Divisive Clustering: Concept and Math

Divisive Clustering is a **top-down hierarchical clustering** algorithm. Unlike agglomerative clustering, which starts with each data point as its own cluster and progressively merges them, divisive clustering starts with all data points in a single cluster and **divides** them into smaller clusters recursively.

Mathematical Overview of Divisive Clustering

The divisive clustering algorithm follows these basic steps:

- 1. **Start with one cluster**: The entire dataset is treated as a single cluster.
- Split the cluster: The cluster is divided into two subclusters based on some distance metric (often using the centroid of the cluster and a distance measure, such as Euclidean distance).
- 3. **Iterate**: Each resulting subcluster is recursively divided until each data point is its own cluster (or until a stopping condition is met, like a desired number of clusters or a specific distance threshold).

Math for Divisive Clustering

1. Cluster Splitting:

- In each iteration, we pick the most dissimilar cluster and divide it into two subclusters. The dissimilarity can be calculated using various distance metrics, such as the Euclidean distance between the centroid of the cluster and the data points.
- We can use clustering algorithms (like K-Means) to split the most dissimilar cluster into two.

2. Dissimilarity Measurement:

 The dissimilarity between clusters is often computed by looking at the distance between the centroid of the clusters or the variance within a cluster.

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4. Splitting the Cluster:

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The most dissimilar cluster is divided into two by using a method like K-Means. The idea is to minimize the variance within each of the two subclusters (similar to how K-Means optimizes centroids).

Steps for Divisive Clustering

- 1. **Initialize** with a single cluster containing all data points.
- 2. **Calculate the centroid** of the cluster.
- 3. **Split the cluster** into two subclusters (using a method like K-Means).
- 4. **Repeat** the process on the resulting subclusters, recursively splitting the most dissimilar clusters.
- 5. **Stop** when the desired number of clusters is reached or another stopping condition is met.