advantages of GA: O conceptually simple; @ do not require the search space to be: continuous, differentiable. unimodal

SGA example: max. f(x)=x2, s.t. 0 < x < 31

Step 1: encoding the decision variable: 25=32. use 5 bits

step 2: initialize the popln: randomly generate 4 solutions 01101 (13), 11000 (24), 01000(8), 10011(19)

Step 3: fitness value

Step 4: reproduction: use roulette wheel to obtain mating pool

Step 5: Xover: Select $\frac{n}{2}$ pair of parents. Use 1-point Xover, randomly generate Xover site k between (1, L-1). here $P_c = 1$.

Step 6: mutation: assume Pm-0.001, 20×0.00 = 0.02 no change in the strings.

String#	initial popln	X	f(x)	%	# selected	Mating pool	Mate	Xover site
1	01101					01101	2	4
2	11000	24	576	49.2	2	11000	1	4
3	01000	8	64	5.5	0	11000	4	2
4	10011	19	361	30.9	1	10011	3	2
Sum		1170		100.0	4	new po	ppln:	
		293				01100	2 . 1	1001
						1101) //	2000

fitness scaling: in first few generations, highly tit solutions dominate given the fitness fix). g = af + b, maintain $g_{avg} = f_{avg}$. the selection. $g_{max} = Cf_{avg}$ to restrict the fittest to have in mating pool.

 $a = \frac{f_{avg}(C-1)}{f_{max} - f_{avg}}, b = f_{avg}(1-\alpha), \quad £af+b<0, \quad £i] \quad a = \frac{f_{avg}}{f_{avg} - f_{min}}, b = f_{avg}(1-\alpha)$

Sigma truncation: $f'=f-(favg-C\cdot T)$, $C=2^3$. T is the variance power law scaling: $f'=g(f)=f^{\alpha}$

Coding Multivariable: if need 5 decimal point precision on X, then U is chosen as the smallest integer satistying $IO^{5}(bi-ai) = 2^{L}-I$ decoding: $X_{i} = ai + decimal(s+ning_{i})(\frac{bi-ai}{2^{L}-I})$ upper bound bound

a population with n members and length L have schemas 22 n.26 depending on diver

4 to selection: 1 roulette wheel QSUS 1 ranking 4 tournament - Stochastic Universal Selection: wheel is rotated once with n markets on the wheel. 转以 > 生成nTstrings (solutions) - Ramking: the popla is sorted w.r.t. titness value, each string is assigned with an offspring count. the selection proportion to the k-th ranked string is: PK = 9max - (K-1) (9max - 9min), 9max, 9min are the allocation for the best and the worst string. quax + quin = = n - Tournament: 随机选2个string进行companison, titness 大的放进 mating pool, 然后放回popln、事员的次选的Tsolution进行Xoven. 3本 Xover: ① I-point ② 2-point ③ uniform - 1-point Xover cannot combine all possible schemas. - 2-point Xover: example: 11**.****.11, * +++.1 * 1+. * * K1=4, K2=8 11**1*1**1, ******** - uniform Xover:随机的文一个等长的template,"I"的物名用卷的。"O"的用的 example: 1001011, 0101101, template: 1101001 offspring 1: 1001101 , offspring 2: 0101011 4种 popla selection: O non-overlapping (主替義) ② elitist:用好的 pavent 作为offspring 进入下一个G (只用最好的) ③ Steady-State reproduction:只用 一部分offspring来行替(保留一些pavent) 四以+入 selection: Unoffspring + 入par Building block: highly tit schemas (short S(H), low order O(H)) Fundamental Theorem: Short & low-order schemas with above popla average titness will increase with exponential speed in subsequent Gs. Two-owned Bandit Problem: Nooins with MI. MZ, J., Jz of 2 arms ①对每个arm, 方试n次, 对出best arm②打型下的N-2n 了投入 best arm中 3 a probability q(n) that the identification is wrong. expected loss: L(N,n) = n | M1-M2 | + q(n) (N-2n) | M1-M2 | determine n to minimize L: dL = [1-2q(n)+ (N-2n) dq(n)]. |M1-11=0, $n^* \approx c \ln \left(\frac{N^*}{8\pi c^2 \ln(N^2)} \right)$, $c = \left(\frac{\sigma_1}{M_1 - M_2} \right)^2$, $N \approx e^{\frac{N^*}{2c}} \sqrt{8\pi c^2 \ln(N^2)} \approx N - n = \# \text{ of thicks}$ i given to best am. Minimal - Deceptive Problem:

· Local Processing

1 edge pixel (xo, yo) in neighborhood of (x, y) is smailar with: 1. magnitude: | \f(x,y) - \f(x0,y0) | < E

2. direction: | θ(x, y) - θ(x0, y0) | < A

同时满足两个条件 🚳 (Xo, yo)与(X, y) linked

@ Hough transform:

line segment y=ax+b 经过来点(xi, yi): yi=axi+b

极华标表示: P= X·COSD + y·SinD 极华标中的点 (b.p)平面中的线(共成)

3 local dominant orientation:

1st-order derivative of gradient:

$$\nabla f(x,y) = \left[\begin{array}{c} G_X(x,y) \\ G_Y(x,y) \end{array} \right] = \left[\begin{array}{c} \partial f(x,y) / \partial x \\ \partial f(x,y) / \partial y \end{array} \right]$$

* magnitude:

 $|\nabla f(x,y)| = |G_X(x,y) + G_Y(x,y)|^{\frac{1}{2}}$

* divection:

$$\mathcal{L}(x,y) = \tan^{-1}\left(\frac{Gy(x,y)}{Gx(x,y)}\right)$$

An image is modeled locally by

$$f(x, y) = h(ax + by)$$

ax+by=t is the line representation $y=-\frac{a}{b}x+t=t$ and x+tof the orientation of fix, y).

(y=ax+b . (2,1) (1,0) > b=-a (2,1) -> b=1-20 \ (b= y-ax P= XW30+ ysinD (1,0) -> P= cos0 12,1) > P = 20030 + Sint (3,2) > P = 3 Cost + 2 Sint

b= yi-axi

 $\nabla f(x,y) = \begin{bmatrix} Gx \\ Gy \end{bmatrix} = \begin{bmatrix} \partial f/\partial x \\ \partial f/\partial y \end{bmatrix} = \begin{bmatrix} ah'(t) \\ bh'(t) \end{bmatrix}$

 $\nabla f(x,y) = G_{\mathbf{x}}(x,y) + jG_{\mathbf{y}}(x,y) = |\nabla f(x,y)| e^{j\theta(x,y)}$ average the squared gradient: [\(\nabla f(x,y)\)^2 = G_x^2 - G_y^2 + j2G_x Gy = | \(\nabla f\)^2 e^{j2\theta} Discriminant Functions

gi(x) = Inp(x|wi) + Inp(wi),

decision boundary: gi(x)=gi(x)

dz=(x, Mi)=(x-Mi)Zi(x-Mi), bi=lnp(wi)- をln/Zil.

· Mahalanobis distance: dzi = (x-µi) Zi'(x-µi)

· Euclidean distance: den = (x-Mi) T(x-Mi)

• In 1-D: $(x-\mu i)^2$, $dE_n = (x-\mu i)^2$

· Case 1: $Z_j = Z_j =$

 $g_i(x) = -\frac{1}{2}(x - \mu_i)^T Z^{-1}(x - \mu_i)$ = $d_Z(x, \mu_i)$

 $g_{i}(x) = (-\frac{1}{2}x^{T}Z^{T}x + \mu_{i}^{T}Z^{T}x)$ $-\frac{1}{2}\mu_{i}^{T}Z^{T}\mu_{i} + \ln p(w_{i})$ $= \mu_{i}^{T}Z^{T}x - \frac{1}{2}\mu_{i}^{T}Z^{T}\mu_{i} + \ln p(w_{i})$ $= w_{i}^{T}x + w_{io}$

decision boundary:

 $g_{i}(x) = g_{i}(x) = 0$ $(w_{i} - w_{j})^{T}x + (w_{i0} - w_{j0}) = 0$ $(\mu_{i} - \mu_{j})^{T}Z^{-1}x - \frac{1}{2}(\mu_{i} - \mu_{j})^{T}Z^{-1}(\mu_{i} - \mu_{j}) + \ln(\frac{P(w_{i})}{P(w_{j})}) = 0$

Example: class $\omega_i : \begin{bmatrix} \frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{2}{3} \end{bmatrix}, \begin{bmatrix} \frac{3}{3} \end{bmatrix}, \begin{bmatrix} \frac{3}{3} \end{bmatrix}, \begin{bmatrix} \frac{3}{3} \end{bmatrix}, \begin{bmatrix} \frac{9}{3} \end{bmatrix}, \begin{bmatrix} \frac{9}{3} \end{bmatrix}, \begin{bmatrix} \frac{9}{3} \end{bmatrix}, \begin{bmatrix} \frac{9}{3} \end{bmatrix}$ class $w_2 : \begin{bmatrix} \frac{7}{3} \end{bmatrix}, \begin{bmatrix} \frac{9}{3} \end{bmatrix}$ Find the Bayes classifier and the

 $M_{1} = \frac{1}{5} \left(\begin{bmatrix} \frac{1}{2} \end{bmatrix} + \begin{bmatrix} \frac{2}{3} \end{bmatrix} + \dots + \begin{bmatrix} \frac{2}{3} \end{bmatrix} \right) = \frac{1}{5} \begin{bmatrix} \frac{11}{10} \\ \frac{1}{45} \end{bmatrix}$ $M_{2} = \frac{1}{5} \left(\begin{bmatrix} \frac{2}{3} \end{bmatrix} + \begin{bmatrix} \frac{8}{3} \end{bmatrix} + \dots + \begin{bmatrix} \frac{8}{3} \end{bmatrix} \right) = \frac{1}{5} \begin{bmatrix} \frac{41}{45} \end{bmatrix}$

 $Z_j = (\frac{1}{N_j} Z_i \times X^T) - M_j M_j^T$

decision boundary.

 $Z_{1} = \frac{1}{5} \left(\begin{bmatrix} \frac{1}{2} \end{bmatrix} \begin{bmatrix} 123 + \dots + \frac{2}{3} \end{bmatrix} \begin{bmatrix} 233 \end{bmatrix} \right)$ $-\frac{1}{5} \times \frac{1}{5} \times \begin{bmatrix} \frac{1}{10} \end{bmatrix} \times \begin{bmatrix} 11 & 103 \end{bmatrix}$ $= \frac{1}{25} \begin{bmatrix} 14 & -5 \\ -5 & 10 \end{bmatrix}.$

 $Z_2 = Z_1 = Z$.

 $\mathbb{Z}^{-1} = \frac{5}{23} \left[\begin{array}{c} 10 & 5 \\ 5 & 14 \end{array} \right]$

with $p(w_1) = p(w_2)$, $Z_1 = Z_2 = Z$: $d_j(x) = x^T Z^{-1} u_j - \frac{1}{2} u_j^T Z^{-1} u_j$

 $Z^{-1}MI = \frac{5}{23}\begin{bmatrix}105\\514\end{bmatrix} \times \frac{1}{5}\begin{bmatrix}11\\10\end{bmatrix} = \frac{1}{23}\begin{bmatrix}160\\195\end{bmatrix},$

 $M_1^T Z_1^T M_1 = \frac{1}{5} [11 \ 10] \times \frac{1}{23} [160] = \frac{742}{23},$

similarly, we obtain:

 $d_2(x) = \frac{635}{23} x_1 + \frac{835}{23} x_2 - 276.56$

di-dz = 0 decision boundary

VRS Implementation:

min. +(X) s.t. g:(x)=0, v=1,...p $h_j(x) = 0$, $\hat{j} = 1, \dots, m$ LK = XK = UK , K=1, ..., N



min. f(X)

s.t. gi(x) = 0. i=1,.... p hj (Xx | KEC) = 0, je Mz LK = RK.j ({XIII & Si, L + K) = UK, KEC, jEM,

re = XK = NK, KECT

Comprehensive Strategy:

1 instead of learning from two exemplars (phest & ghest), each dimension teams from just plest filds

1 instead of learning from phest & ghest for all dim. each dim can learn from a differen exemplar.

(weeks 4~5)

FICL-PSO: Diversity Measure

Swarm diversity: distance to average point

Diversity (S(t)) = $\frac{1}{N} \sum_{i=1}^{N} \left[\frac{2}{A_{i-1}} (x_i^d(t) - \overline{x_i^d(t)})^2 \right] \cdot \overline{x_i^d(t)} = \frac{1}{N} \sum_{i=1}^{N} x_i^d(t)$

exploration subgroup g.: high diversity exploitation subgroup 9: 10m diversity

- The explorative particles are not allowed to access information from exploitative particles.

- Even it exploitation groups suffer from premature convergence. exploration group can rescue them from local optimum

Dynamic - Nultiple - Swam PSO (DMS-PSO)

- Constructed based on local version of PSO
- Two characteristics: O Small Sized Swarms.
 - @ randomized re-grouping scheme
- Popla is divided into several sub-swarms randomly.
- Each sub use its own particles to search optimum.
- The whole popla is re-grouped into new sub-swarms.

Table: results of 1-point Xover (Site is between fixed positions)

1	00		10		
00	Same	Same	same	01 10	
01	same	same	0011	some	
10	same same	11 00	same	same	
1 1	10 01	Same	same	same	

- · The proportions of schemas at time t are: Poo , Pot , Pit
- The probability that a Xover site falling between two fixed positions is $Pe\frac{S(H)}{L-1} = 1 \times \frac{6}{10} = 0.6$
- · Deriving population proportions at time t+1:

consider schema "00", the proportion Poo always survive except:

(a) Xover with "11" with k between fixed position

(b) when "01" and "11" Xover between fixed position, then "00" is created $P_{00}^{t+1} = \frac{f_{00}}{\bar{f}} P_{00}^{t} - a_{0} \frac{f_{00}}{\bar{f}} P_{00}^{t} \frac{f_{11}}{\bar{f}} P_{11}^{t} + a_{0} \frac{f_{01}f_{10}}{\bar{f}^{2}} P_{01}^{t} P_{10}^{t},$

f = foo Poo + Jos Pot + Jos Pot + Jos Pot + Jos Pot is the average fitness.

the parent schemas nill survive if the Xover site is ontside fixed pos.

Neighbor Mutation-based DE for Multi-modap Optimization weeks 6-7 population of solutions at current generation Input For i=1: NP (NP is the paper size) Step1 7. calculate the Euclidean distance between solution i and others 2. select m members with smallest E distance to solution i to construct a subpopla 3. produce an off spring us using DE nithin subpople, i.e., pick Mi, Yz, Ys reset hi within bounds if any of the dimensions exceed the bounds 5. evaluate hi using titness value End tor select NP fitter solutions for next G w.r.t. niching strategy Step 2 popln of solutions for next G Output Difference between multi-obj and single-obj optimization; O one optimum versus multiple optima @ require search and olecision making 1) two spaces-of-interest (objective space & decision space), instead of one Multiple-obj Opt Single-obj Opt estimate min. fi F= Wiji+ Waja + ··· + Waja Weighted - Sum: a relative high-level In importance Intormation min. +m Mobi optimizer s.t. constraints [wi, wz, ..., wm] Ideal - Multi-obj - Opt: one optimal solution high-level ideal Multiple multi-obj optimizer trade-oft solutions information Changes of using SGA to solve multi-obj Opt: Begin) a modity the titness computation popla initialization. 2) Emphasize non-dominated Solutions for convergence 3 Emphasize less-cronded solutions for diversity Con N Evaluation reproduction t=t+1 + mutation

