

Hard Drives

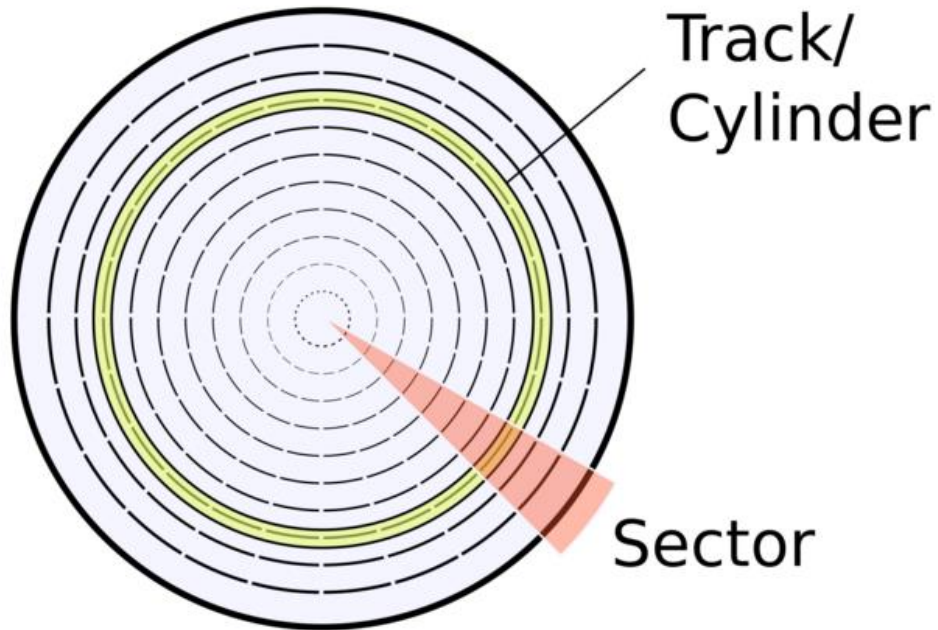
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Lecture Objectives

After this lecture, you should be able to:

- ❑ explain performance characteristics of hard drives
- ❑ calculate the rotational delay of a hard drive given its RPM value
- ❑ calculate the time for a read or write operation
- ❑ calculate the time for a group of read or write operations – random or sequential
- ❑ describe the operation of some I/O schedulers

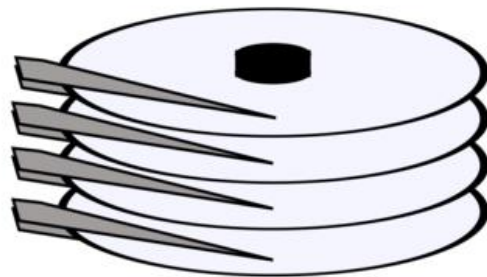
Hard drives



Usually one head for each surface of a platter.

Sectors toward the outside of a platter are bigger.

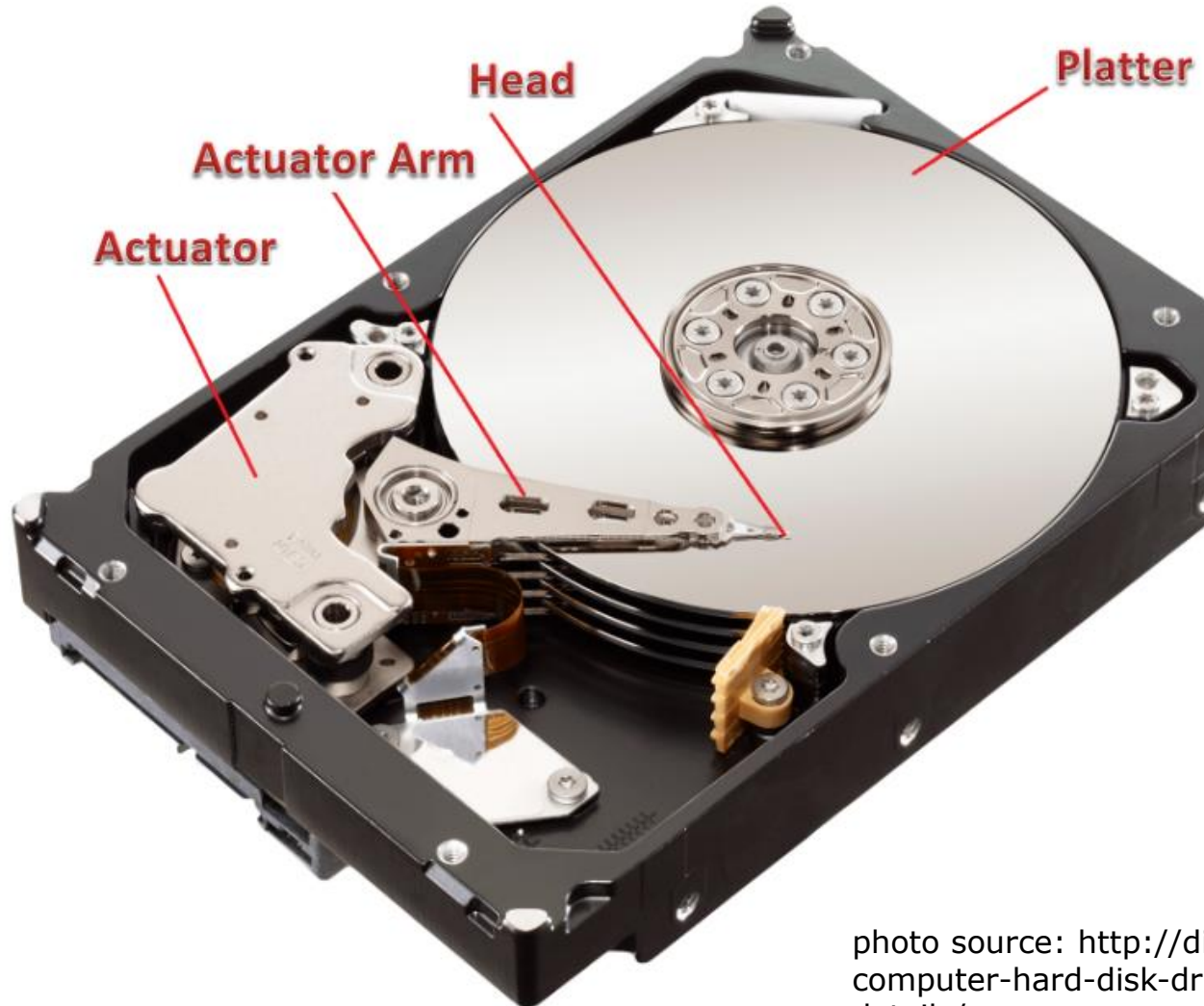
Physical unit of storage = a block



Heads

8 Heads,
4 Platters

Photo detail



The heads are tiny.

The space between a head and the disk surface is about 5000x thinner than a human hair.

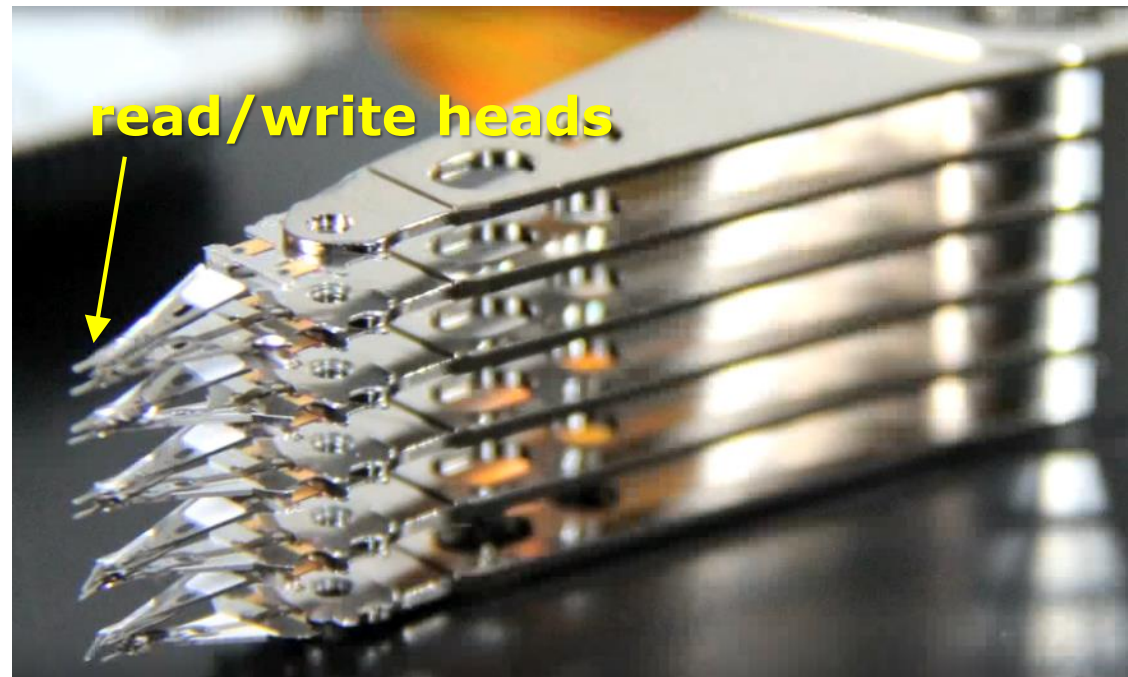
photo source: <http://diwakarpro.com/types-computer-hard-disk-drives-hdd-complete-details/>

Seagate video

[Seagate video](https://www.youtube.com/watch?v=NtPc0jI21i0) <https://www.youtube.com/watch?v=NtPc0jI21i0>

- About 300,000 tracks per inch (along radius) !
- There is actually aerodynamics involved in the design of the head so it will float over the disk surface

Head stack assembly,
from Seagate
video



A drive in operation

<https://youtu.be/p-JJp-oLx58?t=406>

(Van Svenson)



A hard drive is a block device

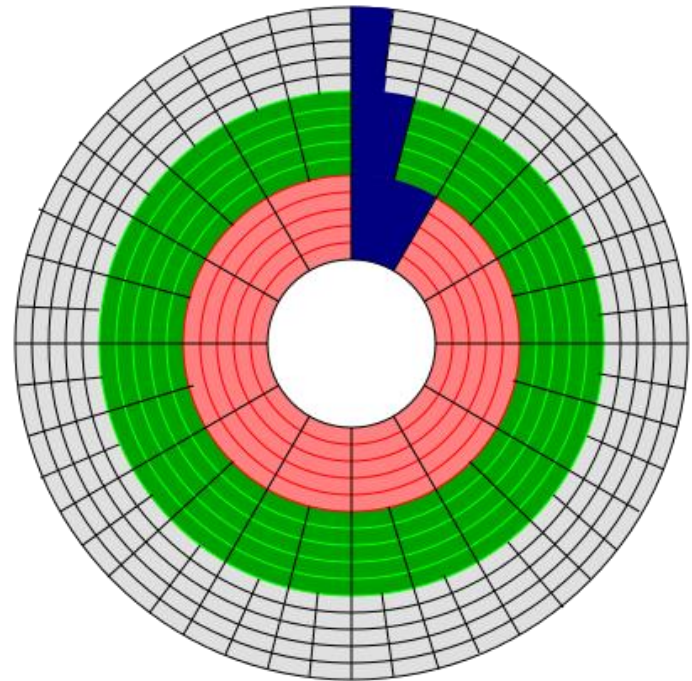
In early disk interfaces, “CHS addressing” was used:

- **C**ylinder
- **H**ead
- **S**ector

Now “logical block addressing” (LBA) is used. A “linear addressing scheme”

Analogy:

- CHS is like street number/street/city
- LBA is like giving every home a single number

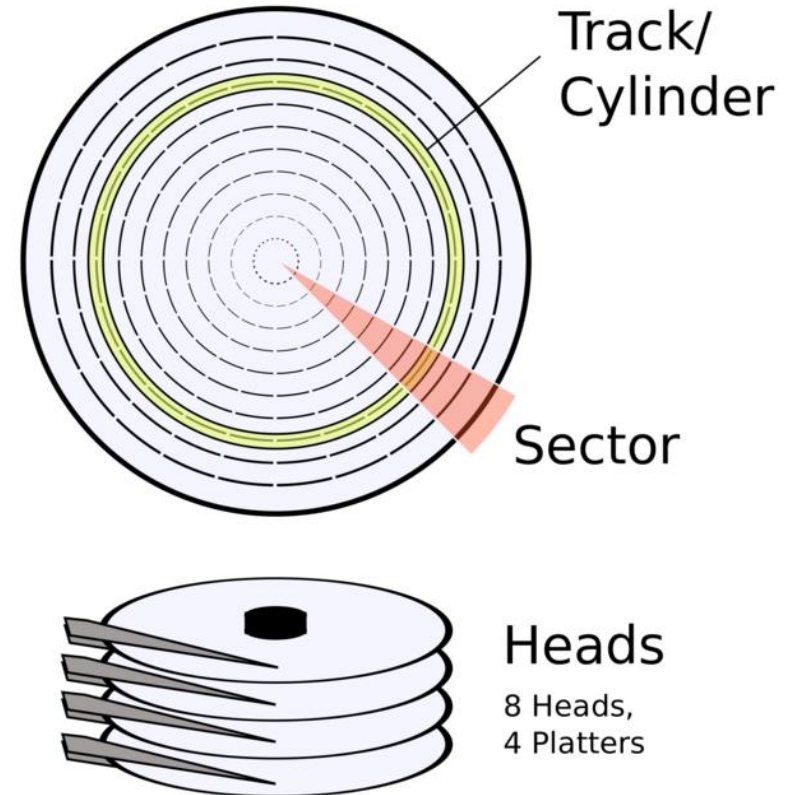


multi-zoned drive

Drive performance

Reading/Writing of a drive involves 3 steps:

1. wait for sector to rotate underneath head (**rotational delay**)
2. move the head to the right track (**seek**)
3. actually transfer the data (**transfer**)



Calculating average rotational delay

If a disk spins at 7200 RPM, what is the average rotational delay?

$$7200 \text{ RPM} = \frac{7200 \text{ rev}}{\text{min}}$$

$$\frac{7200 \text{ rev}}{\text{min}} * \frac{\text{min}}{60 \text{ sec}} = \frac{120 \text{ rev}}{\text{sec}}$$

$$\frac{1 \text{ sec}}{120 \text{ rev}} * \frac{1000 \text{ ms}}{\text{sec}} = 8.3 \frac{\text{ms}}{\text{rev}}$$

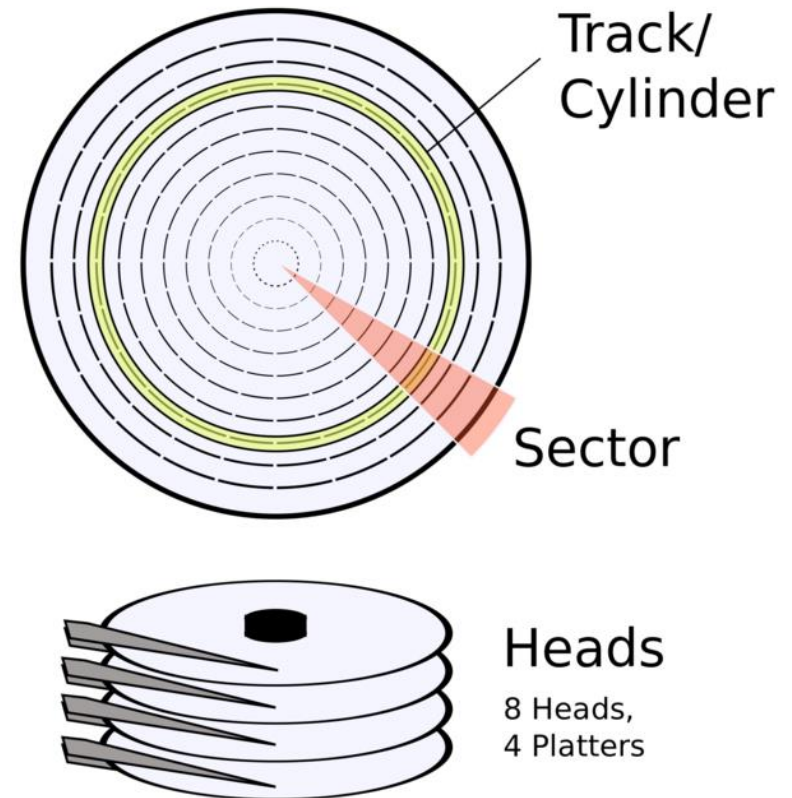
so about 4.2 ms per 1/2 revolution

in one go:

$$\frac{\text{min}}{7200 \text{ rev}} * \frac{60 \text{ sec}}{\text{min}} * \frac{1000 \text{ ms}}{\text{sec}} = \frac{600 \text{ ms}}{72} = 8.3 \frac{\text{ms}}{\text{rev}}$$

How long to transfer data?

- ❑ if a drive spins at 7200 RPM, rotational delay is about 4 ms
- ❑ typical seek time is about 5 ms
- ❑ typical max transfer rate is about 100MB/sec



"access time" = rotational delay + seek time

Calculating time for a read or write

1. wait for sector to rotate underneath head (**rotational delay**)
2. move the head to the right track (**seek**)
3. actually transfer the data (**transfer**)

How long will it take to read 2 MB, assuming:

- rotational delay = 4 ms
- seek time = 5 ms
- transfer rate = 100 MB/s

$$\text{Access time} = 4 \text{ ms} + 5 \text{ ms} = 9 \text{ ms}$$

$$\text{Transfer time} = \frac{1 \text{ s}}{100 \text{ MB}} * 2 \text{ MB} = 0.02 \text{ s} * \frac{1000 \text{ ms}}{\text{s}} = 20 \text{ ms}$$

$$\text{Total} = 9 \text{ ms} + 20 \text{ ms} = 29 \text{ ms}$$

Seagate Barracuda performance

Specifications	3TB ¹
Model Number	ST3000DM001
Interface Options	SATA 6Gb/s NCQ
Performance	
Spindle Speed (RPM)	7200
Cache, Multisegmented (MB)	64
SATA Transfer Rates Supported (Gb/s)	6.0/3.0/1.5
Seek Average, Read (ms)	<8.5
Seek Average, Write (ms)	<9.5
Average Data Rate, Read/Write (MB/s)	156
Max Sustained Data Rate, OD Read (MB/s)	210
Configuration/Organization	
Heads/Disks	6/3
Bytes per Sector	4096

(seagate.com)

Workload analysis

Drive performance will depend a lot on how drive is used.

Consider two cases:

Random workload:

- read 32 KB from each of 100 **random** locations

Sequential workload:

- read 3.2 MB **sequentially**

Assume access time is 10 ms, transfer rate is 100 MB/sec

Exercise

Given: access time is 10 ms, transfer rate is 100 MB/s

We need to read 3.2 MB.

1. How long to do a sequential read of 3.2 MB?
2. How long to do 100 random reads of 32 KB each?

Random vs. Sequential workload

Sequential workload:

- time: access time + transfer time ~ 42 ms
- overall rate: $3.2 \text{ MB}/0.042 \text{ s} \sim 76 \text{ MB/sec}$

Random workload:

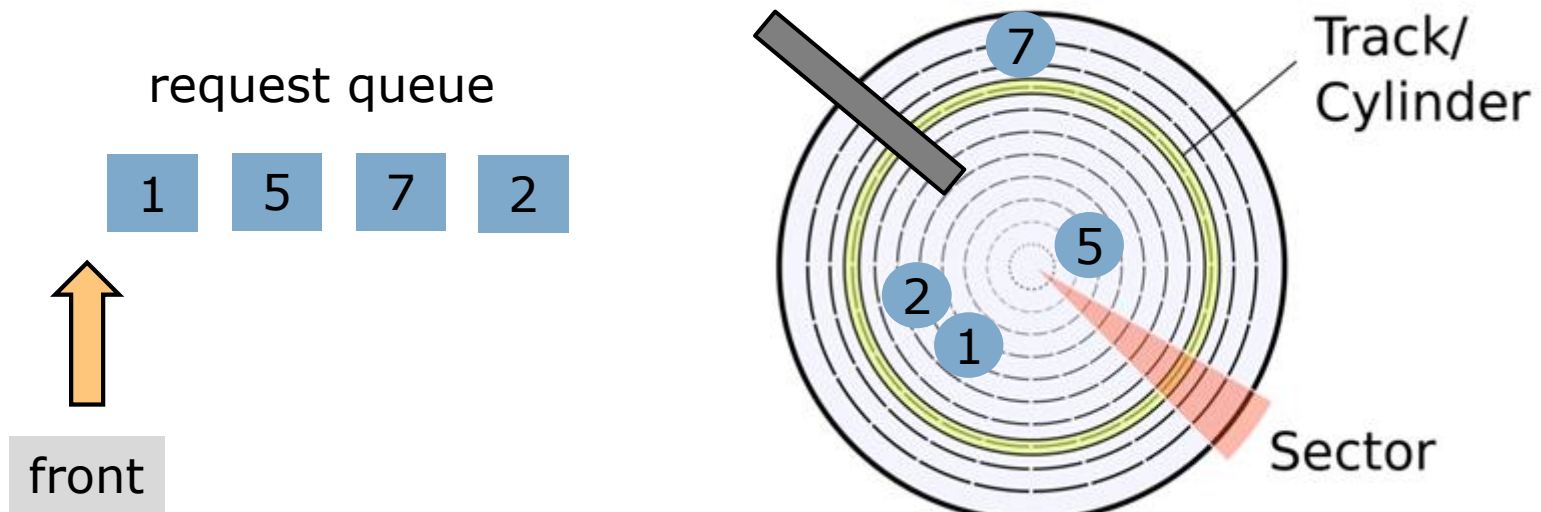
- time: $100 * (\text{access time} + \text{transfer time}) \sim 1030$ ms
- overall rate: $3.2 \text{ MB}/1.03 \text{ s} \sim 3.2 \text{ MB/sec}$

Overall rate is about **24x** better for sequential workload

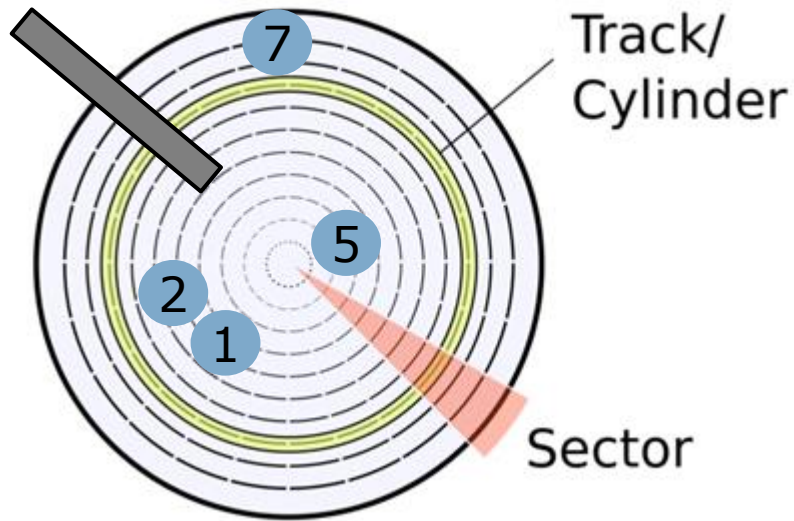
Disk scheduling (aka "I/O scheduling")

Sending requests to a disk in the order the OS receives them → terrible performance

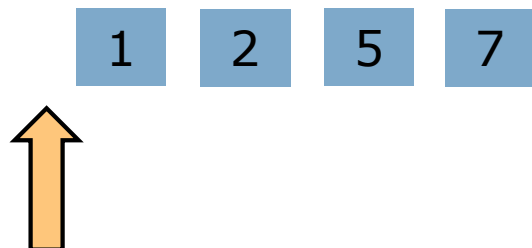
The **disk scheduler** decides the order in which disk requests should be processed.



Shortest Seek Time First (SSTF)



request queue



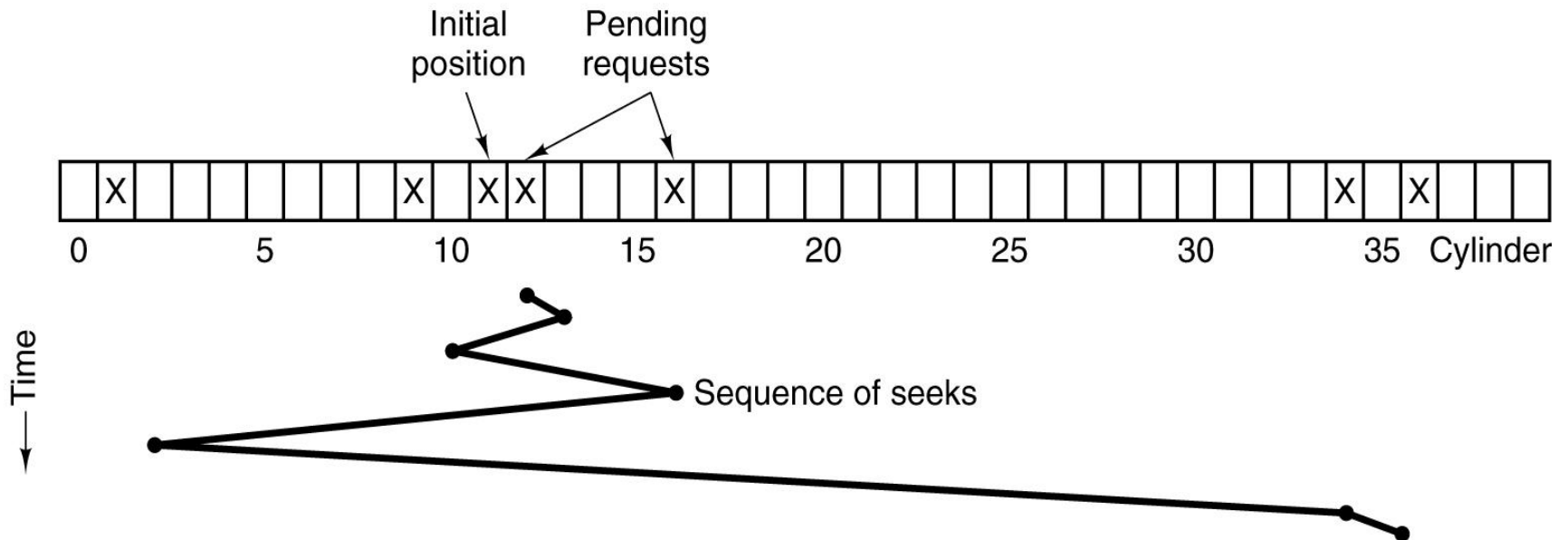
One way to do I/O scheduling: put requests closest to current track at front of queue.

Problem 1: the block address doesn't give track number.

Problem 2: ...?

Visualization of SSTF

A request arrives to read a block on cylinder 11. While the seek is in progress, new requests come in for cylinders 1, 36, 16, 34, 9, and 12, in that order.



Elevator scheduling

I/O scheduling is
like elevator
scheduling

What would happen
if an elevator
always picked up
people from the
closest floor?

starvation



Linux I/O schedulers

❑ Linus Elevator

- performs merging and sorting (replaced in 2.6)

❑ Deadline I/O Scheduler

- gives up elevator approach if old requests exist

❑ Anticipatory I/O Scheduler

- waits a few ms after a seek for more read requests (Linux 2.6 default)

❑ Completely Fair Queuing I/O Scheduler

- one queue for each process
- designed for multimedia workloads

❑ Noop I/O Scheduler

- maintains request queue in FIFO order

Summary

- ❑ disk drive hardware
- ❑ disk drive performance specs
- ❑ workload analysis
- ❑ I/O scheduling