

## Lecture 5

### Partial Redundancy Elimination

- I Forms of redundancy
  - global common subexpression elimination
  - loop invariant code motion
  - partial redundancy
- II Lazy Code Motion Algorithm
  - Mathematical concept: a cut set
  - Basic technique (anticipation)
  - 3 more passes to refine algorithm

Reading: Chapter 9.5

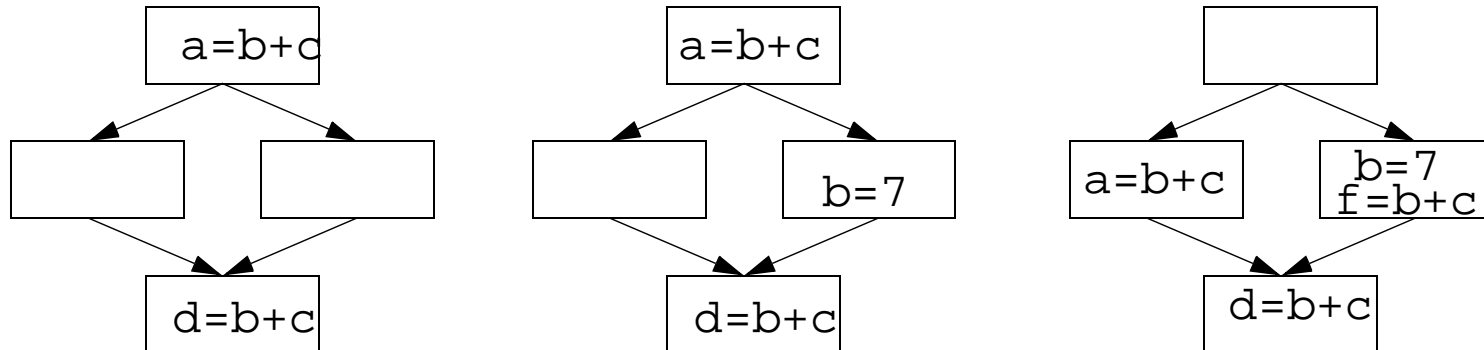
# Overview

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- **Eliminates many forms of redundancy in one fell swoop**
- **Originally formulated as 1 bi-directional analysis**
- **Lazy code motion algorithm**
  - formulated as 4 separate uni-directional passes  
(backward, forward, forward, backward)

## I. Common Subexpression Elimination

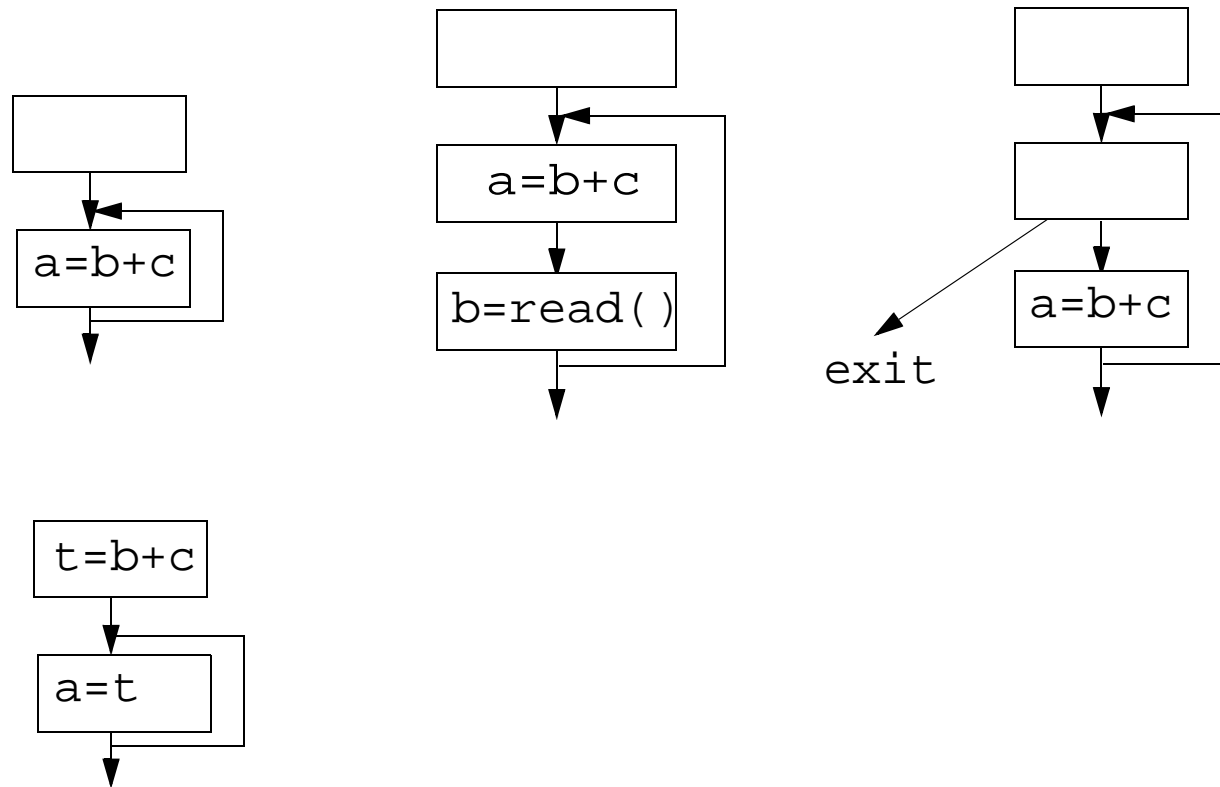
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- **A common expression may have different values on different paths!**
- **On every path reaching  $p$ ,**
  - expression  $b+c$  has been computed
  - $b, c$  not overwritten after the expression

# Loop Invariant Code Motion

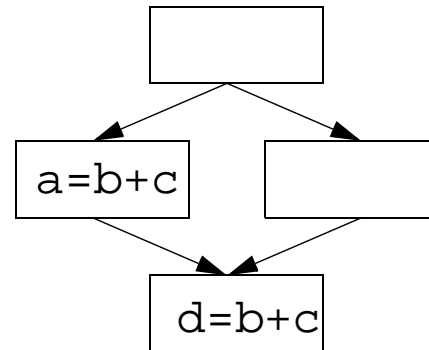
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- Given an expression  $(b+c)$  inside a loop, does the value of  $b+c$  change inside the loop?  
is the code executed at least once?

# Partial Redundancy

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- Can we place calculations of  $b+c$  such that no path re-executes the same expression
- Partial redundancy elimination (PRE)
  - subsumes:
    - global common subexpression (full redundancy)
    - loop invariant code motion (partial redundancy for loops)

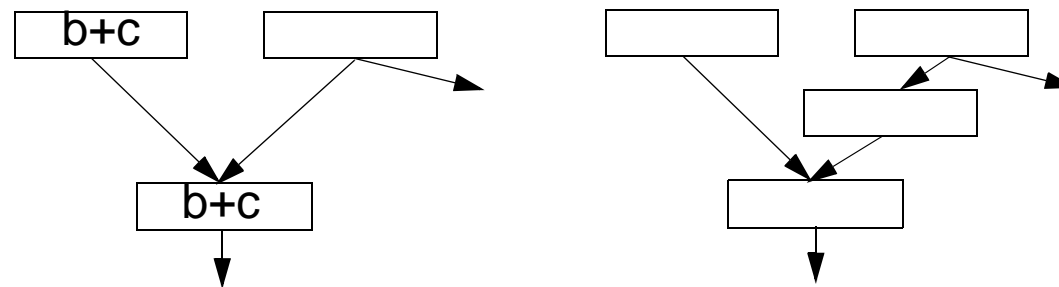
*Unifying theory: More powerful, elegant --> but less direct.*

## II. Preparing the Flow Graph

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- **Key observation**

- A bi-directional (!) data flow can now be replaced with several unidirectional data flows -- much easier
- Better result as well!



- **Definition: Critical edges**

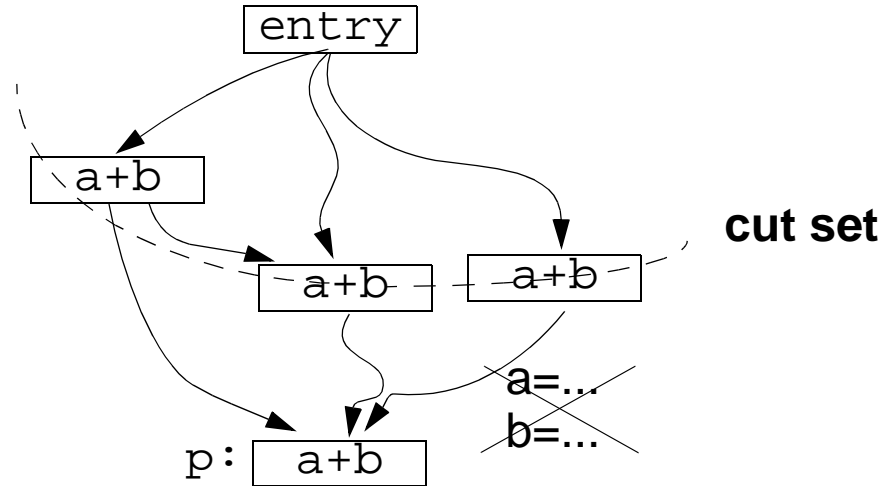
- source basic block has multiple successors
- destination basic block has multiple predecessors

- **Modify the flow graph: (treat every statement as a basic block)**

- To keep algorithm simple: restrict placement of instructions to the beginning of a basic block
- Add a basic block for every edge that leads to a basic block with multiple predecessors (not just on critical edges)

## Full Redundancy: A Cut Set in a Graph

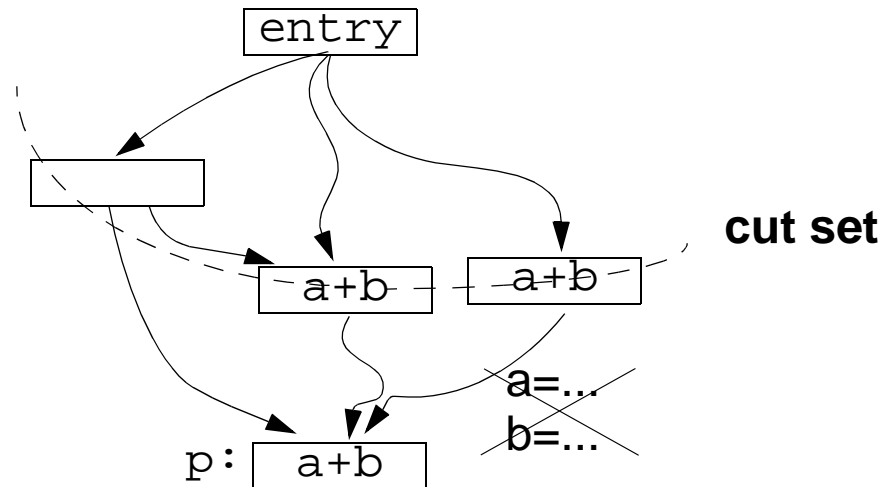
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- **Full redundancy at p: expression `a+b` redundant on all paths**
  - a cut set: nodes that separate entry from p
  - a cut set contains calculation of `a+b`
  - `a`, `b`, not redefined

# Partial Redundancy: Completing a Cut Set

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- **Partial redundancy at p: redundant on some but not all paths**
  - Add operations to create a cut set containing **a+b**
  - Note: Moving operations up can eliminate redundancy
- **Constraint on placement: no wasted operation**
  - **a+b** is “anticipated” at B if its value computed at B will be used along ALL subsequent paths
  - **a**, **b** not redefined, no branches that lead to exit with out use
- **Range where **a+b** is anticipated --> Choice**



## Pass 1: Anticipated Expressions

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- **Backward pass: Anticipated expressions**

**Anticipated[b].in: Set of expressions anticipated at the entry of b**

- An expression is anticipated if its value computed at point p will be used along ALL subsequent paths

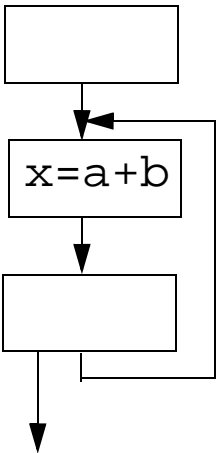
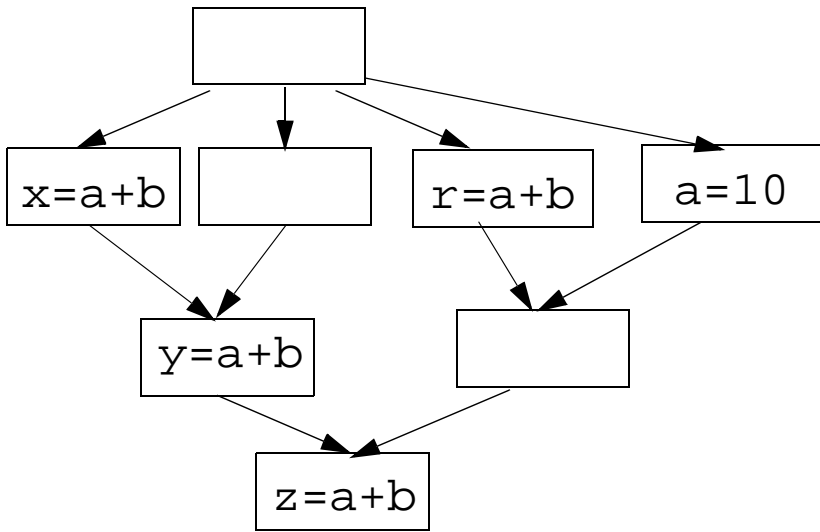
	Anticipated Expressions
Domain	Sets of expressions
Direction	backward
Transfer function	$f_b(x) = EUse_b \cup (x - EKill_b)$ EUse: used exp EKill: exp killed
$\wedge$	$\cap$
Boundary	$in[exit] = \emptyset$
Initialization	$in[b] = \{\text{all expressions}\}$

- **First approximation:**

- place operations at the frontier of anticipation  
(boundary between not anticipated and anticipated)

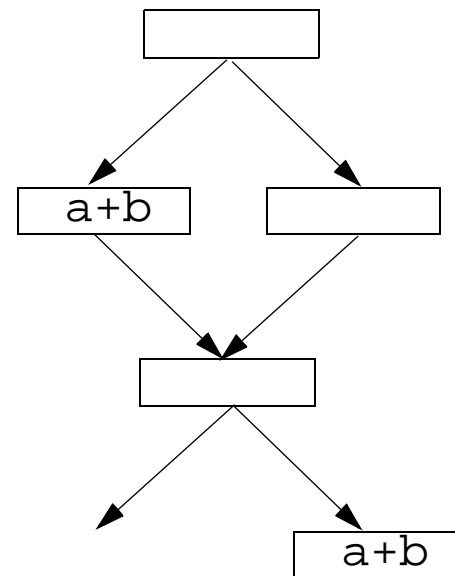
# Examples (1)

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## Examples (2)

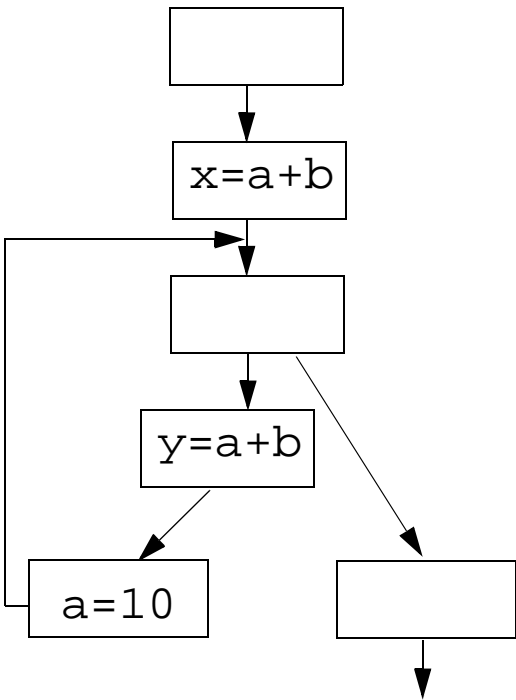
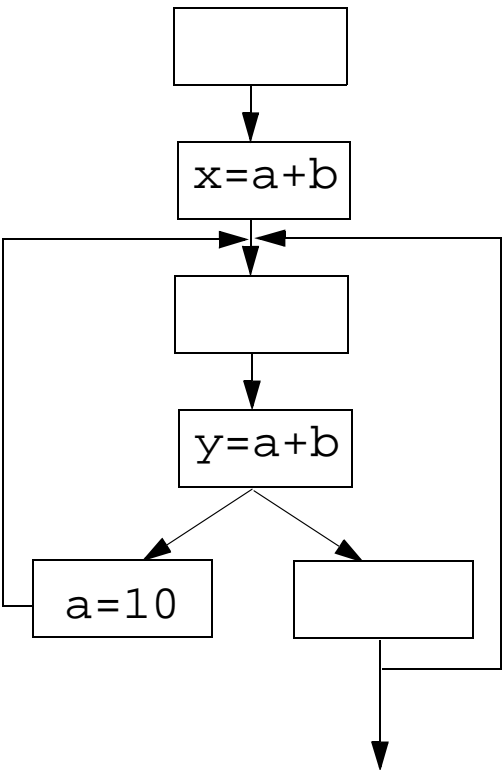
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*Do you know how the algorithm works without simulating it?*

# Examples (3)

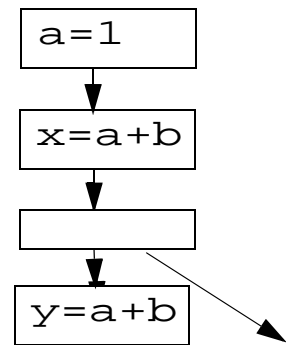
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*There is still some redundancy left!*

## Pass 2: Place As Early As Possible

- First approximation: frontier between “not anticipated” & “anticipated”
- Complication: Anticipation may oscillate



- Pretend we calculate expression e whenever it is anticipated
- e will be **available** at p  
if e has been “anticipated but not subsequently killed” on all paths reaching p

	Available Expressions
Domain	Sets of expressions
Direction	forward
Transfer function	$f_b(x) = (\text{Anticipated}[b].\text{in} \cup x) - \text{EKill}_b$
$\wedge$	$\cap$
Boundary condition	$\text{out}[\text{entry}] = \emptyset$
Initialization	$\text{out}[b] = \{\text{all expressions}\}$

# Early Placement

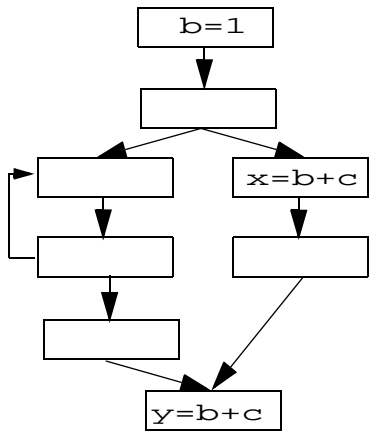
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- **earliest(b)**
  - set of expressions added to block b under early placement
- **Place expression at the earliest point anticipated and not already available**
  - $\text{earliest}(b) = \text{anticipated}[b].\text{in} - \text{available}[b].\text{in}$
- **Algorithm**
  - For all basic block b, if  $x+y \in \text{earliest}[b]$ 
    - at beginning of b:  
create a new variable t  
 $t = x+y$ ,  
replace every original  $x+y$  by t

*Let's be lazy without introducing redundancy.*

## Pass 3: Lazy Code Motion

- Delay without creating redundancy to reduce register pressure



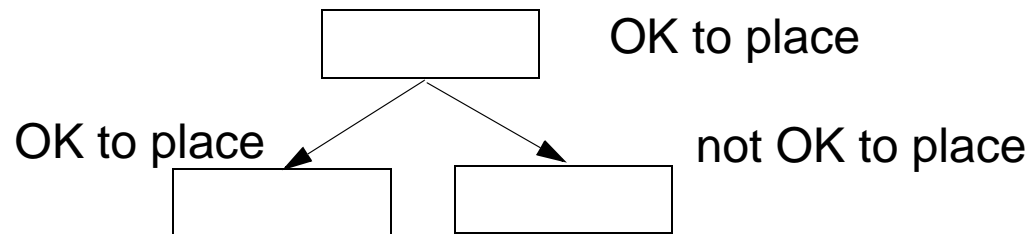
- An expression `e` is postponable at a program point `p` if
  - all paths leading to `p` have seen the earliest placement of `e` but not a subsequent use

	Postponable Expressions
Domain	Sets of expressions
Direction	forward
Transfer function	$f_b(x) = (\text{earliest}[b] \cup x) - \text{EUse}_b$
$\wedge$	$\cap$
Boundary condition	$\text{out}[\text{entry}] = \emptyset$
Initialization	$\text{out}[b] = \{\text{all expressions}\}$

## Latest: frontier at the end of “postponable” cut set

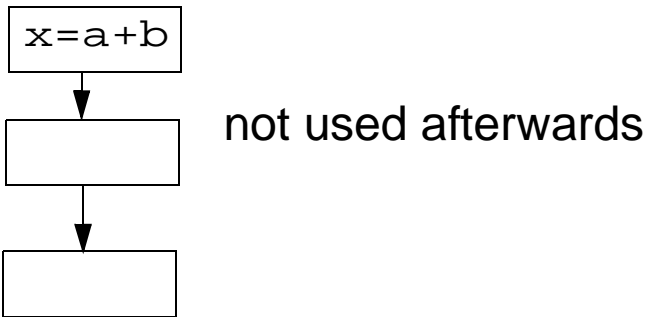
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- $\text{latest}[b] = (\text{earliest}[b] \cup \text{postponable.in}[b]) \cap (\text{EUse}_b \cup \neg(\bigcap_{s \in \text{succ}[b]} (\text{earliest}[s] \cup \text{postponable.in}[s])))$ 
  - OK to place expression: earliest or postponable
  - Need to place at b if either
    - used in b, or
    - not OK to place in one of its successors
- Works because of pre-processing step  
(an empty block was introduced to an edge if the destination has multiple predecessors)
  - if b has a successor that cannot accept postponement, b has only one successor
  - The following does not exist





# Pass 4: Cleaning Up



- **Eliminate temporary variable assignments unused beyond current block**
- **Compute:  $Used.out[b]$ : sets of used (live) expressions at exit of  $b$ .**

	Used Expressions
Domain	Sets of expressions
Direction	backward
Transfer function	$f_b(x) = (EUse[b] \cup x) - latest[b]$
$\wedge$	$\cup$
Boundary condition	$in[exit] = \emptyset$
Initialization	$in[b] = \emptyset$

# Code Transformation

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- For all basic blocks  $b$ ,
  - if  $(x+y) \in (\text{latest}[b] \cap \text{used.out}[b])$ 
    - at beginning of  $b$ :
    - add new  $t = x+y$
    - replace every original  $x+y$  by  $t$

# 4 Passes for Partial Redundancy Elimination

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- *Heavy lifting*: **Cannot introduce operations not executed originally**
  - Pass 1 (backward): Anticipation: range of code motion
  - Placing operations at the frontier of anticipation gets most of the redundancy
- *Squeezing the last drop of redundancy*:  
**An anticipation frontier may cover a subsequent frontier**
  - Pass 2 (forward): Availability
  - Earliest: anticipated, but not yet available
- *Push the cut set out -- as late as possible*  
**To minimize register lifetimes**
  - Pass 3 (forward): Postponability: move it down provided it does not create redundancy
  - Latest: where it is used or the frontier of postponability
- *Cleaning up*  
**Pass 4: Remove temporary assignment**

# Remarks

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- **Powerful algorithm**
  - Finds many forms of redundancy in one unified framework
- **Illustrates the power of data flow**
  - Multiple data flow problems