










FORMULÁRIO DE INTRODUÇÃO AOS SISTEMAS ELETROMAGNÉTICOS - ENG^a BIOMÉDICA

Cálculo vetorial

Produto escalar	Produto vetorial
$\vec{a} \cdot \vec{b} = ab \cos(\theta)$ $\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z$	$ \vec{a} \wedge \vec{b} = ab \sin(\theta)$ $\vec{a} \wedge \vec{b} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix} = (a_y b_z - a_z b_y) \hat{x} + (a_z b_x - a_x b_z) \hat{y} + (a_x b_y - a_y b_x) \hat{z}$

Eletromagnetismo

$q_e = -1,6 \times 10^{-19} \text{ C}$	$m_e = 9,1 \times 10^{-31} \text{ kg}$	$\epsilon_0 \approx 8,854 \times 10^{-12} \text{ Fm}^{-1}$	$\mu_0 = 4 \pi \times 10^{-7} \text{ Hm}^{-1}$
 $k = \frac{1}{4 \pi \epsilon_0} \approx 8,988 \times 10^9 \text{ N} \cdot \text{m}^2 \text{C}^{-2}$	$c = \frac{1}{\sqrt{\epsilon_0 \mu_0}} = 299792458 \text{ m/s}$		
Cargas pontuais	 $\vec{E} = \frac{1}{4 \pi \epsilon_0} \frac{Q}{r^2} \hat{r}$	 $V = \frac{1}{4 \pi \epsilon_0} \frac{q}{r} + C$	
	 $\vec{F}_{12} = \frac{1}{4 \pi \epsilon_0} \frac{q_1 q_2}{r_{12}^2} \hat{r}_{12}$	 $U_{12} = \frac{1}{4 \pi \epsilon_0} \frac{q_1 q_2}{r_{12}} + C$	
 $V_c = \frac{Q}{C}$	$U_c = \frac{1}{2} QV$	$V_c = Ed$	 $C = \epsilon \frac{A}{d}$
$i = \frac{dq}{dt} \Leftrightarrow q = \int i dt$	$V_R = Ri$	$P_R = Ri^2$	$R = \rho \frac{L}{A}$ $\rho = \rho_0 + \alpha \rho_0 (T - T_0)$
$V_L = L \frac{di}{dt}$	$U_L = \frac{1}{2} Li^2$	$\kappa = \kappa_0 + \chi_0 + \frac{1}{2} \alpha \chi_0^2$	
$\vec{B} = \int \frac{\mu_0 i d\vec{l} \wedge \hat{r}}{4 \pi r^2}$	$\vec{B}_{\text{centro bobine}} = \frac{\mu_0 Ni}{2a} \hat{z}$	$\vec{B}_{\text{eixo bobine}} = \frac{\mu_0 Ni a^2}{2(a^2 + L^2)^{3/2}} \hat{z}$	
$\vec{B}_{\text{fio retilíneo infinito}} = \frac{\mu_0 i}{2 \pi r} \hat{\theta}$	$B_{\text{interior solenóide}} = \frac{\mu_0 Ni}{L}$	$B_{\text{interior toróide}} = \frac{\mu_0 Ni}{2 \pi r}$	
$\vec{F}_m = q \vec{v} \wedge \vec{B}$	$R = \frac{mv}{qB}$	$R = \frac{mv_{\perp}}{qB}; \text{ Passo} = v_{\parallel} T$	
$\vec{F} = \int_L I d\vec{l} \wedge \vec{B}$	$\vec{F}_L = \vec{F}_e + \vec{F}_m = q\vec{E} + q\vec{v} \wedge \vec{B}$	$\vec{m} = Ni A \hat{A}$	$\vec{\tau} = \vec{m} \wedge \vec{B}$
$\phi = \iint \vec{B} \cdot d\vec{A}$	$\phi = \frac{Li}{\text{[H]}}$	$\phi_2 = Mi_1$	
$fem = -\frac{d\phi}{dt}$	$fem = -L \frac{di}{dt}$	$fem_2 = -M \frac{di_1}{dt}$	
$\begin{cases} E = E_0 \sin(kx - \omega t) \\ B = B_0 \sin(kx - \omega t) \end{cases}$	$k = \frac{2\pi}{\lambda}$	$\omega = 2\pi f$	$\vec{S} = \frac{1}{\mu_0} \vec{E} \wedge \vec{B}$ $\bar{S} = \frac{E_0^2}{2\mu_0 c}$

$$\Delta V = \vec{E} \cdot \Delta \vec{S} \quad \left| \Delta u_m \right| = \left| \Delta u_p + \Delta u_e \right|$$

$$\text{[V]} \quad \text{[Vm]} \quad \text{[m]} \quad \left| = \left| q \Delta V + \frac{1}{2} m (\vec{v}_f^2 - \vec{v}_i^2) \right| \right|$$