

Bayesian Bandits, Thompson Sampling

Henry Vu

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Stochastic Bandits: Problem Settings

Given $A = \{1, 2, \dots, K\}$ the set of action and (possibly) number of rounds $n \geq K$
for $t = 1, 2, \dots, n$ **do**:

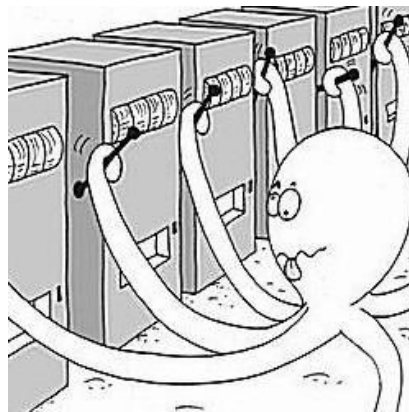
Algorithm pulls arm $A_t \in A$

A reward vector $(X_{t,1}, X_{t,2}, \dots, X_{t,n})$ is generated

Algorithm observes reward x_{t,A_t}

end for

Goal: Minimizing the static regret, i.e. *gap* between the fixed optimal action and the algorithm's choices



Bayesian Learning

- Notation:
 - X_i : Reward of arm i , a random variable
 - $P(X_i; \theta_i)$: Unknown reward distribution, parameterized by θ_i
 - $R(i) = E[X_i]$: Mean reward of arm i
- **Idea:** Assume a prior of the reward distribution $P(\theta_i)$. After observing reward sequence $x_{1,i}, x_{2,i}, \dots, x_{t,i}$, we can update the posterior distribution $P(\theta_i | x_{1,i}, \dots, x_{t,i})$
- **Bayes' Theorem:**
$$P(\theta_i | x_{1,i}, \dots, x_{t,i}) \propto P(x_{1,i}, \dots, x_{t,i} | \theta_i) * P(\theta_i)$$

Bayesian Learning

- Posterior over θ_i , $P(\theta_i|x_{1,i}, x_{2,i}, \dots, x_{t,i})$, allows us to estimate:
 - the distribution over the next reward $X_{t+1,i}$ for each arm i

$$P(X_{t+1,i}|x_{1,i}, \dots, x_{t,i}) = \int_{\theta} P(X_{t+1,i}; \theta_i) P(\theta_i|x_{1,i}, \dots, x_{t,i}) d\theta$$

- Distribution over $R(i)$ if the mean is a function of parameter θ_i

$$P(\theta_i|x_{1,i}, x_{2,i}, \dots, x_{t,i}) = P(R(i)|x_{1,i}, x_{2,i}, \dots, x_{t,i})$$

- Guide exploration by sampling from the posterior distribution.

Bayesian Bandits

- Bayesian bandits fall under the category of stochastic bandits.
- In the Bayesian setting, we assume a *prior* distribution for the reward distribution and update the *posterior* after each reward realization.
- Use *Bayesian learning* to select action based on the full distribution instead of a bound like in UCB: $P(R(i)|x_{1,i}, \dots, x_{t,i})$.

Simple Case: Bernoulli Bandits

- The likelihood function $P(X_i; \theta_i)$ follows a Bernoulli distribution with mean $R(i) = \theta_i$. $x_i = 1$ with probability θ_i and $x_i = 0$ with probability $1 - \theta_i$.
- Reward of each arm $X_{t,i} \in [0, 1]$.
- The likelihood of observing reward x_i for a Bernoulli(θ) distribution is:

$$P(x_i|\theta) = \theta^{x_i}(1-\theta)^{1-x_i}$$

Conjugate Prior:

- If the *posterior* distribution is in the same probability distribution family as the *prior* distribution, then they are called **conjugate distributions**.
- For Bernoulli likelihood, the *Beta* distribution is its **conjugate prior** since the *posterior* distribution is a Beta distribution.

$$P(\theta_i | x_{1,i}, \dots, x_{t,i}) \propto P(x_{1,i}, \dots, x_{t,i} | \theta_i) * P(\theta_i)$$

The diagram illustrates the components of the conjugate prior formula. Three green arrows point from the labels below to the corresponding terms in the equation above:

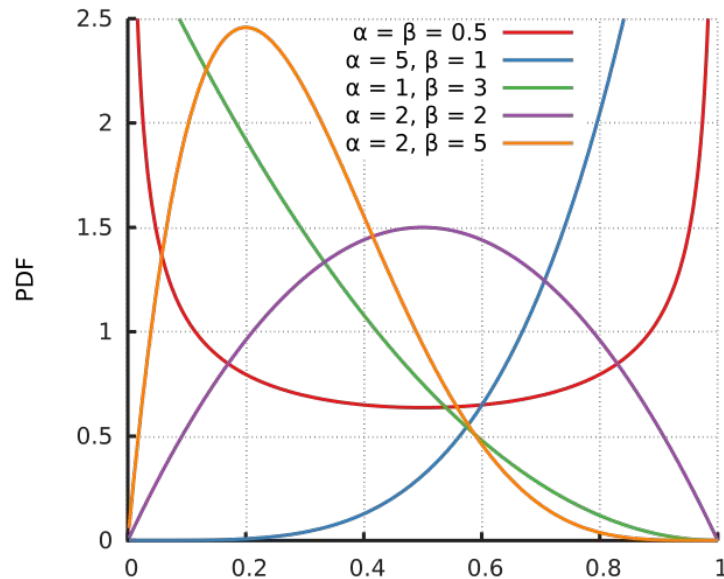
- An arrow points from "Posterior: Beta" to $P(\theta_i | x_{1,i}, \dots, x_{t,i})$.
- An arrow points from "Likelihood: Bernoulli" to $P(x_{1,i}, \dots, x_{t,i} | \theta_i)$.
- An arrow points from "Prior: Beta" to $P(\theta_i)$.

Beta distribution

- $P(\theta_i)$ follows a Beta distribution

$$\text{Beta}(\theta_i; \alpha_i, \beta_i) \sim \theta_i^{\alpha_i-1} (1 - \theta_i)^{\beta_i-1}$$

- $\alpha_i - 1$: # of 1's
- $\beta_i - 1$: # of 0's
- $E[\theta_i] = \alpha_i / (\alpha_i + \beta_i)$



Thompson Sampling

- Given:
 - Set of parameters $\theta = (\theta_1, \dots, \theta_k)$ and prior distribution $P(\theta_i)$
 - A likelihood function $P(X_i|\theta_i)$
 - Some past observations $x_{1,i}, \dots, x_{t,i}$
- Idea:
 - Sample from the current posterior $P(\theta_i|x_{1,i}, \dots, x_{t,i})$ for each arm i
 - Choose a maximizing arm from the sampled rewards
 - Update the posterior distribution of the chosen arm
$$P(\theta_i|x_{1,i}, \dots, x_{t,i}) \propto P(x_{1,i}, \dots, x_{t,i}|\theta_i)P(\theta_i)$$

Thompson Sampling for Bernoulli Bandits

Algorithm 5 Thompson Samplings

```
1: Input: horizon  $n$ , number of arms  $K$ , parameters  $\alpha$  and  $\beta$ ;  
2: for  $t = 1, \dots, n$  do  
3:   for  $i = 1, \dots, K$  do  
4:     Sample  $\hat{\theta}_i \sim \text{Beta}(\alpha_i, \beta_i)$   
5:   end for  
6:    $A_t \leftarrow \arg \max_i \hat{\theta}_i$   
7:   Take action  $A_t$  and observe  $x_{t,A_t}$   
8:    $(\alpha_{x_t}, \beta_{x_t}) \leftarrow (\alpha_{A_t} + x_{t,A_t}, \beta_{A_t} + 1 - x_{t,A_t})$   
9: end for
```

Start with $\alpha, \beta = [1]_1^K$. So the arms are uniformly distributed

Comparison

Greedy Method

- Sample

$$\hat{\theta}_i \leftarrow \alpha_i / (\alpha_i + \beta_i)$$

- Action Selection

$$A_t \leftarrow \arg \max_i \hat{\theta}_i$$

⇒ No exploration, only
consider the best so far

Thompson Sampling

- Sample

$$\hat{\theta}_i' \sim \text{Beta}(\alpha_i, \beta_i)$$

- Action Selection

$$A_t \leftarrow \arg \max_i \hat{\theta}_i'$$

⇒ Some exploration

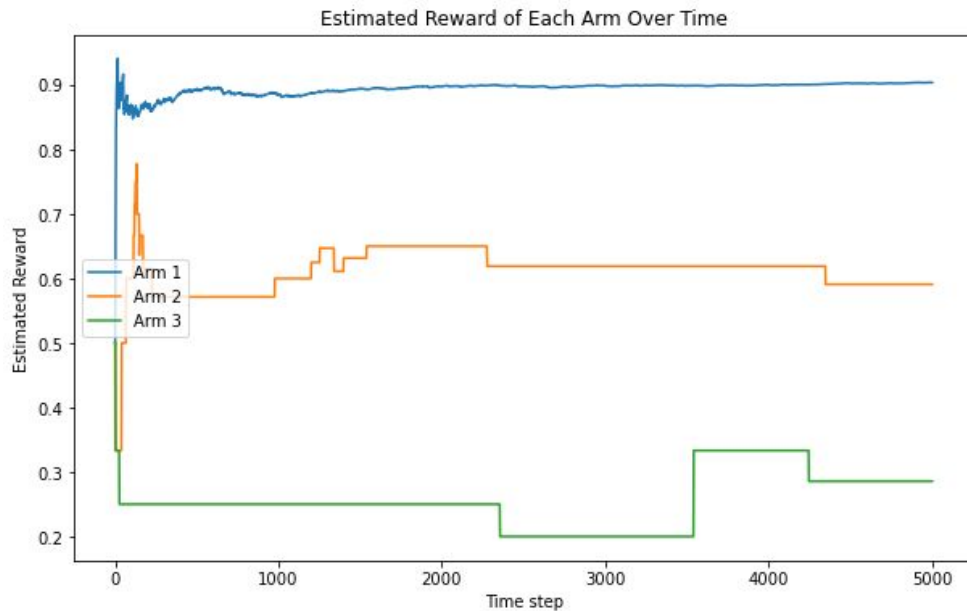
Bernoulli Thompson Sampling

- Posterior distribution update for arm i after observing reward $x_{t,i}$:

$$\begin{aligned} P(\theta_i | x_{t,i}) &\propto P(x_{t,i} | \theta_i) P(\theta_i) \\ &\propto \theta_i^{x_{t,i}} (1 - \theta_i)^{1-x_{t,i}} \theta_i^{\alpha_i-1} (1 - \theta_i)^{\beta_i-1} \\ &= \theta_i^{\alpha_i-1+x_{t,i}} (1 - \theta_i)^{\beta_i-1+1-x_{t,i}} \\ &\propto \text{Beta}(\alpha_i + x_{t,i}, \beta_i + 1 - x_{t,i}) \end{aligned}$$

Simple Example

- 3 armed bandits with Bernoulli reward distribution as follows
[0.9, 0.5, 0.2]



Regret Bound

- For the simple case of Bernoulli bandits established above, the regret of Thompson Sampling when the priors are initialized with a uniform distribution is:

$$\max_{\theta'} \mathbb{E}[\text{Regret}_n | \theta = \theta'] = O\left(\sqrt{Kn \log(n)}\right)$$

Thompson Sampling for Contextual Bandits with
Linear Payoffs

Shipra Agrawal
Microsoft Research

Navin Goyal
Microsoft Research

February 4, 2014

General Thompson Sampling

Algorithm 3 Greedy(\mathcal{X}, p, q, r)

```
1: for  $t = 1, 2, \dots$  do
2:   #estimate model:
3:    $\hat{\theta} \leftarrow \mathbb{E}_p[\theta]$ 
4:
5:   #select and apply action:
6:    $x_t \leftarrow \operatorname{argmax}_{x \in \mathcal{X}} \mathbb{E}_{q_{\hat{\theta}}}[r(y_t) | x_t = x]$ 
7:   Apply  $x_t$  and observe  $y_t$ 
8:
9:   #update distribution:
10:   $p \leftarrow \mathbb{P}_{p,q}(\theta \in \cdot | x_t, y_t)$ 
11: end for
```

Algorithm 4 Thompson(\mathcal{X}, p, q, r)

```
1: for  $t = 1, 2, \dots$  do
2:   #sample model:
3:   Sample  $\hat{\theta} \sim p$ 
4:
5:   #select and apply action:
6:    $x_t \leftarrow \operatorname{argmax}_{x \in \mathcal{X}} \mathbb{E}_{q_{\hat{\theta}}}[r(y_t) | x_t = x]$ 
7:   Apply  $x_t$  and observe  $y_t$ 
8:
9:   #update distribution:
10:   $p \leftarrow \mathbb{P}_{p,q}(\theta \in \cdot | x_t, y_t)$ 
11: end for
```

Next Time

- Gittins Index
- Restless Bandits

Thank you!