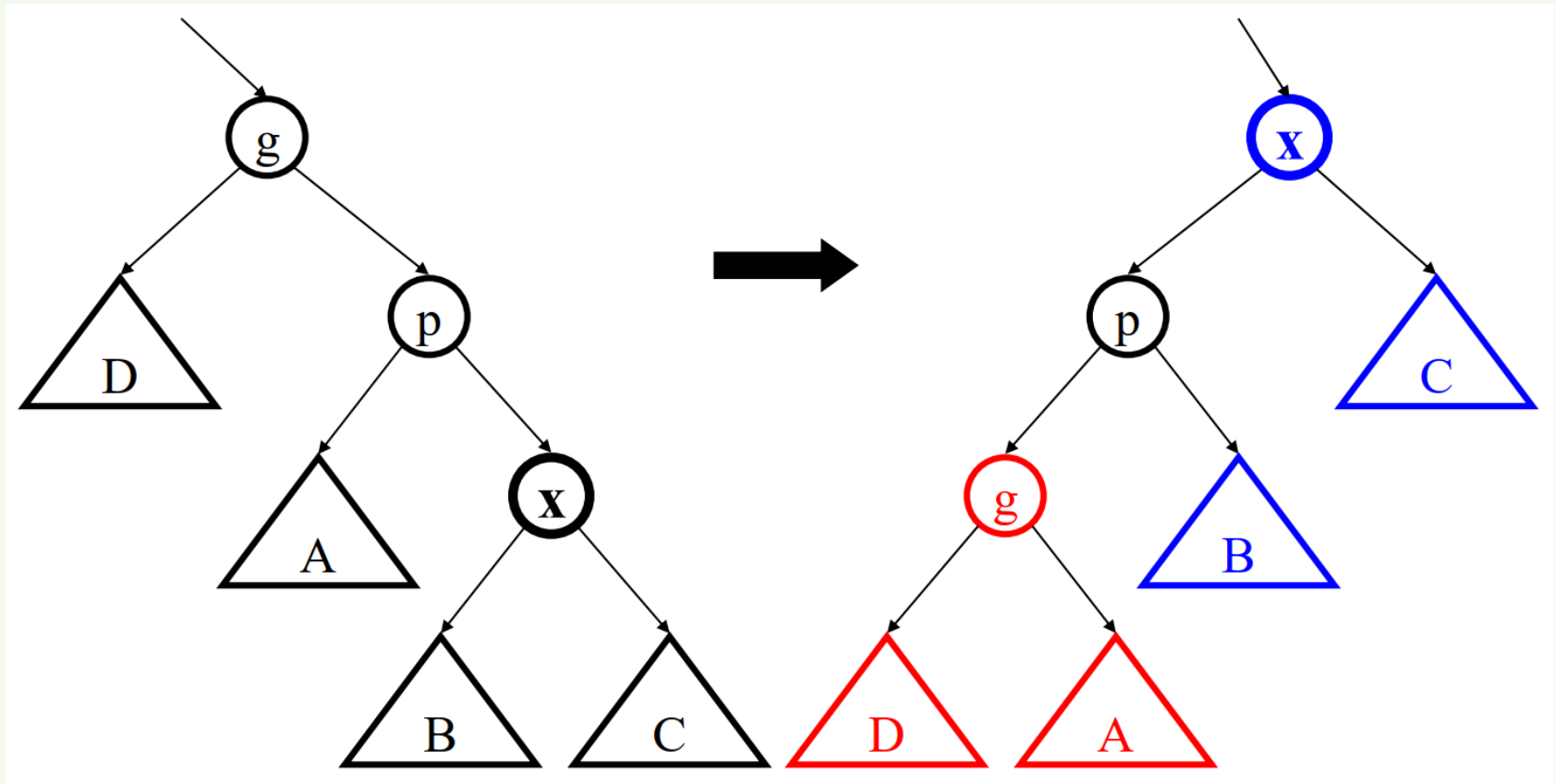
Zig (AVL single rotation)





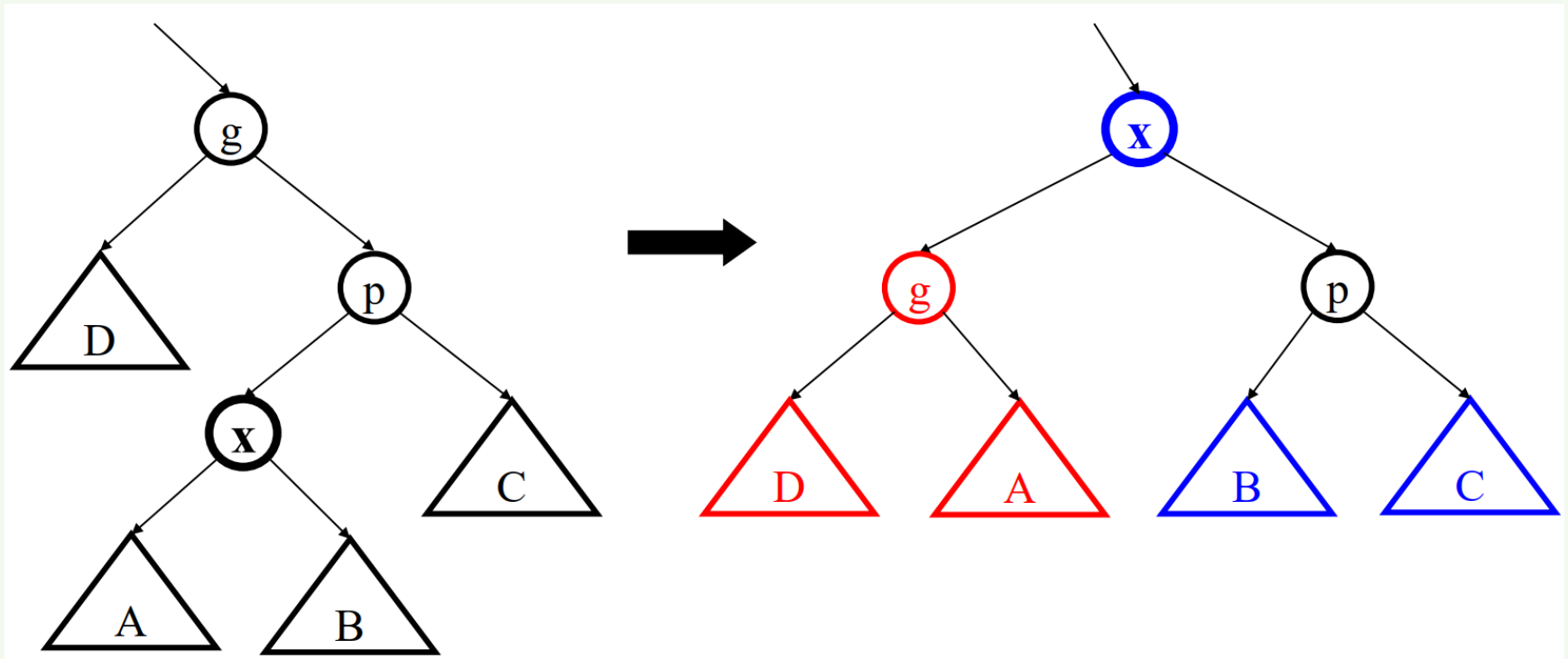
# Access (LL, RR) Grandchild

## Zig-Zag



# Access (LR, RL) Grandchild

Zig-Zag



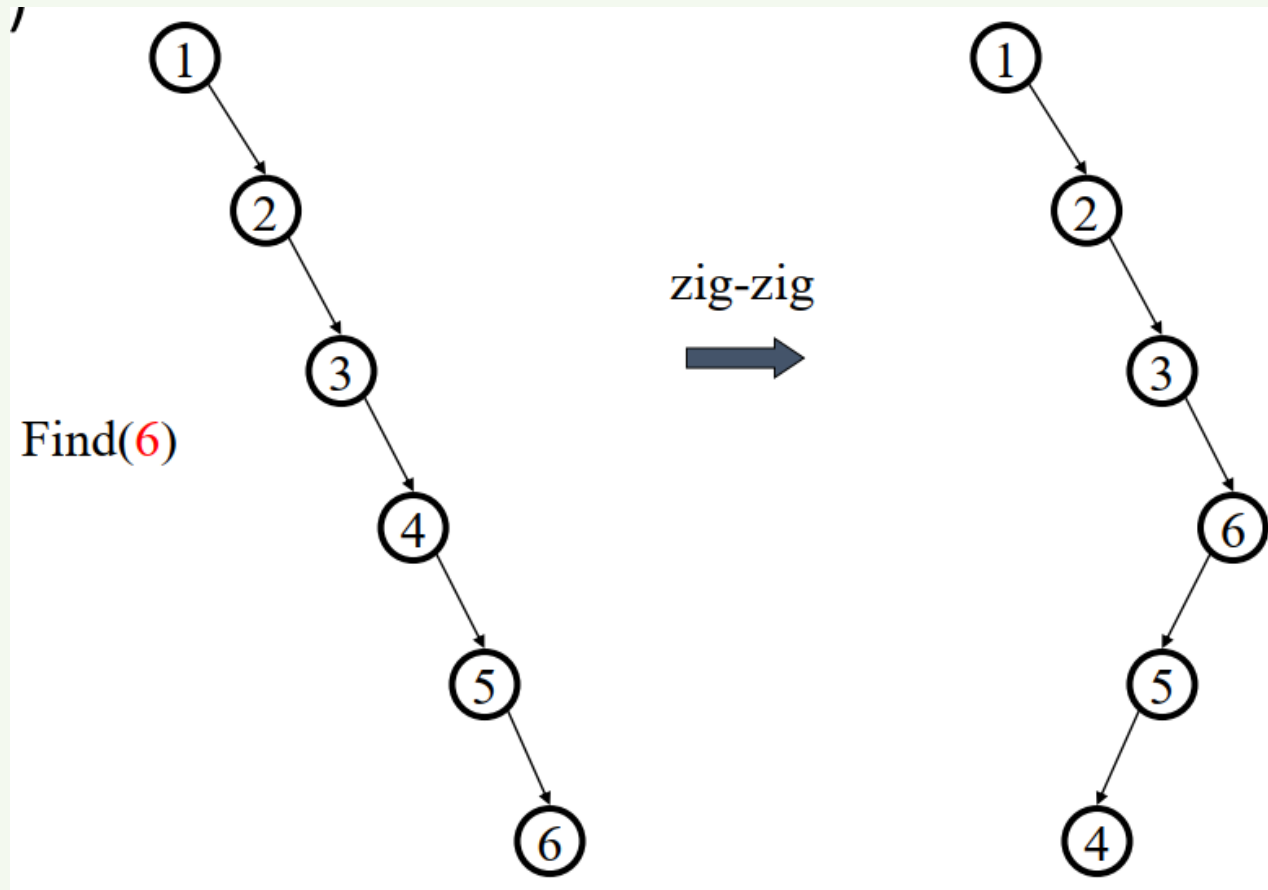
# Splay Operations: Find

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- Find the node in normal BST manner
- Splay the node to the root Are not perfectly balanced all the time

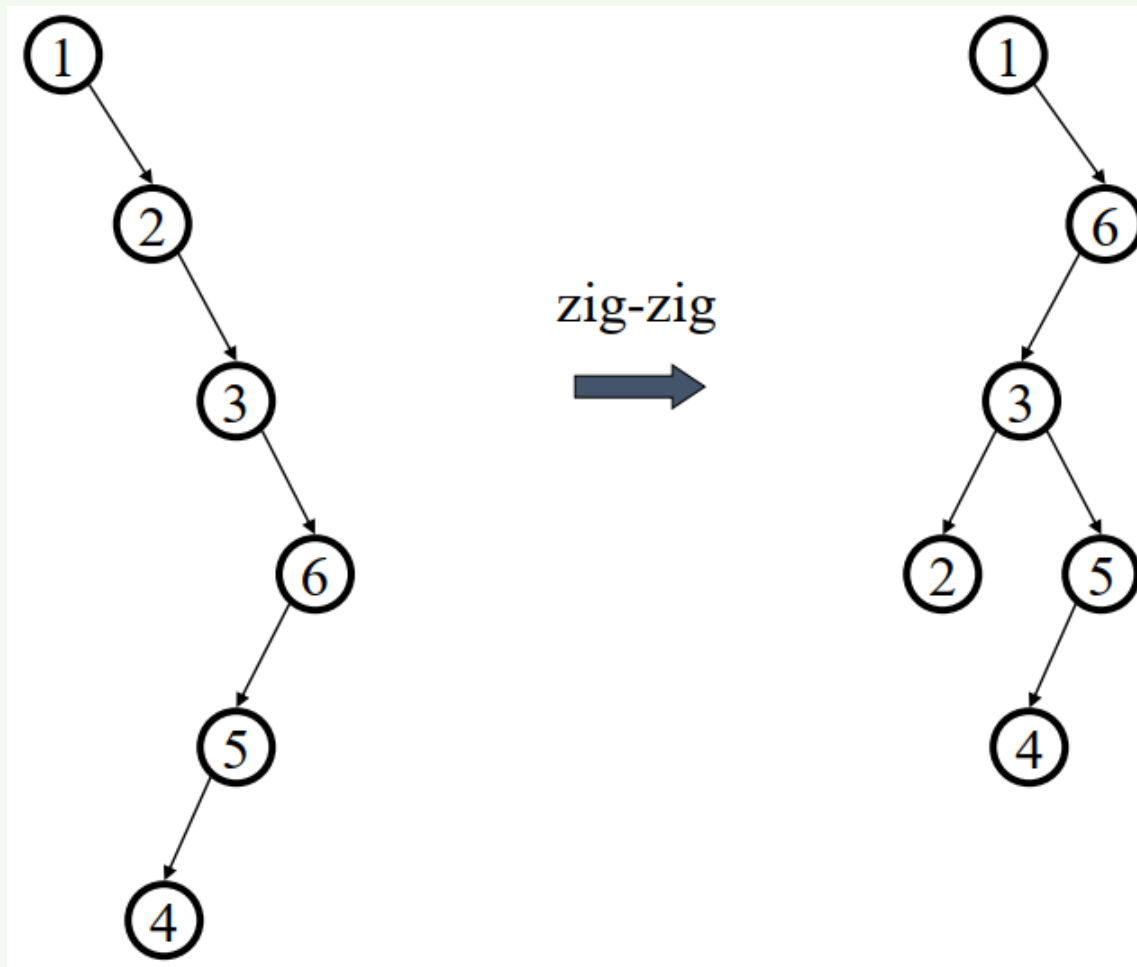
# Splaying Example

Find(6)



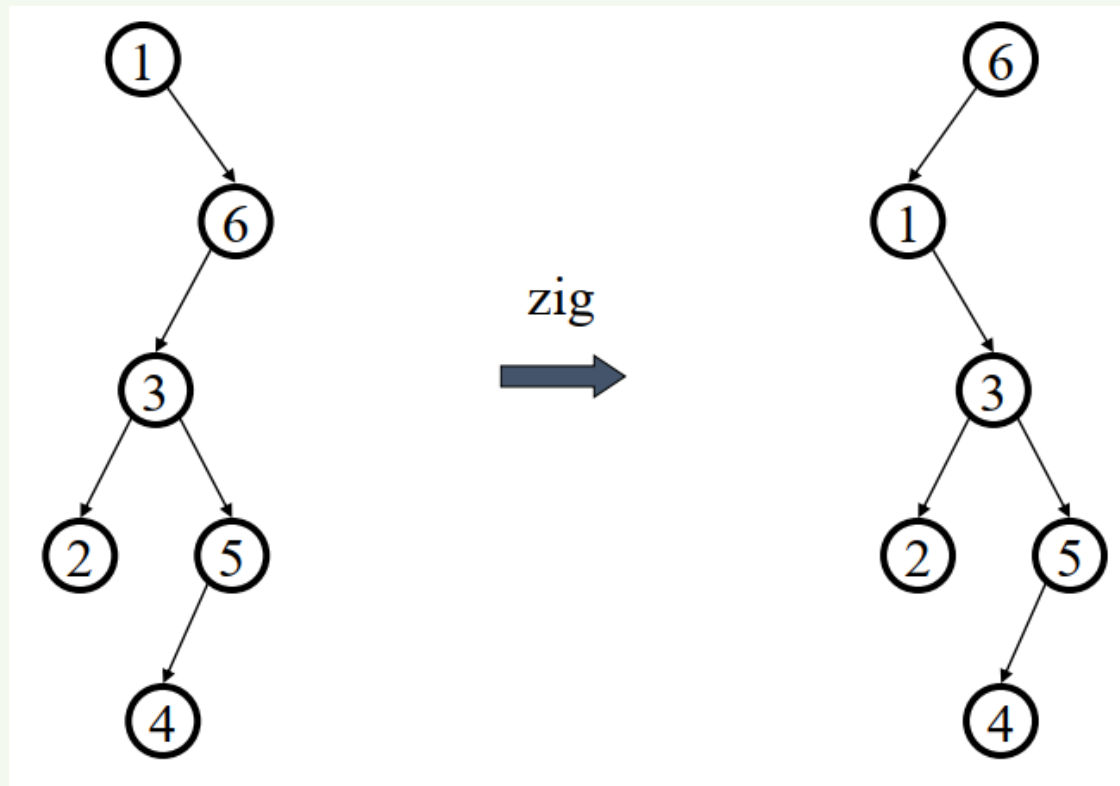
# Splaying Example

... still splaying ...



# Splaying Example

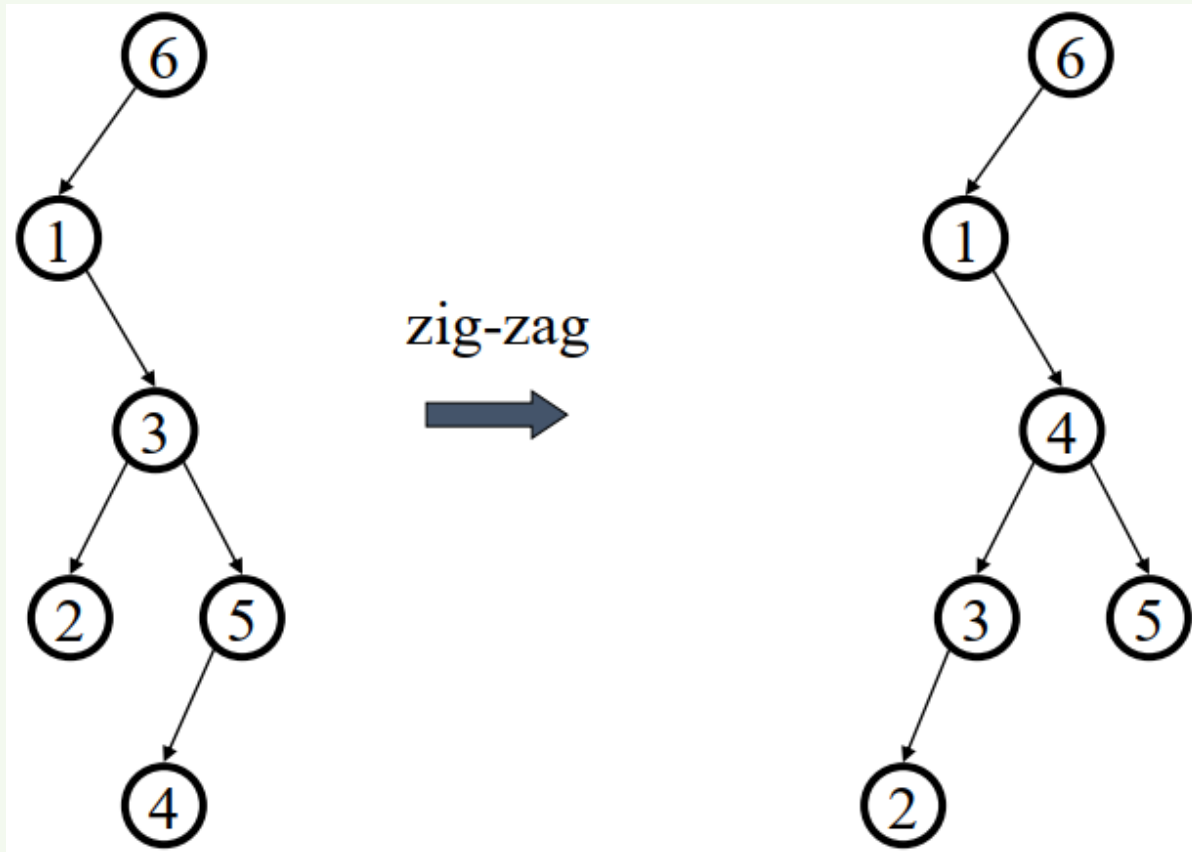
... 6 splayed out!



# Splaying Example

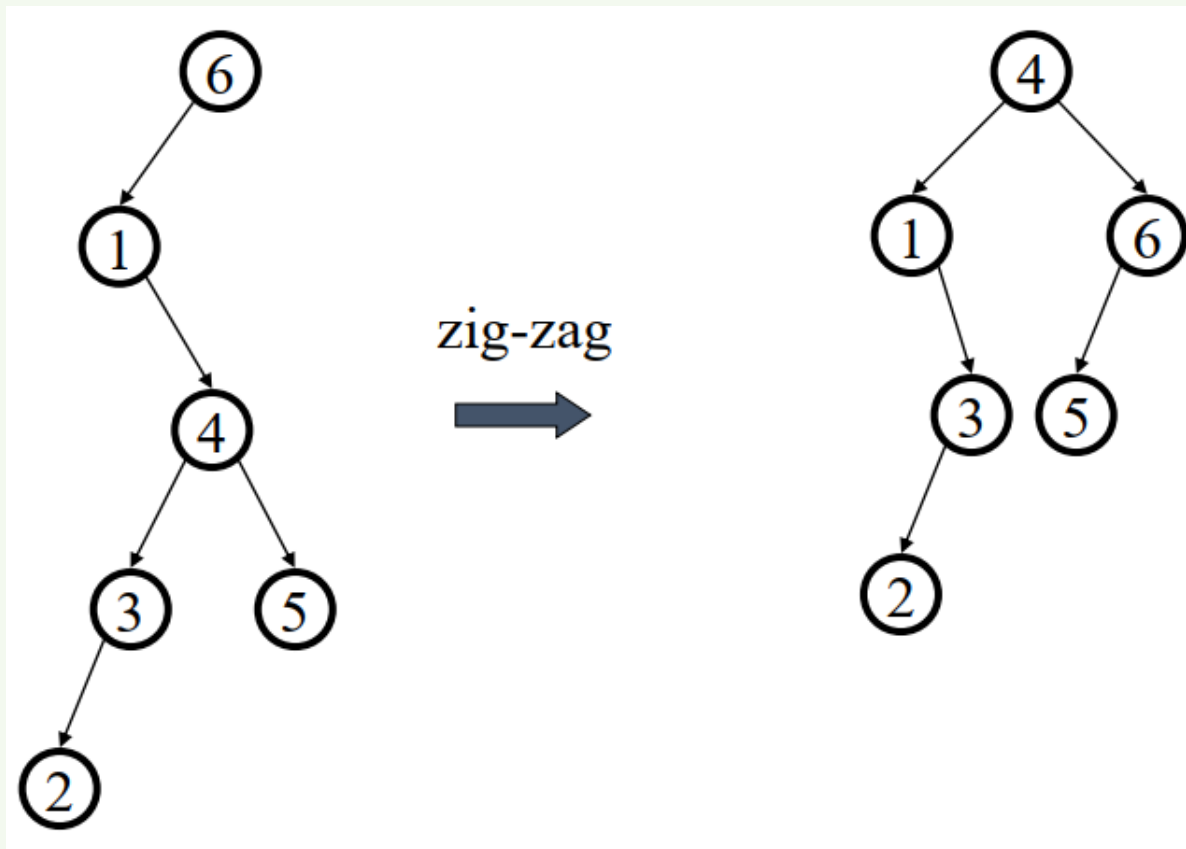
Find (4)

Splay it Again!



# Splaying Example

... 4 splayed out!





# Analyzing Calls to a Data Structure

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- Some algorithms involve repeated calls to one or more data structures
- Example:
  - repeatedly insert keys into a dynamic array
  - repeatedly remove the smallest key from the heap
- When analyzing the running time of the overall algorithm, need to sum up the time spent in all the calls to the data structure
- When different calls take different times, how can we accurately calculate the total time?

# Amortized Analysis

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- Purpose is to accurately compute the total time spent in executing a sequence of operations on a data structure
- Three different approaches:
  - **aggregate method**: brute force
  - **accounting method**: assign costs to each operation so that it is easy to sum them up while still ensuring that result is accurate
  - **potential method**: a more sophisticated version of the accounting method
- In Amortized Analysis, we analyze a sequence of operations and guarantee a worst-case average time which is lower than the worst-case time of a particular expensive operation.

# Dynamic Array Insertion

Item No.	1	2	3	4	5	6	7	8	9	10	.....
Table Size	1	2	4	4	8	8	8	8	16	16	.....
Cost	1	2	3	1	5	1	1	1	9	1	.....

$$\text{Amortized Cost} = \frac{(1 + 2 + 3 + 5 + 1 + 1 + 9 + 1 \dots)}{n}$$

We can simplify the above series by breaking terms 2, 3, 5, 9.. into two as (1+1), (1+2), (1+4), (1+8)

$$\begin{aligned} \text{Amortized Cost} &= \frac{\overbrace{[ (1 + 1 + 1 + 1 \dots) ]}^{n \text{ terms}} + \overbrace{[ (1 + 2 + 4 + \dots) ]}^{[\log_2(n-1)] + 1 \text{ terms}}}{n} \\ &\leq \frac{[n + 2n]}{n} \\ &\leq 3 \end{aligned}$$

$$\text{Amortized Cost} = O(1)$$

# Splay Tree Algorithm Analysis

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- Worst case time is  $O(n)$
- Amortized time for all operations is  $O(\log n)$ 
  - a sequence of  $M$  operations on an  $n$ -node splay tree takes  $O(M \log n)$  time.
  - Maybe not now, but soon, and for the rest of the operations

# Why Splaying Helps

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- If a node on the access path is at depth  $d$  before the splay, it's final depth  $\leq 3 + d/2$ 
  - Exceptions are the root, the child of the root, and the node splayed
- Overall, nodes which are below nodes on the access path tend to move closer to the root

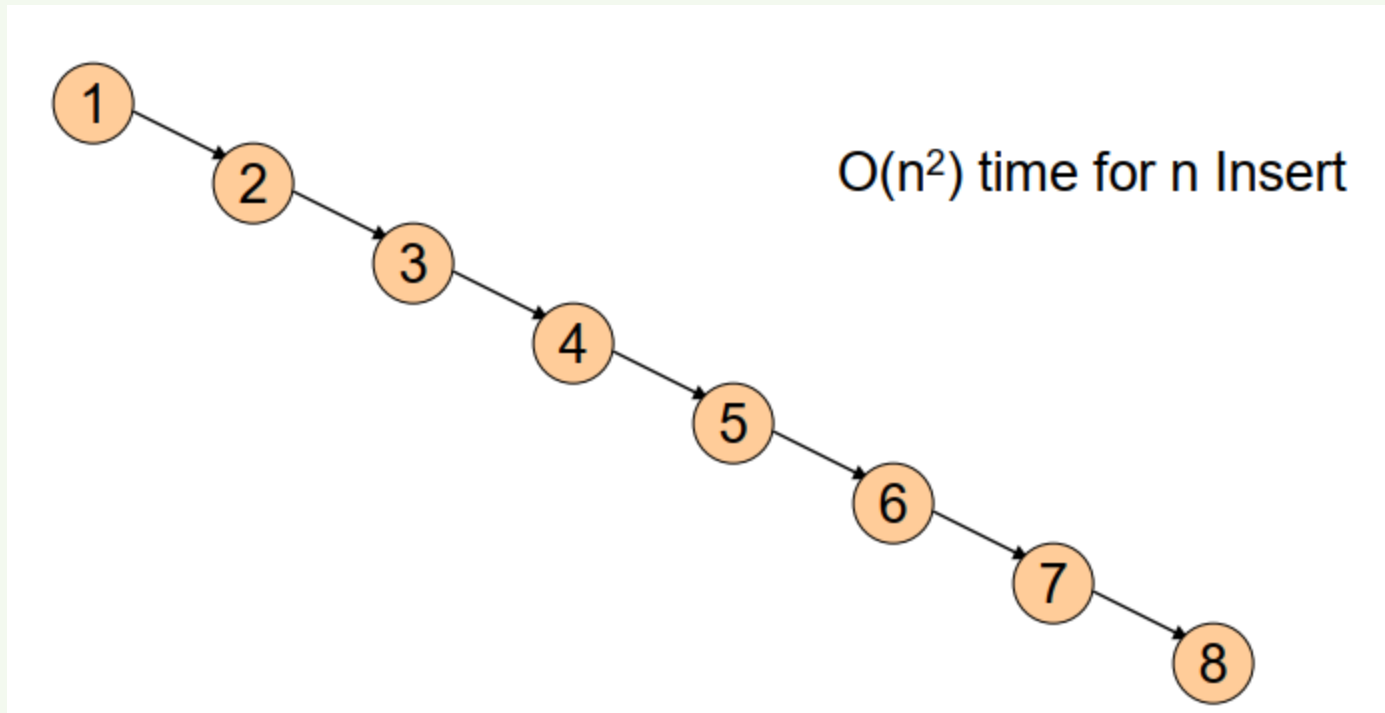
# Splay Tree Insert and Delete

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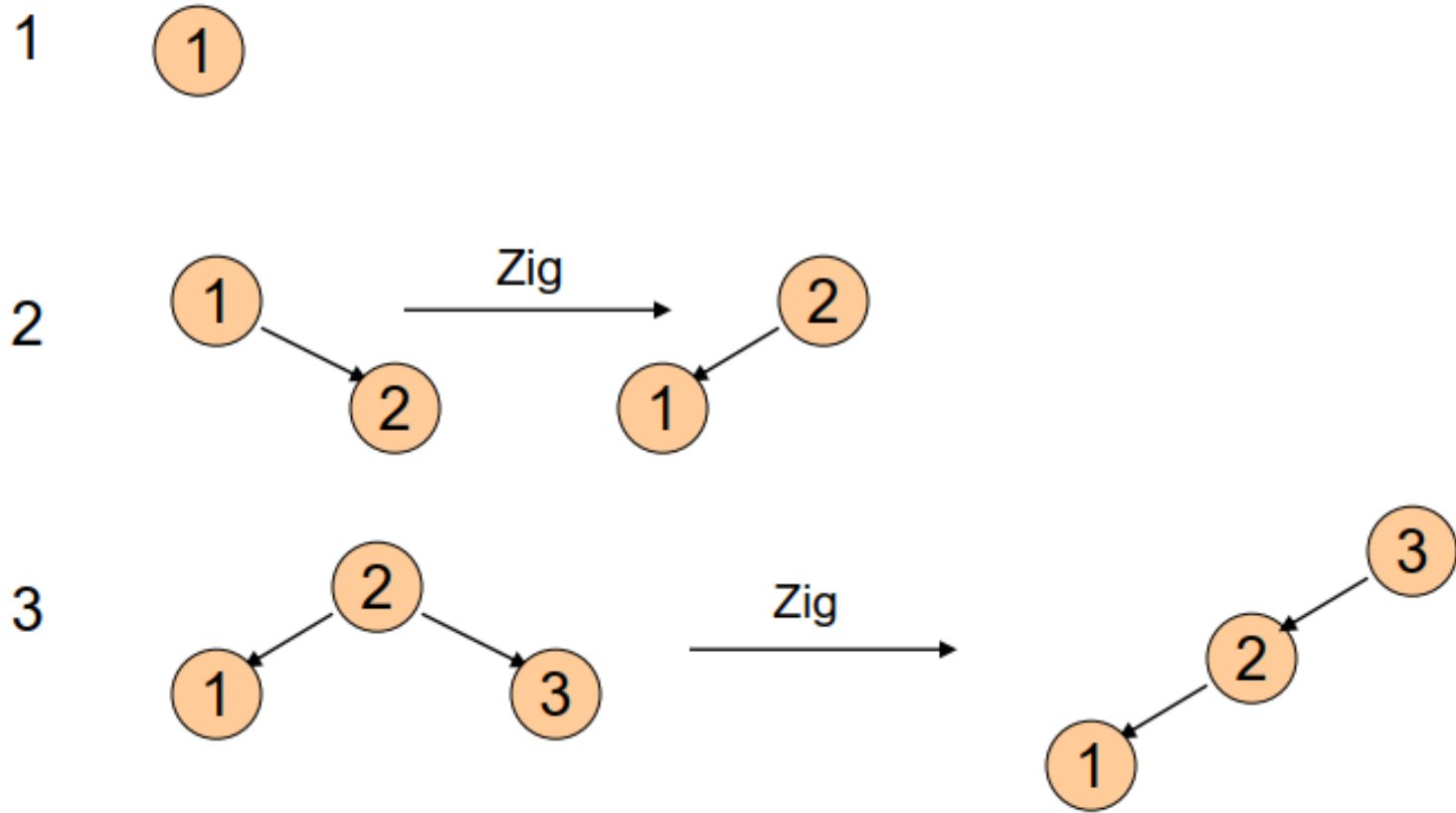
- Insert  $x$ 
  - Insert  $x$  as normal then splay  $x$  to root.
- Delete  $x$ 
  - Find  $x$
  - Splay  $x$  to root and remove it
  - Splay the max in the left subtree to the root
  - Attach the right subtree to the new root of the left subtree.

# Example Insert

- Inserting in order 1, 2, 3, ..., 8
- Without self-adjustment

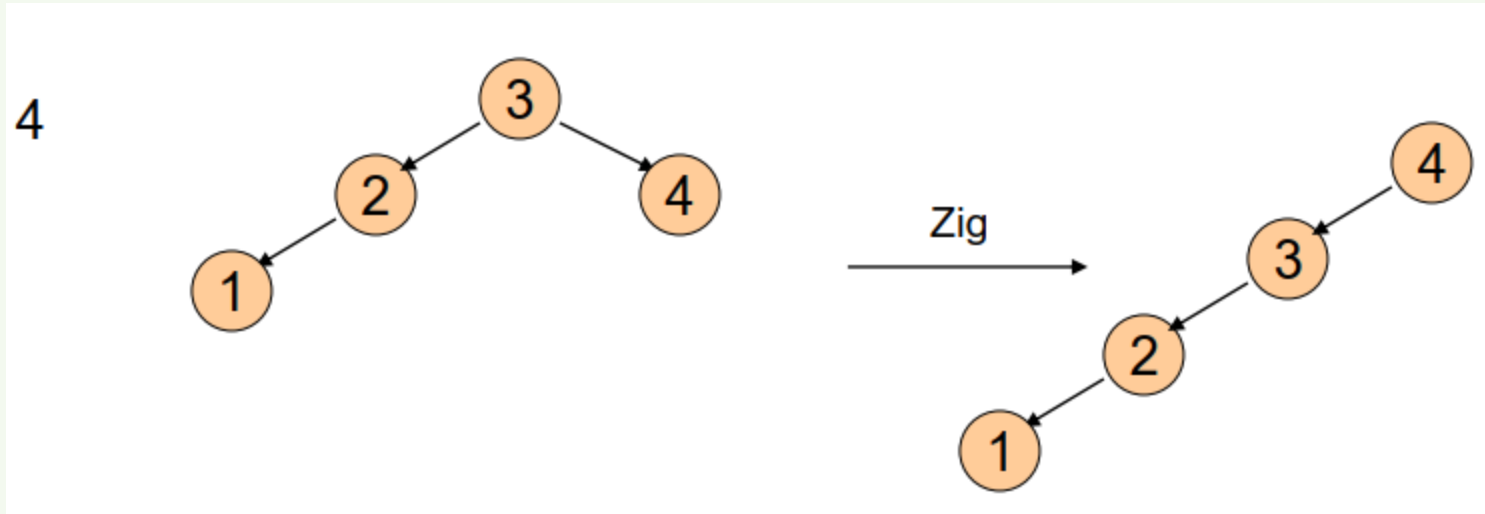


# With Self-Adjustment



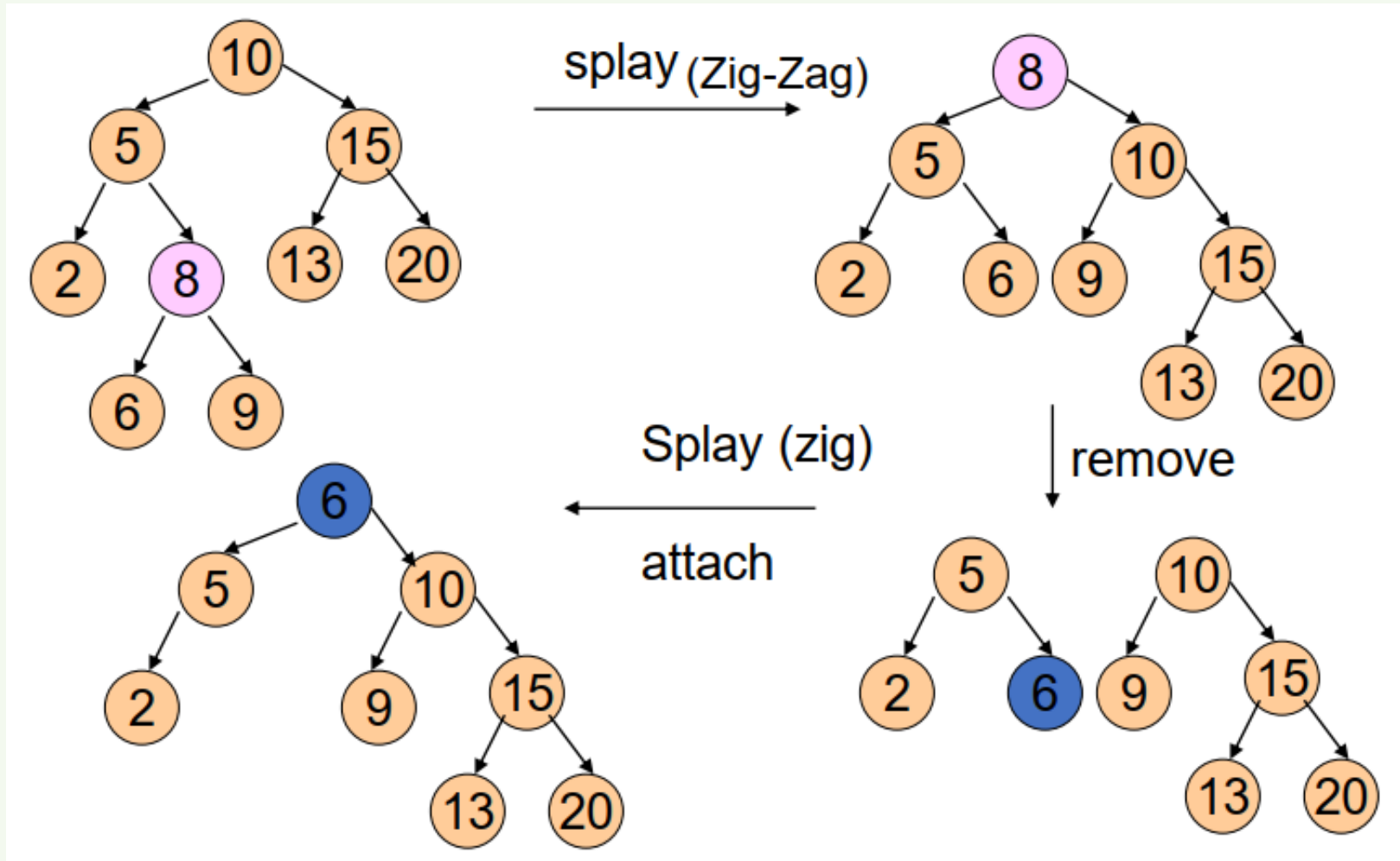


# With Self-Adjustment



Each Insert takes  $O(1)$  time therefore  $O(n)$  time for  $n$  Insert!!

# Example Deletion



# Summary of Search Trees

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- Problem with Binary Search Trees: Must keep tree balanced to allow fast access to stored items
- AVL trees: Insert/Delete operations keep tree balanced
- Splay trees: Repeated Find operations produce balanced trees
- Splay trees are very effective search trees
  - relatively simple: no extra fields required
  - excellent locality properties:
    - frequently accessed keys are cheap to find (near top of tree)
    - infrequently accessed keys stay out of the way (near bottom of tree)