

SPAN AND LINEAR INDEPENDENCE

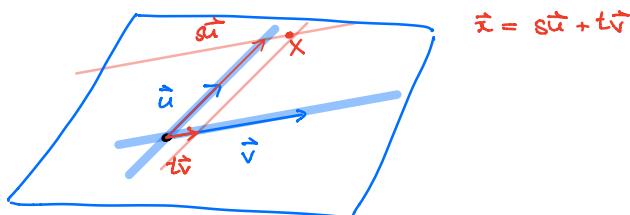
Recall: A vector \vec{v} is a linear combination of vectors $\vec{v}_1, \dots, \vec{v}_k$ in \mathbb{R}^n if there are scalars $c_1, c_2, \dots, c_k \in \mathbb{R}$ so that

$$\vec{v} = c_1\vec{v}_1 + \dots + c_k\vec{v}_k.$$

- The scalars c_1, \dots, c_k are called the coefficients of the linear combination.
- Let \vec{u}, \vec{v} be non-parallel vectors in \mathbb{R}^3 .

We know that the plane through the origin O and with direction vectors \vec{u}, \vec{v} is given by

$$\mathcal{P} = \{ \vec{x} = s\vec{u} + t\vec{v}; s, t \in \mathbb{R} \}$$



On the other hand, $\{ \vec{x} = s\vec{u} + t\vec{v}; s, t \in \mathbb{R} \}$ is just the set of all linear combinations of \vec{u}, \vec{v} .

Definition: If $S = \{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \}$ is a set of vectors in \mathbb{R}^n , then the span of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ is denoted

$$\text{span}(S) \quad \text{or} \quad \text{span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k)$$

and is the set of all linear combinations of $\vec{v}_1, \dots, \vec{v}_k$.

$$\begin{aligned} \text{So } \text{span}(S) &= \text{span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k) \\ &= \left\{ \vec{v} \in \mathbb{R}^n \mid \vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_k \vec{v}_k \right\}, \\ &\quad \text{for some } c_1, \dots, c_k \in \mathbb{R}. \end{aligned}$$

Example: We just saw that $\mathbb{P} = \text{span}(\vec{u}, \vec{v})$.

Definition: If $\text{span}(S) = \mathbb{R}^n$, we say that S is a **spanning set** for \mathbb{R}^n , or that $\vec{v}_1, \dots, \vec{v}_k$ **span** \mathbb{R}^n .

i.e. every vector in \mathbb{R}^n can be written as a linear combination of $\vec{v}_1, \dots, \vec{v}_k$.

Example: The standard vectors $\vec{e}_1, \dots, \vec{e}_n$ span \mathbb{R}^n , because

every $\vec{v} \in \mathbb{R}^n$. $\vec{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$ can be written as

$$\vec{v} = v_1 \vec{e}_1 + \dots + v_n \vec{e}_n.$$

Example Let $S = \{\vec{v}\}$, one non-zero vector.

$$\text{span}(\vec{v}) = \{ \vec{x} \in \mathbb{R}^n \mid \vec{x} = t\vec{v} \text{ for some } t \in \mathbb{R} \}.$$

This is the vector form of the line passing through the origin with direction vector \vec{v} .

Exercise: What if $\vec{v} = \vec{0}$? Then what is $\text{span}(\vec{v})$?

$$\begin{aligned} \text{Solution} \quad \text{span}(\vec{v}) &= \{ \vec{x} \in \mathbb{R}^n \mid \vec{x} = t\vec{v} \text{ for some } t \in \mathbb{R} \} \\ &= \vec{0} \\ &= \{ \vec{0} \}. \end{aligned}$$

Example Let \vec{u}, \vec{v} be two non-zero vectors in \mathbb{R}^n .

Then $\text{span}(\vec{u}, \vec{v}) = \{ \vec{x} \in \mathbb{R}^n \mid \vec{x} = s\vec{u} + t\vec{v}, s, t \in \mathbb{R} \}$.

- We know that if \vec{u}, \vec{v} are not parallel, then

$\text{span}(\vec{u}, \vec{v}) = \text{plane } P \text{ through } O \text{ with direction vectors } \vec{u}, \vec{v}$.

Exercise: What if \vec{u} and \vec{v} are parallel?

Solution: we can write $\vec{v} = c\vec{u}$ for some $c \in \mathbb{R}$.

$$\begin{aligned}\text{then } \text{span}(\vec{u}, \vec{v}) &= \{ \vec{x} \in \mathbb{R}^n \mid \vec{x} = s\vec{u} + t\vec{v}, s, t \in \mathbb{R} \} \\ &= \{ \vec{x} \in \mathbb{R}^n \mid \vec{x} = s\vec{u} + tc\vec{u}, s, t \in \mathbb{R} \} \\ &= (s+tc)\vec{u}\end{aligned}$$

So $\text{span}(\vec{u}, \vec{v}) = \text{span}(\vec{u}) = \{ \text{all scalar multiples} \}$
of \vec{u}

This is the line through O with direction vector \vec{u} .

Remark: It seems like often the span of n vectors gives an n -dimensional space

- 1 \rightarrow line
- 2 \rightarrow plane

but sometimes we get a space that is smaller than this.

Goal: What is the property of the set S that corresponds to this behaviour?

Definition: • A set of vectors $\vec{v}_1, \dots, \vec{v}_k$ is called **linearly independent** if the equation

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_k\vec{v}_k = \vec{0}$$

has exactly one solution, which is

$$c_1 = c_2 = \dots = c_k = 0.$$

i.e. there is no non-trivial linear combination of the \vec{v}_i which gives $\vec{0}$.

- If there is more than one solution, we say the set is **linearly dependent**.

Example: If \vec{u}, \vec{v} are parallel, then they are linearly dependent

proof: suppose $\vec{v} = c\vec{u}$, $c \in \mathbb{R}$

$$\text{Then } c\vec{u} - \vec{v} = \vec{0}.$$

so $\vec{0}$ is a non-trivial linear combination of \vec{u}, \vec{v} .

Equivalently, the equation

$$c_1\vec{u} + c_2\vec{v} = \vec{0}$$

has solution ($c_1 = c$, $c_2 = -1$).

And so $\{\vec{u}, \vec{v}\}$ is linearly dependent.

Example:

Show that if \vec{u}, \vec{v} are not parallel, then they are linearly independent.

Hint: Suppose $c_1\vec{u} + c_2\vec{v} = \vec{0}$.

We want to show that $c_1 = c_2 = 0$.

Solution: Suppose that $c_1 \neq 0$, for example.

Then $\vec{u} = -\frac{c_2}{c_1}\vec{v}$, which would imply

\vec{u} & \vec{v} are parallel.

But we know that they are not parallel, so
we must have $c_1=0$.

Similarly for c_2 . \square

Example: The set $\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$ is linearly independent in \mathbb{R}^3 .

Solution Suppose we have

$$c_1\vec{e}_1 + c_2\vec{e}_2 + c_3\vec{e}_3 = \vec{0}. \quad (*)$$

We need to show that $c_1=c_2=c_3=0$.

$$\text{But } c_1\vec{e}_1 + c_2\vec{e}_2 + c_3\vec{e}_3 = c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

$$(*) : \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow c_1 = c_2 = c_3 = 0,$$

as desired.

Example: Let $\vec{u} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 3 \\ 0 \\ -2 \end{bmatrix}$, $\vec{w} = \begin{bmatrix} 5 \\ 4 \\ 0 \end{bmatrix}$

The set S is linearly dependent because

$$\vec{w} = 2\vec{u} + \vec{v}$$

$$\text{So } 2\vec{u} + \vec{v} + (-1)\vec{w} = \vec{0}.$$

i.e. $c_1=2$, $c_2=1$, $c_3=-1$ give a non-trivial solution

$$\text{to } c_1\vec{u} + c_2\vec{v} + c_3\vec{w} = \vec{0}.$$

Some facts about linear independence

- A set $S = \{\vec{v}\}$ with just one vector is linearly independent

$$\Leftrightarrow \vec{v} \neq \vec{0}.$$

- in this case, it spans a line through the origin.
- A set $S = \{\vec{u}, \vec{v}\}$ of two vectors is linearly independent
 $\Leftrightarrow \vec{u}$ & \vec{v} are not parallel.
- in this case, it spans a plane through the origin.
- Let $S = \{\vec{u}, \vec{v}, \vec{w}\}$, with $\vec{u}, \vec{v}, \vec{w} \in \mathbb{R}^3$.
 - S spans $\mathbb{R}^3 \Leftrightarrow \vec{u}, \vec{v}, \vec{w}$ are linearly independent.
- More generally, if $S = \{\vec{v}_1, \dots, \vec{v}_n\}$, a set of n vectors in \mathbb{R}^n .
 - then S spans $\mathbb{R}^n \Leftrightarrow S$ is linearly independent.

Summary of the lecture:

- Let $S = \{\vec{v}_1, \dots, \vec{v}_k\}$ be a set of vectors in \mathbb{R}^n .
 - The **span** of S is the set of all linear combinations of the vectors $\vec{v}_1, \dots, \vec{v}_k$.
 - S is **linearly independent** if

$$c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0} \Rightarrow c_1 = c_2 = \dots = c_k = 0.$$
 - otherwise, S is **linearly dependent**.

You should be able to:

- use and define these terms
- determine when a set of one or two vectors is linearly independent & write down its span.