

# Nonlinear Partial Differential Equations.

## • Exterior Domain Problem.

$$\begin{cases} -\Delta w + (w \cdot \nabla) w + \nabla p = 0 & \text{in } \Omega \subseteq \mathbb{R}^2 \\ \nabla \cdot w = 0 & \text{in } \Omega \\ w|_{\partial\Omega} = 0 \\ w(x) \rightarrow w_\infty = \lambda e_1 \text{ as } |x| \rightarrow \infty \end{cases}$$

## • Incompressible Navier-Stokes equations in three-dimensions.

$$\begin{cases} \partial_t v - \Delta v + (v \cdot \nabla) v + \nabla p = 0 & \text{in } \mathcal{D} \subseteq \mathbb{R}^3 \times \mathbb{R} \\ \nabla \cdot v = 0 & \text{in } \mathcal{D}. \end{cases}$$

## • Monge-Ampère Equation.

$$\det D^2 u = f \quad \text{in } \Omega \subset \mathbb{R}^n$$

for an unknown function  $u: \Omega \rightarrow \mathbb{R}$

Main Problems {

- Existence results for solutions.
- Localization theorems
- Geometry of sublevel sets
- Regularity results in the interior and at the boundary
- Classification of Global solutions
- Spectral theory.

## • Sine-Gordon equation

$$\partial_t^2 u - \partial_x^2 u + \sin(u) = 0$$

One of the first PDEs found to admit a family of breathers., which is given explicitly by

$$u(x, t) = 4 \arctan \left( \frac{m}{w} \frac{\sin(\omega t)}{\cosh(mx)} \right), \quad m, \omega > 0, \quad m^2 + \omega^2 = 1.$$

## • Klein-Gordon equations.

$$\partial_t^2 u - \partial_x^2 u + u - \frac{1}{3} u^3 - f(u) = 0,$$

where the nonlinearity  $f$  satisfies

$f(u)$  is a real-analytic odd function  
and  $f(u) = O(u^5)$  near 0.

\* K-G equation, general form:  $(\partial_t^2 v - \partial_x^2) v + F(v) = 0$ , where  $F(v)$

is a smooth real valued odd function  $F(x)$  with  $F'(0) > 0$  and  $F'''(0) < 0$ .

### • Burgers Equation

$$u_t = u u_x = D u_{xx}.$$

The above equation is nonlinear due to the product of  $u x$ . This elliptic equation is a simple case of the liquid flow

### • Diffusion-Reaction Equation (Fisher Equation).

$$u_t = D u_{xx} + f(u),$$

wherein  $f(u)$  is a polynomial of  $u$ , which denotes the reaction part of the equation, the diffusion part is  $D u_{xx}$ .

### • Compressible Navier - Stokes equations

The compressible fluid dynamics equations describe a fluid flow whose expression is given as:

$$\partial_t \rho + \nabla \cdot (\rho \mathbf{v}) = 0, \quad \rho (\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}) = -\nabla p + \eta \Delta \mathbf{v} + (\zeta + \eta/3) \nabla (\nabla \cdot \mathbf{v}),$$

$\partial_t (\epsilon + \rho v^2/2) + \nabla \cdot [(\epsilon + p + \rho v^2/2) \mathbf{v} - \mathbf{v} \cdot \boldsymbol{\sigma}'] = 0$ ,  
where  $\rho$  is the mass density,  $\mathbf{v}$  is the fluid velocity,  $p$  is the gas pressure,  $\epsilon$  is an internal energy describable by the equation of state,  $\boldsymbol{\sigma}'$  is the viscous stress tensor,  $\eta$  and  $\zeta$  are shear and bulk viscosity, respectively.

This equation can be applied to describe aerodynamics around airplane wings and interstellar gas dynamics.

### • Shallow - water Equations

$$\partial_t h + \nabla \cdot \mathbf{h} \mathbf{u} = 0, \quad \partial_t \mathbf{h} \mathbf{u} + \nabla \cdot \left( \mathbf{u}^2 \mathbf{h} + \frac{1}{2} g_r h^2 \right) = -g_r h \nabla b.$$

wherein,  $\mathbf{u} = u, v$  being the velocities in the horizontal and vertical direction,  $h$  describing the water depth, and  $b$  describing a spatially varying bathymetry.