

# Inverse

only  $n \times n$  matrix has inverse.

1. Find Inverse Matrix.  $\rightarrow A \cdot B = I$

1) row reduction.

e.g.  $A = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 3 \\ 4 & -3 & 8 \end{bmatrix}$ .  $A^{-1}$  ?

if 左边不能化到 identity matrix or not invertible

$$\left[ \begin{array}{ccc|ccc} 0 & 1 & 2 & 1 & 0 & 0 \\ 1 & 0 & 3 & 0 & 1 & 0 \\ 4 & -3 & 8 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\dots} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -9/2 & 7 & -3/2 \\ 0 & 1 & 0 & -2 & 4 & -1 \\ 0 & 0 & 1 & 3/2 & -2 & 1/2 \end{array} \right]$$

$\uparrow$   $I_3$   $\uparrow$   $A^{-1}$

2) use determinant

①  $2 \times 2$ :  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ :  $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

$\det(A) = ad-bc$ . (invertible iff  $\det(A) \neq 0$ ).

e.g. Find inverse of  $\begin{bmatrix} 8 & 6 \\ 5 & 4 \end{bmatrix}$ , use it to solve the system  $\begin{cases} 8x_1 + 6x_2 = 2 \\ 5x_1 + 4x_2 = -1 \end{cases}$

$$A^{-1} = \frac{1}{32-30} \begin{bmatrix} 4 & -6 \\ -5 & 8 \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ -5/2 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 6 \\ 5 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \Rightarrow A^{-1} \cdot A \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = A^{-1} \begin{bmatrix} 2 \\ -1 \end{bmatrix} \\ \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = A^{-1} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ -5/2 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} \\ \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ -9 \end{bmatrix}$$

②  $3 \times 3$ : BAS. FM 1.4

2. Identity Matrix & Elementary Matrix.

1) Identity Matrix:  $I_n$ : all entries are 0 except diagonal.

e.g.  $I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ .  $I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \dots$

解方程:  
M ① row reduction  
M ② 两边同乘 inverse matrix.

$$\textcircled{1} A I_n = I_n A \quad A: n \times n.$$

$$\textcircled{2} A \cdot B = I \rightarrow A \cdot B = B \cdot A.$$

左乘相当于  
作一个相同的  
的 row operation

2). Elementary Matrix: performing a single elementary row operation on an identity matrix.

$\textcircled{1} E: m \times m, A: m \times n: EA$ . make  $A$  operate the same row operation that from  $I_m \rightarrow E$ .

$$\text{e.g. } E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & 0 & 1 \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{bmatrix}, A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$

$$L_3 \xrightarrow{R_3 - 4R_1} E_1 \quad \therefore E_1 A = \begin{bmatrix} a & b & c \\ d & e & f \\ g-4a & h-4b & i-4c \end{bmatrix}$$

$$L_3 \xrightarrow{R_2 \leftrightarrow R_3} E_2 \quad \therefore E_2 A = \begin{bmatrix} a & b & c \\ g & h & i \\ d & e & f \end{bmatrix}$$

$$L_3 \xrightarrow{R_3 \cdot 5} E_3 \quad \therefore E_3 A = \begin{bmatrix} a & b & c \\ g & h & i \\ 5d & 5e & 5f \end{bmatrix}$$

$\textcircled{2}$  each elementary matrix  $E$  is invertible. (The inverse of  $E$  use the same type of row operation to back to  $I$ ).

$$\rightarrow A = E_1^{-1} \cdot E_2^{-1} \cdot \dots \cdot E_k^{-1}$$

$$\rightarrow A^{-1} = E_k \cdot E_{k-1} \cdot \dots \cdot E_2 \cdot E_1.$$

$$(E_k \cdot E_{k-1} \cdot \dots \cdot E_2 \cdot E_1) \cdot A = I.$$

$\Rightarrow$

$$A = I \cdot (E_k \cdot E_{k-1} \cdot \dots \cdot E_2 \cdot E_1)^{-1}$$

$$\Rightarrow A = E_1^{-1} \cdot E_2^{-1} \cdot \dots \cdot E_{k-1}^{-1} \cdot E_k^{-1}.$$

e.g.  $A = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$ . Find  $E$ s and  $E^{-1}$ s of  $A$ .

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \xrightarrow[E_1]{R_2 - R_1} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} \xrightarrow[E_2]{R_2 \cdot (-1)} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \xrightarrow[E_3]{R_1 - 2R_2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\therefore E_1 = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \quad E_2 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad E_3 = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}$$

$$\text{By } A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\therefore E_1^{-1} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, E_2^{-1} = (-1) \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$E_3^{-1} = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

e.g.  $A$  is  $3 \times 3$ ,  $A^T + 5I$  is nonsingular

$$(A^T + 5I)^{-1} = \begin{bmatrix} 1 & 3 & 0 \\ 0 & -1 & 0 \\ 2 & 2 & 1 \end{bmatrix} \text{ find } A.$$

$$A^T + 5I = \left( \begin{bmatrix} 1 & 3 & 0 \\ 0 & -1 & 0 \\ 2 & 2 & 1 \end{bmatrix} \right)^{-1}$$

$$\Rightarrow A^T = \begin{bmatrix} 1 & 3 & 0 \\ 0 & -1 & 0 \\ -2 & -4 & 1 \end{bmatrix} - \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$\Rightarrow A^T = \begin{bmatrix} -4 & 3 & 0 \\ 0 & -6 & 0 \\ -2 & -4 & -4 \end{bmatrix}$$

$$\Rightarrow A = \begin{bmatrix} -4 & 0 & -2 \\ 3 & -6 & -4 \\ 0 & 0 & -4 \end{bmatrix}$$

### 3. Invertible Linear Transformation.

For a lin trans.  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  ( $n=m$ ). is invertible iff  $T$  is both one-to-one and onto. ( $\text{null}(T) = \{\vec{0}\}$ ;  $\text{range}(T) = \mathbb{R}^m$ ).  
( $\text{null}(M) = \{\vec{0}\}$ ;  $\text{col}(M) = \mathbb{R}^m$ ).

$$T(\vec{v}) = M \cdot \vec{v}$$

1)  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  is invertible if the standard matrix of  $T$  is invertible.

2)  $n=m$ .

3) If  $T$  is invertible and  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$  is a lin ind subset in  $\mathbb{R}^n$ , then  $\{T(\vec{v}_1), T(\vec{v}_2), \dots, T(\vec{v}_k)\}$  is a lin ind subset in  $\mathbb{R}^n$ .

4. Properties when  $A$  is  $n \times n$  invertible matrix

①  $A$  is row equivalent to  $n \times n$  identity matrix.  
 $\rightarrow$  after row ops.

②  $A$  has  $n$  pivot positions.

③ The equation  $A\vec{x} = \vec{b}$  has only trivial solution.

$$A\vec{x} = \vec{0} \rightarrow A^{-1} \cdot A\vec{x} = A^{-1} \cdot \vec{0} \rightarrow \vec{x} = \vec{0}.$$

④  $\forall \vec{b} \in \mathbb{R}^n$ .  $A\vec{x} = \vec{b}$  has at least one solution.

$$A\vec{x} = \vec{b} \rightarrow \vec{x} = A^{-1} \cdot \vec{b}.$$

⑤ The columns of  $A$  form a lin ind set.

⑥ The columns of  $A$  form a basis of  $\mathbb{R}^n$ .

⑦ The lin trans  $T(\vec{x}) = A\vec{x}$  is one-to-one.

$$\textcircled{8} \text{null}(A) = \{\vec{0}\}$$

$$\textcircled{9} \dim(\text{null}(A)) = 0$$

⑩ The lin trans  $T(\vec{x}) = A\vec{x}$  is onto.

⑪ The columns of  $A$  spans  $\mathbb{R}^n$ .

$$\textcircled{12} \text{col}(A) = \mathbb{R}^n.$$

$$\textcircled{13} \dim(\text{col}(A)) = n$$

$$\textcircled{14} \text{rank}(A) = n$$

⑮ There is an  $n \times n$  matrix  $C$  s.t.  $C \cdot A = I$ .

⑯ There is an  $n \times n$  matrix  $D$  s.t.  $A \cdot D = I$ .

⑰  $A^T$  is an invertible matrix.

