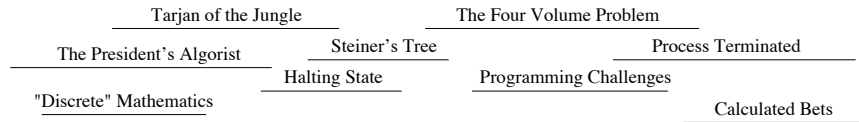


# Selecting the Right Jobs

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A movie star wants to select the maximum number of starring roles such that no two jobs require his presence at the same time.



# The Movie Star Scheduling Problem

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Input: A set  $I$  of  $n$  intervals on the line.

Output: What is the largest subset of mutually non-overlapping intervals which can be selected from  $I$ ?

Give an algorithm to solve the problem!

## Earliest Job First

---

Start working as soon as there is work available:

EarliestJobFirst( $I$ )

Accept the earliest starting job  $j$  from  $I$  which does not overlap any previously accepted job, and repeat until no more such jobs remain.

# Earliest Job First is Wrong!

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The first job might be so long (War and Peace) that it prevents us from taking any other job.

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## Shortest Job First

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Always take the shortest possible job, so you spend the least time working (and thus unavailable).

ShortestJobFirst( $I$ )

While ( $I \neq \emptyset$ ) do

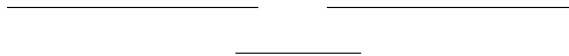
    Accept the shortest possible job  $j$  from  $I$ .

    Delete  $j$ , and intervals which intersect  $j$  from  $I$ .

# Shortest Job First is Wrong!

---

Taking the shortest job can prevent us from taking two longer jobs which barely overlap it.



## First Job to Complete

---

Take the job with the earliest completion date:

OptimalScheduling( $I$ )

While ( $I \neq \emptyset$ ) do

    Accept job  $j$  with the earliest completion date.

    Delete  $j$ , and whatever intersects  $j$  from  $I$ .

## First Job to Complete is Optimal!

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Other jobs may well have started before the first to complete ( $x$ ), but all must at least partially overlap each other.

Thus we can select at most one from the group.

The first these jobs to complete is  $x$ , so the rest can only block out more opportunities to the right of  $x$ .



# Robot Tour Optimization

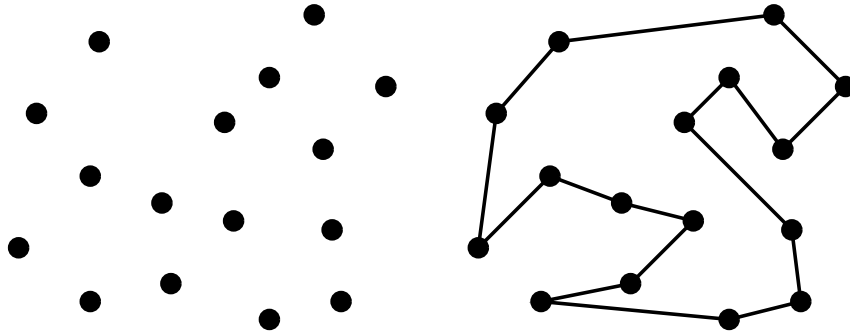
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Suppose you have a robot arm equipped with a tool, say a soldering iron. To enable the robot arm to do a soldering job, we must construct an ordering of the contact points, so the robot visits (and solders) the points in order.

We seek the order which minimizes the testing time (i.e. travel distance) it takes to assemble the circuit board.

# Find the Shortest Robot Tour

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You are given the job to program the robot arm. Give me an algorithm to find the best tour!

## Nearest Neighbor Tour

---

A popular solution starts at some point  $p_0$  and then walks to its nearest neighbor  $p_1$  first, then repeats from  $p_1$ , etc. until done.

Pick and visit an initial point  $p_0$

$$p = p_0$$

$$i = 0$$

While there are still unvisited points

$$i = i + 1$$

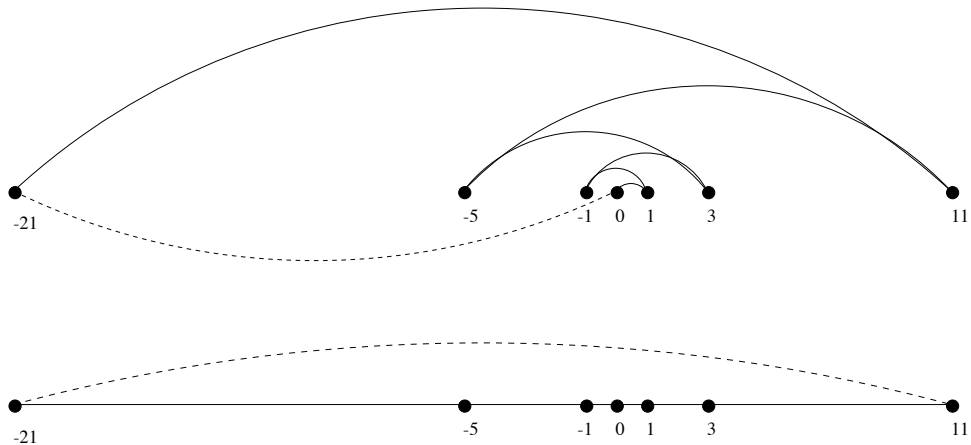
Let  $p_i$  be the closest unvisited point to  $p_{i-1}$

Visit  $p_i$

Return to  $p_0$  from  $p_i$

# Nearest Neighbor Tour is Wrong!

---



Starting from the leftmost point will not fix the problem.

# Closest Pair Tour

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Another idea is to repeatedly connect the closest pair of points whose connection will not cause a cycle or a three-way branch, until all points are in one tour.

Let  $n$  be the number of points in the set

$d = \infty$

For  $i = 1$  to  $n - 1$  do

    For each pair of endpoints  $(x, y)$  of partial paths

        If  $\text{dist}(x, y) \leq d$  then

$x_m = x, y_m = y, d = \text{dist}(x, y)$

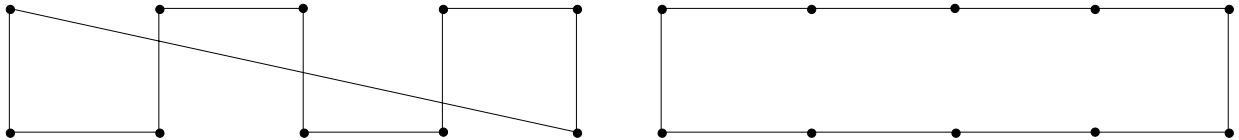
        Connect  $(x_m, y_m)$  by an edge

Connect the two endpoints by an edge.

# Closest Pair Tour is Wrong!

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Although it works correctly on the previous example, other data causes trouble:



## A Correct Algorithm: Exhaustive Search

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We could try all possible orderings of the points, then select the one which minimizes the total length:

$$d = \infty$$

For each of the  $n!$  permutations  $\Pi_i$  of the  $n$  points

    If  $(cost(\Pi_i) \leq d)$  then

$$d = cost(\Pi_i) \text{ and } P_{min} = \Pi_i$$

Return  $P_{min}$

Since all possible orderings are considered, we are guaranteed to end up with the shortest possible tour.

## Exhaustive Search is Slow!

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Because it tries all  $n!$  permutations, it is much too slow to use when there are more than 10-20 points.

No efficient, correct algorithm exists for the *traveling salesman problem*, as we will see later.