Henrik Brådland Jan. 2021

Project proposal – IKT442

I would like to work alone in order to make it easier to coordinate with my master thesis.

As I have a background in mechatronics, I would like to try to solve an environment related to robot control. Ether by implementing a routing system for a vacuum-cleaning robot that will try to clean a known grid-based room in the shortest time or learning a car how to drive around a circuit (like this).