

Non-homo System

1. Non-homo System: $\vec{x}' = P(t) \cdot \vec{x} + q(t)$.

1) General solⁿ: $\vec{x} = \vec{x}_c(t) + \vec{x}_p(t) = C_1 \vec{x}^{(1)} + \dots + C_n \vec{x}^{(n)} + \vec{x}_p(t)$.

2) 找 $\vec{x}_p(t)$ 方法.

①. Diagonalization: A diagonalizable \leftrightarrow distinct eigenvalue λ .

i). $T = (\vec{v}_1 \dots \vec{v}_n)$ be matrix of eigenvector of A .

$D = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$ be matrix of eigenvalue of A .

ii) Let $\vec{x} = T \cdot \vec{y} \Rightarrow \vec{y}' = D \cdot \vec{y} + T^{-1} \cdot q(t)$ solve 1st order using integrating factor.

iii) $\vec{x} = T \cdot \vec{y}$.

②. Undetermined Coefficient. (出现重复的, 然后设 $\vec{x}_p(t)$).

注意: 若 $q(t)$ 出现 $e^{\lambda t}$ where λ is eigenvalue, let $x_p = a t e^{\lambda t} + b e^{\lambda t}$.
以前一项, 现在两项.

③. Variation of Parameter (通用).

i). find $\psi(t)$.

ii). Let $\vec{x}(t) = \psi(t) \cdot \vec{u}(t) \Rightarrow \vec{u}(t)' = \psi^{-1}(t) \cdot q(t)$.

iv). $\vec{u}(t) = \int \psi^{-1}(t) \cdot q(t) dt + \vec{c}$.

v). $\vec{x}(t) = \psi(t) \cdot \vec{u}(t)$.

2. 练习题.

e.g. $\vec{x}' = \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix} \vec{x} + \begin{pmatrix} 2e^{-t} \\ 2t \end{pmatrix}$

① $\vec{x}_c(t)$: $A = \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix}$, $A - \lambda I = \begin{pmatrix} -2-\lambda & 1 \\ 1 & -2-\lambda \end{pmatrix} = (-2-\lambda)^2 - 1 = 0$.

$\therefore \lambda_1 = -3, \lambda_2 = -1. \Rightarrow (2+\lambda)^2 = 1$.

when $\lambda_1 = -3$, $A - \lambda I = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow v_1 = -v_2 \Rightarrow \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

when $\lambda_2 = -1$, $A - \lambda I = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \Rightarrow \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow v_1 = v_2 \Rightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

$\therefore \vec{x}_c(t) = C_1 \cdot e^{-3t} \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix} + C_2 \cdot e^{-t} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

②. $\psi(t) = \begin{pmatrix} e^{-3t} & e^{-t} \\ -e^{-3t} & e^{-t} \end{pmatrix}$.

Let $\vec{x}(t) = \psi(t) \cdot \vec{u}(t) \Rightarrow \vec{u}(t)' = \psi^{-1}(t) \cdot q(t)$.

$\det(\psi(t)) = e^{-4t} + e^{-4t} = 2e^{-4t}$.

$$\psi^{-1}(t) = \frac{e^{4t}}{2} \begin{pmatrix} e^{-t} & -e^{-t} \\ e^{-3t} & e^{-3t} \end{pmatrix} = \begin{pmatrix} \frac{e^t}{2} & -\frac{e^t}{2} \\ \frac{e^t}{2} & \frac{e^t}{2} \end{pmatrix}$$

$$\begin{aligned} \therefore \vec{u}(t)' &= \psi^{-1}(t) \cdot g(t) \\ &= \begin{pmatrix} \frac{e^t}{2} & -\frac{e^t}{2} \\ \frac{e^t}{2} & \frac{e^t}{2} \end{pmatrix} \begin{pmatrix} 2e^t \\ 3t \end{pmatrix} = \begin{pmatrix} e^{2t} \cdot e^{-t} - \frac{3}{2} t \cdot e^{2t} \\ 1 + \frac{3}{2} t \cdot e^t \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \therefore \vec{u}_1(t) &= \int e^{2t} - \frac{3}{2} t \cdot e^{2t} dt = \frac{e^{2t}}{2} - \int \frac{3}{2} t \cdot e^{2t} dt \\ &= \frac{e^{2t}}{2} - \left(\frac{3}{2} t \cdot \frac{e^{2t}}{2} - \int \frac{3}{2} \cdot \frac{e^{2t}}{2} dt \right) \\ &= \frac{e^{2t}}{2} - \left(\frac{3te^{2t}}{2} - \int \frac{e^{2t}}{2} dt \right) \\ &= \frac{e^{2t}}{2} - \frac{3te^{2t}}{2} + \frac{e^{2t}}{6} + C_1 \end{aligned}$$

$$\begin{aligned} \vec{u}_2(t) &= \int 1 + \frac{3}{2} t \cdot e^t dt = t + \frac{3}{2} \int t \cdot e^t dt \\ &= t + \frac{3}{2} (t \cdot e^t - \int e^t dt) \\ &= t + \frac{3}{2} (t \cdot e^t - e^t) + C_2 \\ &= t + \frac{3}{2} t \cdot e^t - \frac{3}{2} e^t + C_2 \end{aligned}$$

$$\begin{aligned} \therefore \vec{x}(t) &= \psi(t) \cdot \vec{u}(t) = \begin{pmatrix} e^{-3t} & e^{-t} \\ -e^{-3t} & e^{-t} \end{pmatrix} \cdot \begin{pmatrix} \frac{e^{2t}}{2} - \frac{3te^{2t}}{2} + \frac{e^{2t}}{6} + C_1 \\ t + \frac{3}{2} t \cdot e^t - \frac{3}{2} e^t + C_2 \end{pmatrix} \\ &= \begin{pmatrix} e^{-3t} \left(\frac{e^{2t}}{2} - \frac{3te^{2t}}{2} + \frac{e^{2t}}{6} + C_1 \right) + e^{-t} \left(t + \frac{3}{2} t \cdot e^t - \frac{3}{2} e^t + C_2 \right) \\ -e^{-3t} \left(\frac{e^{2t}}{2} - \frac{3te^{2t}}{2} + \frac{e^{2t}}{6} + C_1 \right) + e^{-t} \left(t + \frac{3}{2} t \cdot e^t - \frac{3}{2} e^t + C_2 \right) \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{2} e^{-t} - \frac{1}{2} t + \frac{1}{6} + C_1 \cdot e^{-3t} + t \cdot e^{-t} + \frac{3}{2} t - \frac{3}{2} + C_2 \cdot e^{-t} \\ -\frac{1}{2} e^{-t} + \frac{1}{2} t - \frac{1}{6} - C_1 \cdot e^{-3t} + t \cdot e^{-t} + \frac{3}{2} t - \frac{3}{2} + C_2 \cdot e^{-t} \end{pmatrix} \\ &= C_1 \cdot e^{-3t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + C_2 \cdot e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \frac{1}{2} e^{-t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + t \cdot e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \begin{pmatrix} -\frac{5}{6} \\ -\frac{1}{3} \end{pmatrix} \end{aligned}$$

e.g. $\vec{x} = \begin{pmatrix} 2 & -5 \\ 1 & -2 \end{pmatrix} \vec{x} + \begin{pmatrix} -\cos t \\ \sin t \end{pmatrix}$.

