

# Towards Temporal Fusion Beyond the Field of View for Camera-based Semantic Scene Completion

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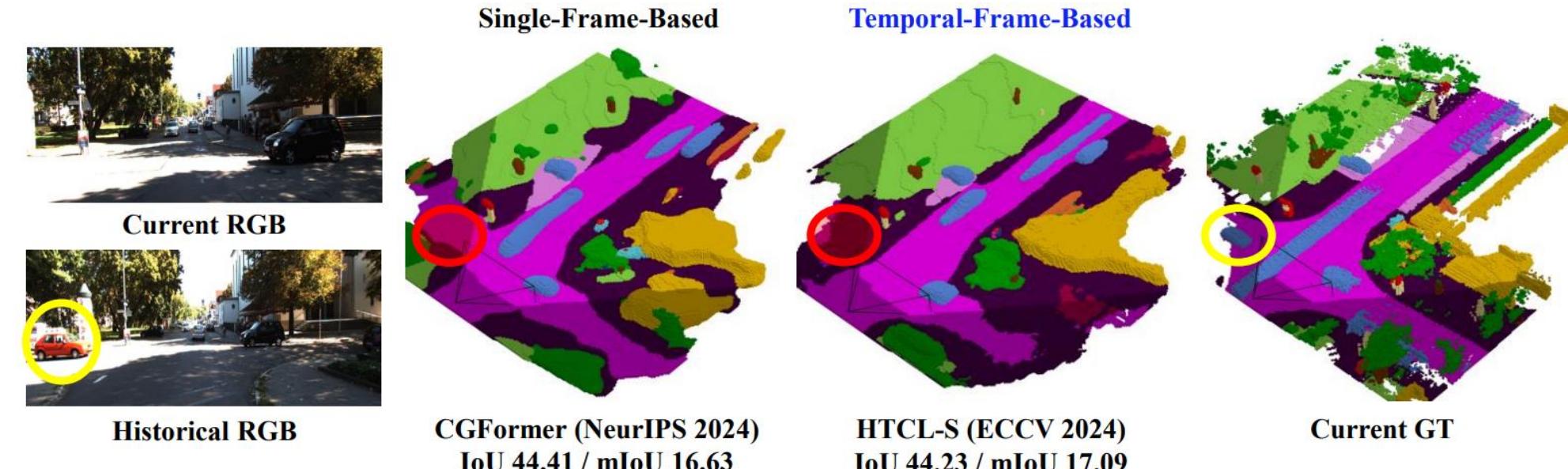
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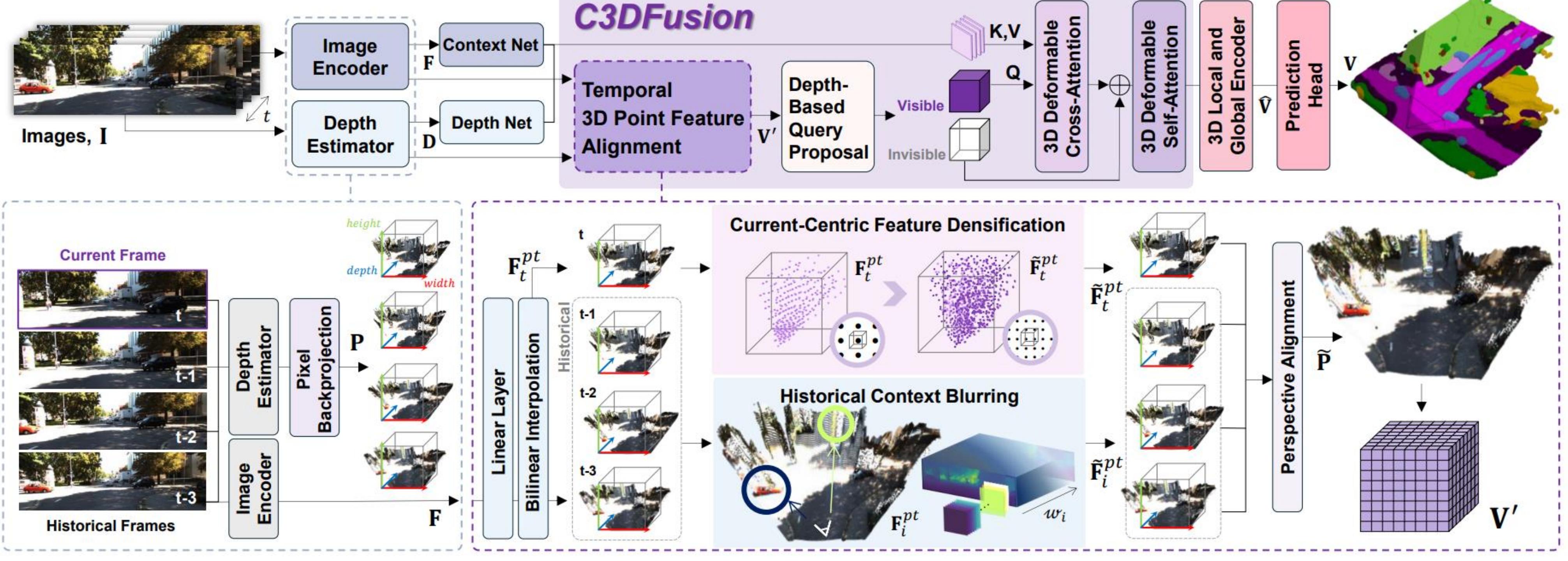
## Motivation



- Temporal fusion is widely used in camera-based 3D SSC, but improvements are mostly limited to **in-camera-view regions**.
- Out-of-camera-view blind spots** (safety-critical near the ego vehicle) remain poorly completed, even though **past frames may contain the missing context**.
- This motivates **out-of-view completion via temporal cues**, by fusing historical and current features in the current frame's 3D metric space.

## Methodology

### ✓ Overview



## Experiments

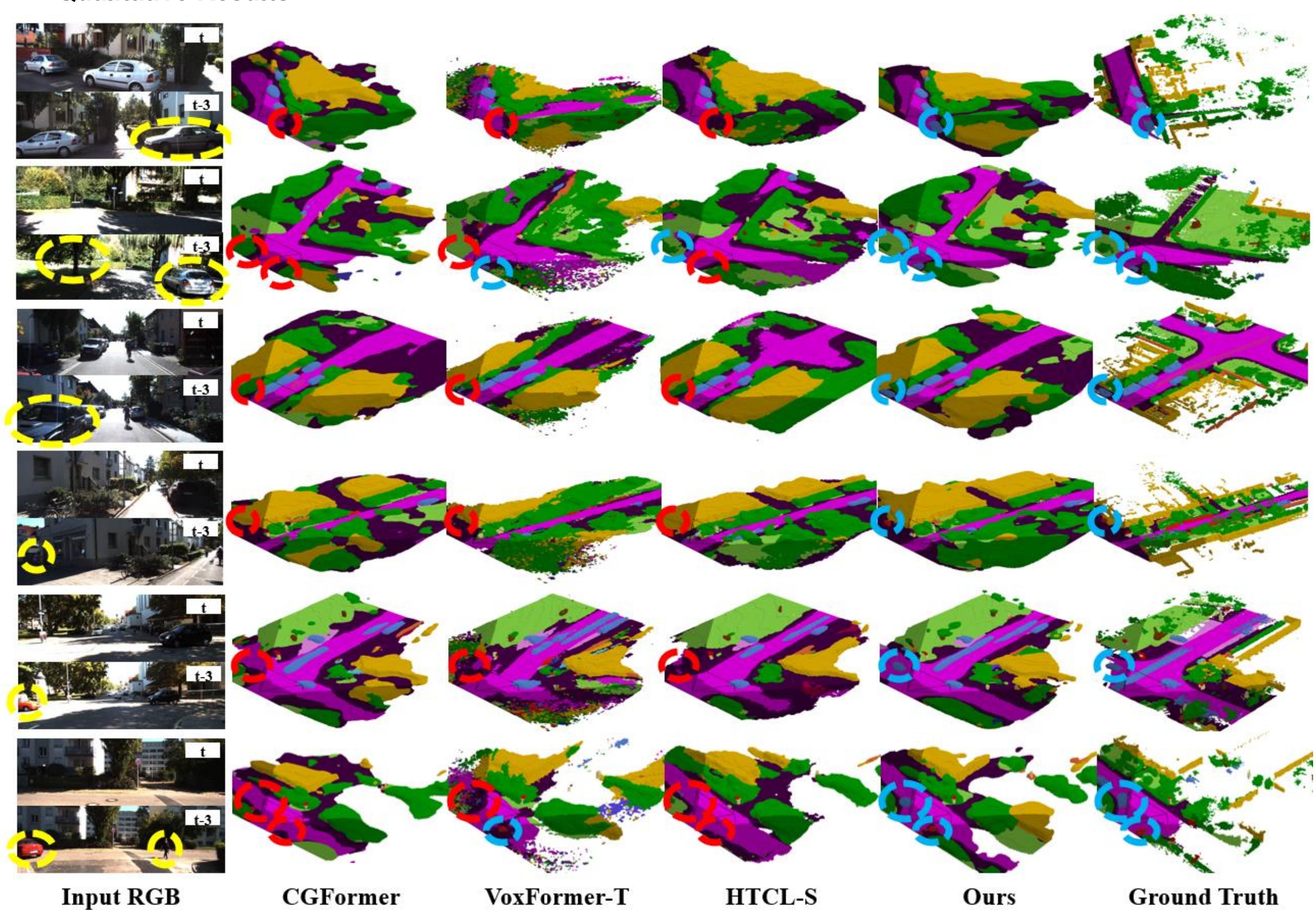
### ✓ Quantitative results on SemanticKITTI hidden test set.

Method	Input	IoU	mIoU	Single-Frame-Based																				OOV (val.) IoU	OOV (val.) mIoU
				road	sidewalk	parking	other-gnd.	building	car	truck	bicycle	motorcycle	other-veh.	vegetation	trunk	terrain	person	bicyclist	motorcyclist	fence	pole	sign			
MonoScene	Mono	34.16	11.08	54.70	27.10	24.80	5.70	14.40	18.80	3.30	0.50	0.70	4.40	14.90	2.40	19.50	1.00	1.40	0.40	11.10	3.30	2.10	31.07	7.02	
TPVFormer	Mono	34.25	11.26	55.10	27.20	27.40	6.50	14.80	19.20	3.70	1.00	0.50	2.30	13.90	2.60	20.40	1.10	2.40	0.30	11.00	2.90	1.50	30.76	7.87	
OccFormer	Mono	34.53	12.32	55.90	30.30	31.50	6.50	15.70	21.60	1.20	1.50	1.70	3.20	16.80	3.90	21.30	2.20	1.10	0.20	11.90	3.80	3.70	30.46	8.68	
Symphonies	Stereo	42.19	15.04	58.40	29.30	26.90	11.70	24.70	23.60	3.20	3.60	2.60	5.60	24.20	10.00	23.10	3.20	1.90	2.00	16.10	7.70	8.00	23.48	6.40	
CGFormer	Stereo	44.41	16.63	64.30	34.20	34.10	12.10	25.80	26.10	4.30	3.70	1.30	2.70	24.50	11.20	29.30	1.70	3.60	0.40	18.70	8.70	9.30	33.54	9.06	
L2COCe-C	Stereo	44.31	17.03	66.00	35.00	33.10	13.50	25.10	27.20	3.00	3.50	3.60	4.30	25.20	11.50	30.10	1.50	2.40	0.20	20.50	9.10	8.90	32.24	8.55	
ScanSSC	Stereo	44.54	17.40	66.20	35.90	35.10	12.50	25.30	27.10	3.50	3.50	3.20	6.10	25.20	11.00	30.60	1.80	5.30	0.70	20.50	8.40	8.90	33.60	9.50	
L2COCe-D	Stereo	45.37	18.18	<b>68.20</b>	<b>36.90</b>	34.60	<b>16.20</b>	25.80	28.30	4.50	4.90	3.30	<b>7.20</b>	26.20	11.90	32.00	2.10	2.40	0.30	21.60	<b>9.60</b>	<b>9.50</b>	31.85	10.05	
<b>Ours</b>	<b>Stereo</b>	<b>47.62</b>	<b>18.98</b>	<b>67.00</b>	<b>36.30</b>	<b>33.20</b>	<b>19.30</b>	<b>30.60</b>	<b>29.00</b>	<b>3.30</b>	<b>5.40</b>	<b>4.40</b>	<b>4.70</b>	<b>29.60</b>	<b>14.70</b>	<b>33.80</b>	<b>1.60</b>	<b>2.80</b>	<b>0.30</b>	<b>22.80</b>	<b>11.40</b>	<b>10.40</b>	<b>44.37</b>	<b>17.17</b>	

### ✓ Quantitative results on SSCBench-KITTI-360 test set.

Method	Input	IoU	mIoU	Single-Frame-Based																				OOV (test) IoU	OOV (test) mIoU
				car	bicycle	motorcycle	truck	other-veh.	person	road	parking	sidewalk	other-gnd.	building	fence	vegetation	terrain	pal	sign	other-struct.					
MonoScene	Mono	37.87	12.31	19.34	0.43	0.58	8.02	2.03	0.86	48.35	11.38	28.13	3.32	32.89	3.53	26.15	16.75	6.92	5.67	4.20	3.09	-	-	-	-
TPVFormer	Mono	40.22	13.64	21.56	1.09	1.37	8.06	2.57	2.38	52.99	11.99	31.07	3.78	34.83	4.80	30.08	17.52	7.46	5.86	2.70	-	-	-	-	-
OccFormer	Mono	40.27	13.81	22.58	0.66	0.26	9.89	3.82	2.77	54.30	13.44	31.53	3.55	36.42	4.80	31.00	19.51	7.77	8.51	6.95	4.60	-	-	-	-
Symphonies	Stereo	44.12	18.58	30.02	1.85	5.90	<b>25.07</b>	<b>12.06</b>	<b>8.20</b>	54.94	13.83	32.76	<b>6.93</b>	35.11	8.58	38.33	11.52	14.01	9.57	<b>14.44</b>	<b>11.28</b>	34.39	11.93	44.72	15.61
CGFormer	Stereo	48.07	20.05	29.85	3.42	3.96	17.59	6.79	6.63	<b>63.85</b>	17.15	40.72	5.53	42.73	8.22	38.80	24.94	16.24	17.45	10.18	6.77	45.09	15.44	-	-
ScanSSC	Stereo	48.29	<b>20.14</b>	29.91	3.78	4.28	14.34	<b>9.08</b>	6.65	62.21	18.16	40.19	5.16	42.68	8.83	<b>38.84</b>	<b>25.50</b>	16.60	<b>19.14</b>	10.30	6.89	45.09	15.44	-	-
<b>Ours</b>	<b>Stereo</b>	<b>49.28</b>	<b>21.74</b>	<b>31.16</b>	<b>5.39</b>	<b>7.01</b>	<b>18.12</b>	8.25	5.66	<b>63.70</b>	<b>19.12</b>	<b>41.64</b>	5.09	<b>43.93</b>	<b>10.43</b>	<b>40.73</b>	<b>27.62</b>	<b>19.30</b>	<b>23.08</b>	<b>12.34</b>	<b>8.74</b>	<b>52.41</b>	<b>23.72</b>	-	-

### ✓ Qualitative Results



## Ablation Studies

### ✓ Ablation study of C3DFusion.

'TPFA', 'HCB', and 'CCFD' denote temporal 3D point feature alignment, historical context blurring, and current-centric feature densification.

	TPFA	HCB	CCFD	IoU	mIoU
Baseline				48.59	16.58
(a)	✓			49.09	18.45
(b)	✓	✓		48.99	18.88
(c)	✓	✓	✓	48.87	18.86
<b>Ours</b>	✓	✓	✓	<b>49.53</b>	<b>19.31</b>

### ✓ Generalization of C3DFusion

across other leading camera-based SSC models.

| Method | IoU |
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| --- | --- |