

$$f(a, b)$$

$$\cancel{x'}$$

$$\frac{\partial f(a, b)}{\partial a}$$

$$\frac{\partial f(a, b)}{\partial b}$$

$$\frac{\partial^2 f(a, b)}{\partial a^2}$$

$$\frac{\partial^2 f(a, b)}{\partial b^2}$$

$$\frac{\partial^2 f(a, b)}{\partial a \partial b}$$

$$\frac{\partial^2 f(a, b)}{\partial b \partial a}$$

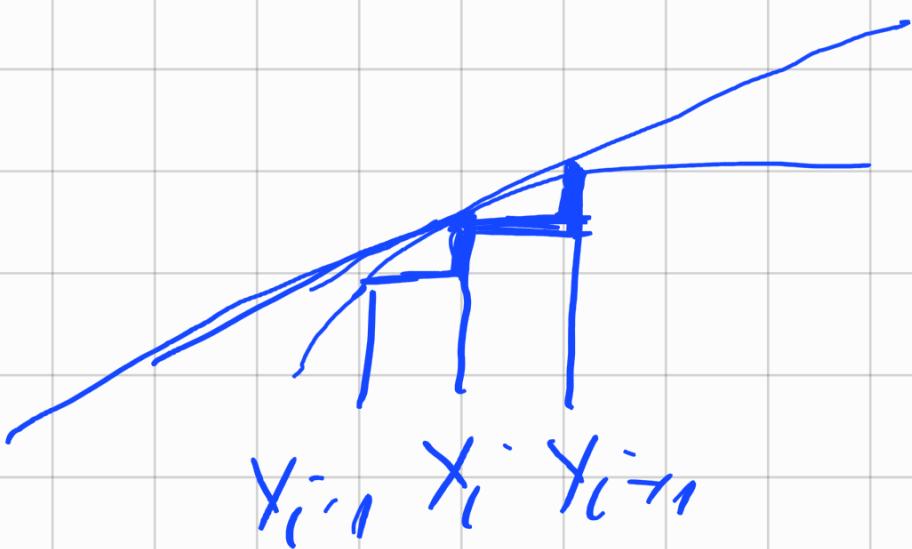
$$f'(x_0) = \lim_{\Delta x \rightarrow 0} \frac{f(x_1) - f(x_0)}{\Delta x}$$

$$\Delta x = x_1 - x_0$$

$$\Delta x \rightarrow 0 \quad \cancel{\Delta x}$$

$$f'(x_0) = \frac{f(x_1) - f(x_0)}{\Delta x}$$

$$f'(x_i) = \frac{f(x_{i+1}) - f(x_i)}{\Delta x}$$



$$f(x_{i+1}) - f(x_i) =$$

$$f(x_i) - f(x_{i-1})$$

$$f'(x_i) = \frac{f(x_i) - f(x_{i-1})}{\Delta x}$$

$$f(a_{i,0})$$

b'

$$\underline{f(a_{i,0})}$$

$$\frac{\partial^2 f(a_{i,0}, b)}{\partial a^2} =$$

$$\frac{\partial}{\partial a} \left(\frac{\partial f(a_i, b)}{\partial a} \right) =$$

$$\frac{\partial}{\partial a} \left(\frac{f(a_{i+1}, b) - f(a_i, b)}{\Delta a} \right) =$$

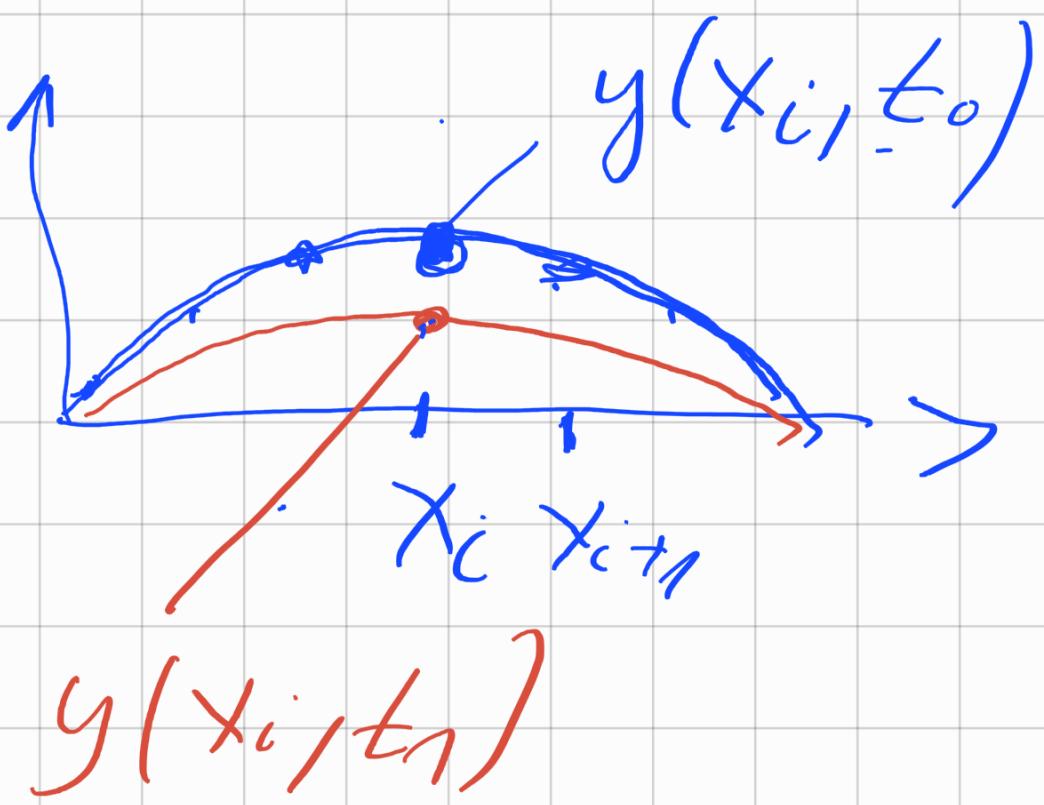
$$\frac{\partial f(a_{i+1}, b)}{\partial a} - \frac{\partial f(a_i, b)}{\partial a}$$

$\underbrace{\hspace{10em}}$
 Δa

$$\frac{f(a_{i+1}, b) - f(a_i, b)}{\Delta a} = \frac{f(a_i, b) - f(a_{i-1}, b)}{\Delta a} =$$

$$f(a_{i+1}, b) = 2f(a_i, b) + f(a_{i-1}, b)$$

$$\Delta a^2$$



$$\frac{\partial y(x_i, t)}{\partial t} = v(x_i, t)$$

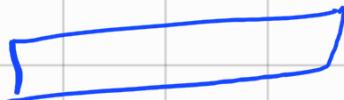
$$\frac{\partial^2 y(x_i, t)}{\partial t^2} = a(x_i, t)$$

α_1

$$\frac{\partial^2 y(x_i, t)}{\partial t^2} = w \frac{\partial^2 y(x_i, t)}{\partial x^2}$$

$$w - \cos t$$

$$w = 1 \frac{m}{s}$$



$$\frac{\partial^2 f(x_i, t)}{\partial x^2} =$$

$$\frac{f(x_{i+1}, t) - 2f(x_i, t) + f(x_{i-1}, t)}{\Delta x}$$

$$\Delta x = \frac{L}{n}$$



$$y(x_0, t_0) = \dots$$

$$y(x_1, t_0) = \dots$$

$$y(x_n, t_0) = \dots$$

$$v(x_0, t_0) = 0$$

$$v(x_1, t_0) = \dots$$

$$v(x_n, t_0) = 0$$

$$a(x_0, t_0) = 0$$

$$a(x_1, t_0) =$$

$$\frac{y(x_2, t_0) - 2y(x_1, t_0) + y(x_0, t_0)}{\Delta x^2}$$

$$y(X_i; t_1) = y(X_i; t_0) + v(X_i; t_0) \cdot s$$

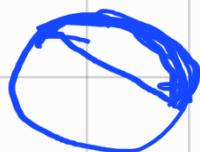
$$v(X_i; t_1) = v(X_i; t_0) + a(X_i; t_0) \cdot s$$

$$a(X_i; t_1) = \dots$$



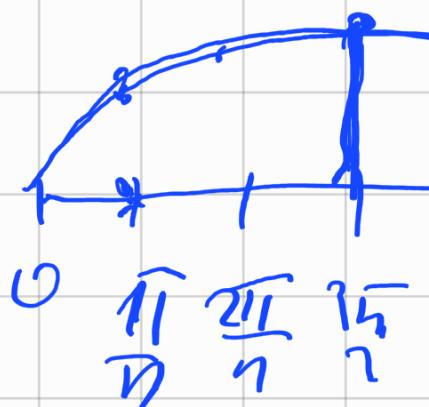
$$L_1 = L$$

A ————— B



$$\angle = \overline{\pi}$$

$$\Delta x = \frac{\angle}{n}$$



n

$$\Delta x = \frac{\pi}{n}$$

$$\Delta x = \frac{\pi}{n}$$

$$y(x_i, t_0) \sim [0] - [1] \cdot t - [1] \cdot t^2$$

$$v(x_i, t_0) \sim [0] + [1] \cdot \sin(\omega t)$$



$$E_K = \sum E_{K_i}$$

$$E_{K_i} = \frac{m_i v_i^2}{2}$$

$$W = 1 \frac{m}{s}$$

$$W = \sqrt{\frac{T}{g}} = 1$$

$$T = g = 1$$

$$m = g \cdot \bar{V}$$



$$\rho = \text{const} \cdot V = \rho \cdot L$$

$$V = L$$

$$\frac{L}{n} = \Delta x$$

$$\rho = \text{const}$$

$$m_i = \Delta x$$

$$E_{K_i} = \frac{\Delta x \cdot v_i^2}{2}$$

$$E_K = \sum_{i=0}^n \frac{\Delta x \cdot v_i^2}{2}$$

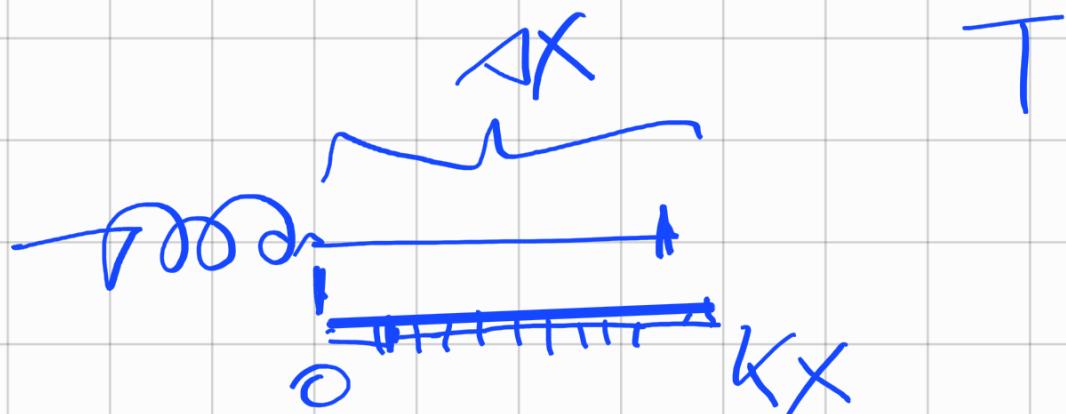
$$E_k = \frac{1}{2} \sum_{i=0}^n V_i$$



E_p



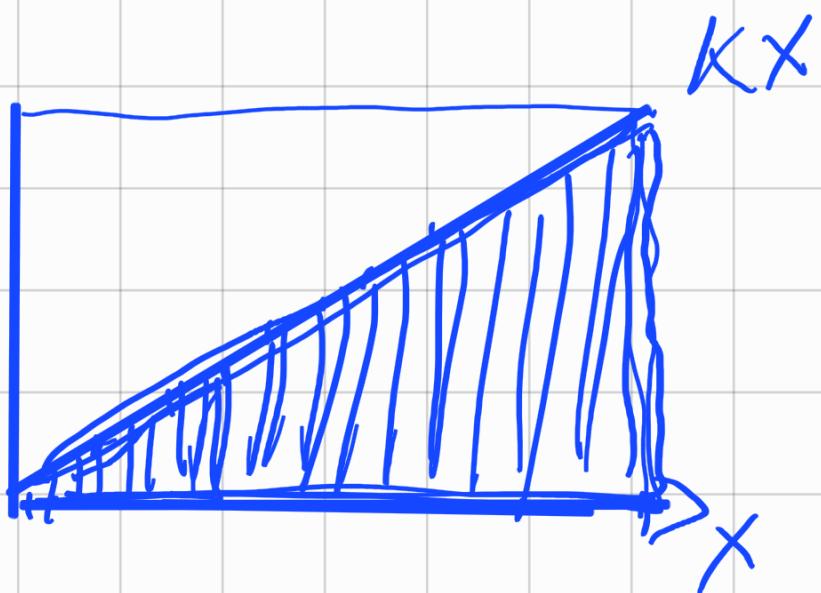
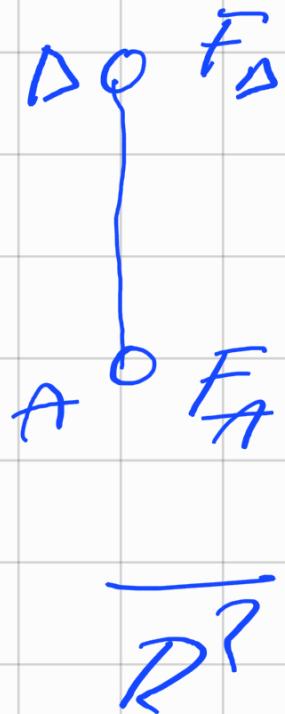
$$F = -k\Delta x$$



$$W = F_s \cdot \Delta X$$

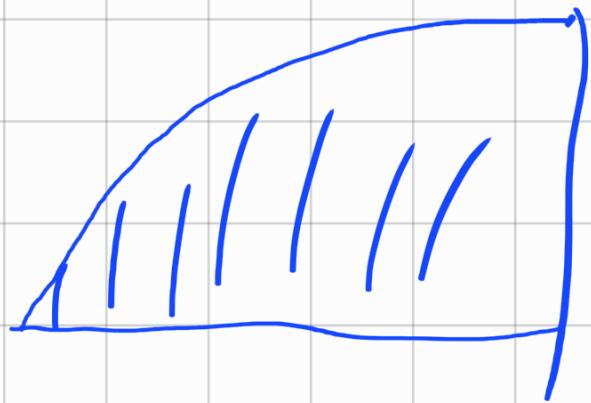
$$F_s = \frac{0 + kx}{2}$$

$$W = \frac{kx^2}{2}$$



$$\int kx \, dx$$

$$k \int x \, dx = k \frac{x^2}{2}$$



$$E_p = \frac{k \Delta y}{2}.$$

$$T = k \Delta x$$

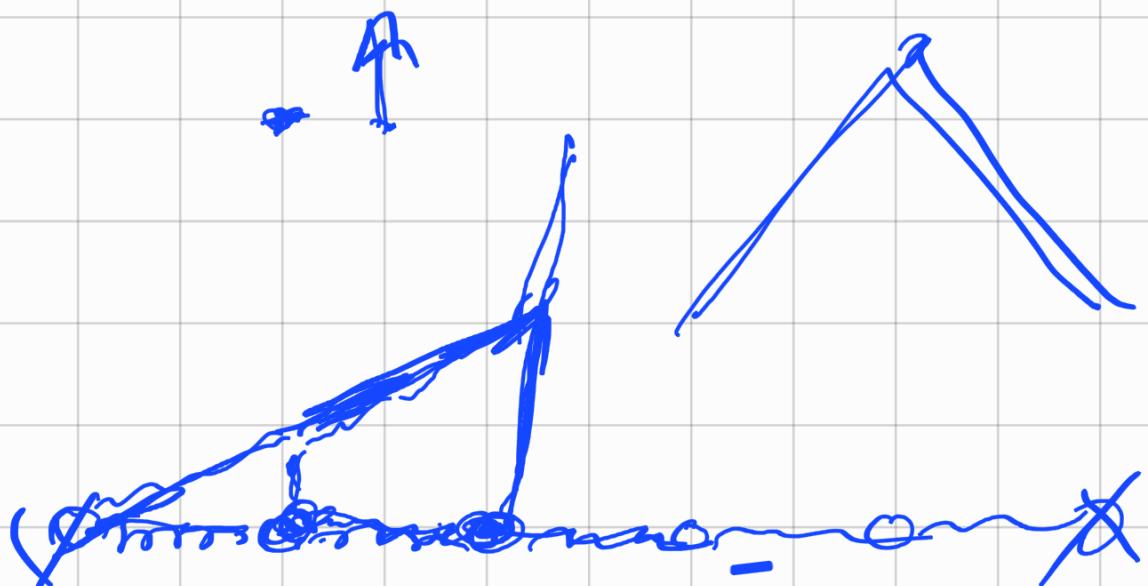
$$1 = k \Delta x \Rightarrow k = \frac{1}{\Delta x}$$

$$E_{p_i} = \frac{1}{\Delta x} \cdot \frac{\Delta y_i}{2}$$

$$E_{\theta} = \sum_{l=0}^n \frac{\Delta y_i^2}{2\Delta x}$$

$$\bar{E}_{\theta} = \frac{1}{2\Delta x} \sum_{l=0}^n \Delta y_i^2$$

$$\Delta y_i = y(x_i) - y(x_{i-1})$$



~~SECRET~~