12.2 K-maps: Introduction

K-maps

A **K-map** is a graphical function representation that eases the simplification process for expressions involving a few variables, by adjacently placing minterms that differ in exactly one variable. K-map is short for **Karnaugh map**. "Map" is used like how a country map lays out cities next to each other. A K-map lays out minterms instead.

A K-map lays out possible minterms as adjacent cells (boxes). Adjacent minterm cells differ by exactly one variable. Each function minterm cell gets a 1; other cells get 0.

A K-map is a reoriented truth table.

| PARTICIPATION 12.2.1: A 2-variable K-map: Adjacent cells differ in exactly one variable. | | |
|--|-------------------------------|--|
| Start 2x speed y = a'b' + ab' a | a b y 0 0 1 0 1 0 1 0 1 1 1 0 | |
| PARTICIPATION 12.2.2: 2-variable K-map | | |
| a b 0 | 0 1 0 1 (J) | |
| Given function y = ab + a'b, represented 1) (J) corresponds to which minterm? | in the above figure's K-map. | |
| Check Show answer 2) (K) corresponds to which minterm? Check Show answer | | |
| 3) (L) should have what value (0 or 1)? | | |
| Check Show answer 4) Cells (J) and (K) differ in what variab a, or b? | le: | |
| Check Show answer 5) Cells (L) and (K) differ in what variab a, or b? | le: | |
| Check Show answer 6) Cells (L) and (J) differ in how many variables? | | |
| Check Show answer | | |

Because adjacent minterm cells differ in exactly one variable, a K-map's key benefit is to make i(j + j') simplification opportunities obvious: Adjacent 1's are an i(j + j') opportunity. Circling two adjacent 1's graphically represents the algebraic simplification i(j + j') = i(1) = i. After drawing such a circle, a designer can write a product term with the differing variable omitted. $\begin{array}{ll} \textbf{PARTICIPATION} \\ \textbf{ACTIVITY} \end{array} \hspace{0.5cm} 12.2.3: \hspace{0.5cm} \text{Simplification with a 2-variable K-map: } \textbf{i}(\textbf{j}+\textbf{j}') \hspace{0.5cm} \text{opportunities are obvious.} \end{array}$ Start 2x speed A powerful feature of a K-map is how easily replicating a minterm is achieved (recall an earlier section's example), merely by circling a cell **PARTICIPATION** 12.2.4: Circling a 1 twice is like replicating a minterm to create i(j + j')opportunities. Start 2x speed Table 12.2.1: Rules for simplifying a sum-of-minterms expression with a K-Rule 1: Cover every 1 at least once using circles. Add circle's term to expression. Rule 2: Use fewest and largest circles possible, to achieve simplest expression. PARTICIPATION 12.2.5: Basic 2-variable K-map. 0 0 0 Consider the K-maps in the figure above. 1) Circle (L) is what simplified term? Check Show answer 2) Is circle (M) necessary? Type: yes or no Check Show answer 3) Is circle (P) a good circle? Type: yes or Check Show answer Example: Out-of-bed alarm An example in an earlier section involved sounding an alarm (s = 1) if a person was up from bed (u = 1) and a button pressed (b = 1), or a person was up and button was not pressed. The captured equation was s = ub + ub'. A K-map can be used to simplify the equation. PARTICIPATION 12.2.6: Simplifying with a K-map: Out-of-bed alarm. Start 2x speed

| s = ub + ub' s = u Out-of-bed alarm u 0 0 0 0 0 1 1 1 1 u | |
|---|-------------------------------|
| PARTICIPATION 12.2.7: Out-of-bed alarm system. | |
| Consider the example above. | |
| 1) The designer captured behavior as s = ub + ub', but simplification yielded s = u. Thus, the designer incorrectly captured the original behavior. True False | |
| The simplification on the K-map was | |
| quite obvious. | |
| O True O False | |
| - 1.40 | |
| Example: Motion-sensing light An earlier section captured a motion-sensing lamp's behavior and then simplified algebraically. That example oby a K-map instead. | can more-easily be simplified |
| PARTICIPATION ACTIVITY 12.2.8: Simplifying with a K-map: Motion-sensing light. | |
| Start 2x speed | |
| Inputs: m: motion sensed | |
| t test mode Outputs: i: illuminate lamp Goal: Illuminate lamp if motion and not test mode, or if test mode and no motion, or if test mode and motion | |
| Algebraic simplification $ i = mt' + tm' + tm $ $ i = mt' + mt + mt $ $ i = mt' + mt + mt + mt $ $ i = mt' + mt + mt + mt $ $ i = mt' + mt + mt + mt $ $ i = m(t + t) + (m' + m) t $ $ i = m(1) + (1)t $ $ i = m(1) + t(1) $ $ i = m + t $ $ T$ | |
| PARTICIPATION 12.2.9: Motion-sensing light system. | |
| Consider the example above. | |
| 1) How many equations were involved using algebraic simplification?2 | |
| O 8 | _ |
| How many circles were drawn using K-map simplification? 2 | U |
| O 3 | _ |
| 3) K-maps help with simplification by not obeying algebraic properties.True | |
| O False | |
| Provide feedback on this section | |