

3 Algorithms for Network Resilience

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January 2019

Algorithm 1: ComputeDistance

Input: Graph $g = (V, E)$; source node $i \in V$

Output: $d_j \in \mathbb{R}, \forall j \in V$

```
1 foreach  $j \in V$  do
2    $d_j \leftarrow \infty$ ;
3  $d_i \leftarrow 0$ ;                                     // Start by visiting the source node  $i$ 
4 Initialize  $Q$  to an empty queue;;
5  $enqueue(Q, i)$ ;
6 while  $Q$  is not empty do
7    $j \leftarrow dequeue(Q)$ ;
8   foreach neighbor  $h$  of  $j$  do
9     if  $d_h = \infty$  then
10       $d_h \leftarrow d_j + 1$ ;
11       $enqueue(Q, h)$ ;
12 return  $d$ ;
```

Discussion 1: The algorithm performs $n+m$ operations. The first loop runs n times. The second loop runs for a multiple of m operations. Each edge is traversed exactly twice in this algorithm.

Algorithm 2: IsBipartite

Input: Graph $g = (v, E)$ **Output:** a boolean number

```
1 foreach  $j \in V$  do
2   Initialize  $c$  to an empty mapping;
3    $c_j \leftarrow 0$ ;
4    $c_i \leftarrow 1$ ; // start with any node  $i \in V$ 
5   Initialize  $Q$  to an empty queue;
6   enqueue( $Q, i$ );
7   while  $Q$  is not empty do
8      $j \leftarrow$  dequeue( $Q$ );
9     foreach neighbor  $h$  of  $j$  do
10      if  $c_h = c_j$  then
11        return False;
12      else if  $c_h = 0$  then
13         $c_h = -c_j$ ;
14        enqueue( $Q, h$ )
15 return True
```

Discussion 2: The first loop runs n operations. The second loop checks the neighbors of each node dequeued, and traverses each edge twice, so it is a multiple of m operations.

Algorithm 3: ComputeLargestCCSize

Input: Graph $g = (v, E)$ **Output:** an integer

```
1 Initialize P to an empty queue;
2 Initialize v to an empty mapping;
3 foreach  $j \in V$  do
4    $v_j \leftarrow False$ ;
5    $enqueue(P, j)$ ;
6  $s \leftarrow 0$ ;
7 while  $P$  is not empty do
8    $m \leftarrow dequeue(P)$ ;
9   if  $v_m = False$  then
10     $v_m \leftarrow True$ ;
11     $k \leftarrow 1$ ;
12    Initialize  $Q$  to an empty queue;
13     $enqueue(Q, m)$ ;
14    while  $Q$  is not empty do
15       $j \leftarrow dequeue(Q)$ ;
16      foreach neighbor  $h$  of  $j$  do
17        if  $v_h = False$  then
18           $v_h \leftarrow True$ ;
19           $enqueue(Q, h)$ ;
20           $k \leftarrow k + 1$ ;
21    if  $k > s$  then
22       $s = k$ ;
23 return  $s$ ;
```

Discussion 3: The first loop in the algorithm runs n operations. In the second loop, the algorithm runs BFS first on a node, and again on nodes that are not previously explored. So when all the nodes and edges in the graph are explored, each edge is traversed twice so it is still a multiple of m operations. Therefore, the algorithm runs $m+n$ operations.