# Emotionally Expressive Motion Controller for Virtual Character Locomotion Animations

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## **MOTIVATION**



"Neutral"
[The Sims 4, Maxis, 2014]



"Angry"



"Confident"



"Energized"



"Sad"



"Afraid"

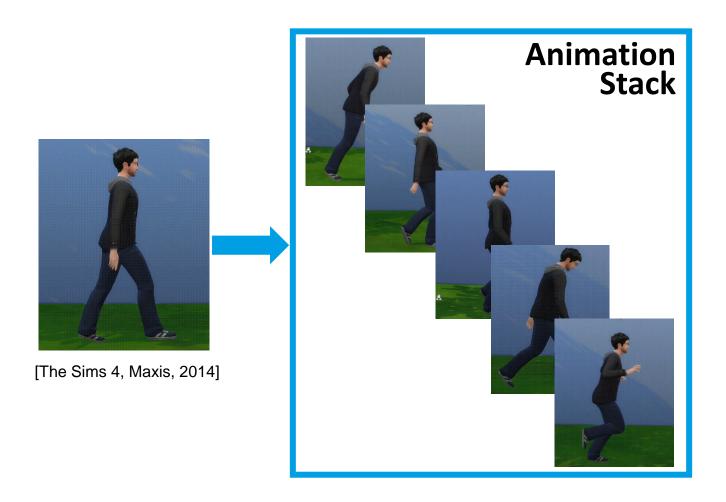
#### **PROBLEM**

 New Animation for each Emotion

Variants of Baseline

 Repeat Process for each Motion

 Time Consuming & Expensive



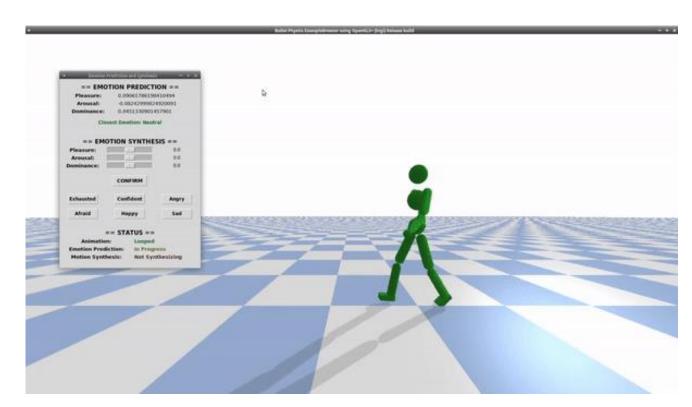
## SOLUTION

Automatic

Real-Time

 No Additional Data or Training Required

 Works with both Kinematic and Policy-Based Physics-Enabled characters



**Emotionally Expressive Motion Controller** 

## **RELATED WORK – DeepMimic & Spacetime Bounds**



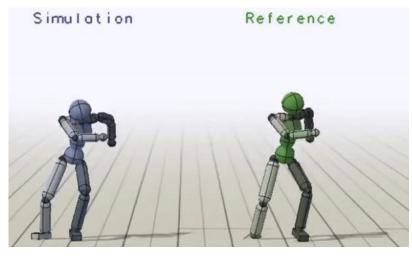
[Bandai-Namco Research Inc., 2022]



[https://youtu.be/GuBEup\_90EQ?t=350, 2020]



[DeepMimic, Li-Ke Ma et al., 2021]

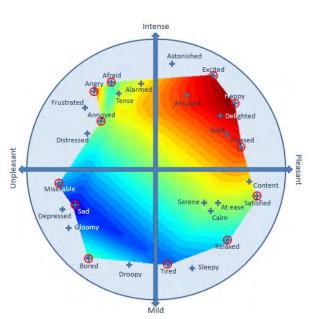


[Spacetime Bounds, Xue Bin Peng et al., 2018]

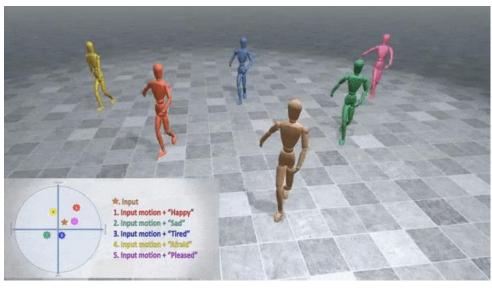
#### Problems:

- No way to explicitly audit the outcome animation
- No way to tweak a character's motion after training

#### **RELATED WORK – Emotion Control of Dance Movements**



	Basic LMA Features f <sup>i</sup>		Derived Features f <sup>i</sup>			
		Description	max	min	std	mean
Вору	$f^1$	Left foot-hip distance	f1	f <sup>2</sup>	f <sup>3</sup>	f <sup>4</sup>
	$f^2$	Right foot-hip distance	f <sup>5</sup>	f <sup>6</sup>	f <sup>7</sup>	f <sup>8</sup>
	$f^3$	Left hand-shoulder distance	f°9	f 10	f 11	f 12
	f <sup>4</sup>	Right hand-shoulder distance	$\tilde{f}^{13}$	$\tilde{f}^{14}$	f 15	f 16
	f <sup>5</sup>	Hands distance	$\tilde{f}^{17}$	$\tilde{f}^{18}$	f 19	$\hat{f}^{20}; \hat{f}^{1}$
	f <sup>6</sup>	Left hand-head distance	$\tilde{f}^{21}$	$\tilde{f}^{22}$	$\tilde{f}^{23}$	$\tilde{f}^{24}$
	$f^7$	Right hand-head distance	$\tilde{f}^{25}$	$\tilde{f}^{26}$	$\tilde{f}^{27}$	$\tilde{f}^{28}$
	f <sup>8</sup>	Left hand-hip distance	f <sup>29</sup>	f <sup>30</sup>	f <sup>31</sup>	$\hat{f}^{32}; \hat{f}^{2}$
	f <sup>9</sup>	Right hand-hip distance	f <sup>33</sup>	Ĵ <sup>34</sup>	f 35	$\hat{f}^{36}; \hat{f}^{3}$
	f <sup>10</sup>	Hip-ground distance	f <sup>37</sup>	f <sup>38</sup>	f <sup>39</sup>	$\hat{f}^{40}; \hat{f}^{4}$
	f <sup>11</sup>	Hip-ground minus feet-hip	f'41	f*42	f*43	f*44
	$f^{12}$	Feet distance	f 45	$\tilde{f}^{46}$	$\tilde{f}^{47}$	$\tilde{f}^{48}; \hat{f}^{5}$
	$f^{13}$	Left hand and chest	f 113	f*114	f*115	$\tilde{f}^{116}$ ; $\hat{f}^{30}$
	f14	Right hand and chest	$\tilde{f}^{117}$	$\tilde{f}^{118}$	$\tilde{f}^{119}$	$\hat{f}^{120}; \hat{f}^{31}$
	$f^{15}$	Deceleration peaks				$\tilde{f}^{49}; \hat{f}^{6}$
	f <sup>16</sup>	Pelvis velocity	₹50		f <sup>51</sup>	f <sup>52</sup> ; f <sup>7</sup>
	f <sup>17</sup>	Left hand velocity	$\tilde{f}^{53}$		$\tilde{f}^{54}$	₹55; £8
	f18	Right hand velocity	₹56		f 57	f <sup>58</sup> ; f <sup>9</sup>
	f 19	Left foot velocity	₹59		₹60	$\hat{f}^{61}; \hat{f}^{10}$
RT	f <sup>20</sup>	Right foot velocity	₹61		₹61	f'64; f11
EFFORT	f <sup>21</sup>	Pelvis acceleration	$\tilde{f}^{65}; \hat{f}^{12}$		766	, ,,
Щ	f <sup>22</sup>	Left hand acceleration	f <sup>67</sup> ; f <sup>13</sup>		₹68	
	f <sup>23</sup>	Right hand acceleration	$\tilde{f}^{69}$ ; $\hat{f}^{14}$		f70	
	f <sup>24</sup>	Left foot acceleration	$\hat{f}^{71}$ ; $\hat{f}^{15}$		₹72	
	f 25	Right foot acceleration	$\tilde{f}^{73}$ : $\hat{f}^{16}$		£74	
	f <sup>26</sup>	Jerk	f <sup>75</sup> ; f <sup>17</sup>		j 76	
	f27	Volume (5 joints)	£77	₹ <sup>78</sup>	f*79	$\tilde{f}^{80}$ : $\hat{f}^{18}$
	f 28	Volume (All joints)	₹81	₹82	₹83	f <sup>84</sup> ; f <sup>19</sup>
	f <sup>29</sup>	Torso height	₹85	₹86	₹87	₹88; Ê20
Æ	f30	Hands level				f89_f91; f21_f23
SHAPE	f31	Volume (upper body)	f*97	f*98	f*99	₹100. £26
On.	f32	Volume (lower body)	f 101	₹102	₹103	f 104; f 27
	f <sup>33</sup>	Volume (right side)	₹105	₹106	₹107	f 108; f 28
	f34	Volume (left side)	f109	₹110	f*111	₹112, <b>£</b> 29
	f35	Total distance			<b>-</b> /	f <sup>92</sup> ; f <sup>24</sup>
SPACE	f36	Area per second	£93	₹94	₹95	f <sup>96</sup> : f <sup>25</sup>
SP.	f <sup>37</sup>	Total volume				₹121



[Emotion Control of Unstructured Dance Movements, Andreas Aristidou et al., 2017]

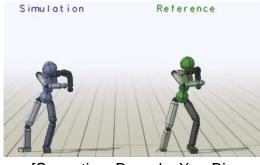
#### Problems:

- Does not work with learned Policy-Based Physics-Enabled Controllers
- Changes take time to apply
- Focuses on non-generic dance animations

#### **RELATED WORK – Emotion Control of Dance Movements**

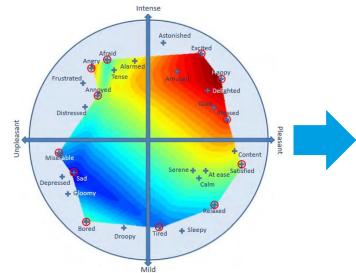


[DeepMimic, Li-Ke Ma et al., 2021]



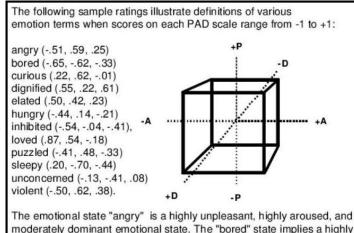
[Spacetime Bounds, Xue Bin Peng et al., 2018]

#### **RCM Emotional Model**



[Emotion Control of Unstructured Dance Movements, Andreas Aristidou et al., 2017]

#### PAD Emotional Model



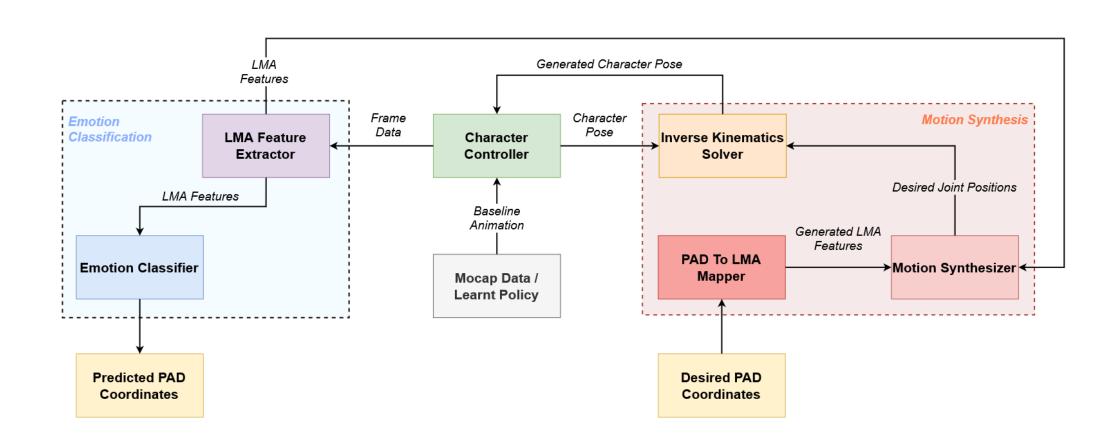
[Joost Broekens et al., 2004]

unpleasant, highly unaroused, and moderately submissive state.

#### Problems:

- Does not work with learned Policy-Based Physics-Enabled Controllers
- Changes take time to apply
- Focuses on non-generic dance animations

#### **EMOTIONALLY EXPRESSIVE MOTION CONTROLLER**

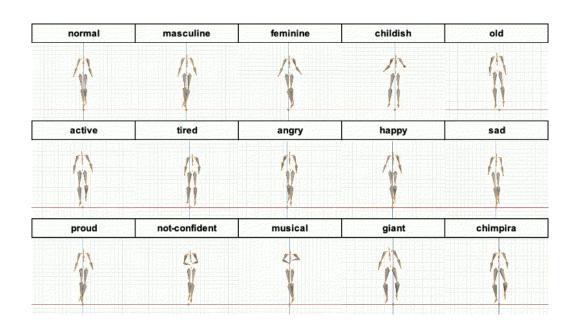


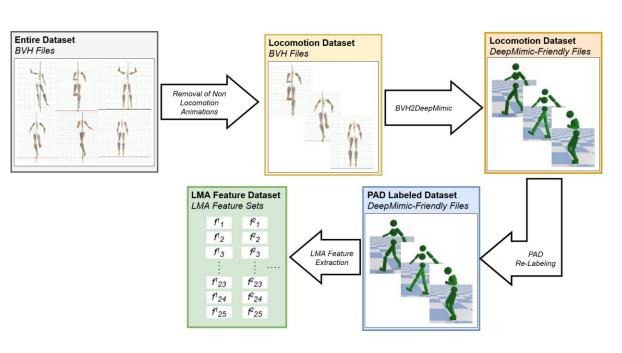
#### DATASET

 Various Motions in different Emotional Styles

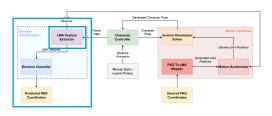
Only Locomotion Animations were kept

 78551 LMA Feature Sets in 14 different Emotional Styles





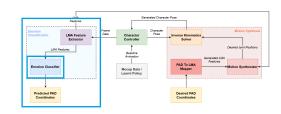
## LMA FEATURE EXTRACTOR

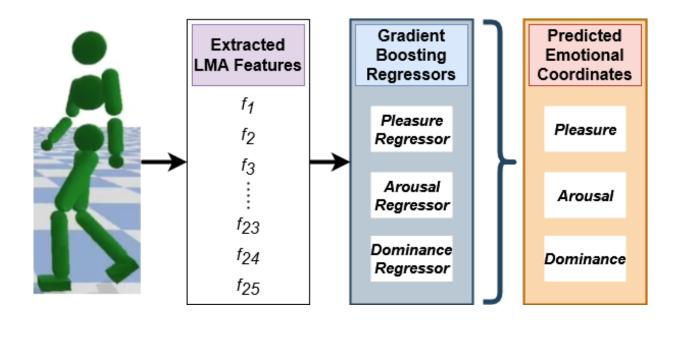


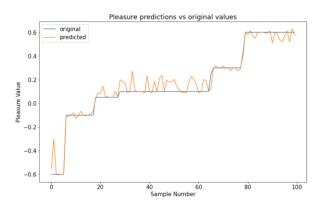
LMA Feature	f	LMA Category
Max Hand Distance	$f_1$	Body
Avg. Left Hand - Hip Distance	$f_2$	Body
Avg. Right Hand - Hip Distance	$f_3$	Body
Max Stride Length	$f_4$	Body
Avg. Left Hand - Chest Distance	$f_5$	Body
Avg. Right Hand - Chest Distance	$f_6$	Body
Avg. Left Elbow - Hip Distance	$f_7$	Body
Avg. Right Elbow - Hip Distance	$f_8$	Body
Avg. Chest - Pelvis Distance	$f_9$	Body
Avg. Neck - Chest Distance	$f_{10}$	Body
Avg. Total Body Volume	$f_{11}$	Shape
Avg. Lower Body Volume	$f_{12}$	Shape
Avg. Upper Body Volume	$f_{13}$	Shape
Avg. Area between Hands and Neck	$f_{14}$	Shape
Avg. Area between Feet and Hip	$f_{15}$	Shape
Left Hand Speed	$f_{16}$	Effort
Right Hand Speed	$f_{17}$	Effort
Left Foot Speed	$f_{18}$	Effort
Right Foot Speed	$f_{19}$	Effort
Neck Speed	$f_{20}$	Effort
Left Hand Acceleration Magnitude	$f_{21}$	Effort
Right Hand Acceleration Magnitude	$f_{22}$	Effort
Left Foot Acceleration Magnitude	$f_{23}$	Effort
Right Foot Acceleration Magnitude	$f_{24}$	Effort
Neck Acceleration Magnitude	$f_{25}$	Effort

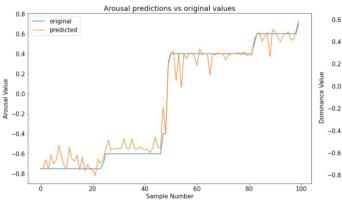
```
"frame_counter": index of the frame at which LMA features were computed,
"label": PAD Emotional Coordinates (3D),
"lma_features": [
     max hand_distance (1D),
     average l_hand_hip_distance (1D),
average r_hand_hip_distance (1D),
max stride length (distance between left and right foot) (1D),
      average l_hand_chest_distance (1D),
     average r_hand_chest_distance (1D),
average l_elbow_hip_distance (1D),
average r_elbow_hip_distance (1D),
     average chest_pelvis_distance (1D),
     average neck_chest_distance (1D),
     average total_body_volume (1D),
average lower_body_volume (1D),
average upper_body_volume (1D),
triangle area between hands and neck (1D),
      triangle area between feet and root (1D),
     1_hand speed (1D),
r_hand speed (1D),
1_foot_speed (1D),
      r_foot_speed (1D),
      neck speed (1D),
     l_hand acceleration magnitude (1D),
r_hand acceleration magnitude (1D),
l_foot acceleration magnitude (1D),
      r_foot acceleration magnitude (1D),
     neck acceleration magnitude (1D)
```

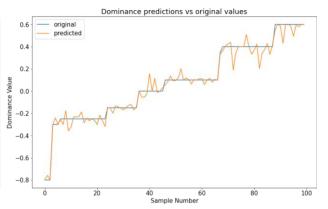
## LMA TO PAD REGRESSION

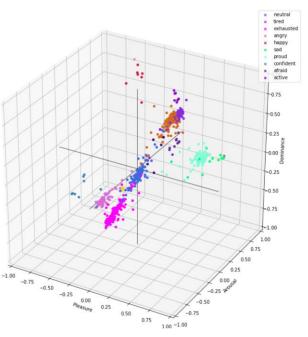




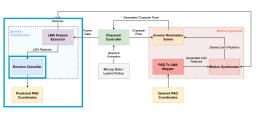


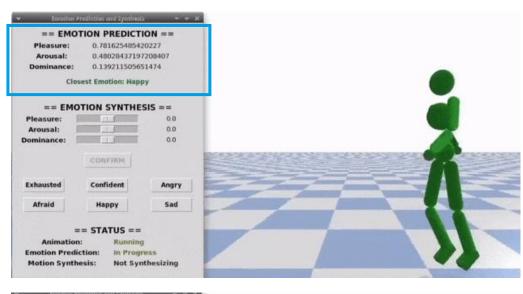


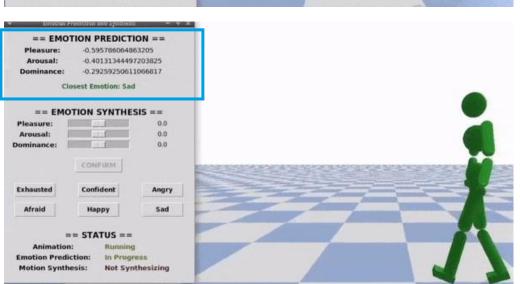


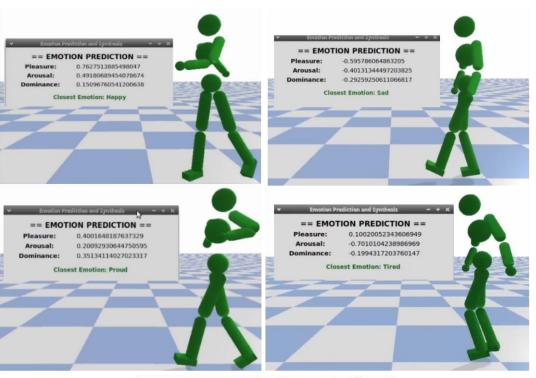


## **EMOTIONAL CLASSIFICATION**



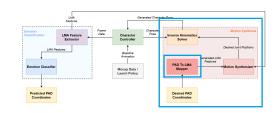


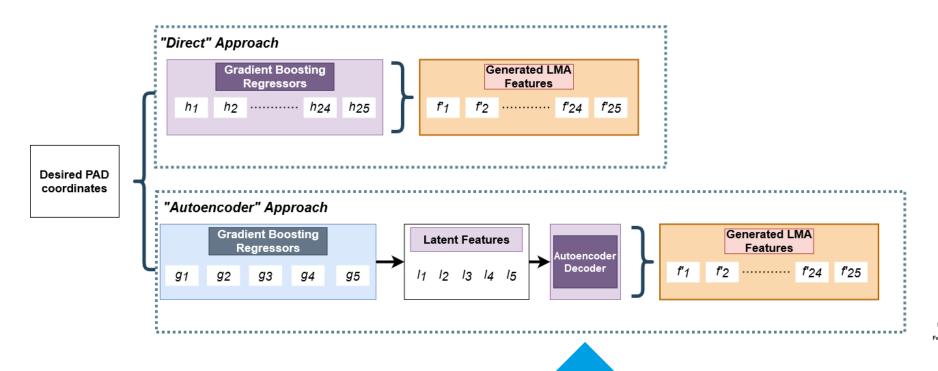


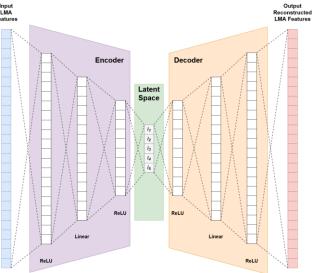




## PAD TO LMA REGRESSION





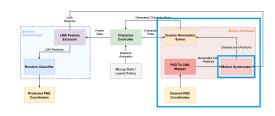


## **MOTION SYNTHESIS**

- Compute new desired positions/rotations for core joints
- 6 Heuristic Rules

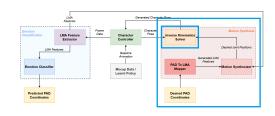
 Coefficients to represent the difference between Baseline's and Generated LMA Features

$$\sum_{t} \| \hat{f} - f_t c \|^2$$



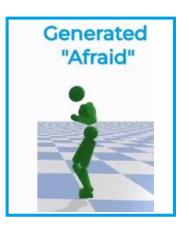
Rule	Associated LMA Features
g1: Modifies Hip Height Raises or lowers the character's Hip, changing the body volume.	Avg. Chest-Pelvis Distance $(f_8)$ ; Avg. Total Body Volume $(f_{10})$ ; Avg. Lower Body Volume $(f_{11})$ ; Avg. Area Feet-Hips Triangle $(f_{14})$ ;
g2: Modifies the Chest's Position Raises or lowers the character's Chest, making their back appear slumped over or straight.	Avg. Chest-Pelvis Distance $(f_8)$ ; Avg. Total Body Volume $(f_{10})$ ; Avg. Upper Body Volume $(f_{12})$ ;
g3: Modifies the Hands' Positions Pulls each Hand towards or away from the character's body. Also raises or lowers each Hand towards the character's chest.	Max Hand Distance $(f_0)$ ; Avg. Left Hand-Hip Distance $(f_1)$ ; Avg. Right Hand-Hip Distance $(f_2)$ ; Avg. Left Hand-Chest Distance $(f_4)$ ; Avg. Right Hand-Chest Distance $(f_5)$ ; Avg. Total Body Volume $(f_{10})$ ; Avg. Upper Body Volume $(f_{12})$ ; Avg. Area Hands-Neck Triangle $(f_{13})$ ;
g4: Modifies Elbows Positions Pulls each Elbow towards or away from the character's body, changing their upper volume.	Avg. Left Elbow-Hip Distance $(f_6)$ ; Avg. Right Elbow-Hip Distance $(f_7)$ ; Avg. Total Body Volume $(f_{10})$ ; Avg. Upper Body Volume $(f_{12})$ ;
g5: Modifies the Feets' Positions Increases or decreases the distance between each Foot, changing the stride length.	Max Stride Length $(f_3)$ ; Avg. Total Body Volume $(f_{10})$ ; Avg. Lower Body Volume $(f_{11})$ ; Avg. Area Feet-Hips Triangle $(f_{14})$ ;
g6: Modifies Neck Tilt Tilts the character's Neck towards or away from their chest.	Avg. Neck-Chest Distance $(f_9)$ ; Avg. Total Body Volume $(f_{10})$ ; Avg. Upper Body Volume $(f_{12})$ ;

## **NVERSE KINEMATICS**



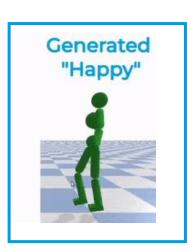


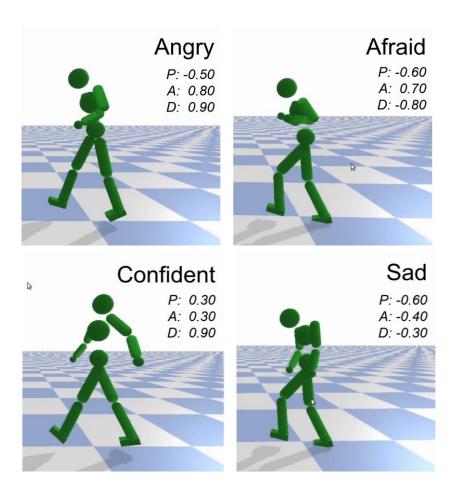






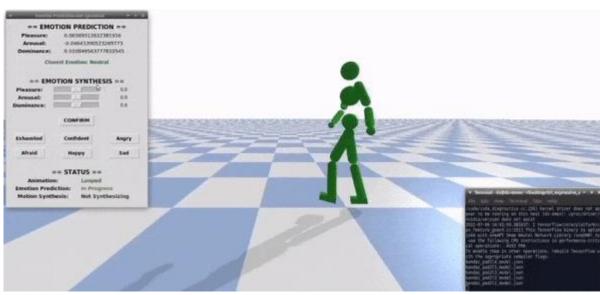


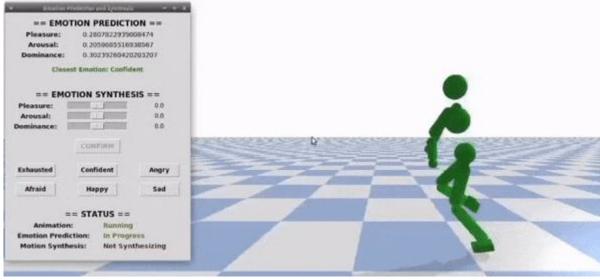




#### **EMOTIONALLY EXPRESSIVE MOTION CONTROLLER**

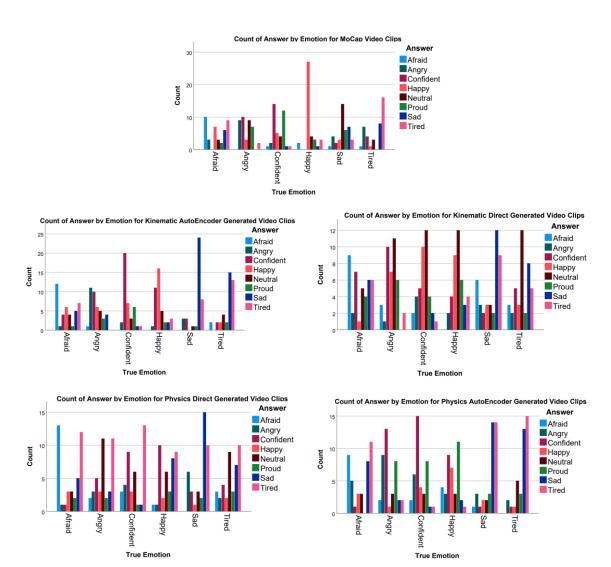




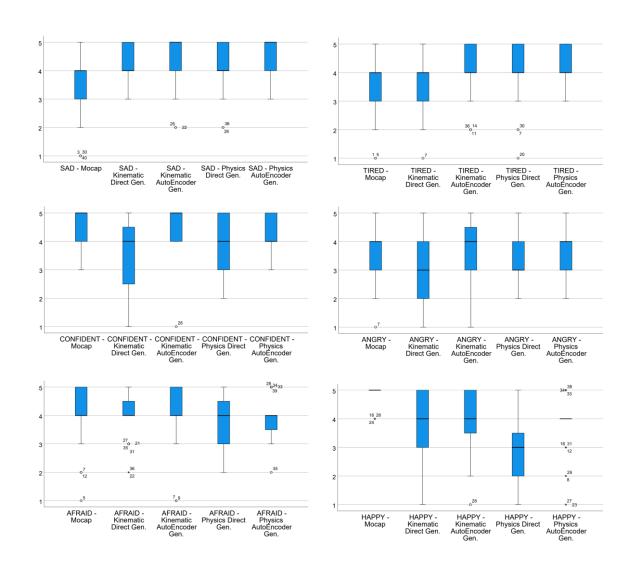


## **USER TESTS**

#### **Emotional Selection Task**

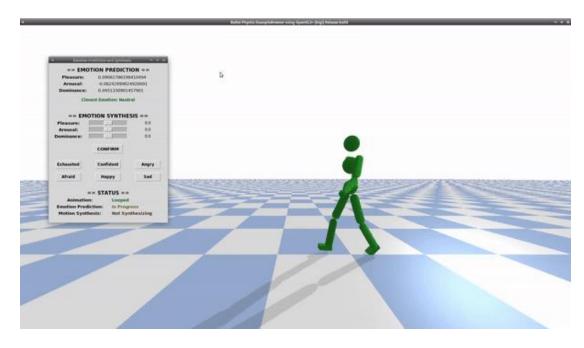


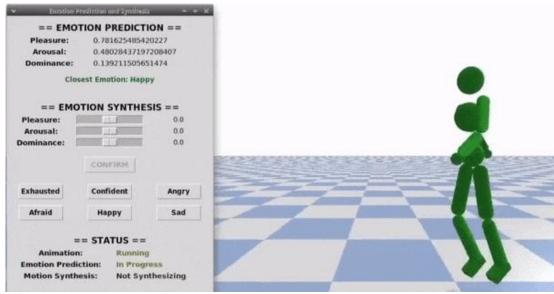
#### **Primed Emotional Agreement Task**



## CONCLUSION

- Automatic System for Emotionally Expressive Motion Synthesis of Locomotion Animations
- Works with both Kinematic and Policy-Based Physics-Enabled Character Controllers
- Emotions specified using the PAD Model
- Emotional Prediction and Motion Synthesis in Real Time
- No need for extra data or training
- Quality of synthesized motions validated through User Tests
- Work accepted for publishing in IEEE ISM 2022





## Thank you for listening!

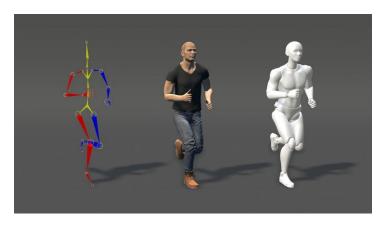


## **NDEX**

- Motivation
- Related Work
- Emotionally Expressive Motion Controller
- User Testing
- Conclusion

## **BACKGROUND** – Computer Animation

[Bandai-Namco Research Inc., 2022]



[https://youtu.be/z93e5\_7P54g, 2020]

#### **Kinematic Controllers**



[Blender, 2022]

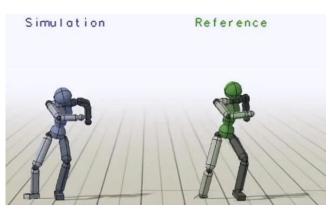


[https://youtu.be/GuBEup\_90EQ?t=350, 2020]



[DeepMimic, Li-Ke Ma et al., 2021]

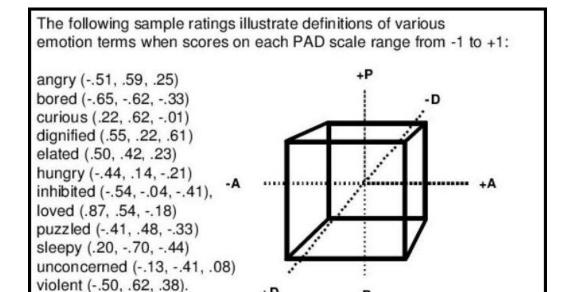




[Spacetime Bounds, Xue Bin Peng et al., 2018]

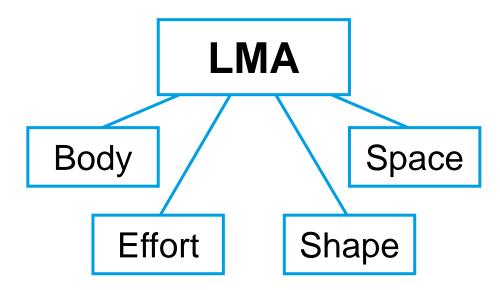
#### **BACKGROUND – Emotional Models & Laban Movement Analysis**

#### PAD Emotional Model



The emotional state "angry" is a highly unpleasant, highly aroused, and moderately dominant emotional state. The "bored" state implies a highly unpleasant, highly unaroused, and moderately submissive state.

[Joost Broekens et al., 2004]



Feature	Category
Hands Distance	Body
Hip-Ground Distance	Body
Left Foot Velocity	Effort
Pelvis Acceleration	Effort
Volume (All joints)	Shape
Torso Height	Shape
Total Distance	Space
Area Per Second	Space