

```
In [13]: 1 #importing necessary packages
2 from sympy.interactive import printing
3 printing.init_printing(use_latex=True)
4 from sympy import *
5 import sympy as sp
6 import numpy as np
7 import matplotlib.pyplot as plt
```

Q1 (a)

Here we find the general solution for second order linear differential equation that is homogeneous with constant coefficients

in class we solved $y'' + y = 0$ and we realized that y can take two forms either exponential e^{kx} or sin

This is because when we plug either to the equation and solve then we end up with 0 as expected

so we expect our solution-general solution- to be in the form of:

$y = A \sin() + B \sin()$ where A and B are coefficients or

$y = Ae^{\omega k} + Be^{\omega k}$

Either of the above forms is correct

```
In [14]: 1 #expressing ω,t as symbols that we will use later where omega where ω=sqrt(k/m)
2 ω,t=sp.symbols(' ω t')
3 #expressing x as a fuction
4 x=sp.Function('x')
```

```
In [15]: 1 #here our fuction is dependant on t
2 diff_2=Eq(sp.Derivative(x(t), t, 2) + ω**2 * x(t),0)
3 #displaying our fuction
4 display(diff_2)
```

$$\omega^2 x(t) + \frac{d^2}{dt^2} x(t) = 0$$

The General solution is as below where **C1** and **C2** are coefficients

```
In [16]: 1 # here we disolve the fuction which means we differenciate with respect to t , solving the equation gives us
          2 #C1 and C2 on the display are place holders
          3 ans= sp.dsolve(sp.Derivative(x(t), t, 2) + ω**2 * x(t))
          4 print("\n General solution\n" )
          5 display(ans)
```

General solution

$$x(t) = C_1 e^{-it\omega} + C_2 e^{it\omega}$$

We solve for our two unknowns c1 and c2

We also substitute relevant variables with intial condition values where

$$\omega_0 = 2,$$

$$x(0) = 1,$$

$$x'(0) = 0$$

```
In [17]: 1 initial_con = [sp.Eq(ans.args[1].subs(t, 0), 1), sp.Eq(ans.args[1].diff(t).subs(t, 0), 0)]
          2 initial_con
```

Out[17]: $[C_1 + C_2 = 1, -iC_1\omega + iC_2\omega = 0]$

```
In [18]: 1 initial_con_ans_1=sp.solve(initial_con)
          2 initial_con_ans_1
```

Out[18]: $\left[\left\{ C_1 : \frac{1}{2}, C_2 : \frac{1}{2} \right\} \right]$

The below equation is as a result of solving for the ciefficients and substitutin with there values:

we then simplified the equation to obtain a simpler version of x(t)

The complex exponentials are not a surprise as we expected an oscillatory fuction from the natural behaviour of springs # **statistical Mechanic NS162**

```
In [19]: 1 initial_con_full_ans = ans.subs(initial_con_ans_1[0])
          2 initial_con_full_ans
```

Out[19]: $x(t) = \frac{e^{it\omega}}{2} + \frac{e^{-it\omega}}{2}$

We substitute the values

$$\omega_0 = 2,$$

$$x(0) = 1,$$

$$x'(0) = 0$$

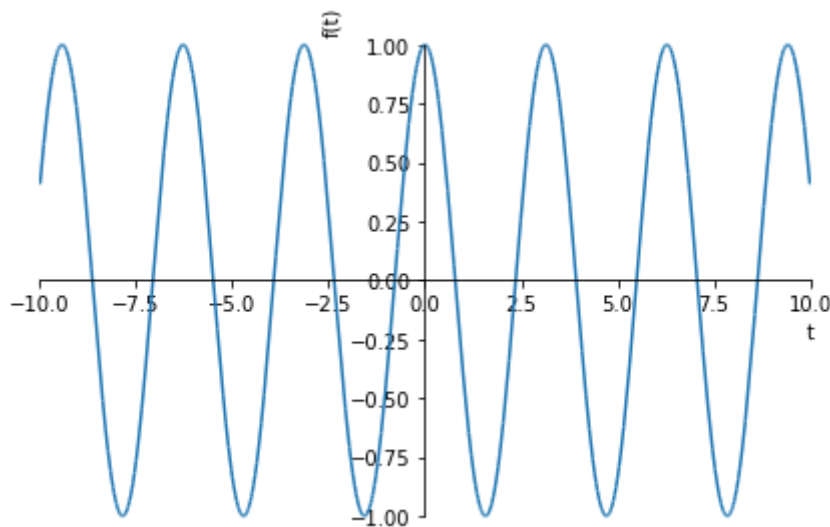
Given in the problem and simplify to obtaining the below function

```
In [20]: 1 x, x_0=sp.symbols('x x_0')
2 given_scenario = sp.simplify(initial_con_full_ans.subs({x_0:1, x:0, ω:2}))
3 given_scenario
```

Out[20]: $x(t) = \cos(2t)$

We then plot the simplified $x(t)$ over range

```
In [21]: 1 sp.plot(given_scenario.rhs)
```



Out[21]: <sympy.plotting.plot.Plot at 0x7fdd0eee2cd0>

The plot above follows the natural behaviour of harmonic oscillators

Q1 (b)

Here we implement our solution using the **complexification technique**

That is : $u=(x+yi)^n$ where y_i is the imaginary part and x is the real part

```
In [22]: 1 ω_1=sp.symbols('ω_1')
```

```
In [23]: 1 diff_1=Eq(sp.Derivative(x(t), t, 2) + ω**2 * x(t),cos(ω_1*t))
          2 display(diff_1)
```

$$\omega^2 x(t) + \frac{d^2}{dt^2} x(t) = \cos(t\omega_1)$$

We already know the genral solution from part a here we just need to include the real part

```
In [24]: 1 complication=dsolve(Eq(sp.Derivative(x(t), t, 2) + ω**2 * x(t),cos(ω_1*t)))
          2 print("\n General solution\n" )
          3 display(complication)
```

General solution

$$x(t) = C_1 e^{-it\omega} + C_2 e^{it\omega} + \frac{\cos(t\omega_1)}{\omega^2 - \omega_1^2}$$

We solve for our two unknowns c1 and c2

We also substitute relevant variables with intial condition values where

$$\omega_0 = 2,$$

$$x(0) = 1,$$

$$x'(0) = 0$$

```
In [25]: 1 complication_sol= [sp.Eq(complication.args[1].subs(t, 0), 1), sp.Eq(complication.args[1].diff(t).subs(t, 0), 0)]
          2 display(complication_sol)
```

$$\left[C_1 + C_2 + \frac{1}{\omega^2 - \omega_1^2} = 1, \quad -iC_1\omega + iC_2\omega = 0 \right]$$

We substitute the values

$$\omega_0 = 2,$$

$$x(0) = 1,$$

$$x'(0) = 0$$

Given in the problem and simplify to obtaining the below fuction

```
In [26]: 1 complication_sol_1=sp.solve(complication_sol)
          2 display(complication_sol_1)
```

$$\left[\left\{ C_1 : \frac{\omega^2 - \omega_1^2 - 1}{2(\omega - \omega_1)(\omega + \omega_1)}, C_2 : \frac{\omega^2 - \omega_1^2 - 1}{2(\omega - \omega_1)(\omega + \omega_1)} \right\} \right]$$

The below equation is as a result of solving for the ciefficients and substitutin with there values:

we then simplified the equation to obtain a simpler version of $x(t)$

The complex exponentials are not a surprise as we expected an oscillatory function from the natural behaviour of springs # **statistical Mechanics NS162**

In [27]:

```
1 complication_sol_full = ans.subs(complication_sol_1[0])
2 display(complication_sol_full)
```

$$x(t) = \frac{(\omega^2 - \omega_1^2 - 1) e^{it\omega}}{2(\omega - \omega_1)(\omega + \omega_1)} + \frac{(\omega^2 - \omega_1^2 - 1) e^{-it\omega}}{2(\omega - \omega_1)(\omega + \omega_1)}$$

$\omega_1 \neq \omega_0$ because the function will be undefined, the denominator will be 0 and this we can not solve the problem

We substitute the values

$$\omega_0 = 2,$$

$$x(0) = 1,$$

$$x'(0) = 0$$

Given in the problem and simplify to obtaining the below function

In [28]:

```
1 given_scenario_2 = sp.simplify(complication_sol_full.subs({x_0:1, x_dot:0, omega:2, omega_1:3}))
2 given_scenario_2
```

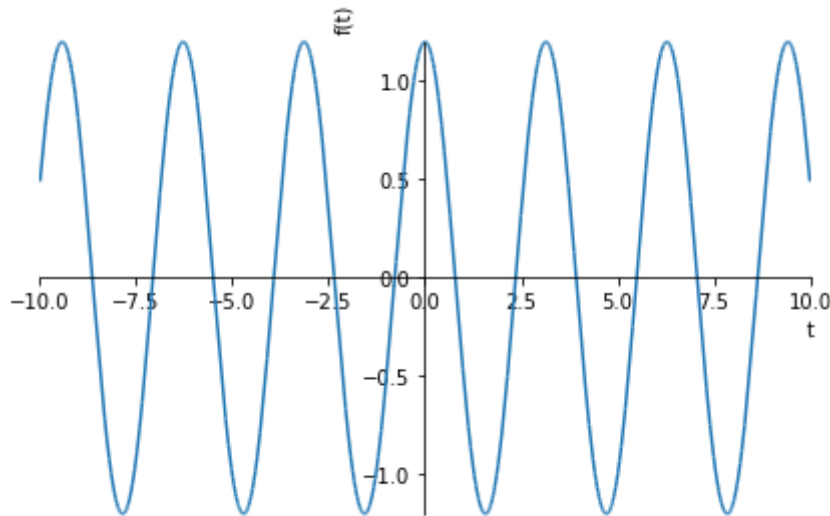
Out[28]:

$$x(t) = \frac{6 \cos(2t)}{5}$$

Q1 (c)

We then plot the simplified $x(t)$ over range

In [29]: 1 sp.plot(given_scenario_2.rhs)



Out[29]: <sympy.plotting.plot.Plot at 0x7fdd0fa10bd0>

The plot above follows the natural behaviour of harmonic oscillators

We repeat Q1 b and c using sin instead, all functions are the same just replace cos with sin, and the explanations are the same too.

In [30]: 1 diff_1_sin=Eq(sp.Derivative(x(t), t, 2) + ω**2 * x(t), sin(ω_1*t))
2 display(diff_1_sin)

$$\omega^2 x(t) + \frac{d^2}{dt^2} x(t) = \sin(t\omega_1)$$

In [31]:

```
1 complication_sin=dsolve(Eq(sp.Derivative(x(t), t, 2) + ω**2 * x(t), sin(ω_1*t)))
2 display(complication_sin)
```

$$x(t) = C_1 e^{-it\omega} + C_2 e^{it\omega} + \frac{\sin(t\omega_1)}{\omega^2 - \omega_1^2}$$

In [32]:

```
1 complication_sol_sin = [sp.Eq(complication_sin.args[1].subs(t, 0), 1), sp.Eq(complication_sin.args[1].
2 display(complication_sol_sin)
```

$$\left[C_1 + C_2 = 1, -iC_1\omega + iC_2\omega + \frac{\omega_1}{\omega^2 - \omega_1^2} = 0 \right]$$

In [33]:

```
1 complication_sol_1_sin=sp.solve(complication_sol_sin)
2 display(complication_sol_1_sin)
```

$$\left[\left\{ C_1 : \frac{\omega^3 - \omega\omega_1^2 - i\omega_1}{2\omega(\omega^2 - \omega_1^2)}, C_2 : \frac{\omega^3 - \omega\omega_1^2 + i\omega_1}{2\omega(\omega^2 - \omega_1^2)} \right\} \right]$$

In [34]:

```
1 complication_sol_full_sin = ans.subs(complication_sol_1_sin[0])
2 display(complication_sol_full_sin)
```

$$x(t) = \frac{(\omega^3 - \omega\omega_1^2 - i\omega_1) e^{-it\omega}}{2\omega(\omega^2 - \omega_1^2)} + \frac{(\omega^3 - \omega\omega_1^2 + i\omega_1) e^{it\omega}}{2\omega(\omega^2 - \omega_1^2)}$$

In [35]:

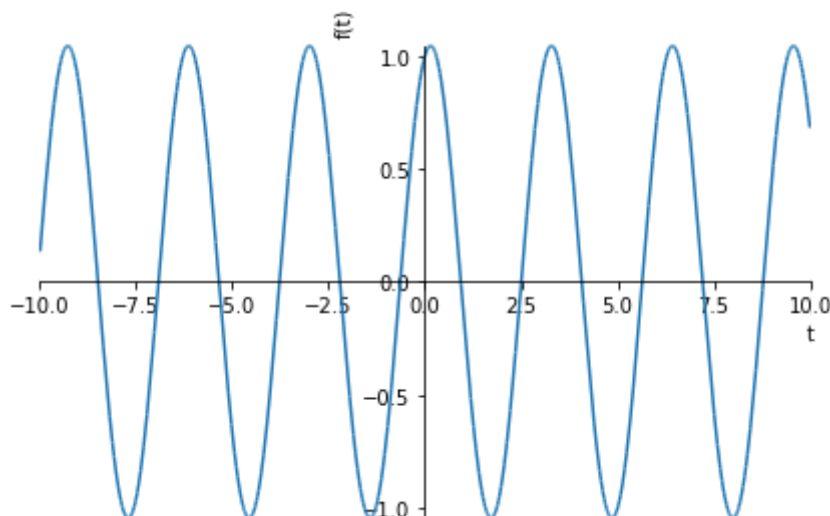
```
1 given_scenario_2_sin = sp.simplify(complication_sol_full_sin.subs({x_0:1, x:0, ω:2, ω_1:3}))
2 given_scenario_2_sin
```

Out[35]:

$$x(t) = \frac{((10 - 3i) e^{4it} + 10 + 3i) e^{-2it}}{20}$$

In [36]:

```
1 sin_plot=sp.plot(given_scenario_2_sin.rhs)
2 sin_plot
```



Out[36]: <sympy.plotting.plot.Plot at 0x7fdd0feb3090>

Q1 (d)

we set $x=f(t)e^{i\omega t}$: we do this because solving it directly leads to undefined solution as we get 0 at the denominator

$$x=f(t)e^{i\omega t}$$

$$x'=f'(t)e^{i\omega t}+i\omega f(t)e^{i\omega t}$$

$$x''=f''(t)e^{i\omega t}+i\omega f'(t)e^{i\omega t}+i\omega f'(t)e^{i\omega t}-\omega^2 * f(t)e^{i\omega t}$$

$$x''+\omega^2 x=f''(t)e^{i\omega t}+2i\omega f'(t)e^{i\omega t}-\omega^2 * f(t)e^{i\omega t}+\omega^2 * f(t)e^{i\omega t}$$

The last terms disappear

$$f''(t)e^{i\omega t}+2i\omega f(t)e^{i\omega t}$$

dislvoing the fuction further yields $e^{i\omega}$

$$e^{i\omega}=\cos\omega+i\sin\omega$$

general solution

$$e^{i\omega} \text{ or } \cos\omega+i\sin\omega$$

```
In [ ]: 1 import cmath
        2 import math
        3 from math import e
        4 i = 1j
```

```
In [ ]: 1 #set x=f(t)e^(i\omega t)
        2 x=sp.Function('f')(t)*e**(i*\omega*t)
        3 display(x)
```

```
In [39]: 1 fuc=Eq(sp.Derivative(x, t, 2) + \omega**2 * x, sin(\omega*t))
        2 display(fuc)
```

$$2.71828182845905^{1.0it\omega} \omega^2 f(t) + \frac{\partial^2}{\partial t^2} 2.71828182845905^{1.0it\omega} f(t) = \sin(t\omega)$$

```
In [41]: 1 complication_ii=dsolve(Eq(sp.Derivative(x, t, 2) + \omega**2 * x, sin(\omega*t)))
        2 display(complication_ii)
```

Q1 (e)

The general solution differ in the coefficients as well as the placement of the imaginary part

in the first one we had general solution in the form $Ae^{i\omega t} + Be^{-i\omega t}$ while in the d part we have $\cos\omega t + i\sin\omega t$:

Q1 (f) Video explanation based on Numerical analysis knowledge

We know that $\omega = \sqrt{k/m}$ where k is the spring constant and m is the mass. If k is big it means the spring is strong that the oscillation will be small but faster, while if m is big the oscillation would be slower due to change of inertia. Applying the same knowledge on the bridge from the 0.21 second the oscillation are slow but big which means the mass is greater than what the spring can hold thus may tend towards breaking point. Some sections of the bridge are vibrating faster but the amplitude is smaller which means the bridge has less weight there that is less than the spring constant. The wind acts as an external agent that acts as a catalyst, here it increased m thus the bridge reached its breaking point. Notice that it breaks fast where the vibration were slow but big ($m \gg k$). This shows how ω which is a function of $\sqrt{k/m}$ contributes in the harmonic oscillation.

Question 2

I recorded two audio from different location

and used <https://www.online-convert.com/result#j=5eaeec88-dddd-426d-a83b-4012d440a97c>
(<https://www.online-convert.com/result#j=5eaeec88-dddd-426d-a83b-4012d440a97c>)

to convert the audi into wave. I then read it through wave.open from scipy

In [50]:

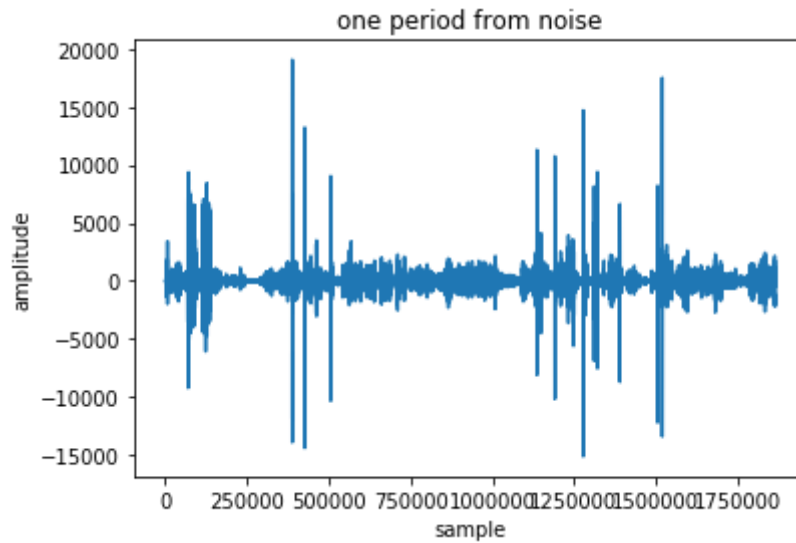
```
1 from scipy.io import wavfile
2 from scipy import *
3 import wave
4 import matplotlib.pyplot as plt
```

In [51]:

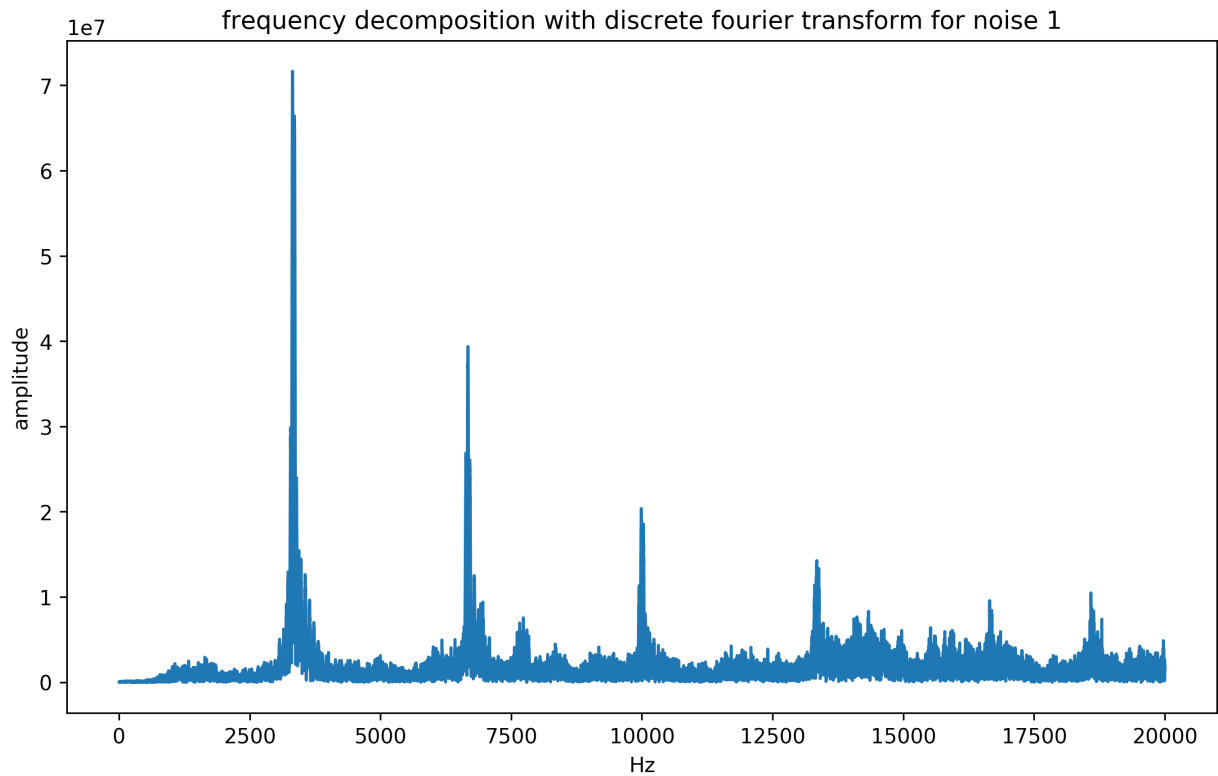
```
1 noise = wave.open("noise1.wav", 'r')
2 noise_rate = np.inf
```

```
In [52]: 1 sig = np.frombuffer(noise.readframes(noise_rate), dtype=np.int16)
2         plt.plot(sig)
3         plt.title("one period from noise")
4         plt.xlabel("sample")
5         plt.ylabel("amplitude")
```

Out[52]: Text(0, 0.5, 'amplitude')



```
In [53]: 1 trans_1 = fft(sig)
2 plt.figure(figsize=(10, 6), dpi=330)
3 plt.plot(abs(trans_1)[:20000])
4 plt.ylabel("amplitude")
5 plt.xlabel("Hz")
6 plt.title("frequency decomposition with discrete fourier transform for noise 1")
7 plt.show()
```



```
In [72]: 1 peak_1=2500+2500/2
2 peak_1
```

Out[72]: 3750.0

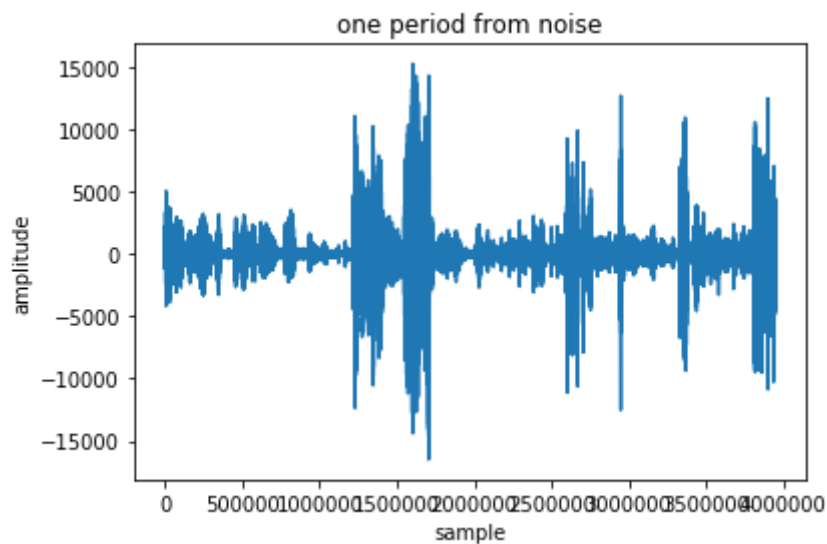
The dominant peak is at around 3750.0HZ

This is the highest frequency after we decompose the wave into finite number of sinusoidal, From the graph we other smaller peaks that reduce over time and flattens towards the 20000HZ

```
In [54]: 1 noise_2 = wave.open("noise2.wav",'r')
          2 noise_rate=np.inf
```

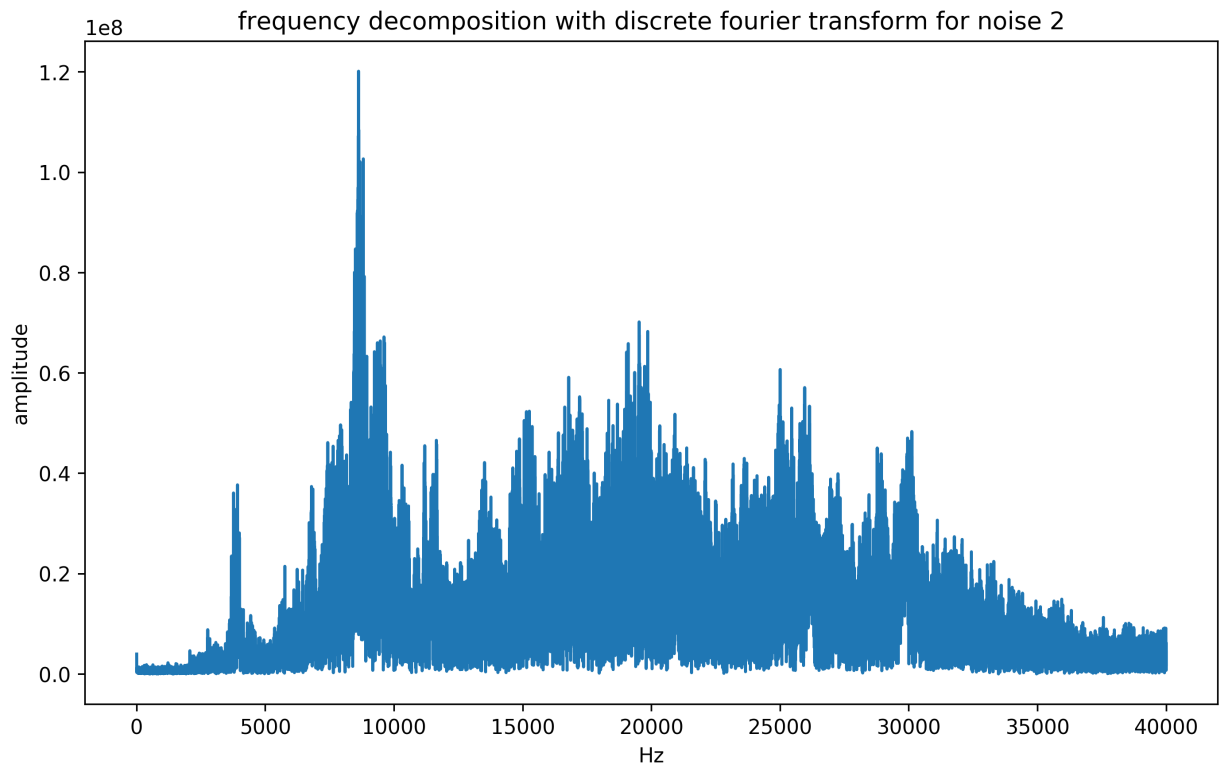
```
In [55]: 1 sig_2 = np.frombuffer(noise_2.readframes(noise_rate), dtype=np.int16)
          2 plt.plot(sig_2)
          3 plt.title("one period from noise")
          4 plt.xlabel("sample")
          5 plt.ylabel("amplitude")
```

Out[55]: Text(0, 0.5, 'amplitude')



```
In [73]: 1 from scipy.signal import find_peaks
2 trans_2 = fft(sig_2)
3 plt.figure(figsize=(10, 6), dpi=330)
4 peaks, _ = find_peaks(trans_2, height=0)
5 plt.plot(abs(trans_2)[:40000])
6 plt.ylabel("amplitude")
7 plt.xlabel("Hz")
8 plt.title("frequency decomposition with discrete fourier transform for noise 2")
9 plt.show()
```

/opt/anaconda3/lib/python3.7/site-packages/scipy/signal/_peak_finding.py:264: ComplexWarning: Casting complex values to real discards the imaginary part
value = np.asarray(value, order='C', dtype=np.float64)



```
In [71]: 1 peak=7500+2500/2
          2 peak
```

Out[71]: 8750.0

The dominant frequency is at around 8750.0HZ

From there the frequency height reduces over time and decreases more between 35000 and 40000. This means that if I was studying and got rid of 8750.0 then noise would reduce significantly. It is at the dominant frequency where the highest energy is found $E = h\nu = hc/\lambda$, where E = energy, h = Planck's constant, ν = frequency, c = the speed of light, and λ = wavelength. # **statistical**
Mechanic NS162. Removing the highest frequency means that noise measured in decibels would be lower

From the second graph I would need earbud that cancels frequency between 2500Hz to 35000Hz as it's the region with more fluctuation and high average energy thus noise

From the 1st graph the noise cancellation should be able to cancel frequencies between 2500Hz to 17500Hz