# **Global Dataflow Optimizations**

Overview of some fundamental machine-independent optimizations

### **Sparse Conditional Constant Propagation: SCCP**

Sumultaneously find constant-valued expressions and eliminate infeasible branches

## **Loop Invariant Code Motion: LICM**

Hoist loop-invariant computations out of one or more loops.

## **Global Common Subexpression Elimination: GCSE**

Identify redundant evaluations of expressions across an entire procedure (i.e., in the presence of control-flow).

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.1/21

CS 426 Topic 11: Global Optimization

# **SCCP: Key Algorithm Strengths**

## **Conditional Constant Propagation**

Simultaneously finds constants + eliminates infeasible branches.

#### Optimistic

Assume every variable may be constant  $(\top)$ , until proven otherwise. Pessimistic  $\equiv$  initially assume nothing is constant  $(\bot)$ .

### Sparse

Only propagates variable values where they are actually used or defined (using *def-use chains* in SSA form).

#### SSA vs. def-use chains

Much faster: SSA graph has fewer edges than def-use graph Paper claims SSA catches more constants (not convincing)

# **Sparse Conditional Constant Propagation: SCCP**

#### Goals

- Identify and replace SSA variables with constant values
- Delete infeasible branches due to discovered constants

## Safety

Analysis: Explicit propagation of constant expressions

Transformation: Most languages allow removal of computations

### Profitability

Fewer computations, almost always (except pathological cases)

### Opportunity

Symbolic constants, conditionally compiled code, simple ICG, ...

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.2/21

CS 426 Topic 11: Global Optimization

# **SCCP Examples**

For Ex. 1, we could do constant propagation and condition evaluation separately, and repeat until no changes. This separate approach is not sufficient for Ex. 3.

### Example 1: Needs Condition Evaluation (can be done separately)

#### Example 2: Needs "Optimistic" initial assumption

# **SCCP Examples**

## Example 3: Needs simultaneous condition evaluation + constant propagation

```
I = 1:
. . .
while (...) {
    J = I;
   I = f(...);
    if (J > 0) I = J;
                      // Always produces 1
}
```

Repeatedly doing constant propagation and condition evaluation separately will not prove *I* or *J* constant.

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.5/21

CS 426 Topic 11: Global Optimization

## **SCCP Overview**

#### Assume:

- Only assignment or branch statements
- Every non- $\phi$  statement is in separate BB

### **Key Ideas**

- 1. Constant propagation lattice =  $\{ \top, C_i, \bot \}$
- 2. Initially: every def. has value ⊤ ("may be constant"). *Initially*: every CFG edge is infeasible, except edges from s
- 3. Use 2 worklists: FlowWL, SSAWL
- 4. Highlights:
  - Visit S only if some incoming edge is executable
  - Ignore  $\phi$  argument if incoming CFG edge not executable
  - If variable changes value, add SSA out-edges to SSAWL
  - If CFG edge executable, add to FlowWL

# **CONST Lattice and Example**

#### Lattice L

Lattice  $L \equiv \{\top, C_i, \bot\}$ . ⊤ intuitively means "May be constant."

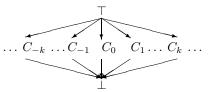
⊥ intuitively means "Not constant."

# Meet Operator, □

 $\top \sqcap X = X, \ \forall X \in L$  $\bot \sqcap X = \bot, \forall X \in L$  $C_i \sqcap C_j = \begin{cases} C_i, & \textit{iff } i = j, \\ \bot, & \textit{otherwise} \end{cases}$ 

### Intuition: A Partial Order $\prec$

 $\perp \prec C_i$  for any  $C_i$ .  $C_i \prec \top$  for any  $C_i$ .  $C_i \not\prec C_i$  (i.e., no ordering).



Meet of X and Y  $(X \sqcap Y)$  is the greatest value  $\prec$  both X and Y.

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.6/21

CS 426 Topic 11: Global Optimization

# **High-Level SCCP Algorithm (1 of 2)**

### SCCP()

```
Initialize(ExecFlags[], LatCell[], FlowWL, SSAWL);
while ((Edge E = GetEdge(FlowWL ∪ SSAWL)) != 0)
    if (E is a flow edge && ExecFlag[E] == false)
        ExecFlag[E] = true
        VisitPhi(\phi) \ \forall \ \phi \in E->sink
        if (first visit to E->sink via flow edges)
             VisitInst(E->sink)
        if (E->sink has only one outgoing flow edge E_{out})
             add \mathbf{E}_{out} to FlowWL
    else if (E is an SSA edge)
        if (E->sink is a \phi node)
             VisitPhi(E->sink)
        else if (E->sink has 1 or more executable in-edges
             VisitInst(E->sink)
```

# **High-Level SCCP Algorithm (2 of 2)**

## VisitPhi( $\phi$ ) :

```
for (all operands U_k of \phi)
    if (ExecFlag[InEdge(k)] == true)
         LatCell(\phi) \sqcap = LatCell(U_k)
         if (LatCell(\phi) changed)
              add SSAOutEdges(\phi) to SSAWL
```

### VisitInst(S):

Many errors in Muchnick

```
val = Evaluate(S)
if (S \text{ is Assignment})
    LatCell(S) = val
    if (LatCell(S) changed)
        add SSAOutEdges(S) to SSAWL
else //S must be a Branch
    Add one or both outgoing edges to FlowWL
```

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.9/21

Topic 11: Global Optimization - p.11/21

CS 426 Topic 11: Global Optimization

# **SCCP Example**

# Some Steps of SCCP Algorithm

Edge	Call	LatVal	Edges Inserted
(1) $S \rightarrow B0$	$VisitInst(I_0)$	$I_0 = 1$	$I_0  ightarrow  ext{if, } I_0  ightarrow I_1, \ B0  ightarrow B1$
(2) $I_0  ightarrow { m if}$	VisitInst(if)	_	$B1 \rightarrow B2, \ B1 \rightarrow B8$
(3) $I_0 \to I_1$	$VisitPhi(I_1)$	$I_1 = 1 \sqcap \top = 1$	$I_1  o J_0$
(4) $I_1 \to J_0$	$VisitInst(J_0)$	$J_0 = 1$	$J_0  o if(\ldots)$
(5) $J_0 \rightarrow if(\ldots)$	VisitInst(if)	_	$B4  ightarrow B5 \;  ext{(not}  B4  ightarrow B6  ext{)}$
(6) $B4 \rightarrow B5$	VisitInst( $I_3$ )	$I_3 = 1$	$I_3 \rightarrow I_4, \ B5 \rightarrow B6$
$(7)  I_3 \to I_4$	VisitInst( $I_4$ )	$I_4 = \top \sqcap 1 = 1$	$I_4  o I_1$
(8) $I_4 \rightarrow I_1$	$VisitInst(I_1)$	$I_1 = 1 \sqcap 1 = 1$	$-$ ( $I_1$ unchanged)

# **SCCP Example**

## Example 3: Needs simultaneous condition evaluation + constant propagation

```
S:
            // entry BB is empty
B0:
            I_0 = 1
            if (I_0 < N_0)
B1:
B2:
                    I_1 = \phi(I_0, I_4)
                    J_0 = I_1
                    I_2 = f(...)
B3:
                    if (J_0 > 0)
B4:
                            \{I_3 = J_0\}
B5:
                    I_4 = \phi(I_2, I_3)
B6:
                    if (I_4 < N_0)
B7:
                            goto B1
B8:
```

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.10/21

CS 426 Topic 11: Global Optimization

# **Loop-invariant Code Motion: LICM (1 of 2)**

// enclosed in natural loop L S: X = A + B;

### Goals

For as many such statements S as possible:

- Move evaluation of *rvalue* (A + B) out of L, if legal
- Move def of *Ivalue* (X) out of L, if legal

### Safety

Analysis: Find reaching defs of each variable in RHS and check if they are all outside the loop, or only one def reaches the variable and it is loop-invariant

Transformation: Next slide

# **Loop-invariant Code Motion: LICM (2 of 2)**

## **Profitability**

- Fewer computations (often, <u>much</u> fewer)
- Adds some copy instructions ⇒ cheaper than any operation
- May stretch some live ranges

## Opportunity

- Array indexing expressions
- Structure indexing expressions
- Effect of previous tranformations (e.g., SCCP, DCE)
- Reordering program subexpressions by loop-level

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.13/21

CS 426 Topic 11: Global Optimization

# **Examples Illustrating Code Motion Rules**

#### Example 1: Invariant def overwritten by later def

### Example 2: Def does not dominate exit

```
for (i=0; i < N; ++i) {
    if (...)
        X = a * b; // hoist a*b but not def of X }</pre>
```

#### Example 3: Multiple defs reach a use

# **Checking Legality of Code Motion**

## Moving expression evaluation out of L:

(E1) Strict: S must dominate all exit nodes from loop L (E1') Relaxed: S must dominate all exit nodes from loop L or X + Y must not cause any exceptions

### Moving def of X out of L:

- (D1) S must dominate all exit nodes from L except exit nodes where X is dead
- (D2) No other statement in the loop must store to X
- (D3) No use of X in L must be reached by any other def of X.

Note: SSA simplifies these conditions!

(D1) S must dominate all exit nodes from L except exit nodes where X is dead

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.14/21

CS 426 Topic 11: Global Optimization

# Algorithm for Loop-Invariant Code Motion (1 of 2)

#### Inputs

Procedure in 3-address form Natural loop L, with preheader block P Def-use and Use-def chains for the procedure

### LICM()

```
repeat (until no new statements are marked)
for (each statement S: X = expr in L)

IsInvariant = true;
for (all operands u \in S)

if (any defs reaching u are within L)

if (more than one def reaches u

|| (the single def d reaching u is

not constant and not invariant))

{ IsInvariant = false; break }

if (IsInvariant) \# expr is loop-invariant

Mark s invariant
```

# Algorithm for Loop-Invariant Code Motion (2 of 2)

```
for (each statement S: X = expr in L) do
   if (S is marked invariant)
      if (BB containing S dominates all loop exits
               | expr causes no exceptions)
         insert tmp = expr just before loop L
      if (conditions (D1)...(D3) are satisfied) {
         insert X = tmp just before loop L;
         delete S
      } else
         replace S with X = tmp
```

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.17/21

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.18/21

CS 426 Topic 11: Global Optimization

# Global Common Subexpression Elimination (1 of 2)

### **Profitability**

- same or fewer evaluations on every path
- add some copy instructions
  - ⇒ many copies coalesce away during allocation
- major cost: can stretch live ranges
  - ⇒ may need forward substitution to undo some CSE results

### Opportunity

- 1. Array indexing expressions
- 2. Structure indexing expressions
- Clean user-written code

incoming paths

Transformation:

CS 426 Topic 11: Global Optimization

# **Algorithm for GCSE**

### Inputs

Goal

Safety

- (1) 3-address code + CFG for a procedure
- (2) Numbered set of expressions  $\mathcal{U} = \{e_1, \dots e_N\}$ Use lexically identical expressions; apply reassociation first

Global Common Subexpression Elimination (1 of 2)

Analysis: AVAIL proves that the value is current

don't add evaluations to any path

Introduce new temporary for each CSE discovered

Eliminate redundant evaluation of an expression if it is available on all

(3) Available expressions,  $AVAIL_{in}(B)$ , for each block B

#### GCSE()

```
EverRedundant[i] = false, \forall 1 < i < N;
for each block B
    for each statement S: X = Y op Z in B
         if (e_i = "Y \ op \ Z" \in AVAIL_{in}(B))
               and e_i is not killed before S in B)
             EverRedundant[j] = true
             Create new temporary tmp_i
             Replace S with X = tmp_i }
```

# Algorithm for GCSE

```
for each block B for each original statement T: X = Y op Z in B if (EverRedundant[k]) // where e_k = \text{``}Y op Z'' { replace T with the pair: tmp_j = Y \text{ op } Z W = tmp_j }
```

University of Illinois at Urbana-Champaign

Topic 11: Global Optimization - p.21/21