

N^{th} Order non-Homo

$y_c(t)$: 用 Homo 1. General solⁿ: $y(t) = y_c(t) + y_p(t)$.

法求即可.

1) Undetermined Coefficient 求 $y_p(t)$.

① 找 $y(t) = C_1 y_1 + \dots + C_n y_n$ as usual.

② 设出 $y_p(t)$.

③ 求出 $y_p'(t), \dots, y_p^{(n)}(t)$ substitute into ODE. (因为 $y_p(t)$ 也是解).

④ 求出 $y_p(t)$ 中 coeff. 的值.

⑤ $y(t) = y_c(t) + y_p(t)$.

先通过 Homo
找 y_1, \dots, y_n

2) Variation of Parameter (General)

① 求出 Wronskian.

$$\det(W[y_1, \dots, y_n]) = \det \begin{pmatrix} y_1 & \dots & y_n \\ y_1' & \dots & y_n' \\ \vdots & & \vdots \\ y_1^{(n-1)} & \dots & y_n^{(n-1)} \end{pmatrix}_{n \times n} = y_1^{(n-1)} \cdot \omega_1 + y_2^{(n-1)} \cdot \omega_2 + \dots + y_n^{(n-1)} \cdot \omega_n.$$

(正负号放到 ω 中)

② 求出 $\omega_1, \dots, \omega_n$. (用 y_1, \dots, y_n 的 $(-, -, +, -)$)

$$\omega_1 = \begin{vmatrix} y_2 & \dots & y_n \\ \vdots & & \vdots \\ y_2^{(n-2)} & \dots & y_n^{(n-2)} \end{vmatrix}_{(n-1) \times (n-1)} \quad \omega_n = \begin{vmatrix} y_1 & \dots & y_{n-1} \\ \vdots & & \vdots \\ y_1^{(n-2)} & \dots & y_{n-1}^{(n-2)} \end{vmatrix}_{(n-1) \times (n-1)}.$$

③ 求出 $u_1(t), \dots, u_n(t)$. (记得加对应 C_i 在积分后).

$$u_i(t) = \int \frac{g(t) \cdot \omega_i(t)}{\omega(t)} dt.$$

④ $y(t) = u_1 y_1 + \dots + u_n y_n (= C_1 y_1 + \dots + C_n y_n + y_p(t))$.

e.g. Third Order:

$$\textcircled{1} W = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix} = y_1'' \cdot \omega_1 + y_2'' \cdot \omega_2 + y_3'' \cdot \omega_3.$$

$$\textcircled{2} \omega_1 = \begin{vmatrix} y_2 & y_3 \\ y_2' & y_3' \end{vmatrix}; \omega_2 = - \begin{vmatrix} y_1 & y_3 \\ y_1' & y_3' \end{vmatrix}; \omega_3 = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}.$$

3) General Abel Theorem: $W(t) = C \cdot e^{-\int p_1(t) dt}$.
(先写成 std. form.)

↑ $n-1$ 阶导前系数.

2. ~~题~~

i) General solⁿ.

e.g. $y''' - 2y'' + 4y' = e^t \cdot \sin(\sqrt{3}t)$.

Undetermined Coeff.

ii) Solve Homo:

$$r^3 - 2r^2 + 4r = 0 \Rightarrow r(r^2 - 2r + 4) = 0.$$

$$\Rightarrow r_1 = 0, \quad r_{2,3} = 1 \pm \sqrt{3}i$$

$$\therefore y(t) = C_1 + C_2 \cdot e^t \cdot \sin(\sqrt{3}t) + C_3 \cdot e^t \cdot \cos(\sqrt{3}t) + y_p(t).$$

iii) Let $y_p(t) = t \cdot e^t \cdot (A \cos(\sqrt{3}t) + B \sin(\sqrt{3}t))$. repeat once.

iii) $y_p'(t) = (A \cdot e^t \cdot \cos(\sqrt{3}t) + B \cdot e^t \cdot \sin(\sqrt{3}t)) + t \cdot e^t \cdot (-A \sin(\sqrt{3}t) + B \cos(\sqrt{3}t)) + \dots$

Variation of Parameter:

i) Solve Homo and get y_1, y_2, y_3 .

$$r^3 - 2r^2 + 4r = 0 \Rightarrow r(r^2 - 2r + 4) = 0.$$

$$\Rightarrow r_1 = 0, \quad r_{2,3} = 1 \pm \sqrt{3}i$$

$$y_1(t) = 1; \quad y_2(t) = e^t \cdot \cos(\sqrt{3}t); \quad y_3(t) = e^t \cdot \sin(\sqrt{3}t).$$

ii) Solve Wronskian:

$$W[y_1, \dots, y_n] = \det \begin{pmatrix} 1 & e^t \cos(\sqrt{3}t) & e^t \sin(\sqrt{3}t) \\ 0 & e^t \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \sin(\sqrt{3}t) & e^t \sin(\sqrt{3}t) + \sqrt{3} \cdot e^t \cos(\sqrt{3}t) \\ 0 & e^t \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \sin(\sqrt{3}t) - \sqrt{3} \cdot e^t \cos(\sqrt{3}t) & e^t \sin(\sqrt{3}t) + \sqrt{3} \cdot e^t \cos(\sqrt{3}t) - 3 \cdot e^t \sin(\sqrt{3}t) \end{pmatrix}$$

$$= \cdot W_1 + (e^t \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \sin(\sqrt{3}t) - \sqrt{3} \cdot e^t \sin(\sqrt{3}t) - \sqrt{3} \cdot e^t \cos(\sqrt{3}t))$$

$$\cdot W_2 + (e^t \sin(\sqrt{3}t) + \sqrt{3} \cdot e^t \cos(\sqrt{3}t) + \sqrt{3} \cdot e^t \cos(\sqrt{3}t) - 3 \cdot e^t \sin(\sqrt{3}t)) \cdot W_3.$$

$$W_1 = \det \begin{pmatrix} e^t \cos(\sqrt{3}t) & e^t \sin(\sqrt{3}t) \\ e^t \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \sin(\sqrt{3}t) & e^t \sin(\sqrt{3}t) + \sqrt{3} \cdot e^t \cos(\sqrt{3}t) \end{pmatrix}.$$

$$= e^t \cos(\sqrt{3}t) \cdot [e^t \sin(\sqrt{3}t) + \sqrt{3} \cdot e^t \cos(\sqrt{3}t)] - e^t \sin(\sqrt{3}t) \cdot [e^t \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \sin(\sqrt{3}t)].$$

$$= e^{2t} \sin(\sqrt{3}t) \cdot \cos(\sqrt{3}t) + \sqrt{3} \cdot e^{2t} \cos^2(\sqrt{3}t) - e^{2t} \sin(\sqrt{3}t) \cdot \cos(\sqrt{3}t) + \sqrt{3} \cdot e^{2t} \sin^2(\sqrt{3}t)$$

$$= \sqrt{3} \cdot e^{2t}$$

$$\omega_2 = -\det \begin{pmatrix} 1 & e^t \cdot \sin(\sqrt{3}t) \\ 0 & e^t \cdot \sin(\sqrt{3}t) + \sqrt{3} \cdot e^t \cdot \cos(\sqrt{3}t) \end{pmatrix}$$

$$= -e^t \cdot \sin(\sqrt{3}t) - \sqrt{3} \cdot e^t \cdot \cos(\sqrt{3}t).$$

$$\omega_3 = \det \begin{pmatrix} 1 & e^t \cdot \cos(\sqrt{3}t) \\ 0 & e^t \cdot \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \cdot \sin(\sqrt{3}t) \end{pmatrix}$$

$$= e^t \cdot \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \cdot \sin(\sqrt{3}t).$$

$$\therefore \omega = \omega_1 + (e^t \cdot \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \cdot \sin(\sqrt{3}t) - \sqrt{3} \cdot e^t \cdot \sin(\sqrt{3}t) - \sqrt{3} \cdot e^t \cdot \cos(\sqrt{3}t)) \cdot \omega_2 +$$

$$(e^t \cdot \sin(\sqrt{3}t) + \sqrt{3} \cdot e^t \cdot \cos(\sqrt{3}t) + \sqrt{3} \cdot e^t \cdot \cos(\sqrt{3}t) - 3 \cdot e^t \cdot \sin(\sqrt{3}t)) \cdot \omega_3$$

$$= \sqrt{3} \cdot e^{2t} + [(1 - \sqrt{3}) \cdot e^t \cdot \cos(\sqrt{3}t) - 2\sqrt{3} \cdot e^t \cdot \sin(\sqrt{3}t)] \cdot [-e^t \cdot \sin(\sqrt{3}t) -$$

$$\sqrt{3} \cdot e^t \cdot \cos(\sqrt{3}t)] + [-2 \cdot e^t \cdot \sin(\sqrt{3}t) + 2\sqrt{3} \cdot e^t \cdot \cos(\sqrt{3}t)] \cdot [e^t \cdot \cos(\sqrt{3}t) - \sqrt{3} \cdot e^t \cdot \sin(\sqrt{3}t)]$$

$$= \dots$$

$$\text{iii) } u_1 = \int \frac{g(t) \cdot \omega_1}{\omega} dt; u_2 = \int \frac{g(t) \cdot \omega_2}{\omega} dt; u_3 = \int \frac{g(t) \cdot \omega_3}{\omega} dt.$$

$$\text{iv) } y(t) = u_1 \cdot y_1 + u_2 \cdot y_2 + u_3 \cdot y_3.$$

$$\text{eg. } y''' + y'' - y' - y = 8e^{-t}.$$

Variation of Parameter:

$$\text{i) } r^3 + r^2 - r - 1 = 0.$$

$$\Rightarrow (r-1) \cdot (r^2 + 2r + 1) = 0.$$

$$\Rightarrow (r-1) \cdot (r+1)^2 = 0.$$

$$r_1 = 1, \quad r_{2,3} = -1.$$

$$y_1 = e^t; y_2 = e^{-t}; y_3 = t \cdot e^{-t}.$$

$$\text{ii) } \omega = \det \begin{pmatrix} e^t & e^{-t} & t \cdot e^{-t} \\ e^t & -e^{-t} & e^{-t} - t \cdot e^{-t} \\ e^t & e^{-t} & -2e^{-t} + t \cdot e^{-t} \end{pmatrix}$$

$$= e^t \cdot \omega_1 + e^{-t} \cdot \omega_2 + (-2e^{-t} + t \cdot e^{-t}) \cdot \omega_3.$$

$$\omega_1 = \det \begin{pmatrix} e^{-t} & t \cdot e^{-t} \\ -e^{-t} & e^{-t} - t \cdot e^{-t} \end{pmatrix} = e^{-2t} - t \cdot e^{-2t} + t \cdot e^{-2t} = e^{-2t}.$$

$$\omega_2 = -\det \begin{pmatrix} e^t & t \cdot e^{-t} \\ e^t & e^{-t} - t \cdot e^{-t} \end{pmatrix} = -1 - t - t = -2t - 1$$

$$\omega_3 = \det \begin{pmatrix} te^t & e^{-t} \\ e^t & -e^{-t} \end{pmatrix} = -1 - 1 = -2.$$

$$\begin{aligned} \therefore \omega &= e^t \cdot (e^{-2t}) + e^{-t} \cdot (2t-1) + (-2e^{-t} + t \cdot e^{-t}) \cdot (-2) \\ &= e^{-t} + 2t \cdot e^{-t} - e^{-t} + 4e^{-t} - 2t \cdot e^{-t} \\ &= 4e^{-t} \end{aligned}$$

$$\begin{aligned} \text{ii) } u_1 &= \int \frac{g(t) \cdot \omega_1}{\omega} dt = \int \frac{8e^{-t} \cdot e^{-2t}}{4e^{-t}} dt = \int 2 \cdot e^{-2t} dt \\ &= -e^{-2t} + C_1 \end{aligned}$$

$$\begin{aligned} u_2 &= \int \frac{g(t) \cdot \omega_2}{\omega} dt = \int \frac{8e^{-t} \cdot (2t-1)}{4e^{-t}} dt = \int 2(2t-1) dt \\ &= 2t^2 - 2t + C_2 \end{aligned}$$

$$\begin{aligned} u_3 &= \int \frac{g(t) \cdot \omega_3}{\omega} dt = \int \frac{8e^{-t} \cdot (-2)}{4e^{-t}} dt = \int -4 dt \\ &= -4t + C_3. \end{aligned}$$

$$\begin{aligned} \text{iv) } y(x) &= (-e^{-2t} + C_1) \cdot e^t + (2t^2 - 2t + C_2) \cdot e^{-t} + (-4t + C_3) \cdot t \cdot e^{-t} \\ &= C_1 \cdot e^t + C_2 \cdot e^{-t} + C_3 \cdot t \cdot e^{-t} + (-e^{-t} + 2t^2 \cdot e^{-t} - 2t \cdot e^{-t} + 4t^2 \cdot e^{-t}) \\ &= C_1 \cdot e^t + C_2 \cdot e^{-t} + C_3 \cdot t \cdot e^{-t} + e^{-t} \cdot (-2t^2 - 2t - 1) \\ &= C_1^* \cdot e^t + C_2^* \cdot e^{-t} + C_3^* \cdot t \cdot e^{-t} - \underbrace{2t^2 \cdot e^{-t}}_{y_p(t)}. \end{aligned}$$