

reliability function $r : V \times V \rightarrow [0, 1]$. You need to give an efficient algorithm which will output the reliability of the most reliable path from s to t in G .

For any points $u, v \in V$, $r(u, v)$ is the probability that the communication link (u, v) will not fail: $0 \leq r(u, v) \leq 1$. Note that if there is a path with two edges, for example, from u to v to w , then the reliability of that path is $r(u, v) \cdot r(v, w)$. **[6 points]**

4. exercise 24.1-3 from CLRS

Given a weighted, directed graph $G = (V, E)$ with no negative-weight cycles, let m be the maximum over all vertices $v \in V$ of the minimum number of edges in a shortest path from the source s to v . (Here, the shortest path is by weight, not the number of edges.) Suggest a simple change to the Bellman-Ford algorithm that allows it to terminate in $m + 1$ passes, even if m is not known in advance. **[5 points]**

5. exercise 25.2-4 from CLRS. More specifically, show that $O(n^2)$ space can be achieved **without sacrificing correctness** by dropping the superscripts in the Floyd-Warshall algorithm by computing the distance matrices $\mathcal{D}^{(k)}$ in place using a single matrix \mathcal{D} . **[5 points]**

Total: 30 points

note(s)

- For questions 2 and 3 you need only modify the RELAX method and perhaps change the priority queue of Dijkstra's/Prim's method.