

```
In [1]: 1 import numpy as np
2 import cmath
3 import time
4 import matplotlib.pyplot as plt
5 import scipy.io.wavfile as wavfile
6 import scipy.integrate as integrate
7 # import random
```

## Lab Book 01

```
In [2]: 1 def FMatrix(n):
2     F = np.zeros((n, n), dtype=complex)
3     omega = np.exp(-2*cmath.pi/n*1j)
4     for i in range(n):
5         for j in range(n):
6             F[i][j] = pow(omega, i*j)
7     return F
8
```

```
In [3]: 1 n = 10
2 Fn = FMatrix(n)
3 print(f"Check F{n} is symmetric by F{n} = F{n}.T:\n{Fn == Fn.T}")
4 nI = n*np.eye(n)
5 Fn_conj = np.conj(Fn)
6 # print(f"F{n}:\n{Fn}")
7 # print(f"F{n}·F{n}_conj = \n{Fn@Fn_conj}")
8 # print(f"{n}·I = \n{nI}")
9 print(
10     f"Check ||F{n}·F{n}_conj|| = ||{n}·I||:\n{np.isclose(np.linalg.
11     norm(Fn@Fn_conj, np.linalg.norm(nI)) < 1e-10)}")
```

Check F10 is symmetric by F10 = F10.T:

```
[[ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]
 [ True  True  True  True  True  True  True  True  True  True]]
```

Check ||F10·F10\_conj|| = ||10·I||:

True

## Lab Book 02

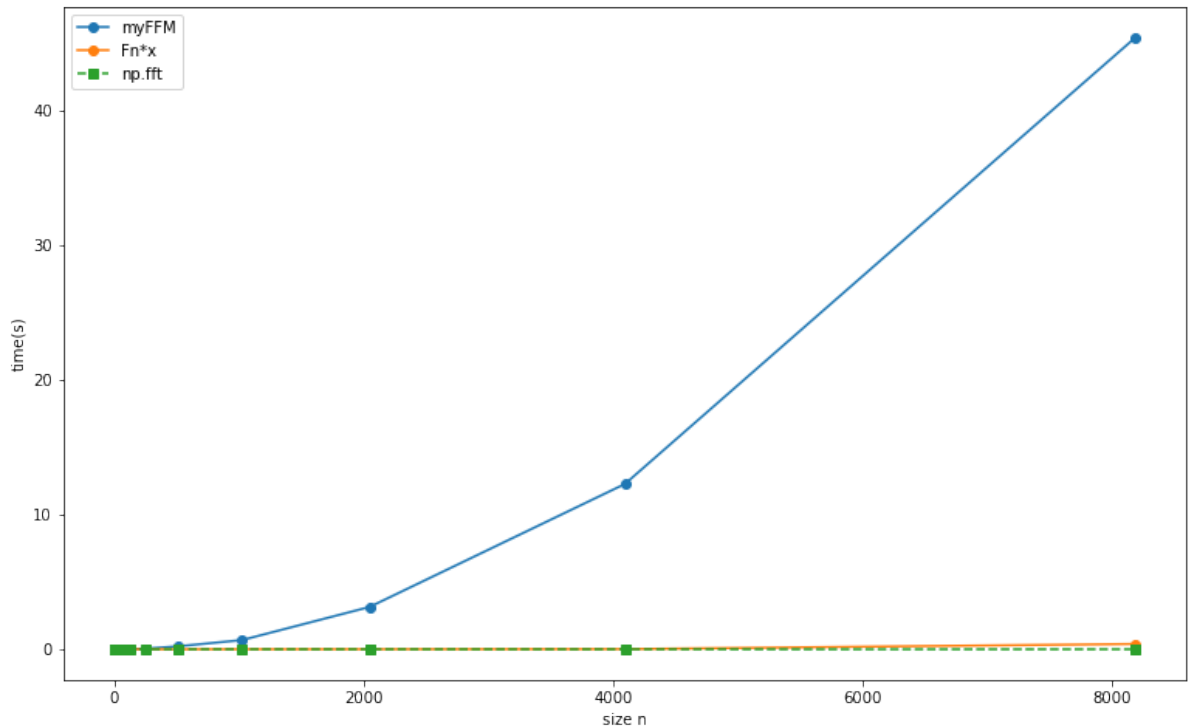
```

In [4]: 1 ns = [pow(2, i) for i in range(14)] # 12/14
2 FFM_runtime = np.zeros((len(ns), 3))
3 print("{0:^20}{1:^20}{2:^20}".format(
4     "Build Fn", "Calculate DFT", "Use np.fft"))
5 for i in range(len(ns)):
6     xs = np.arange(1, ns[i]+1)
7     time_start = time.time()
8     # Build matrix Fn
9     Fn = FFMatrix(ns[i])
10    time1 = time.time()
11    # Calculate DFT
12    x_hat = Fn @ xs
13    time2 = time.time()
14    # Calculate the same DFT with np.fft
15    Fn2 = np.fft.fft(xs)
16    time3 = time.time()
17    FFM_runtime[i][0] = time1-time_start
18    FFM_runtime[i][1] = time2-time1
19    FFM_runtime[i][2] = time3-time2
20    print(
21        f'{FFM_runtime[i][0]:^20.16f}{FFM_runtime[i][1]:^20.16f
22

```

Build Fn	Calculate DFT	Use np.fft
0.0000371932983398	0.0006787776947021	0.0001871585845947
0.0000460147857666	0.0020492076873779	0.0002048015594482
0.0000450611114502	0.0001018047332764	0.0000228881835938
0.0000460147857666	0.0000090599060059	0.0000100135803223
0.0004668235778809	0.0000169277191162	0.0000150203704834
0.0006151199340820	0.0000281333923340	0.0000298023223877
0.0024969577789307	0.0000498294830322	0.0002212524414062
0.0109620094299316	0.0009467601776123	0.0004591941833496
0.0499477386474609	0.0001351833343506	0.0000789165496826
0.2213809490203857	0.0002779960632324	0.0000419616699219
0.6824581623077393	0.0008959770202637	0.0000710487365723
3.1462609767913818	0.0034582614898682	0.0001409053802490
12.2830846309661865	0.0112092494964600	0.0002660751342773
45.4605779647827148	0.3940839767456055	0.0006079673767090

```
In [5]: 1 plt.figure(figsize=(13, 8))
2 plt.clf()
3 plt.plot(ns, FFM_runtime[:, 0], 'o-', label='myFFM',)
4 plt.plot(ns, FFM_runtime[:, 1], 'o-', markersize=6, label='Fn*x')
5 plt.plot(ns, FFM_runtime[:, 2], 's--', label='np.fft')
6 plt.xlabel('size n')
7 plt.ylabel('time(s)')
8 plt.legend(loc='best')
9 plt.show()
10
```



Due to the double for loops of size  $n$  used in my DFT, the time complexity of it is  $O(n^2)$ , therefore when the size of matrix is pretty big, the time consumed is increasing at a rate of  $n^2$ . Compared to the  $O(n \cdot \log n)$  time complexity of FFT, the DFT method is really time consuming and low efficient when  $n$  is big.

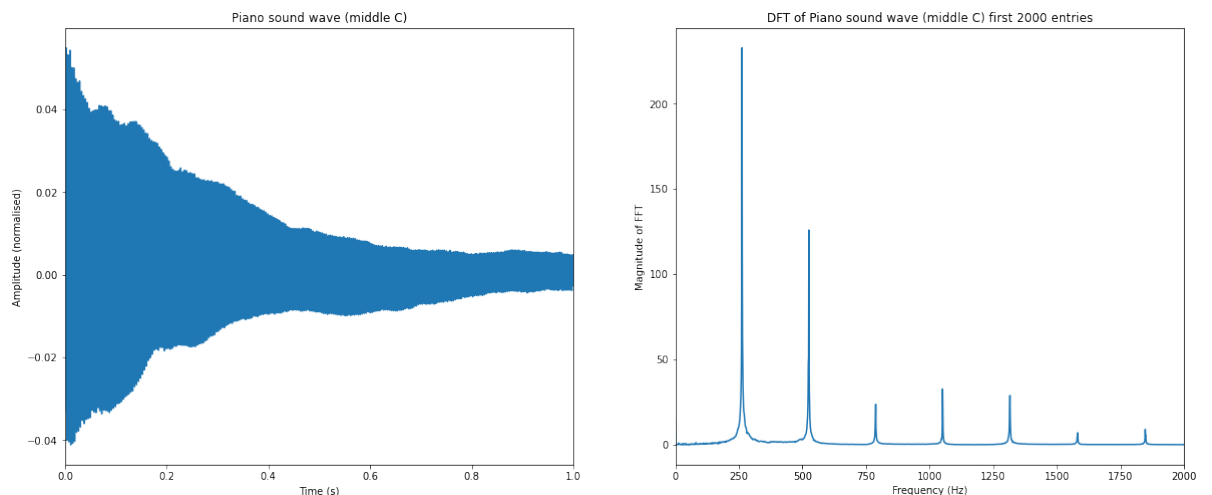
## Lab Book 03

```
In [6]: 1 data = np.loadtxt('lab5_piano_data.csv', delimiter=',')
2 time = np.linspace(0.0, 1.0, len(data)) # data represents 1 se
3 print("CSV has a vector of size =", data.shape)
4 np.random.seed(0)
5 noisy_data = data + 0.005 * np.random.randn(len(data))
6
```

CSV has a vector of size = (44100,)

```
In [7]: 1 # Save data as playable files
2 samplerate = 44100 # samples per second in the audio
3 # Note: after an inverse DFT you usually get complex values wit
4 # (of size machine epsilon), which we need to remove before sav
5 wavfile.write('my_audio.wav', samplerate, np.real(data))
6 wavfile.write('my_audio_noise.wav', samplerate, np.real(noisy_d
```

```
In [8]: 1 plt. figure(figsize= (20,8))
2 plt. subplot(1,2,1)
3 plt. plot(time,data)
4 plt.title('Piano sound wave (middle C)')
5 plt.xlabel('Time (s)')
6 plt.ylabel('Amplitude (normalised)')
7 plt. xlim(0.0,1.0)
8
9 plt. subplot(1,2,2)
10 plt. plot(np. arange(len(data)),abs(np. fft. fft(data[:]))))
11 plt.title('DFT of Piano sound wave (middle C) first 2000 entrie
12 plt.xlabel('Frequency (Hz)')
13 plt.ylabel('Magnitude of FFT')
14 plt. xlim(0.0,2000)
15
16 plt.show()
```

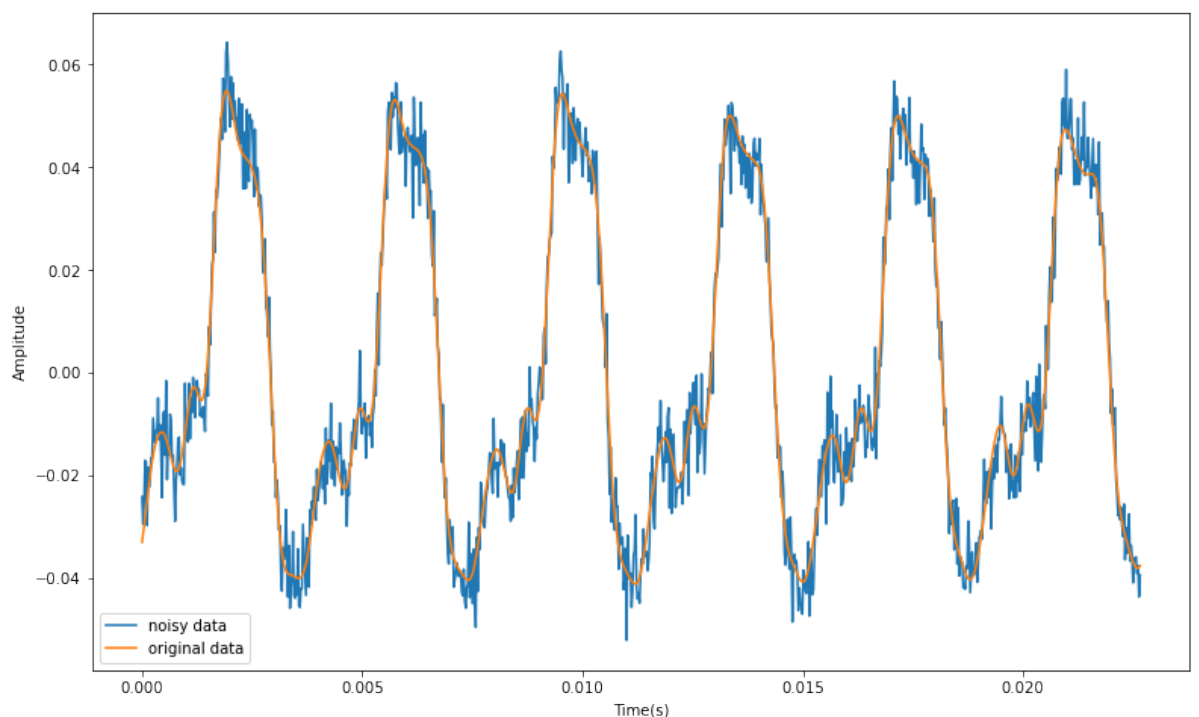


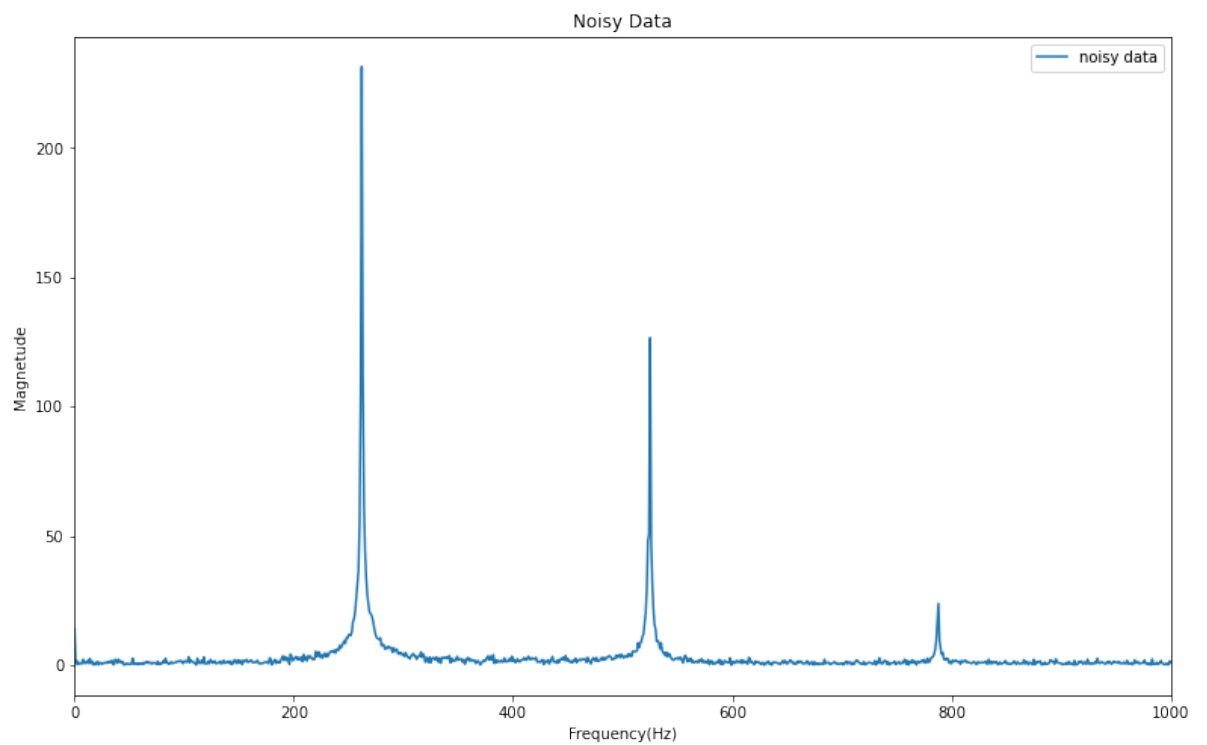
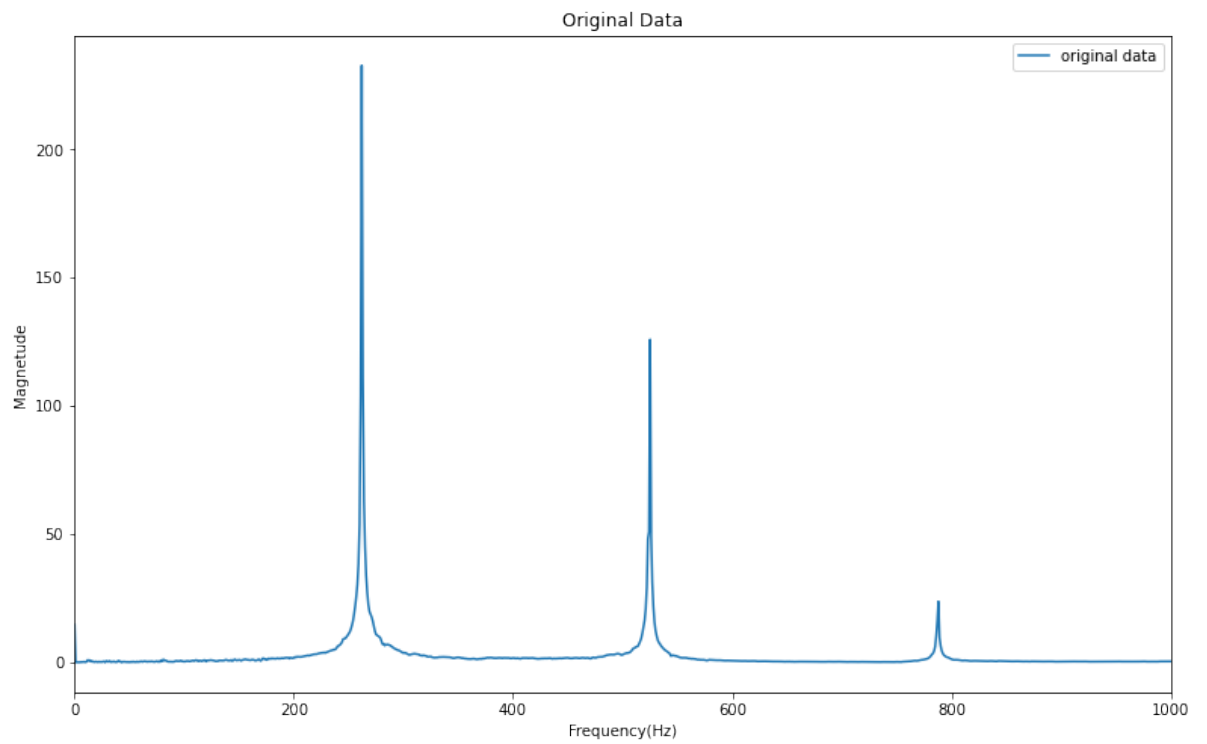
In [9]:

```

1 frequency = data.shape[0]
2 time = np.linspace(0, 1, data.shape[0])
3 fs = np.arange(0, frequency)
4 # first 2000 elements
5 n = 1000
6
7 plt.figure(figsize=[13, 8])
8 plt.plot(time[:n], noisy_data[:n], label='noisy data')
9 plt.plot(time[:n], data[:n], label='original data')
10 plt.xlabel('Time(s)')
11 plt.ylabel('Amplitude')
12 plt.legend(loc='best')
13 plt.show()
14
15 plt.figure(figsize=[13, 8])
16 # plt.plot(fs, np.fft.fftshift(
17 #     abs(np.fft.fft(np.real(noisy_data)))), label='noisy data'
18 plt.plot(fs, abs(np.fft.fft(np.real(data))), label='original da
19 plt.xlabel('Frequency(Hz)')
20 plt.ylabel('Magnetude')
21 plt.title('Original Data')
22 plt.legend(loc='best')
23 plt.xlim(0, n)
24 plt.show()
25
26 noisy_data_hat = np.fft.fft(noisy_data)
27 plt.figure(figsize=[13, 8])
28 plt.plot(fs, abs(noisy_data_hat), label='noisy data')
29 # plt.plot(fs, np.fft.fftshift(
30 #     abs(np.fft.fft(np.real(data)))), label='original data')
31 plt.xlabel('Frequency(Hz)')
32 plt.ylabel('Magnetude')
33 plt.title('Noisy Data')
34 plt.legend(loc='best')
35 plt.xlim(0, n)
36 plt.show()

```

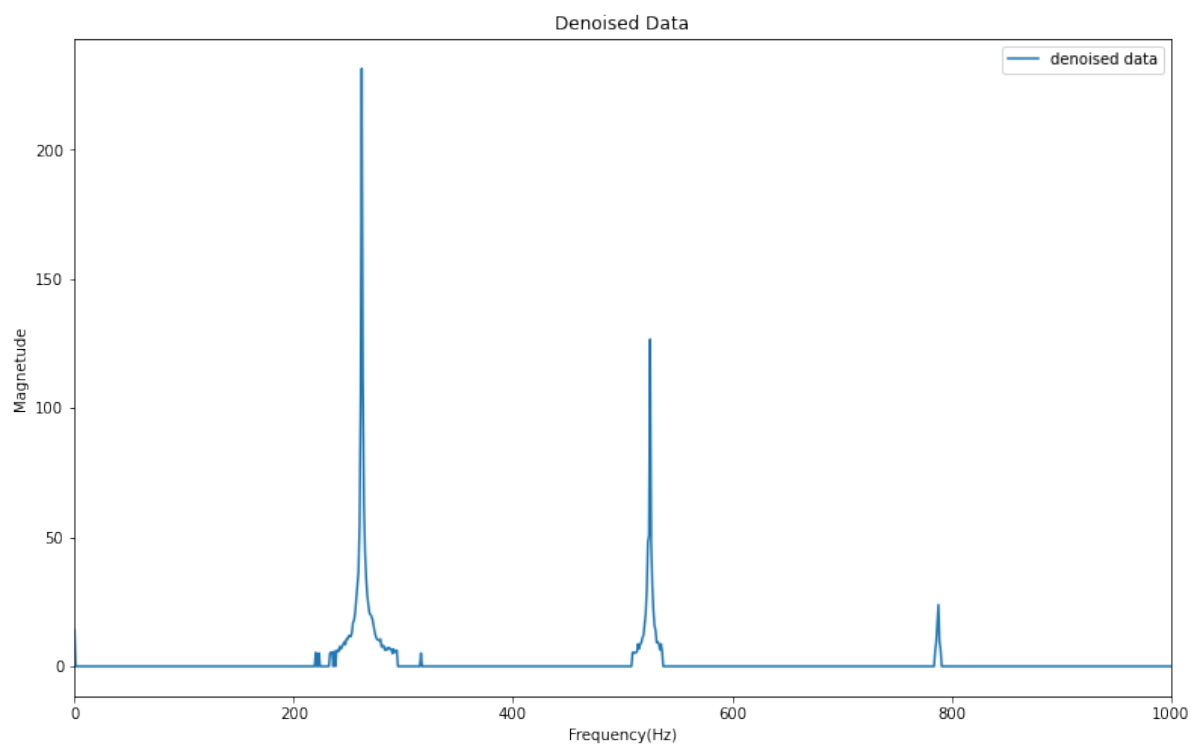




```
In [10]: 1 def remove_magnitude(x,lim):  
2         if abs(x) < lim:  
3             return 0  
4         else:  
5             return x
```

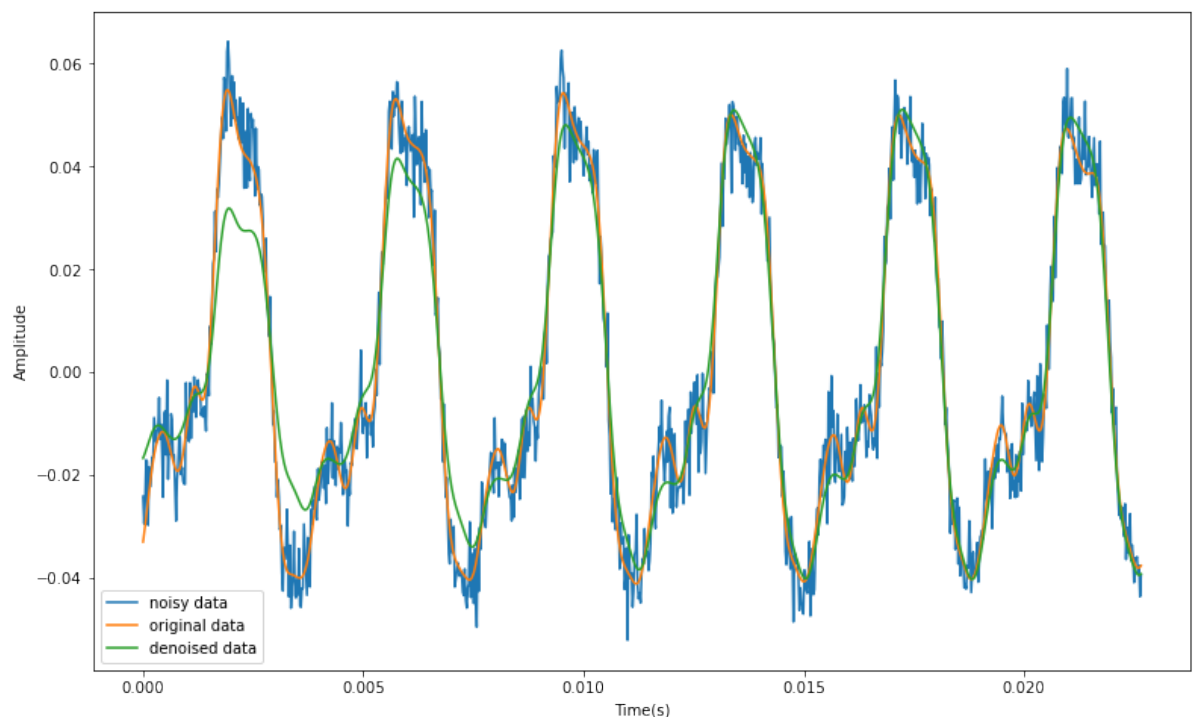
```
In [11]: 1 denoised_hat = list(map(remove_magnitude,noisy_data_hat,[5]*fre
```

```
In [12]: 1 plt.figure(figsize=[13, 8])
2 plt.plot(fs, list(map(abs,denoised_hat)), label='denoised data')
3 plt.xlabel('Frequency(Hz)')
4 plt.ylabel('Magnetude')
5 plt.legend(loc='best')
6 plt.title('Denoised Data')
7 plt.xlim(0, n)
8 plt.show()
9
```



```
In [13]: 1 denoised = np.fft.ifft(denoised_hat)
2
3 plt.figure(figsize=[13, 8])
4 plt.plot(time[:n], noisy_data[:n], label='noisy data')
5 plt.plot(time[:n], data[:n], label='original data')
6 plt.plot(time[:n], denoised[:n], label='denoised data')
7 plt.xlabel('Time(s)')
8 plt.ylabel('Amplitude')
9 plt.legend(loc='best')
10 plt.show()
11
```

/Users/x\_x/opt/anaconda3/lib/python3.7/site-packages/matplotlib/cookiecutter/\_\_init\_\_.py:1298: ComplexWarning: Casting complex values to real discards the imaginary part  
return np.asarray(x, float)



```
In [14]: 1 err_with_data = np.linalg.norm(denoised-data)
2 # print(denoised)
3 # print(data)
4 err_with_noisy = np.linalg.norm(data-noisy_data)
5 # print(err_with_data)
6 # print(err_with_noisy)
7 print(f"The error of denoised data and noisy data against original data are 0.3475626828391964 and 1.0451029075185467 respectively.")
8 print(f"The denoised signal is clearly closer to the original signal.")
```

The error of denoised data and noisy data against original data are 0.3475626828391964 and 1.0451029075185467 respectively.  
The denoised signal is clearly closer to the original signal.

## Lab Book 04



```
In [15]: 1 P = 10000
          2 u0 = 1/P # initial condition
          3 T = 100 # end time
          4 n = 200 # use n+1 equally spaced time steps
          5 ts = np.linspace(0, T, n+1) # vector of timesteps, tk = ts[k]
          6 h = T / n # gap between timesteps
```

In [16]:

```

1  def f(t, u):
2      c = 0.2
3      return c * u * (1-u)
4
5
6  def u(t):
7      P = 10000
8      c = 0.2
9      return 1/(1+(P-1)*np.exp(-c*t))
10
11
12 def Euler(t0, u0, n):
13     u_Euler = np.zeros((n+1,))
14     u_Euler[0] = u0
15     for k in range(n):
16         u_Euler[k+1] = u_Euler[k] + h * f(ts[k], u_Euler[k])
17     return u_Euler
18
19
20 def Heun(t0, u0, n):
21     u_Heun = np.zeros((n+1,))
22     u_Heun[0] = u0
23     for k in range(n):
24         u_Heun[k+1] = u_Heun[k] + 0.5 * h * \
25             (f(ts[k], u_Heun[k]) + f(ts[k]+h, u_Heun[k]+h*f(ts[
26     return u_Heun
27
28
29 def RK4(t0, u0, T, n):
30     h = T / n
31     ts = []
32     us = []
33     ts.append(t0)
34     us.append(u0)
35     # i = 0
36     # while ts[i]+h <= tmax:
37     for i in range(n):
38         k1 = f(ts[i], us[i])
39         k2 = f(ts[i] + 0.5 * h, us[i] + 0.5 * h * k1)
40         k3 = f(ts[i] + 0.5 * h, us[i] + 0.5 * h * k2)
41         k4 = f(ts[i] + h, us[i] + h * k3)
42         us.append(us[i] + (h / 6)*(k1 + 2 * k2 + 2 * k3 + k4))
43         ts.append(ts[i] + h)
44         # i += 1
45     return ts, us
46

```

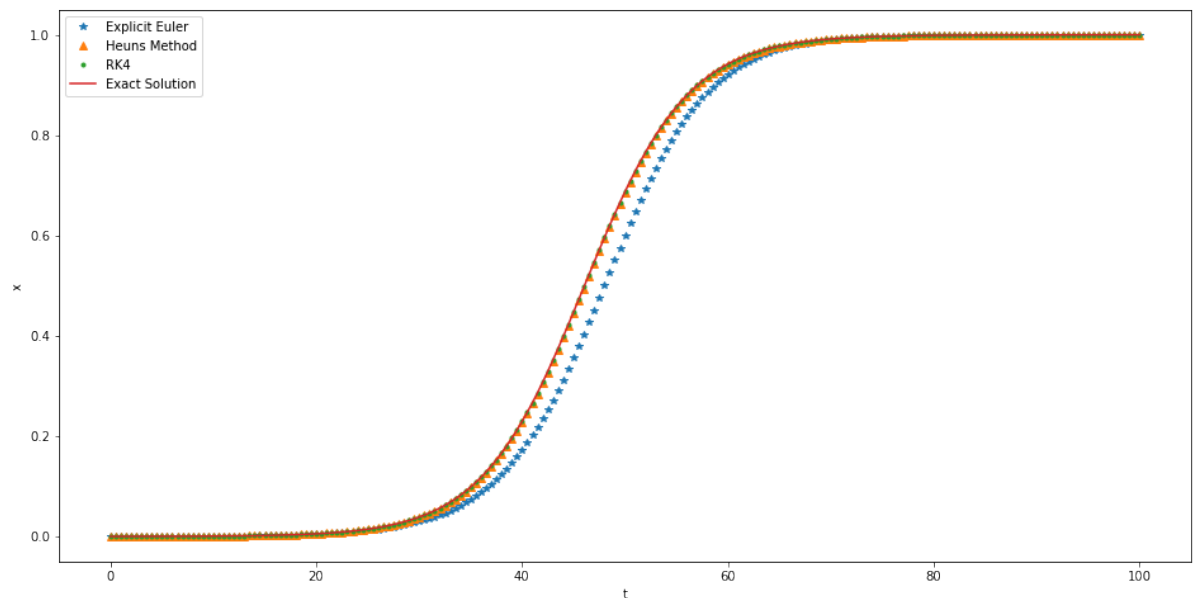
In [17]:

```

1  u_Euler = Euler(0, u0, n)
2  u_Heun = Heun(0, u0, n)
3  ts_RK4, u_RK4 = RK4(0, u0, T, n)
4  u_exact = u(ts)

```

```
In [18]: 1 plt.figure(figsize=[16, 8])
2 plt.plot(ts, u_Euler, '*', label='Explicit Euler')
3 plt.plot(ts, u_Heun, '^', label='Heuns Method')
4 plt.plot(ts_RK4, u_RK4, '.', label='RK4')
5 plt.plot(ts, u_exact, label='Exact Solution')
6 plt.xlabel('t')
7 plt.ylabel('x')
8 plt.legend(loc='best')
9 plt.show()
10
```



The Explicit Euler method has a much lower accuracy compared to Heuns Method and RK4.

This solution of ODE shows the whole process of the spread of a disease in 100 days. We can see a quick raise in infected population between 40-60 days and about 80% of the population will be infected in this period if no method like quarantine and vaccine.

## Lab Book 05

```

In [19]: 1 ns = [50, 100, 200, 400, 800, 1600]
2 E = []
3 H = []
4 RK = []
5 hss = []
6 print("{0:^7}{1:^20}{2:^20}{3:^20}".format("h", "Euler", "Heun"
7 for n in ns:
8     ts = np.linspace(0, T, n+1)
9     h = T / n
10    u_Euler = Euler(0, u0, n)
11    u_Heun = Heun(0, u0, n)
12    ts_RK4, u_RK4 = RK4(0, u0, T, n)
13    u_exact = u(ts)
14    Euler_max = max(abs(u_Euler-u_exact))
15    Heun_max = max(abs(u_Heun-u_exact))
16    RK4_max = max(abs(u_RK4-u_exact))
17    hss.append(h)
18    E.append(Euler_max)
19    H.append(Heun_max)
20    RK.append(RK4_max)
21    print(f'{h:^5.5f}{Euler_max:^20.16f}{Heun_max:^20.16f}{RK4_
22

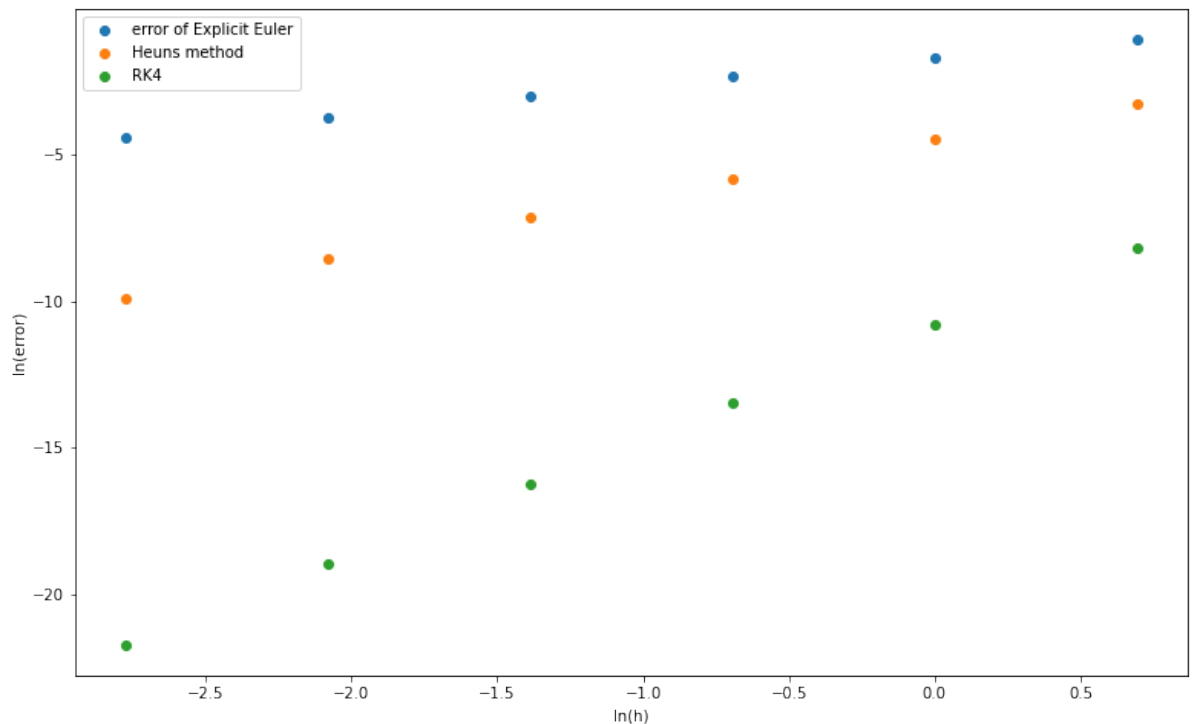
```

h	Euler	Heun	RK4
2.00000	0.3511787828005281	0.0392733327566064	0.0002786116269167
1.00000	0.1876126831731261	0.0112001559813495	0.0000203235920652
0.50000	0.0961272883004560	0.0029997295057085	0.0000013730543685
0.25000	0.0485262270538754	0.0007761598708744	0.0000000892409335
0.12500	0.0243630855173878	0.0001974844529142	0.0000000056883146
0.06250	0.0122042807862079	0.0000498082592145	0.0000000003590142

```

In [20]: 1 plt.figure(figsize=[13, 8])
2 plt.scatter(np.log(hss), np.log(E), label='error of Explicit Eu
3 plt.scatter(np.log(hss), np.log(H), label='Heuns method')
4 plt.scatter(np.log(hss), np.log(RK), label='RK4')
5 plt.legend()
6 plt.xlabel('ln(h)')
7 plt.ylabel('ln(error)')
8 plt.show()
9 slope1 = np.polyfit(np.log(hss), np.log(E), 1)[0]
10 slope2 = np.polyfit(np.log(hss), np.log(H), 1)[0]
11 slope3 = np.polyfit(np.log(hss), np.log(RK), 1)[0]
12 print(f"the order of convergence of Explicit Euler method is {s
13 print(f"the order of convergence of Heun's method is {slope2}")
14 print(f"the order of convergence of RK4 is {slope3}")
15

```



the order of convergence of Explicit Euler method is 0.9729965612487067

the order of convergence of Heun's method is 1.9297731741060276

the order of convergence of RK4 is 3.919458729847732

## Lab Book 06

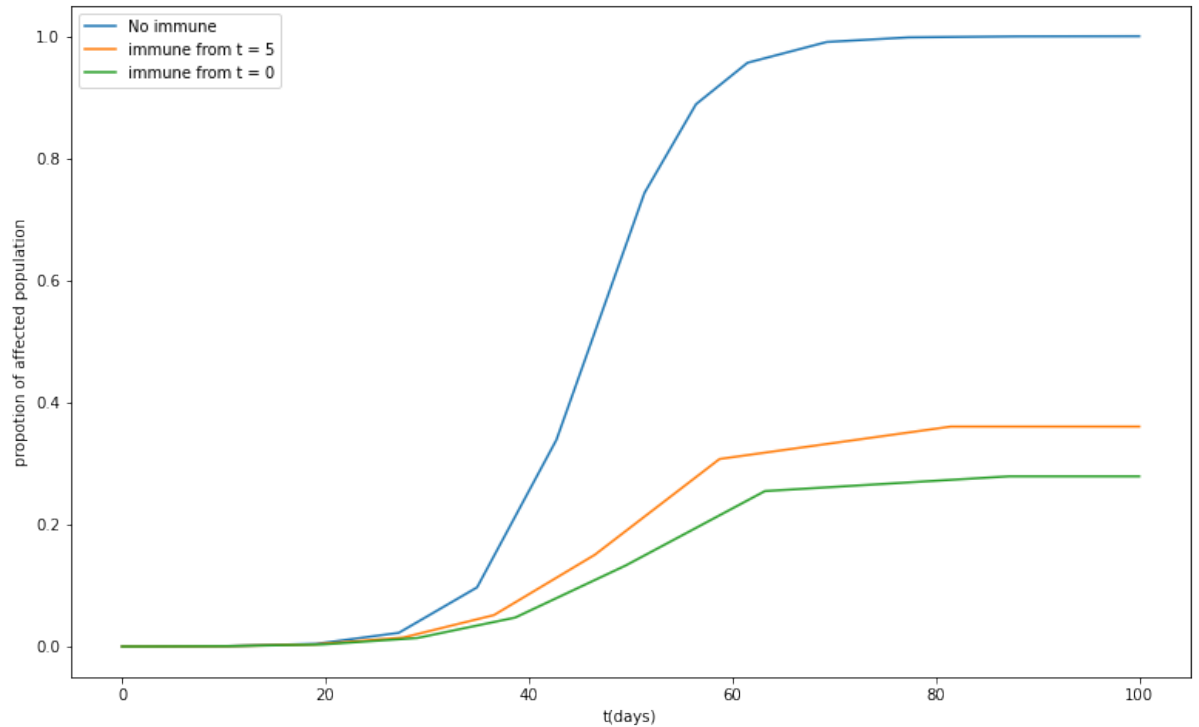
In [21]:

```
1 def f_immu(t, u):
2     c = 0.2
3     return c * u * max(1-u-0.01*max(t-5, 0), 0)
4
5
6 def f_immu0(t, u):
7     c = 0.2
8     return c * u * max(1-u-0.01*t, 0)
9
```

In [22]:

```
1 P = 10000
2 u0 = np.array([1/P])
3 T = 100
4 sol = integrate.solve_ivp(f, [0, T], u0, method='RK45')
5 # print(sol.y)
6 sol_immu = integrate.solve_ivp(f_immu, [0, T], u0, method='RK45')
7 # print(sol_immu.y)
8 healthy = sol.y * P
9 healthy_immu = sol_immu.y * P
10 sol_immu0 = integrate.solve_ivp(f_immu0, [0, T], u0, method='RK45')
11 healthy_immu0 = sol_immu0.y * P
12
```

```
In [23]: 1 plt.figure(figsize=[13, 8])
2 plt.plot(sol.t, sol.y[0,:], label='No immune')
3 plt.plot(sol_immu.t, sol_immu.y[0,:], label='immune from t = 5')
4 plt.plot(sol_immu0.t, sol_immu0.y[0,:], label='immune from t = 0')
5 plt.xlabel('t(days)')
6 plt.ylabel('propotion of affected population')
7 plt.legend(loc='best')
8 plt.show()
9
```



```
In [24]: 1 print(f"Without immune, the number of healthy people mathmetica
2 print(f"\nWith vaccinating from the fifth day, the mathmetically
3 extra_healthy = abs(sol_immu0.y[0][-1] - sol_immu.y[0][-1])
4 print(f"\n{extra_healthy*P} (815) more people will be healthy i
```

Without immune, the number of healthy people mathmetically is 0.74 88286951184975, which means almost no one is still healthy after 100 days.

With vaccinating from the fifth day, the mathmetically number of healthy people after 100 days is 6395.897785341395, which is about 6396 people.

814.9610528256312 (815) more people will be healthy if we start vaccination from t = 0 after 100 days.

## Lab Book 07

```

In [25]: 1 def f(x):
          2     return np.sin(np.pi*x)
          3
          4
          5 def f_t_ut(a, b, c, n, u):
          6     delta_x = 1 / n
          7     u_k = np.zeros(n+1)
          8     u_k[0] = a
          9     u_k[-1] = b
         10     for i in range(1, n):
         11         u_k[i] = c * (u[i-1] - 2 * u[i] + u[i+1]) / pow(delta_x, 2)
         12     return u_k
         13

```

```

In [26]: 1 def PDE_solver(a, b, c, f, t_max, n):
          2     delta_t = t_max / (pow(n, 2))
          3     delta_x = 1 / n
          4     j = np.arange(n+1)
          5     xs = j * delta_x
          6     u = np.zeros((pow(n, 2)+1, n+1))
          7     # u = np.array([f(xs)])
          8     u[0] = f(xs)
          9     # t = 0
         10     # while t <= t_max:
         11     #     u_next = u[-1] + [delta_t * f_t_ut(a, b, c, n, u[-1])]
         12     #     u = np.append(u, u_next, axis=0)
         13     #     t += delta_t
         14     for i in range(1, u.shape[0]):
         15         u[i] = u[i-1] + [delta_t * f_t_ut(a, b, c, n, u[i-1])]
         16     return u
         17

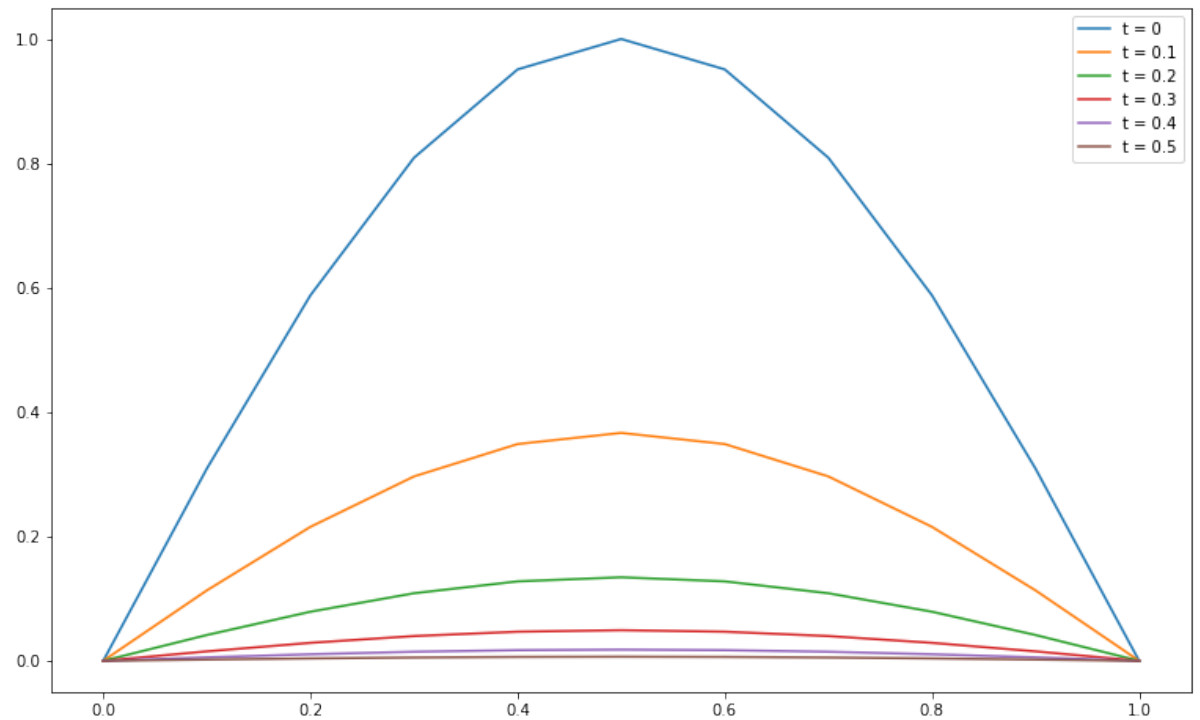
```



In [27]:

```
1 a = 0
2 b = 0
3 c = 1
4 t_max = 0.5
5 n = 10
6 u = PDE_solver(a, b, c, f, t_max, n)
7 print(u.shape)
8 xs = np.linspace(0, 1, len(u[0]))
9 ts = np.linspace(0, t_max, 6)
10 t_index = (ts*100/t_max)
11 plt.figure(figsize=[13, 8])
12 for i in t_index:
13     i = int(i)
14     plt.plot(xs, u[i])
15 plt.legend(['t = 0', 't = 0.1', 't = 0.2', 't = 0.3', 't = 0.4']
16 plt.show()
17
```

(101, 11)



## Lab Book 08

In [28]:

```
1 def f(x):
2     return 0.5 - x
3
```

```
In [29]: 1 alpha1 = 0.48
2 dt1 = alpha1/pow(n,2)
3 alpha2 = 0.5
4 dt2 = alpha2/pow(n,2)
5 alpha3 = 0.52
6 dt3 = alpha3/pow(n,2)
7 n = 100
8
```

```
In [30]: 1 u1 = PDE_solver(0.5,-0.5,1,f,alpha1,n)
2 u2 = PDE_solver(0.5,-0.5,1,f,alpha2,n)
3 u3 = PDE_solver(0.5,-0.5,1,f,alpha3,n)
4
```

```
/Users/x_x/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:11: RuntimeWarning: overflow encountered in double_scalars
```

```
# This is added back by InteractiveShellApp.init_path()
```

```
/Users/x_x/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:15: RuntimeWarning: invalid value encountered in add
```

```
from ipykernel import kernelapp as app
```

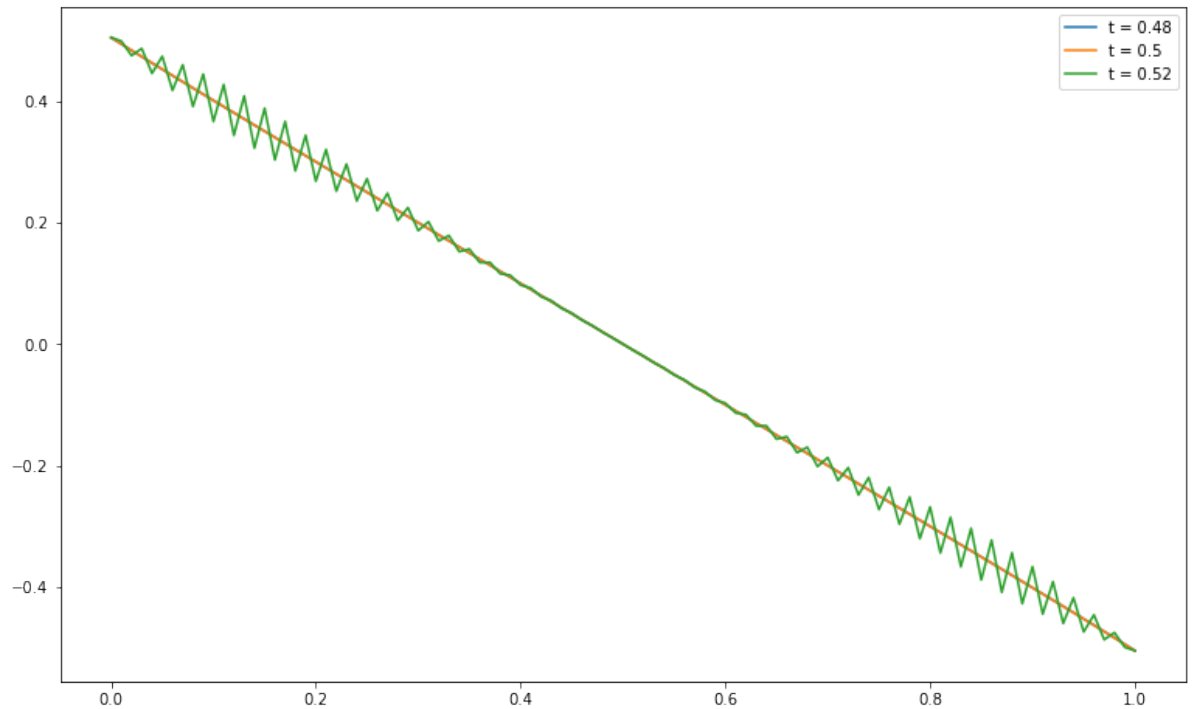
```
/Users/x_x/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:11: RuntimeWarning: invalid value encountered in double_scalars
```

```
# This is added back by InteractiveShellApp.init_path()
```

```

In [31]: 1 xs = np.linspace(0, 1, len(u1[0]))
          2 ts = np.linspace(0, t_max, 6)
          3 t_index = 200
          4 plt.figure(figsize=[13, 8])
          5 plt.plot(xs, u1[t_index], label = 't = 0.48')
          6 plt.plot(xs, u2[t_index], label = 't = 0.5')
          7 plt.plot(xs, u3[t_index], label = 't = 0.52')
          8 plt.legend()
          9 plt.show()
         10

```



Both  $t = 0.48$  and  $t = 0.5$  gives correct solution because  $dt \leq dx^2 / 2c$ .

However when  $t = 0.52$ ,  $dt > dx^2 / 2c$ , therefore the method we use to find the solution to the heat equation is no longer stable and leads to the fluctuations in solutions.