

HENRY NGUYEN

San Jose, CA | (206) 751-6618 | henrynguyen.vp@gmail.com

Website: henrynp.github.io | GitHub: github.com/HenryNVP | LinkedIn: linkedin.com/in/henrynguyen-vp

EDUCATION

Master of Science in Artificial Intelligence

San Jose State University

- Coursework: AI & Data Engineering, Deep Learning, Reinforcement Learning, Autonomous Driving, MLOps

Exp. May 2026

San Jose, CA

Bachelor of Engineering in Mechatronic Engineering

Ho Chi Minh City University of Technology

Apr. 2023

Vietnam

TECHNICAL SKILLS

AI & Agents: LLMs, LangGraph, GraphRAG, MCP, Vector/Graph DBs, Agentic Workflows

Machine Learning: PyTorch, TensorRT, ONNX, CUDA, Quantization, Transformers, CNNs, RecSys

Robotics: ROS2, LiDAR-Camera Fusion, 3D Perception, Navigation, Control Systems, System Integration

Software & DevOps: Python, FastAPI, Docker, Microservices, Prometheus, Edge AI (Jetson, ONNX Runtime)

FEATURED AI PROJECTS

AI Tutor: RAG-Powered Learning Platform | *GenAI, RAG, MCP, FastAPI, OpenAI Agents SDK*

- Built a full-stack **multi-agent** educational system that ingests documents to generate cited answers, adaptive quizzes, and lesson notes via a source-filtered **RAG** pipeline using **ChromaDB**.
- Implemented an **MCP server** and secure Python execution with **FastAPI** backend, enabling structured tool use, real-time data visualization from CSVs, and adaptive learning features that track student progress.

ROS2 BEV-Fusion: Real-Time 3D Perception | *Python, ROS2, TensorRT, CUDA, Jetson, Edge AI*

- Developed an optimized **BEVFusion** 3D perception pipeline for multi-camera and LiDAR fusion, validated on NuScenes and deployed as a modular **ROS2** package.
- Optimized end-to-end inference with **TensorRT** and quantization, achieving ~7 FPS for the full BEVFusion pipeline on Jetson Orin Nano and publishing **ROS2** detection outputs with latency metrics.

FastViT Mobile Optimization | *PyTorch, Android, Quantization, Knowledge Distillation*

- Re-architected FastViT by replacing Multi-Head Attention with **Performer Attention** ($O(N)$) and implementing **FP16 quantization**, achieving a **4.8x speedup** on Android with **identical Top-1 accuracy**.

SAM-E: Agentic Enrollment System | *GenAI, RAG, LangGraph, Docker, FastAPI*

- Architected a microservices-based agentic system with three services (Agent, RAG, Enrollment Engine) using **Docker Compose** and **LangGraph** to route user intents to specialized tools.
- Developed a retrieval pipeline using **pgvector** to support academic queries, with planned integration of a **Neo4j** knowledge graph; demonstrated functionality via **FastAPI**, **JWT authentication**, and **Prometheus** metrics.

ADDITIONAL PROJECTS

Image Classification: Engineered a **timm** pipeline with automated **ONNX** export for rapid CNN/ViT benchmarking.

3D Object Detection Pipeline: Built **MMDetection3D** end-to-end inference pipeline for KITTI/nuScenes.

Anime RecSys: Trained and deployed **NeuMF** and **Two-Tower** recommender system via **FastAPI**.

Client Web Projects: Delivered commercial **WordPress** sites with automated booking, increasing client inquiries.

PROFESSIONAL EXPERIENCE

Software Integration Engineer (Automotive Safety Systems)

Bosch Global Software Technologies

Jun. 2023 – Dec. 2023

Ho Chi Minh, Vietnam

- Managed the software release lifecycle for **8+ ESP (Electronic Stability Program)** projects, integrating modules from cross-functional teams to deliver production-ready baselines.
- Executed comprehensive integration testing (**SiL & HiL**) and authored **ISO-compliant validation reports**, identifying critical defects to ensure system stability before delivery.

Undergraduate Researcher

Mechatronics Lab, HCMUT

Aug. 2022 – Dec. 2022

Ho Chi Minh, Vietnam

- Designed an adaptive 3-finger robotic gripper (+200% payload capacity) and engineered a **vision-guided control stack** (C++, YOLO) for a 5-axis manipulator to execute automated pick-and-place tasks.