

Explore-then-Commit and Upper Confidence Bound Algorithm

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Today's agenda

- Recap
- Optimism in the face of uncertainty
- Sub-gaussian distribution
- Explore-Then-Commit algorithm
- Upper Confidence Bound (UCB) algorithm
- Adversarial Bandits

Recap: Regret

- **Regret**: The cost of not always playing the best arm.
- The regret R_n after n plays I_1, I_2, \dots, I_n is defined by

$$R_n = \max_{i=1, \dots, K} \sum_{t=1}^n X_{i,t} - \sum_{t=1}^n X_{I_t,t} .$$

Recap: Stochastic Multi-armed Bandits

- The rewards of arm i are i.i.d according to a fixed probability distribution $\nu_1, \nu_2, \dots, \nu_K$ on $[0, 1]$. These distributions are unknown to the algorithm.

- Let:

$$\mu^* = \max_{i=1,\dots,K} \mu_i \quad \text{and} \quad i^* \in \operatorname{argmax}_{i=1,\dots,K} \mu_i .$$

- In the stochastic setting, pseudo-regret can be written as

$$\tilde{R}_n = n\mu^* - \mathbb{E} \left[\sum_{t=1}^n \mu_{I_t} \right]$$

Recap: Another perspective of regret

- Let $\Delta_i = \mu^* - \mu_i$, and let $T_i(s)$ denote the number of times the algorithm chose arm i on the first s rounds. Regret is also a function of $T_i(s)$ and Δ_i .

$$\bar{R}_n = \left(\sum_{i=1}^K \mathbb{E} T_i(n) \right) \mu^* - \mathbb{E} \sum_{i=1}^K T_i(n) \mu_i = \sum_{i=1}^K \Delta_i \mathbb{E} T_i(n)$$

- We now minimize the weighted sum $\mathbb{E}[T_i(n)]$, where the weights are the respective action gaps.

Recap: simple heuristics

- **Naive:**

Greedy plays the arm with the highest empirical mean \Rightarrow may get stuck due to lack of exploration, regret is linear n .

Play all arms an equal number of times \Rightarrow pure exploration, regret is linear in n

- **e-greedy:**

Exploitation: greedily plays the arm with the highest empirical mean (observed rewards) so far with probability $1-\epsilon$,

Exploration: plays a random arm (including empirically best arm) with probability ϵ .

$\Rightarrow O(\log(n))$ regret

Sub-Gaussian Distribution

- To show the concentration results, a fundamental assumption is that reward $X_{i,t}$ follows a sub-gaussian distribution.
- Random variable X follows a σ^2 -subgaussian distribution if for all $\lambda \in \mathbb{R}$,

$$\mathbb{E}[\exp(\lambda X)] \leq \exp\left(\frac{\lambda^2 \sigma^2}{2}\right)$$

Sub-Gaussian distribution (cont.)

Lemma: Suppose that X is σ_1^2 -subgaussian and X_1 and X_2 are independent and σ_2^2 -subgaussian respectively, then:

- $\mathbb{E}[X] = 0$ and $\mathbb{V}[X] \leq \sigma^2$.
- cX is $c^2\sigma^2$ -subgaussian for all $c \in \mathbb{R}$.
- $X_1 + X_2$ is $(\sigma_1^2 + \sigma_2^2)$ -subgaussian.

Theorem: If X is σ^2 -subgaussian, then

$$\mathbb{P}(X \geq \varepsilon) \leq \exp\left(-\frac{\varepsilon^2}{2\sigma^2}\right).$$

Hoeffding's Bound

- Combining the above Theorem and Lemma, we get

$$\hat{\mu} - \mu = \frac{1}{n} \sum_{i=1}^n (X_i - \mu) \text{ is } \frac{\sigma^2}{n}\text{-subgaussian.}$$

Assume that $X_i - \mu$ are independent, σ^2 -subgaussian random variables. Then, their average $\hat{\mu}$ satisfies

$$\mathbb{P}(\hat{\mu} \geq \mu + \varepsilon) \leq \exp\left(-\frac{n\varepsilon^2}{2\sigma^2}\right),$$

$$\mathbb{P}(\hat{\mu} \leq \mu - \varepsilon) \leq \exp\left(-\frac{n\varepsilon^2}{2\sigma^2}\right).$$

Explore-then-Commit (ETC)

- Each arm is explored m times, then fully commit to the arm with the highest empirical mean. For simplicity, assuming $X_t - \mathbb{E}[X_t]$ is 1-subgaussian.
- Formally,

$$I_t = \begin{cases} i, & \text{if } (t \bmod K) + 1 = i \text{ and } t \leq mK; \\ \operatorname{argmax}_i \hat{\mu}_i(mK), & t > mK, \end{cases}$$

ETC Regret

- $$\begin{aligned} R_n &= \sum_{i=1}^K \Delta_i \mathbb{E}[T_i(n)] \\ &= m \sum_{i=1}^K \Delta_i + (n - mK) \sum_{i=1}^K \Delta_i \mathbb{P} \left(i = \operatorname{argmax}_j \hat{\mu}_j(mK) \right) \\ &\leq m \sum_{i=1}^K \Delta_i + (n - mK) \sum_{i=1}^K \Delta_i \exp \left(-\frac{m\Delta_i^2}{4} \right) \end{aligned}$$

- If m is large, the first term will be too large.
- If m is too small, then the probability that the algorithm commits to the wrong arm will grow and the second term becomes too large.

ETC Regret

- For $K = 2$, $\Delta_1 = 0$ and $\Delta_2 = \Delta$ and choose minimizing $m = \left\lceil \frac{4}{\Delta^2} \log\left(\frac{n\Delta^2}{4}\right) \right\rceil$

$$R_n \leq \Delta + \frac{4}{\Delta} \left(1 + \log\left(\frac{n\Delta^2}{4}\right) \right)$$

- Notice that $R_n \leq n\Delta$, we can take the minimum of the two bounds so that

$$R_n \leq \min \left\{ n\Delta, \Delta + \frac{4}{\Delta} \left(1 + \log\left(\frac{n\Delta^2}{4}\right) \right) \right\}$$

Optimism in the face of Uncertainty

- Random exploration (i.e ϵ -greedy) might take inefficient actions. One approach is to decrease ϵ over time, the other is to be *optimistic* about actions with *high uncertainty*.
- **Intuition:** If the optimism was justified, the algorithm is acting optimally. If the optimism was not, the algorithm learns the true payoff after a sufficient number of time steps.
 \Rightarrow UCB algorithm: $I_t = \operatorname{argmax}_i (\hat{u}_i + \text{bound})$

UCB Algorithm

$$\mathbb{P}(\hat{\mu} \geq \mu + \varepsilon) \leq \exp\left(-\frac{n\varepsilon^2}{2\sigma^2}\right),$$
$$\mathbb{P}(\hat{\mu} \leq \mu - \varepsilon) \leq \exp\left(-\frac{n\varepsilon^2}{2\sigma^2}\right).$$

- By Hoeffding's inequality,

$$\mathbb{P}\left(\hat{\mu} - \mu \geq \sqrt{\frac{2}{n} \log\left(\frac{1}{\delta}\right)}\right) \leq \delta$$

- UCB policy is as follows:

$$I_t = \begin{cases} \operatorname{argmax}_i \left(\hat{\mu}_i(t-1) + \sqrt{\frac{2 \log f(t)}{T_i(t-1)}} \right), & \text{if } t > K; \\ t, & \text{otherwise.} \end{cases}$$

The term inside argmax is called the **index** of arm i

UCB Algorithm (cont).

$$\operatorname{argmax}_i \left(\hat{\mu}_i(t-1) + \sqrt{\frac{2 \log f(t)}{T_i(t-1)}} \right)$$

Exploitation

Exploration

- $T_i(t)$ small \Rightarrow *larger* bound \Rightarrow uncertain, needs exploration
- $T_i(t)$ large \Rightarrow *smaller* bound \Rightarrow more confident to exploit

UCB Regret

Corollary (Lattimore & Szepesvari): The regret of UCB is bounded by

$$R_n \leq \sum_{i: \Delta_i > 0} \left(\Delta_i + \frac{1}{\Delta_i} \left(8 \log f(n) + 8 \sqrt{\pi \log f(n)} + 28 \right) \right).$$

and in particular there exists some universal constant $C > 0$ such that for all $n \geq 2$,

$$R_n \leq \sum_{i: \Delta_i > 0} \left(\Delta_i + \frac{C \log n}{\Delta_i} \right).$$

- This regret bound is unimprovable
- **Proof:** Bound $\mathbb{E}[T_i(n)]$

UCB Regret Proof Sketch

- To estimate $\mathbb{E}[T_i(n)]$, notice that arm i is chosen when UCB_i is either too high OR UCB_1 is too low. In math terms:

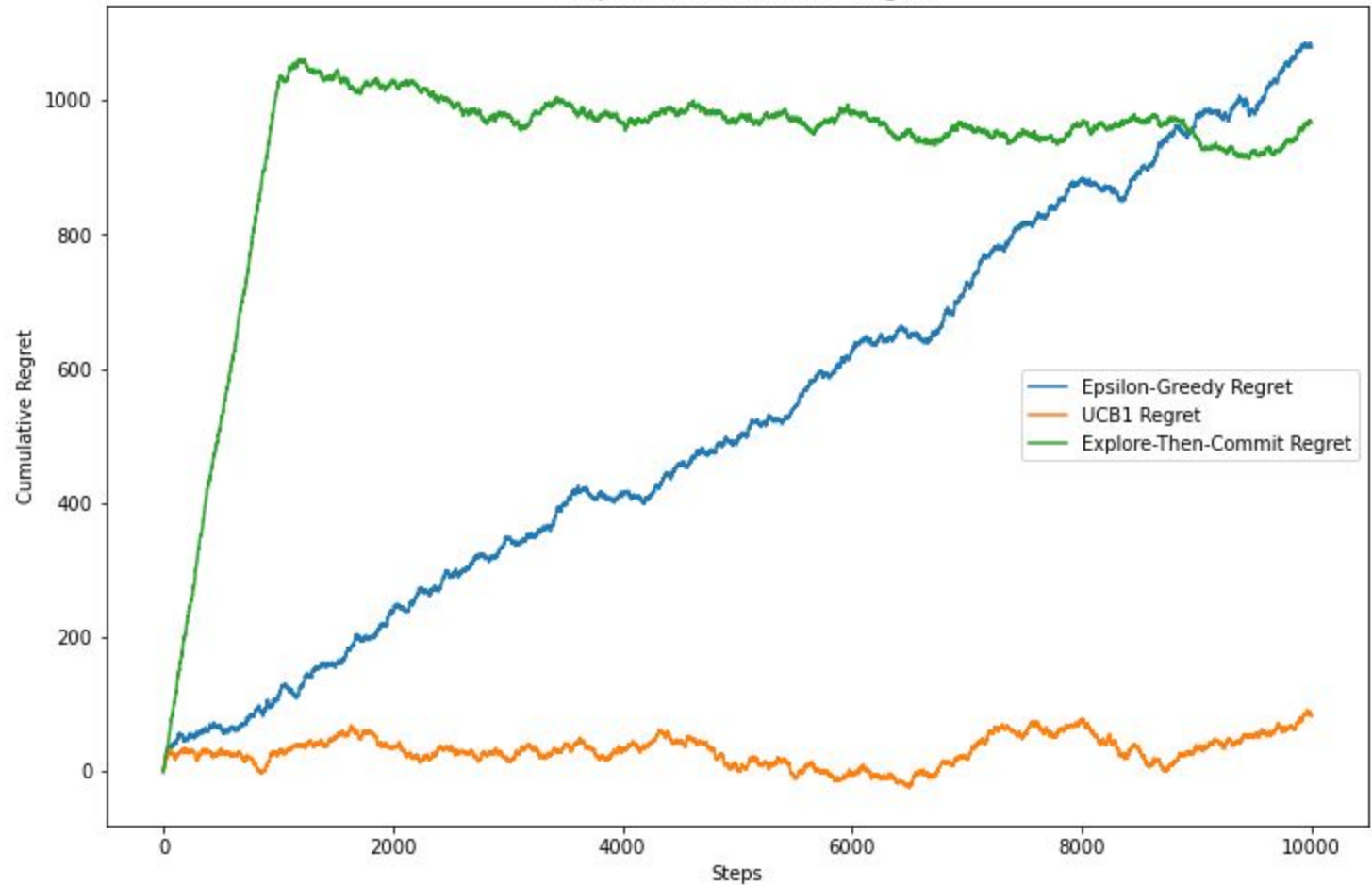
$$\begin{aligned} T_i(n) &= \sum_{t=1}^n \mathbb{I}\{A_t = i\} \\ &\leq \sum_{t=1}^n \left\{ \mathbb{I} \left\{ \hat{\mu}_1(t-1) + \sqrt{\frac{2 \log f(t)}{T_1(t-1)}} \leq \mu_1 - \varepsilon \right\} \right\} \\ &\quad + \sum_{t=1}^n \left\{ \mathbb{I} \left\{ \hat{\mu}_i(t-1) + \sqrt{\frac{2 \log f(t)}{T_i(t-1)}} \geq \mu_1 - \varepsilon \text{ and } A_t = i \right\} \right\}. \end{aligned}$$

Regret

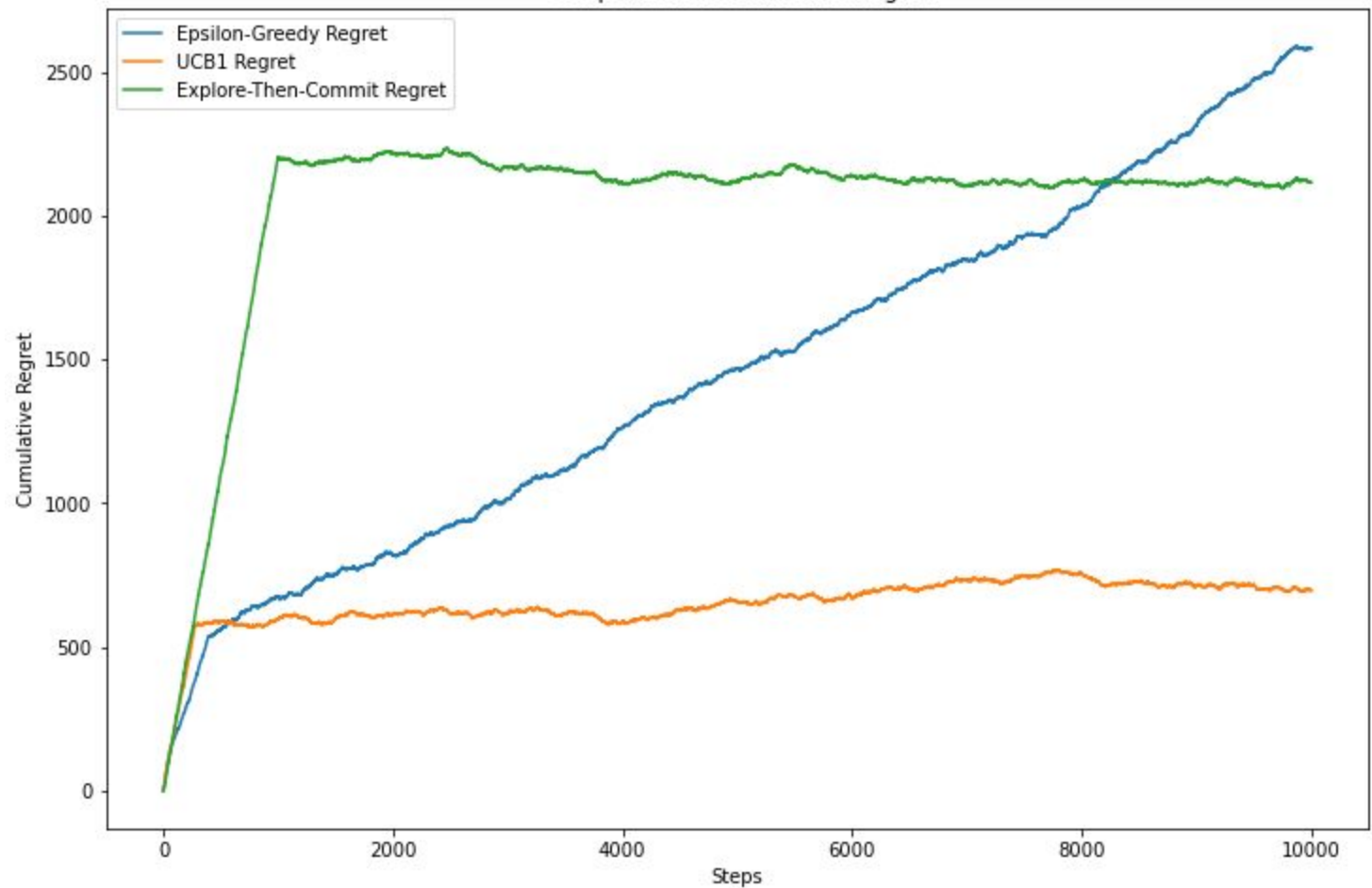
For stochastic bandits, so far, we have seen:

- **ϵ -greedy**: $O(n)$. $O(\log(n))$ if ϵ is a decreasing function of time
- **Explore-then-Commit**: $O(\log(n))$. However, this requires prior knowledge or assumptions about the rewards distribution
- **Upper Confidence Bound**: Balances exploration and exploitation. $O(\log(n))$

Comparison of Cumulative Regret



Comparison of Cumulative Regret



Adversarial Bandits

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Stochastic Bandits

Given $A = \{1, 2, \dots, K\}$ the set of action and (possibly) number of rounds $n \geq K$
for $t = 1, 2, \dots, n$ **do**:

Algorithm pulls arm $I_t \in A$

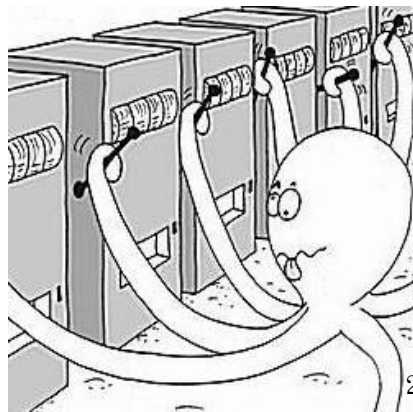
A reward vector $(X_{1,t}, X_{2,t}, \dots, X_{n,t})$ is generated, usually scaled to $[0, 1]$

Algorithm observes reward $X_{I_t,t}$

end for

Goal: Minimizing the regret

Simple formulation, but **no known tractable optimal solution**



Adversarial Bandits: Problem Settings

Given $A = \{1, 2, \dots, K\}$ the set of action and (possibly) number of rounds $n \geq K$

for $t = 1, 2, \dots, n$ **do**:

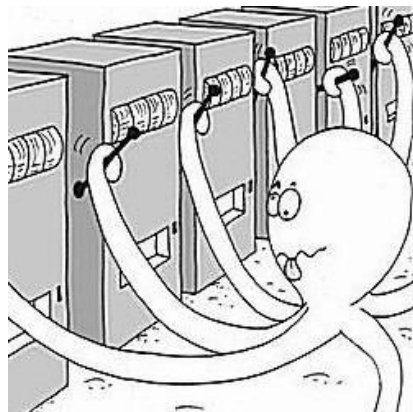
Algorithm pulls arm $I_t \in A$

A reward vector $(x_{1,t}, x_{2,t}, \dots, x_{n,t})$ is given by the adversary (**no underlying distribution**)

Algorithm observes reward $x_{I_t, t}$

end for

Goal: Minimizing the regret



Why adversarial?

- No assumptions about reward distribution \Rightarrow more robust algorithms
- Why regret vs **fixed arm** while losses are changing?
 \Rightarrow switching/dynamic regret
- For now, we still study the **static regret**

Need for Randomization

Example:

- If algorithm chooses action A, $\text{reward}_A = 0$, $\text{reward}_B = 1$
- If algorithm chooses action B, $\text{reward}_A = 1$, $\text{reward}_B = 0$

⇒ Linear regret

⇒ The algorithm needs to randomize its actions to achieve sublinear regret

Adversarial vs Stochastic

- In stochastic bandits, total expected reward to compared to the maximum *expected* reward
- In adversarial bandits, total expected reward to compared to the maximum reward. If randomization is present, compared to the expected maximum reward.

$$\begin{aligned} R_n(\pi, \nu) &= \max_{i \in [K]} \mathbb{E} \left[\sum_{t=1}^n (X_{t_i} - X_{t_{I_t}}) \right] \\ &\leq \mathbb{E} \left[\max_{i \in [K]} \sum_{t=1}^n (X_{t_i} - X_{t_{I_t}}) \right] \\ &= \mathbb{E} [R_n(\pi, X)] \leq R_n^*(\pi), \end{aligned}$$

Next Week

Exp3 Algorithm

Thank you!