Name & UI#: _____

- This is a closed-book, closed-notes exam. No electronic aids are allowed.

- Read each question carefully. Unless otherwise stated you need to justify your answer. *Do not use results not proven in class.*

- Answer the questions in the spaces provided on the question sheets. If you need extra room, use the back sides of each page. If you must use extra paper, make sure to write your name on it and attach it to this exam.

- Do not unstaple or detach pages from this exam.

Question	Points	Score
1	15	
2	25	
3	5	
4	10	
5	10	
6	15	
7	10	
8	10	
Total:	100	

1. Consider the matrix $A = \begin{bmatrix} 1 & 4 & 7 & 8 \\ 2 & 0 & 6 & 2 \\ 0 & 1 & 1 & 2 \end{bmatrix}$.

(a) (8 points) Find a basis for $\text{im}(A)$, the image of A.

$$\text{im}(A) = \text{span}\left(\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 7 \\ 6 \\ 1 \end{bmatrix}, \begin{bmatrix} 8 \\ 2 \\ 2 \end{bmatrix} \right) = \text{span}\left(\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 8 \\ 2 \\ 2 \end{bmatrix} \right)$$

$\checkmark$ $\checkmark$ $\times$ $\checkmark$ $\qquad\qquad$ basis

$$V_3 = 3V_1 + V_2$$

(b) (7 points) Find a basis for $\ker(A)$, the kernel of A.

$$-3V_1 - V_2 + V_3 + 0 V_4 = 0 \implies$$

$$\ker(A) = \text{span}\left(\begin{bmatrix} -3 \\ -1 \\ 1 \\ 0 \end{bmatrix} \right)$$

basis.

2. Consider $T : \mathcal{P}_2 \longrightarrow \mathcal{P}_2$ defined by $T(p(x)) = (1+x)p'(x) + p''(x) + 2p(x)$.

   (a) (5 points) Show that T is a linear transformation.

$$T(p(x)+q(x)) = (1+x)(p(x)+q(x))' + (p(x)+q(x))'' + 2(p(x)+q(x))$$

$$= (1+x)p'(x) + (1+x)q'(x) + p''(x) + q''(x) + 2p(x) + 2q(x)$$

$$= T(p(x)) + T(q(x))$$

$$T(\alpha p(x)) = (1+x)(\alpha p(x))' + (\alpha p(x))'' + 2(\alpha p(x))$$

$$= \alpha(1+x)p'(x) + \alpha p''(x) + 2\alpha p(x) = \alpha T(p(x)).$$

   (b) (6 points) Find the matrix A of T relative to standard basis $\mathfrak{A} = (1, x, x^2)$. Is T an isomorphism?

$$T(1) = 2 \quad\Rightarrow\quad [T(1)]_{\mathfrak{A}} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$$

$$T(x) = (1+x)\cdot 1 + 0 + 2x = 1+3x \quad\Rightarrow\quad [T(x)]_{\mathfrak{A}} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$$

$$T(x^2) = (1+x)(2x) + 2 + 2x^2 = 2 + 2x + 4x^2 \quad\Longrightarrow\quad [T(x^2)]_{\mathfrak{A}} = \begin{bmatrix} 2 \\ 2 \\ 4 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 1 & 2 \\ 0 & 3 & 2 \\ 0 & 0 & 4 \end{bmatrix}$$

(c) (5 points) Find the matrix B of T relative to the basis $\mathcal{B} = (1, 1+x, 2+2x+x^2)$.

$$T(1) = 2 \implies \left[T(1)\right]_{\mathcal{B}} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$$

$$T(1+x) = (1+x)\cdot 1 + 0 + 2 + 2x = 3+3x \implies \left[T(1+x)\right]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix}$$

$$T(2+2x+x^2) = \cdots = 8+8x+4x^2$$

$$\implies \left[T(2+2x+x^2)\right]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix}$$

$$\implies B = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}.$$

(d) (4 points) What is the change of basis matrix S from $\mathcal{B}$ to $\mathcal{A}$?

$$S = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

(e) (5 points) Find a formula for A^k for any positive integer k.
(Don't leave the answer as a product of matrices.)

$$AS = SB, \quad \text{or} \quad A = SBS^{-1} \implies A^k = SB^kS^{-1}.$$

$$A^k = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2^k & 0 & 0 \\ 0 & 3^k & 0 \\ 0 & 0 & 4^k \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2^k & 3^k-2^k & 2\times4^k-2\times3^k \\ 0 & 3^k & 2\times4^k-2\times3^k \\ 0 & 0 & 4^k \end{bmatrix}$$

$$\nearrow$$
$$S^{-1}$$

3. (5 points) Let $U^{2\times2}$ denote the vector space of upper triangular 2×2 matrices. Find all values of a so that

$$\mathcal{B} = \left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 2a \\ 0 & a^2 \end{bmatrix} \right)$$

is a basis for $U^{2\times2}$.

(There are several methods).

Recall that $\left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right)$ is standard basis for $U^{2\times2}$.

If we list the vector in $\mathcal{B}$ relative to $\mathcal{A}$;

$$\underbrace{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}}_{v_1}, \underbrace{\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}}_{v_2}, \underbrace{\begin{bmatrix} 1 \\ 2a \\ a^2 \end{bmatrix}}_{v_3};$$

question becomes whether v_1, v_2, v_3

Is a basis for $\mathbb{R}^3$; equivalently when $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2a \\ 0 & 1 & a^2 \end{bmatrix}$ is invertible.

Answer: $a \neq 1$

4. (10 points) Let P be the plane in $\mathbb{R}^3$ given by $x + 2y - 3z = 0$. Consider the linear transformation

$$T : \mathbb{R}^3 \longrightarrow \mathbb{R}^3 \text{ given by } T(\vec{x}) = \text{proj}_P(\vec{x}),$$

the projection onto P. Construct a basis $\mathfrak{B} = (\vec{v}_1, \vec{v}_2, \vec{v}_3)$ for $\mathbb{R}^3$ such that the matrix B of T relative to $\mathfrak{B}$ is a diagonal matrix. (You need to write the matrix B too).

(Hint: form a basis with the vectors on P and perpendicular to P.)

Following hint let us pick v_1, v_2 from P; v_3 ≠ perpendicular to P.

$$v_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$$

Clearly $B = (v_1, v_2, v_3)$ is a basis &

$$T(v_1) = \text{proj}_P(v_1) = v_1$$

$$\Rightarrow [T(v_1)]_{\mathfrak{B}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$T(v_2) = \text{proj}_P(v_2) = v_2$$

$$\Rightarrow [T(v_2)]_{\mathfrak{B}} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$T(v_3) = \text{proj}_P(v_3) = \vec{0}$$

$$\Rightarrow [T(v_3)]_{\mathfrak{B}} = 0. \quad \text{Thus,}$$

$$B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

5. (a) (3 points) Let A be $n \times k$, B be $k \times m$ matrices. Show that $\ker(B) \subseteq \ker(AB)$.

Let $\vec{x}$ be in $\ker(B)$, that is, $B\vec{x} = \vec{0}$. If we multiply this expression by A,

$$AB\vec{x} = A\vec{0} = \vec{0} \implies \vec{x} \text{ is in } \ker(AB).$$

(b) (7 points) Let A be 5×3, B be 3×5 matrices. Prove that AB cannot be invertible.

$\ker(B) \subseteq \ker(AB) \implies$ nullity $(B) \leq$ nullity (AB).

Since B has 3-rows, rank$(B) \leq 3$.

By Fund. Thm. of Lin. Alg. rank(B) + nullity$(B) = 5$

$\implies$ nullity $(B) \geq 2$.

This means that nullity $(AB) \geq 2$.

$\implies$ AB cannot be invertible.

6. Let V be the subspace of $\mathbb{R}^4$ spanned by the vectors $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$ and $\vec{v}_2 = \begin{bmatrix} 4 \\ 2 \\ -2 \\ 4 \end{bmatrix}$.

(a) (10 points) Find an orthonormal basis for V.

$$\|v_1\| = \sqrt{1+1+1+1} = 2 \implies u_1 = \frac{1}{\|v_1\|} v_1 = \begin{bmatrix} 1/2 \\ 1/2 \\ -1/2 \\ -1/2 \end{bmatrix}.$$

$$v_2^{\perp} = v_2 - \underbrace{(v_2 \cdot u_1)}_{2} u_1 = \begin{bmatrix} 4 \\ 2 \\ -2 \\ 4 \end{bmatrix} - (2)\begin{bmatrix} 1/2 \\ 1/2 \\ -1/2 \\ -1/2 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 5 \end{bmatrix}$$

$$v_2^{\perp} = \sqrt{9+1+1+25} = 6 \implies u_2 = \frac{1}{\|v_2^{\perp}\|} v_2^{\perp} = \begin{bmatrix} 1/2 \\ 1/6 \\ -1/6 \\ 5/6 \end{bmatrix}.$$

$(\vec{u}_1, \vec{u}_2)$ is orthonormal basis for V.

(b) (5 points) Find the projection of $\vec{x} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ on V.

$$\text{proj}_V(\vec{x}) = \underbrace{(\vec{x} \cdot u_1)}_{-2} u_1 + \underbrace{(\vec{x} \cdot u_2)}_{11/3} u_2$$

$$= \begin{bmatrix} -1 \\ -1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 11/6 \\ 11/18 \\ -11/18 \\ 55/18 \end{bmatrix} = \begin{bmatrix} 5/6 \\ -7/18 \\ 7/18 \\ 73/18 \end{bmatrix}$$

7. (10 points) Find the QR-factorization of the matrix $M = \begin{bmatrix} 1 & 4 & -3 \\ 1 & 2 & 1 \\ -1 & -2 & -3 \\ -1 & 4 & 1 \end{bmatrix}$.

$\underset{v_1}{\underbrace{}} \quad \underset{v_2}{\underbrace{}} \quad \underset{v_3}{\underbrace{}}$

$\|v_1\| = 2, \quad \& \quad u_1 = \frac{1}{\|v_1\|} v_1 = \begin{bmatrix} 1/2 \\ 1/2 \\ -1/2 \\ -1/2 \end{bmatrix} \quad \&$

$v_2^\perp = v_3 - \underset{2}{\underbrace{(v_2 \cdot u_1)}} u_1 = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 5 \end{bmatrix} ; \quad \|v_2^\perp\| = 6 ; \quad u_2 = \begin{bmatrix} 1/2 \\ 1/6 \\ -1/6 \\ 5/6 \end{bmatrix}$

from the previous problem. Now:

$v_3^\perp = v_3 - \underset{=0}{\underbrace{(v_3 \cdot u_1)}} u_1 - \underset{=0}{\underbrace{(v_3 \cdot u_2)}} u_2 = \begin{bmatrix} -3 \\ 1 \\ -3 \\ 1 \end{bmatrix} ; \quad \|v_3^\perp\| = \sqrt{20} = 2\sqrt{5}$

$\Rightarrow \quad u_3 = \frac{1}{\|v_3^\perp\|} v_3^\perp = \begin{bmatrix} -3/2\sqrt{5} \\ 1/2\sqrt{5} \\ -3/2\sqrt{5} \\ 1/2\sqrt{5} \end{bmatrix} . \quad \text{Thus:}$

$Q = \begin{bmatrix} 1/2 & 1/2 & -3/2\sqrt{5} \\ 1/2 & 1/6 & 1/2\sqrt{5} \\ -1/2 & -1/6 & -3/2\sqrt{5} \\ -1/2 & 5/6 & -1/2\sqrt{5} \end{bmatrix} \quad R = \begin{bmatrix} \|v_1\| & u_1 \cdot v_2 & u_1 \cdot v_3 \\ 0 & \|v_2^\perp\| & u_2 \cdot v_3 \\ 0 & 0 & \|v_3^\perp\| \end{bmatrix} = \begin{bmatrix} 2 & 2 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 2\sqrt{5} \end{bmatrix}$

8. Select one (you don't need to justify your answer).

   (a) (2 points) We fix a vector $\vec{v}$ in $\mathbb{R}^4$. Let V be the set of all 4×4 matrices A such that $A\vec{v} = \vec{0}$. Then V is a subspace of $\mathbb{R}^{4\times4}$.

   (a) True $\rightarrow$ $O\vec{v} = 0$ $\Rightarrow$ O is in V.
   (b) False $\rightarrow$ if A, B are in V then $(A+B)\vec{v} = A\vec{v} + B\vec{v} = \vec{0}$
                $\rightarrow$ similarly $A \in V$ then $\alpha A \in V$. $\Rightarrow$ $A+B$ is in V.

   (b) (2 points) If A is a 3×7 matrix then

   (a) rank(A) must be greater than 3.
   (b) nullity(A) must be 4 or more.
   (c) ker(A) can be 2 dimensional.

   Since A has 3 rows $\text{rank}(A) \le 3$.

   $\text{rank}(A) + \text{nullity}(A) = 7$.

   (c) (2 points) There is a linear isomorphism from $\mathcal{P}_3$ to $U^{2\times2}$.

   (a) True
   (b) False

   $\nearrow$ $\searrow$ 3-dim.

   4-dim.

   (d) (2 points) Let $\vec{v}_1$ and $\vec{v}_2$ be vectors in $\mathbb{R}^n$ such that $\|\vec{v}_1\| = 2$, $\|\vec{v}_2\| = 3$, $\|\vec{v}_1+\vec{v}_2\| = 4$. Then $\cos(\theta)$, the cosine of the angle between $\vec{v}_1$ and $\vec{v}_2$, is

   (a) $\frac{1}{3}$ (b) $\frac{1}{4}$ (c) $\frac{1}{5}$ (d) $\frac{1}{6}$ $V_1 \cdot V_2 = \|V_1\| \cdot \|V_2\| \cos\theta$

   $16 = \|v_1+v_2\|^2 = (v_1+v_2)\cdot(v_1+v_2) = v_1\cdot v_2 + 2v_1\cdot v_2 + v_2\cdot v_2 = 4 + 2\,v_1\cdot v_2 + 9 \Rightarrow v_1\cdot v_2 = \frac{3}{2}$.

   (e) (2 points) Let $C[0,1]$ be the vector space of all continuous functions defined from interval $[0,1]$ to $\mathbb{R}$. Consider $T : C[0,1] \to C[0,1]$ given by

   $$T(f(x)) = f(x) - \int_0^1 f(x)dx.$$

   (a) T is not a linear transformation, so not an isomorphism.
   (b) T is a linear transformation but not 1-to-1 ($\ker(T)\neq\{0\}$), so not an isomorphism.
   (c) T is an isomorphism.

   $\therefore T(1) = 1 - \int_0^1 1\,dx = 1 - 1 = 0.$

9. (10 points) (Bonus problem!) Let $\vec{v}_1, \vec{v}_2, ..., \vec{v}_m$ be vectors in $\mathbb{R}^n$. Prove that

$$\|\vec{v}_1 + \vec{v}_2 + \cdots + \vec{v}_m\| \leq \|\vec{v}_1\| + \|\vec{v}_2\| + \cdots + \|\vec{v}_m\|.$$

State any theorem & inequality you use.

1st method: We will use triangle inequality successively:

$$\|v_1 + \underbrace{v_2 + v_3 + \cdots + v_m}_{w}\| \leq \|v_1\| + \|v_2 + v_3 + \cdots + v_m\|$$

$$\leq \|v_1\| + \|v_2\| + \|v_3\| + \cdots + v_m\| \leq \cdots \leq \|v_1\| + \|v_2\| + \cdots + \|v_m\|.$$

2nd method:

Cauchy-Schwarz

$$|v \cdot w| \leq \|v\| \cdot \|w\| \qquad \left(\Rightarrow \quad v \cdot w \leq \|v\| \|w\| \right).$$

$$\|v_1 + v_2 + \cdots + v_m\|^2 = (v_1 + v_2 + \cdots + v_m) \cdot (v_1 + \cdots + v_m)$$

$$= \sum_{i,j=1}^{n} v_i \cdot v_j \leq \sum_{i,j=1}^{n} \|v_i\| \|v_j\|$$

$$= \left(\|v_1\| + \cdots + \|v_m\| \right) \cdot \left(\|v_1\| + \cdots + \|v_m\| \right).$$

So the result follows.