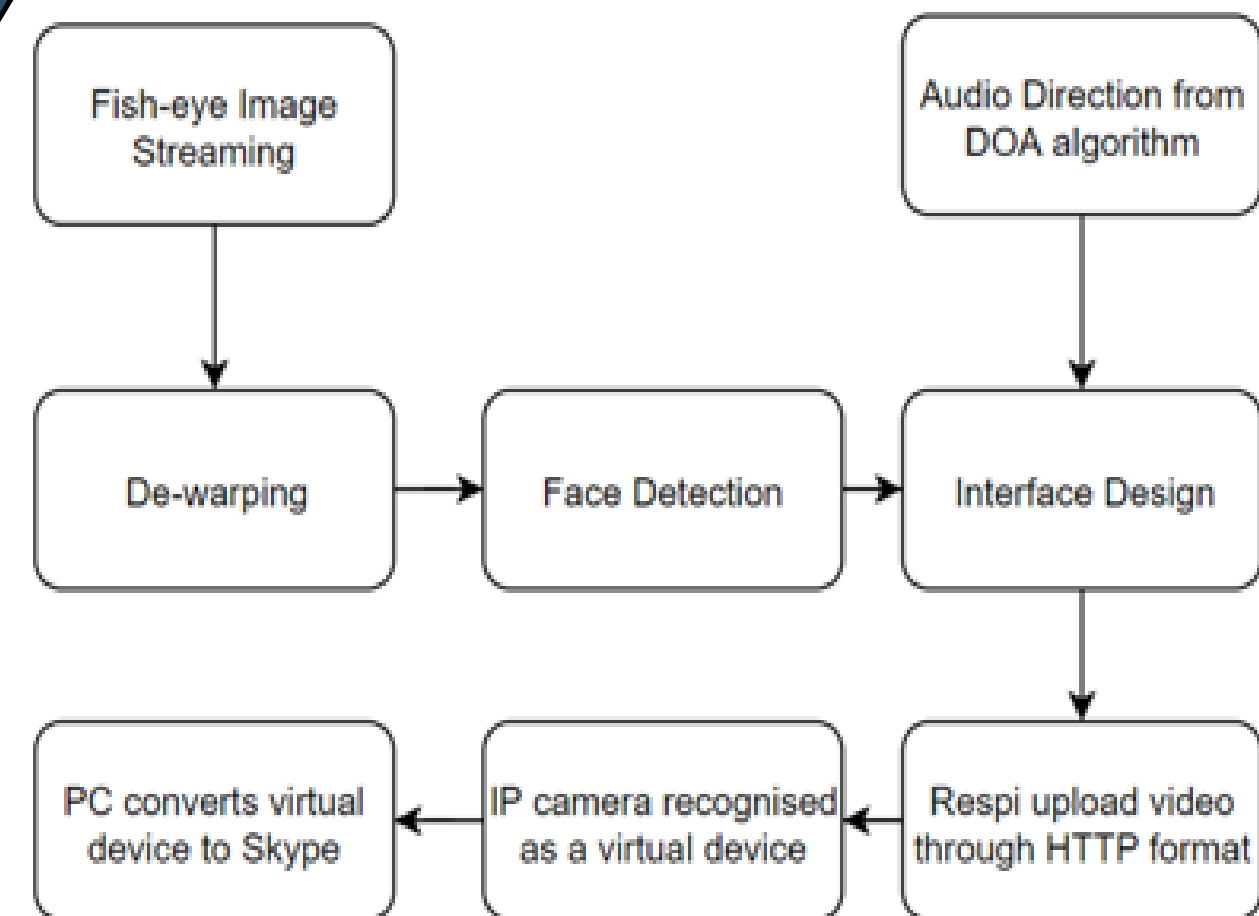
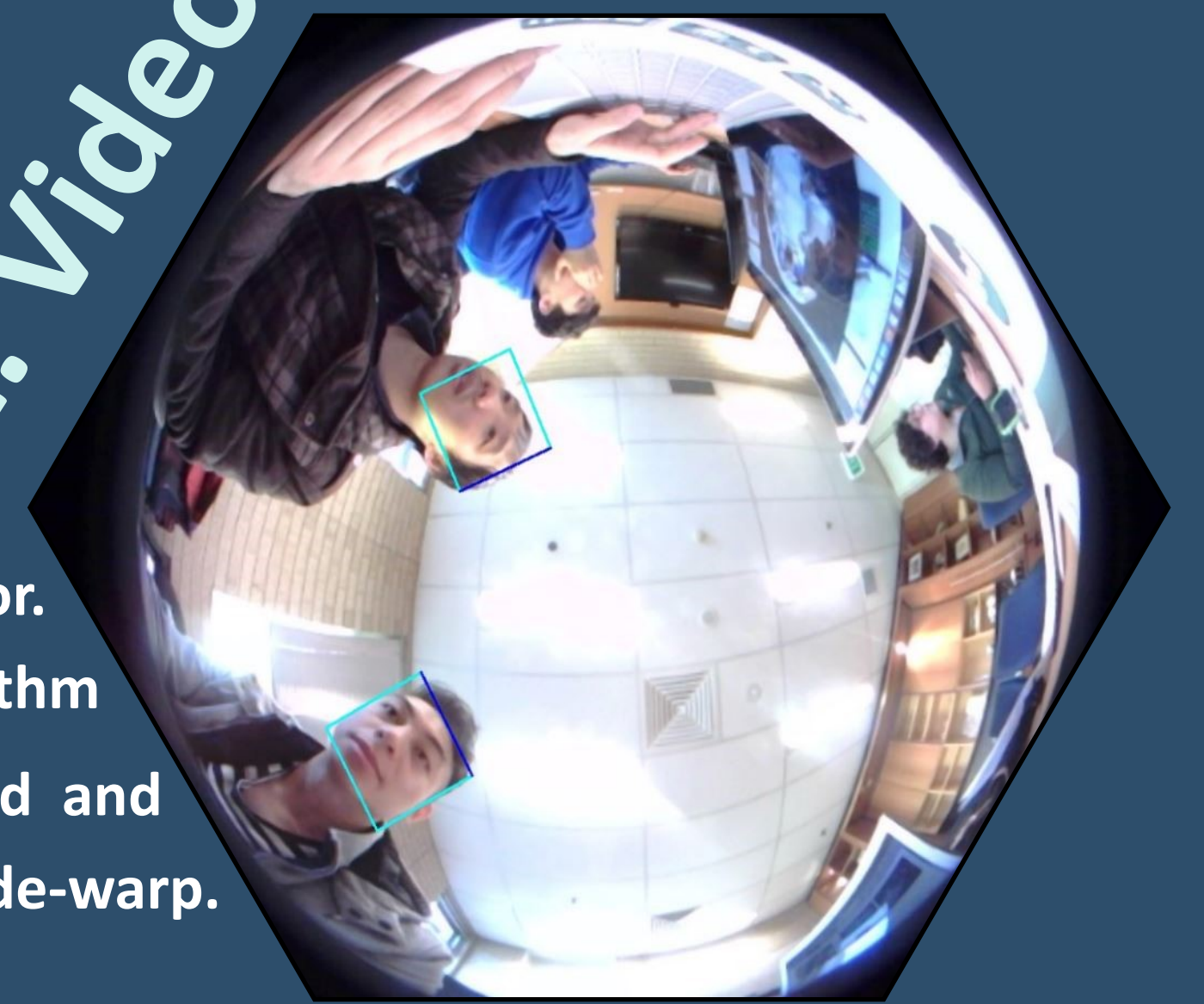


# Methodology



# 360 Degree Web Conference

## 2. Video



Fisheye input from the camera to the processor. Face detection algorithm is then executed and video feed de-warp.



## Face Detection Algorithm

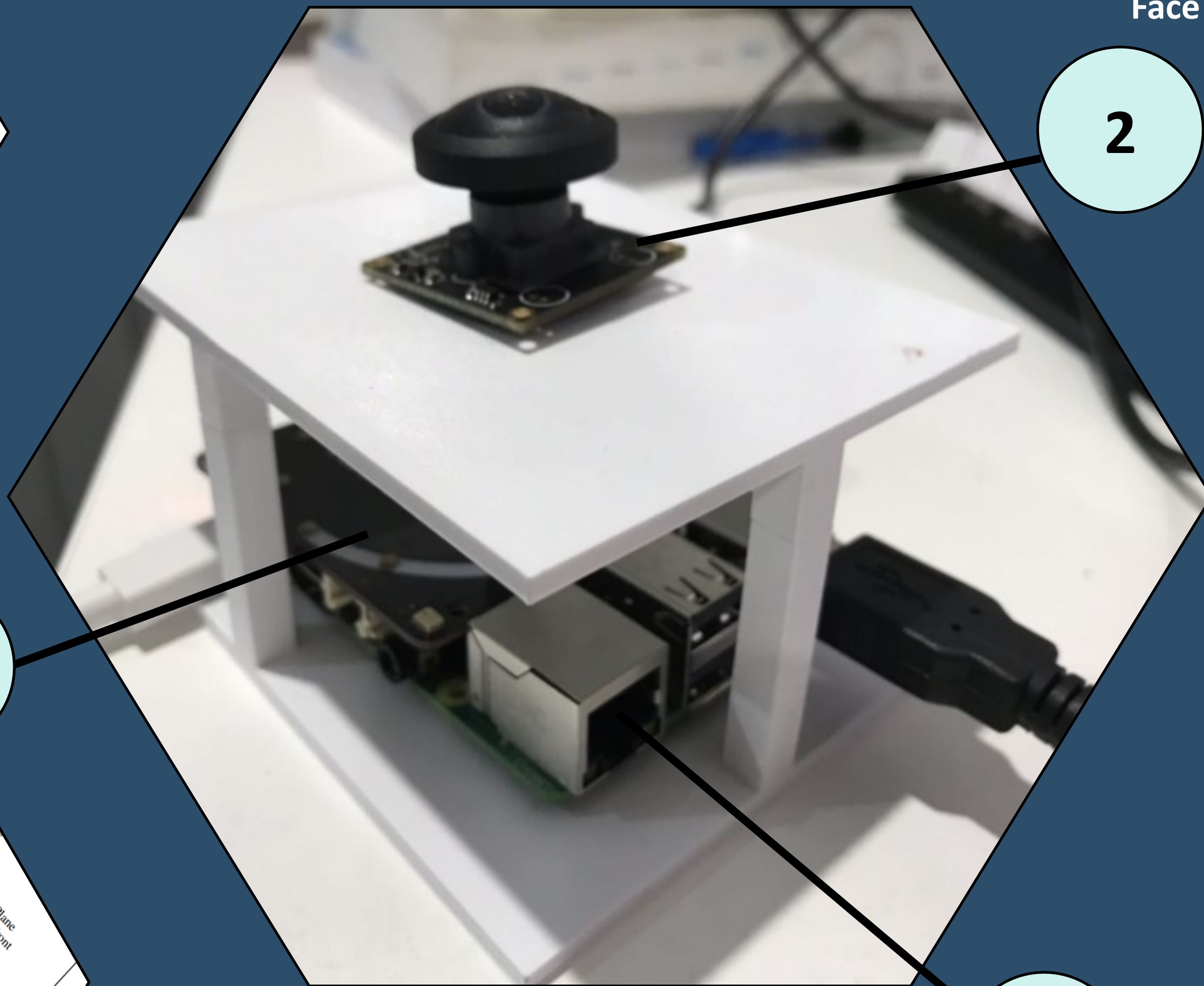
Rotation-invariant face detector:

- Real-time but high computational requirement
- Can detect user at almost any angle

Cascade face detector:

- Real-time and low computational requirement
- Require user image to be right angle

1



3

## Innovation

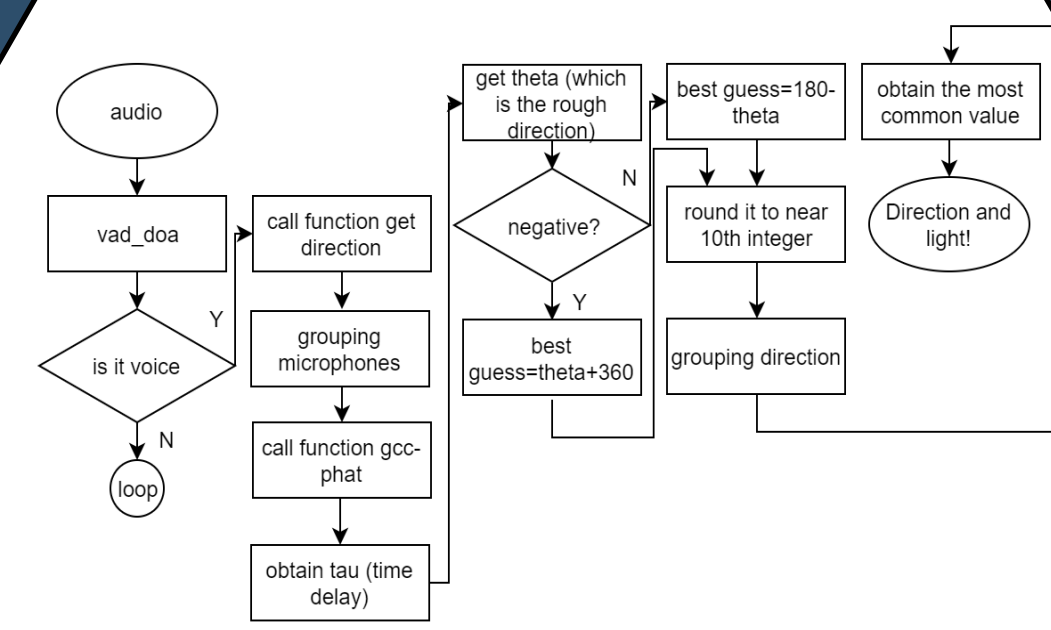
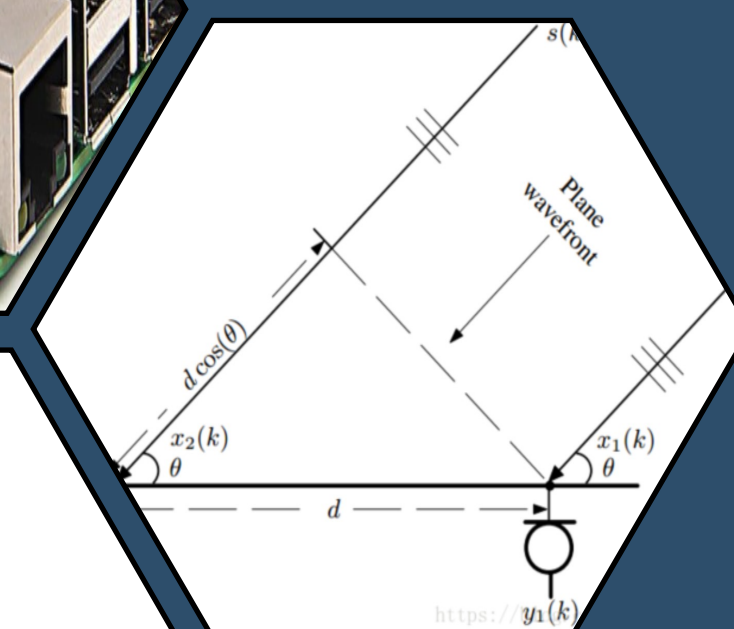
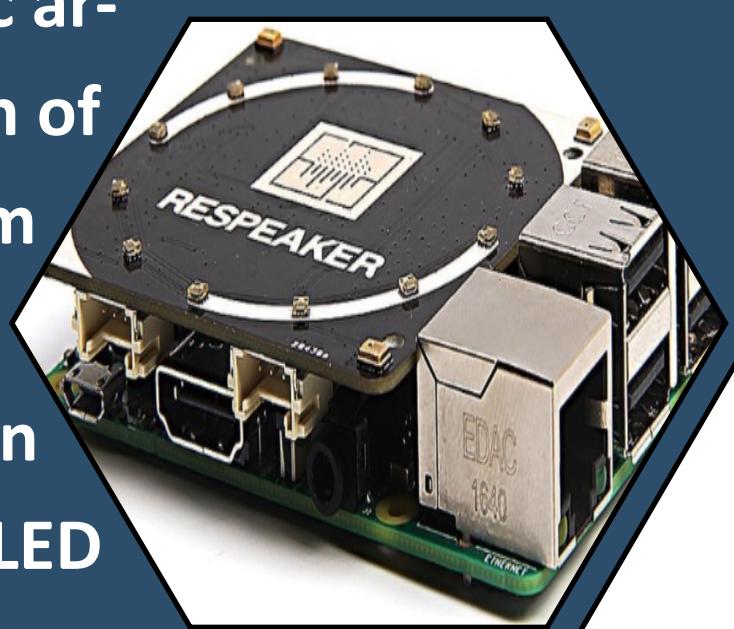
First open source 360 degrees web conferencing camera system.

## 3. Output

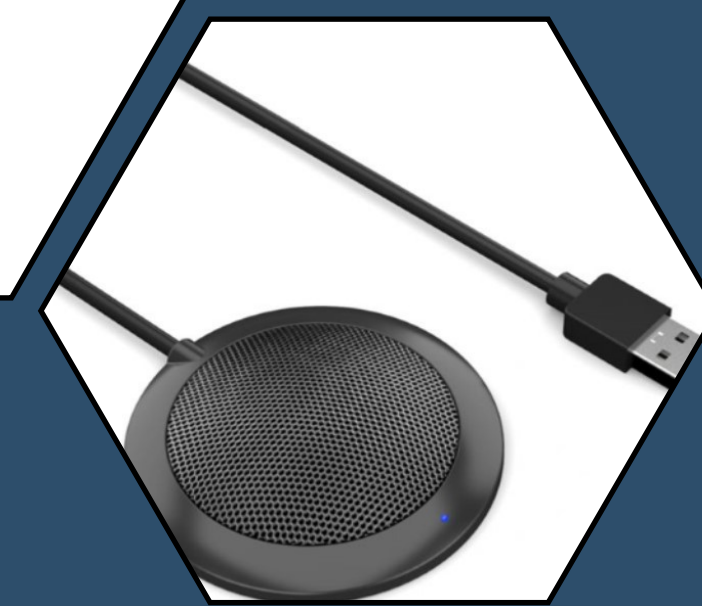


## 1. Sound

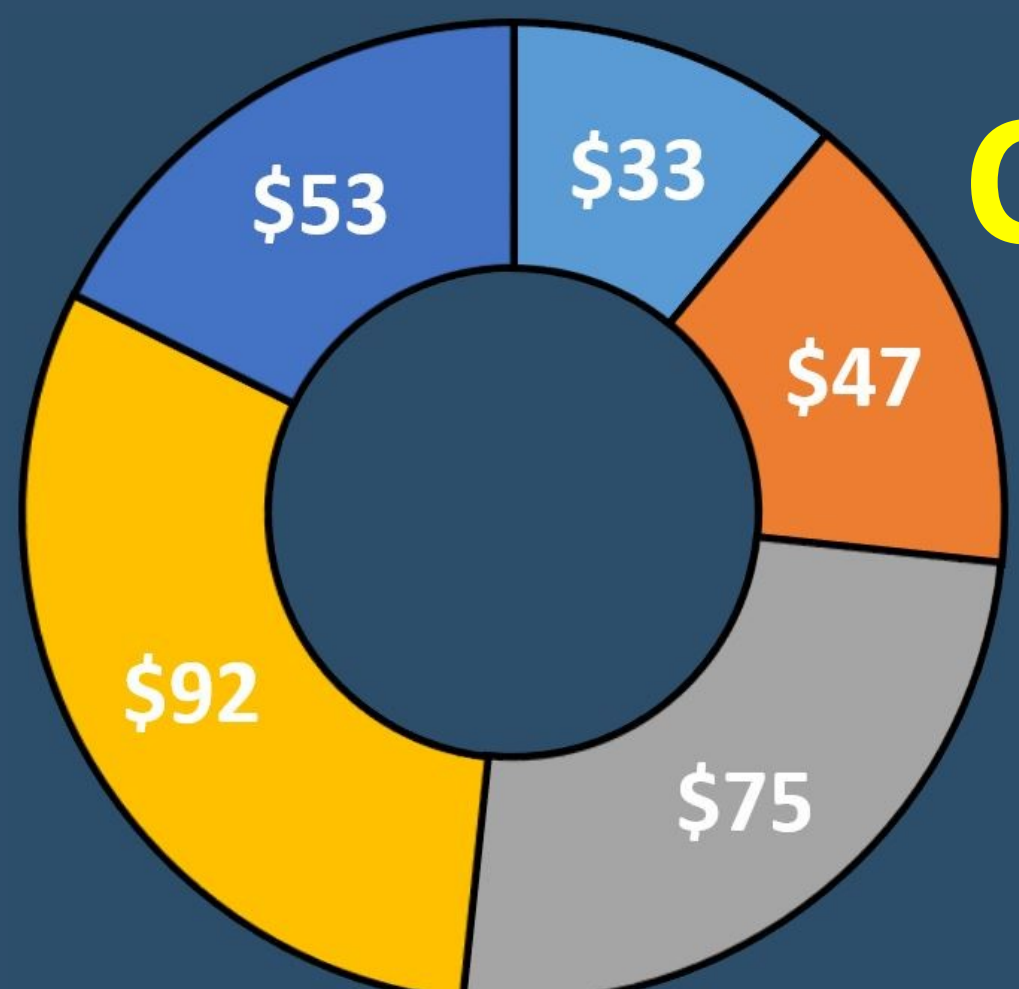
ReSpeaker 4-mic array for Direction of Arrival Algorithm (DOA). Speaker directions is shown by small LED



The audio input is obtained using Tyless USB mic through a 3.5 jack port.



## Costs



- USB Mic
- 4-Mic Array
- Raspberry Pi
- Camera
- Leftover