Cluster Analysis

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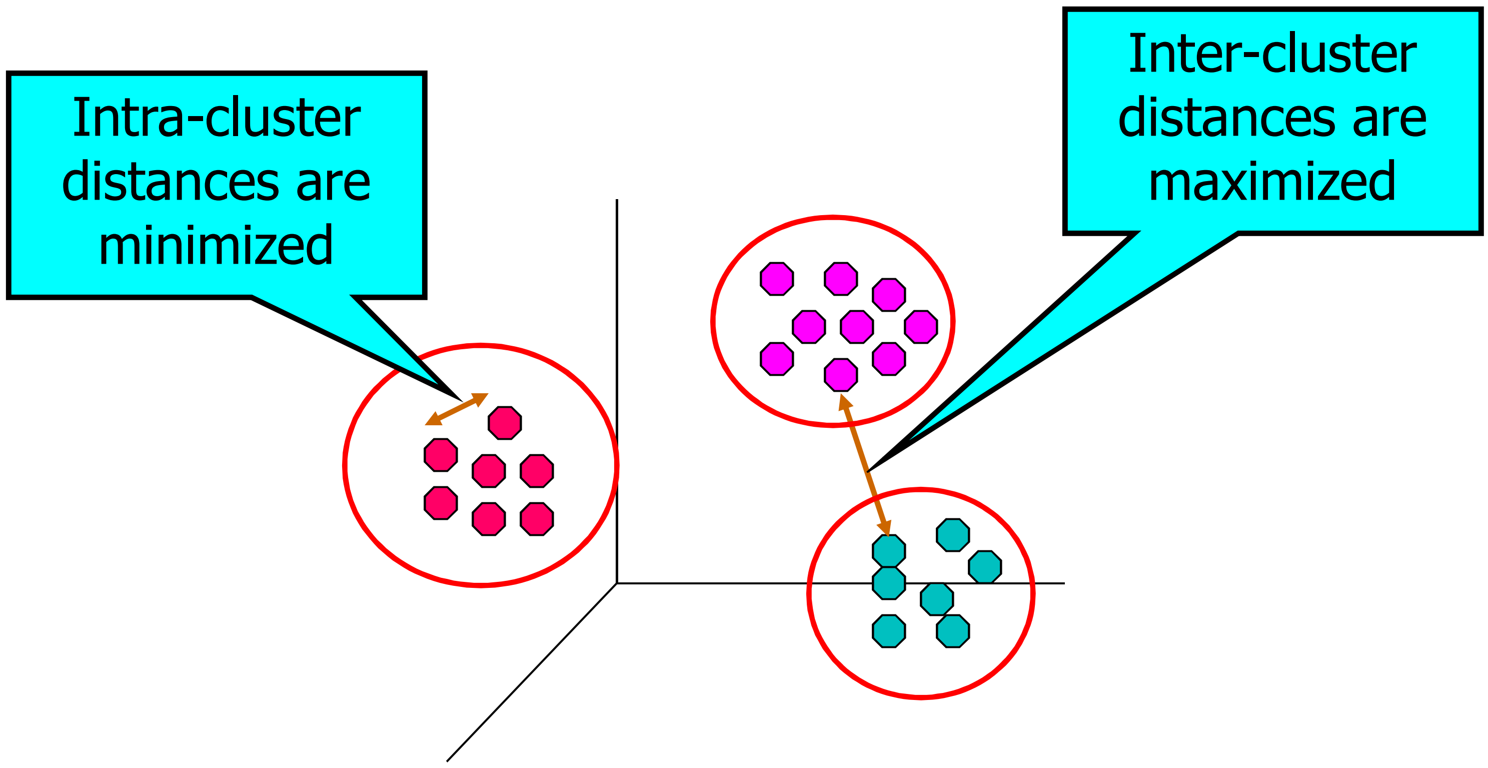
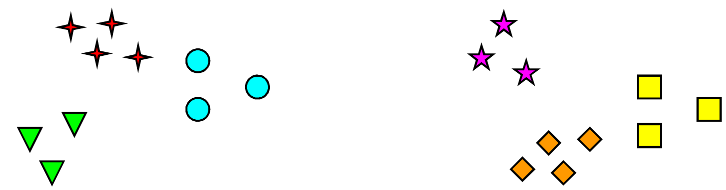
What is Cluster Analysis?

- Finding groups of objects such that the objects in a group will be similar (or related) to one another and different from (or unrelated to) the objects in other groups



Notion of a Cluster can be Ambiguous

How many clusters?



Six Clusters

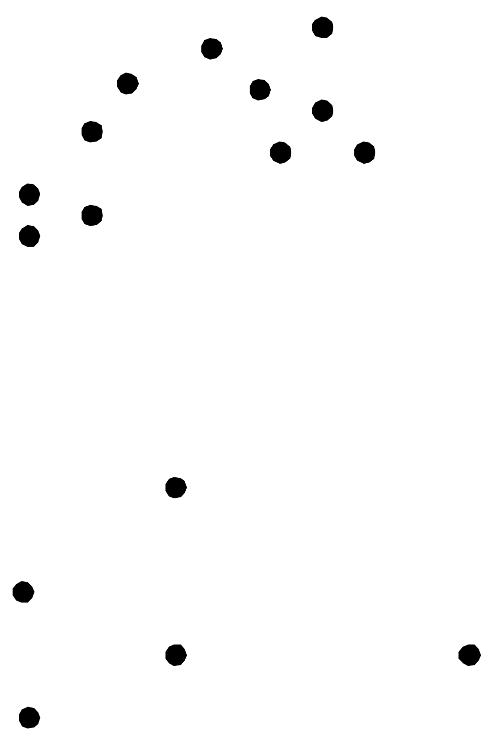
Two Clusters

Four Clusters

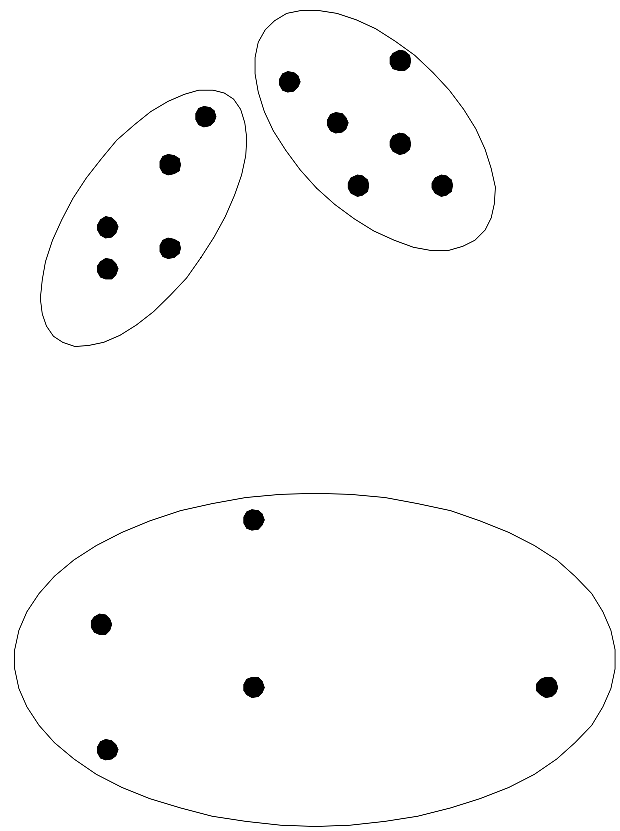
Types of Clusterings

- A clustering is a set of clusters
- Important distinction between hierarchical and partitional sets of clusters
- Partitional Clustering
  - A division of data objects into non-overlapping subsets (clusters) such that each data object is in exactly one subset
- Hierarchical clustering
  - A set of nested clusters organized as a hierarchical tree

Partitional Clustering

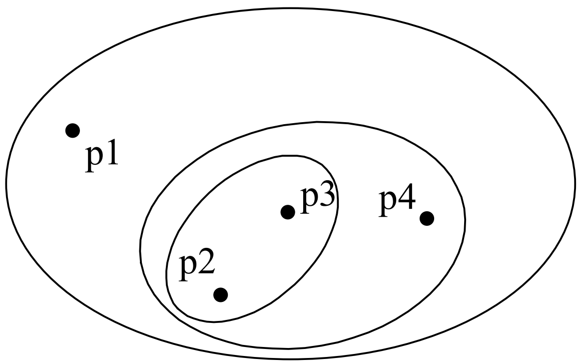


Original Points

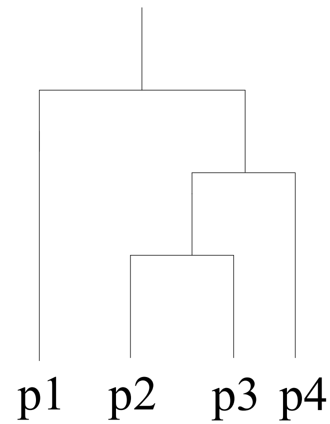


A Partitional Clustering

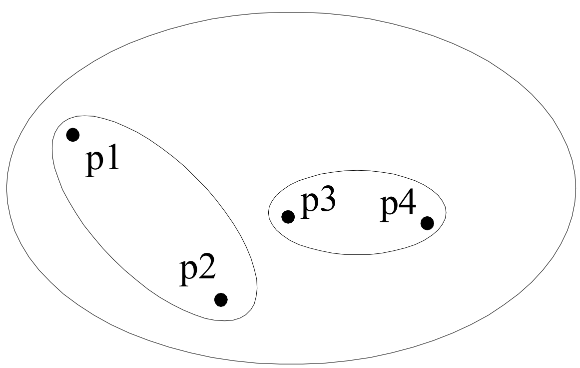
Hierarchical Clustering



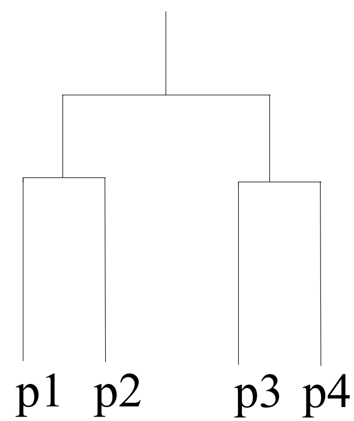
Traditional Hierarchical Clustering



Traditional Dendrogram



Non-traditional Hierarchical Clustering



Non-traditional Dendrogram

Other Distinctions Between Sets of Clusters

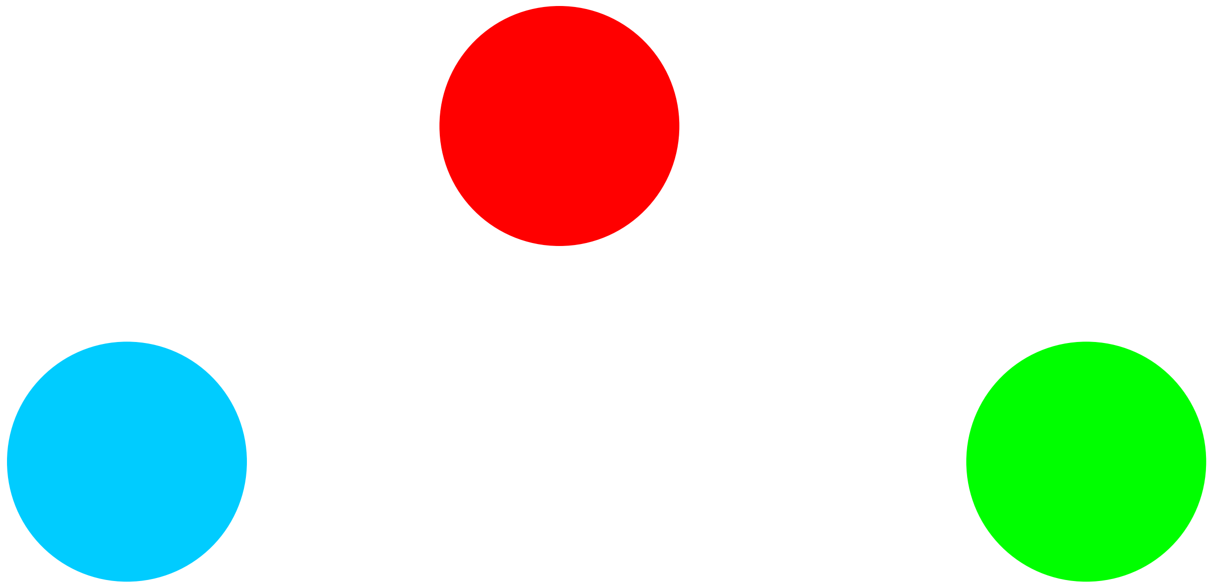
- Exclusive versus non-exclusive
  - In non-exclusive clusterings, points may belong to multiple clusters.
  - Can represent multiple classes or ‘border’ points
- Fuzzy versus non-fuzzy
  - In fuzzy clustering, a point belongs to every cluster with some weight between 0 and 1
  - Weights must sum to 1
  - Probabilistic clustering has similar characteristics
- Partial versus complete
  - In some cases, we only want to cluster some of the data
- Heterogeneous versus homogeneous
  - Clusters of widely different sizes, shapes, and densities

Types of Clusters

- Well-separated clusters
- Center-based clusters
- Contiguous clusters
- Density-based clusters
- Property or Conceptual
- Described by an Objective Function

Types of Clusters: Well-Separated

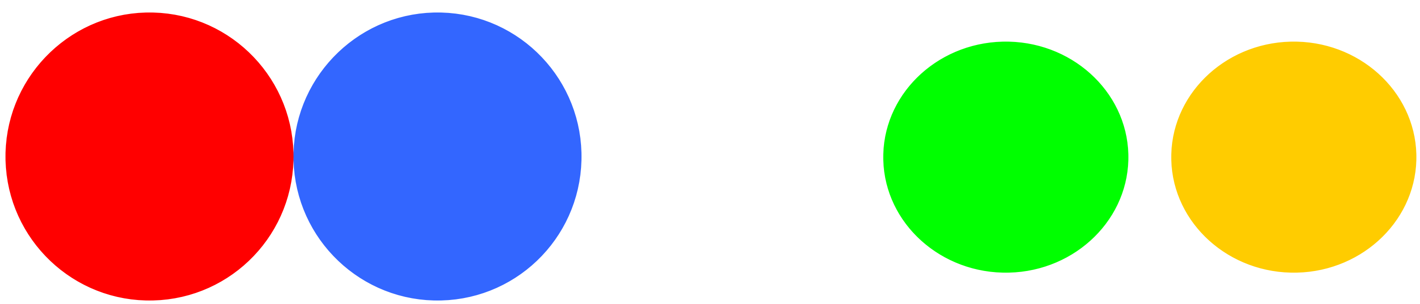
- Well-Separated Clusters:
  - A cluster is a set of points such that any point in a cluster is closer (or more similar) to every other point in the cluster than to any point not in the cluster.



3 well-separated clusters

Types of Clusters: Center-Based

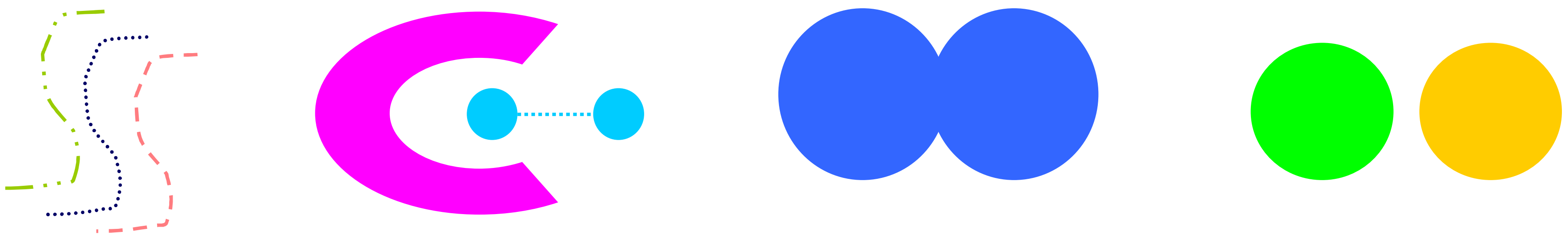
- Center-based
  - A cluster is a set of objects such that an object in a cluster is closer (more similar) to the "center" of a cluster, than to the center of any other cluster
  - The center of a cluster is often a centroid, the average of all the points in the cluster, or a medoid, the most "representative" point of a cluster



4 center-based clusters

Types of Clusters: Contiguity-Based

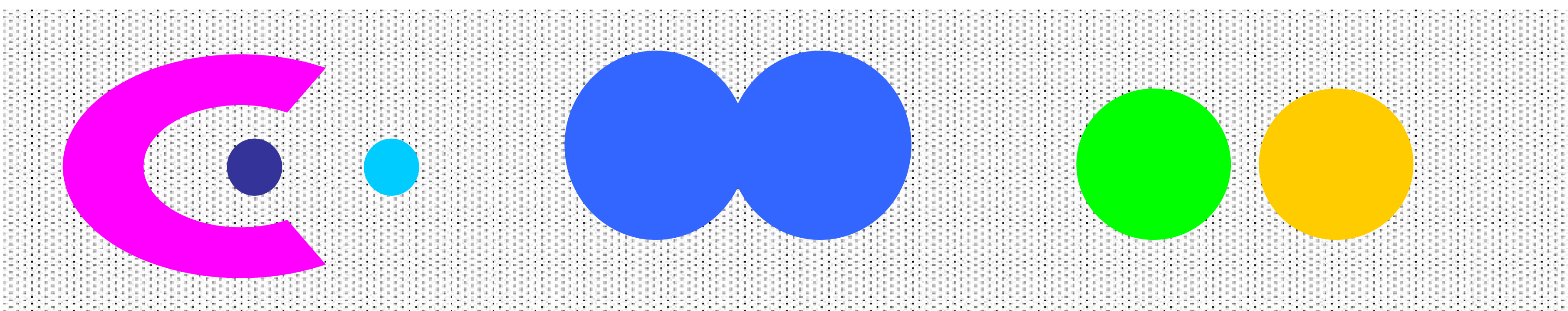
- Contiguous Cluster (Nearest neighbor or Transitive)
  - A cluster is a set of points such that a point in a cluster is closer (or more similar) to one or more other points in the cluster than to any point not in the cluster.



8 contiguous clusters

Types of Clusters: Density-Based

- Density-based
  - A cluster is a dense region of points, which is separated by low-density regions, from other regions of high density.
  - Used when the clusters are irregular or intertwined, and when noise and outliers are present.



6 density-based clusters

Types of Clusters: Conceptual Clusters

- Shared Property or Conceptual Clusters
  - Finds clusters that share some common property or represent a particular concept.

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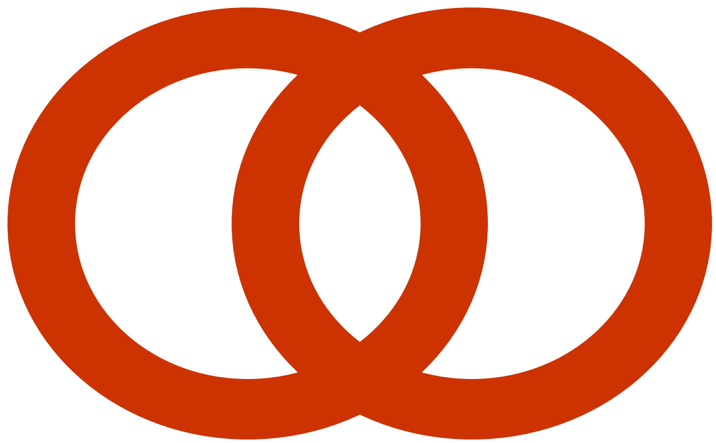


2 Overlapping Circles

Types of Clusters: Objective Function

- Clusters Defined by an Objective Function
  - Finds clusters that minimize or maximize an objective function.
  - Enumerate all possible ways of dividing the points into clusters and evaluate the `goodness' of each potential set of clusters by using the given objective function. (NP Hard)
  - Can have global or local objectives.
    - Hierarchical clustering algorithms typically have local objectives
    - Partitional algorithms typically have global objectives
  - A variation of the global objective function approach is to fit the data to a parameterized model.
    - Parameters for the model are determined from the data.
    - Mixture models assume that the data is a ‘mixture' of a number of statistical distributions.

Clustering Algorithms

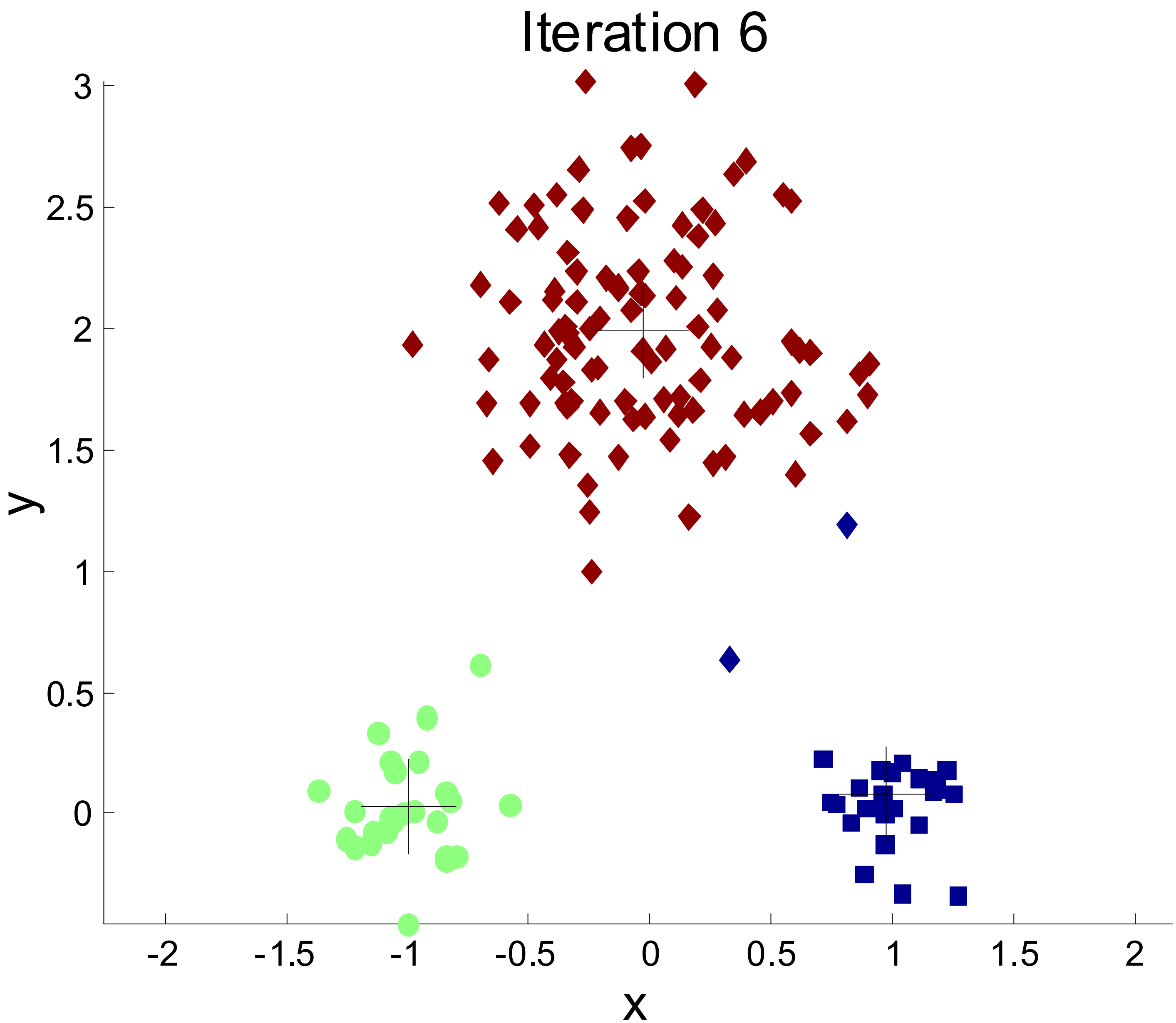
- K-means and its variants
- Hierarchical clustering
- Density-based clustering

K-means Clustering

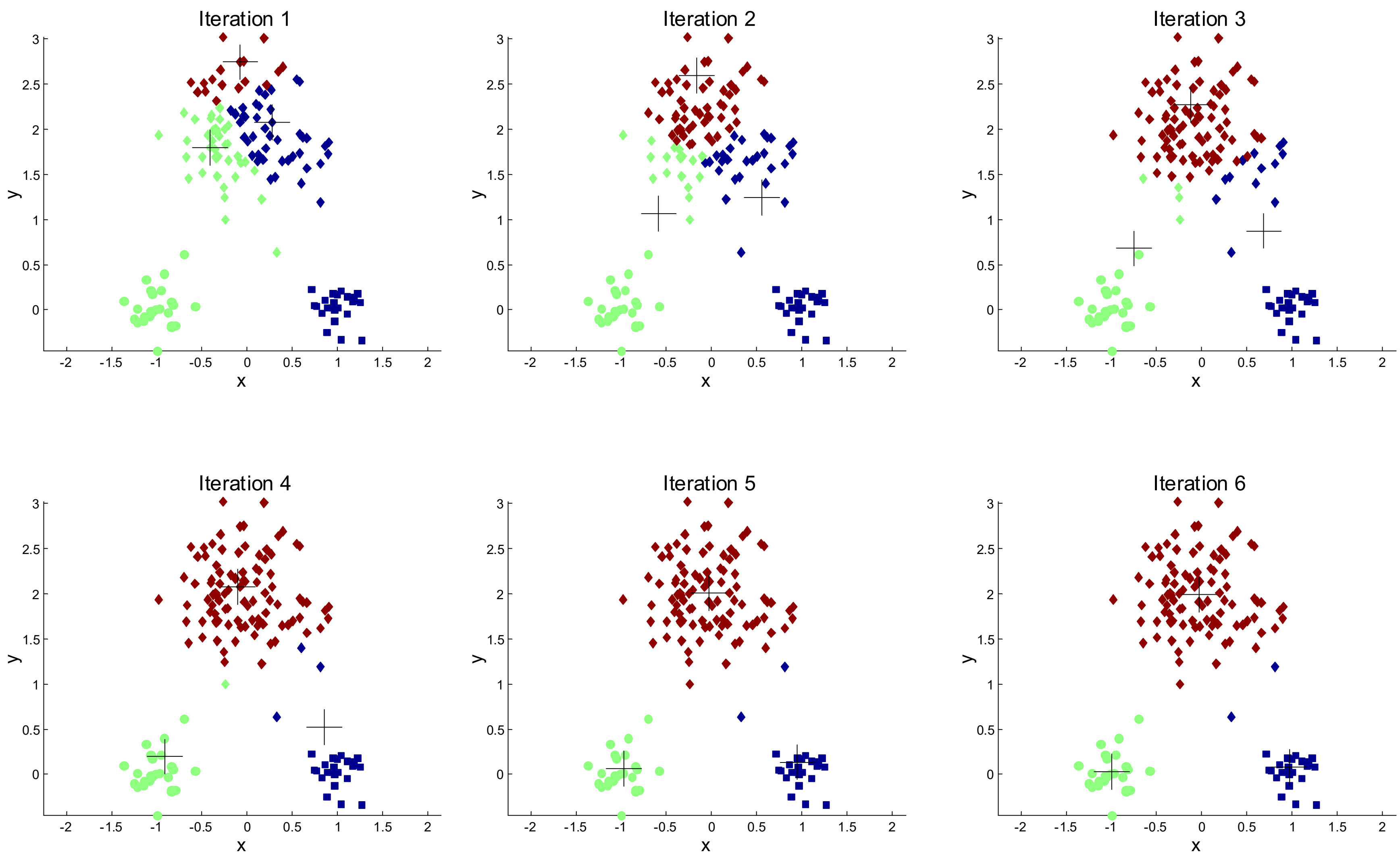
- Partitional clustering approach
- Number of clusters, K, must be specified
- Each cluster is associated with a centroid (center point)
- Each point is assigned to the cluster with the closest centroid
- The basic algorithm is very simple

1: Select K points as the initial centroids.
2: **repeat**
3: Form K clusters by assigning all points to the closest centroid.
4: Recompute the centroid of each cluster.
5: **until** The centroids don't change

Example of K-means Clustering



Example of K-means Clustering



K-means Clustering – Details

- Initial centroids are often chosen randomly.
  - Clusters produced vary from one run to another.
- The centroid is (typically) the mean of the points in the cluster.
- ‘Closeness’ is measured by Euclidean distance, cosine similarity, correlation, etc.
- K-means will converge for common similarity measures mentioned above.
- Most of the convergence happens in the first few iterations.
  - Often the stopping condition is changed to ‘Until relatively few points change clusters’
- Complexity is O(n * K * I * d)
  - n = number of points, K = number of clusters,
    I = number of iterations, d = number of attributes

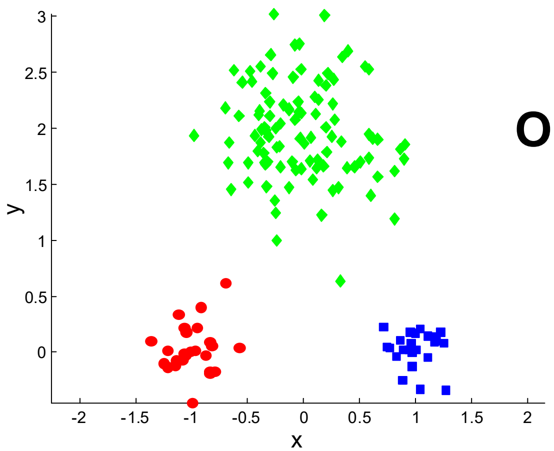
Evaluating K-means Clusters

- Most common measure is Sum of Squared Error (SSE)
  - For each point, the error is the distance to the nearest cluster
  - To get SSE, we square these errors and sum them.

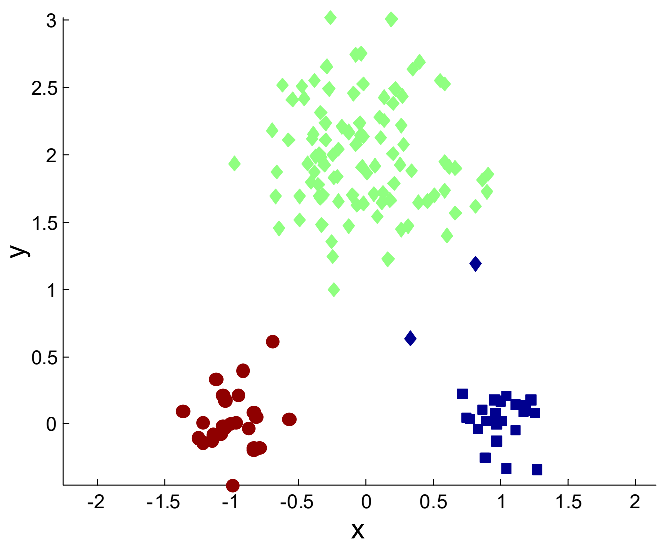
$$SSE = \sum_{i=1}^{K} \sum_{x \in C_i} dist^2(m_i, x)$$

  - x is a data point in cluster C_i and m_i is the representative point for cluster C_i
    - can show that m_i corresponds to the center (mean) of the cluster
  - Given two sets of clusters, we prefer the one with the smallest error
  - One easy way to reduce SSE is to increase K, the number of clusters
    - A good clustering with smaller K can have a lower SSE than a poor clustering with higher K

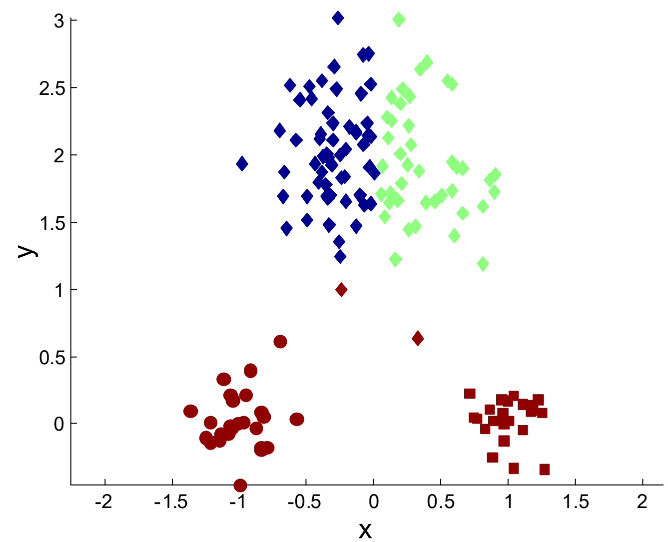
Two different K-means Clusterings



Original Points



Optimal Clustering



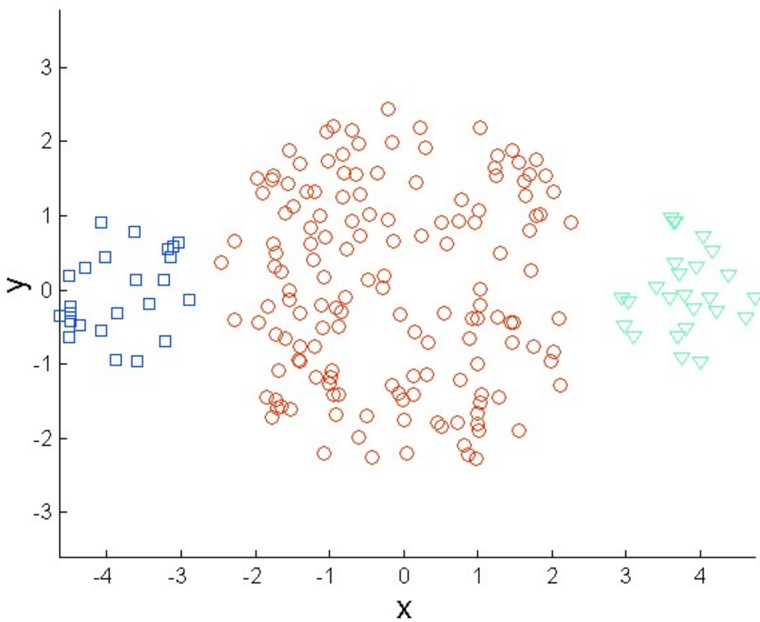
Sub-optimal Clustering

Limitations of K-means

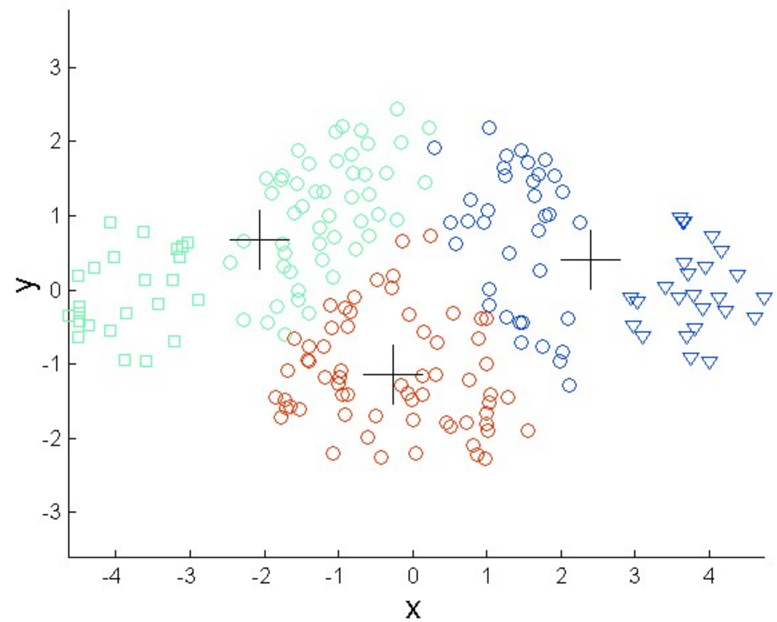
- K-means has problems when clusters are of differing
  - Sizes
  - Densities
  - Non-globular shapes

- K-means has problems when the data contains outliers.

Limitations of K-means: Differing Sizes

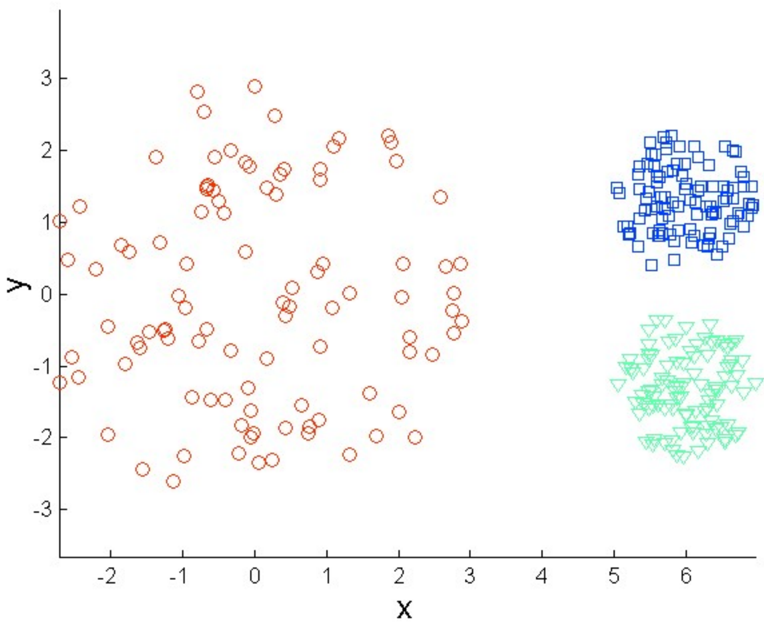


Original Points

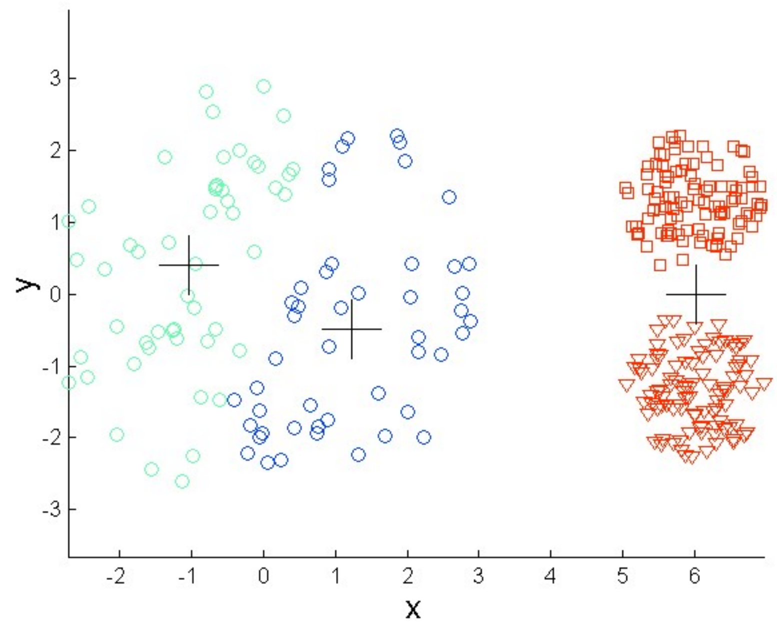


K-means (3 Clusters)

Limitations of K-means: Differing Density

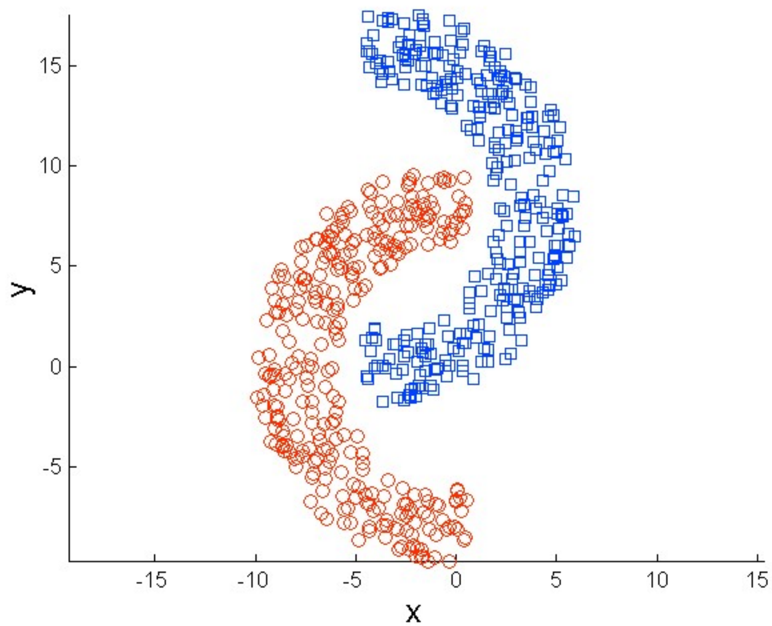


Original Points

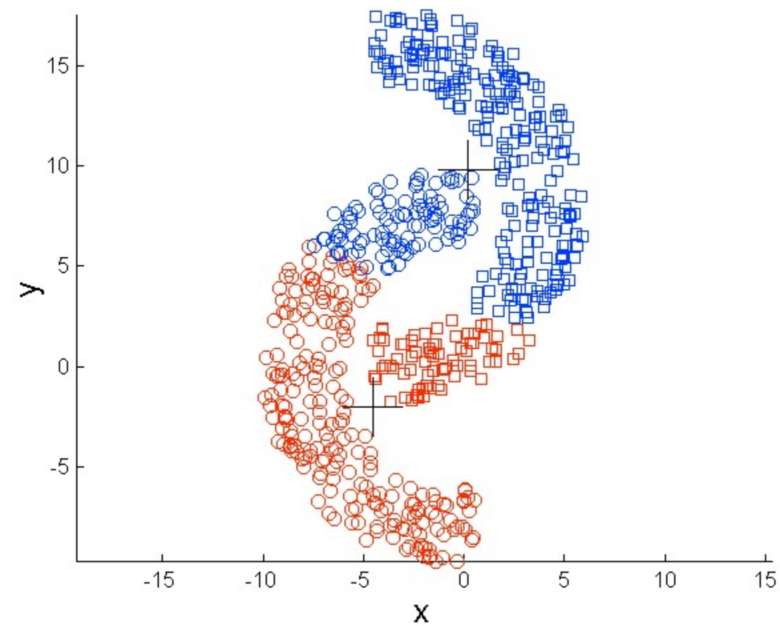


K-means (3 Clusters)

Limitations of K-means: Non-globular Shapes

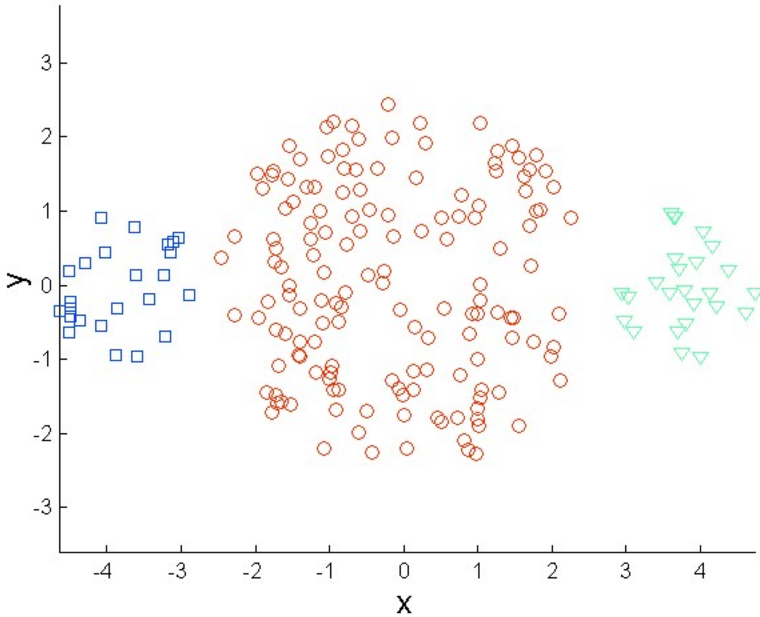


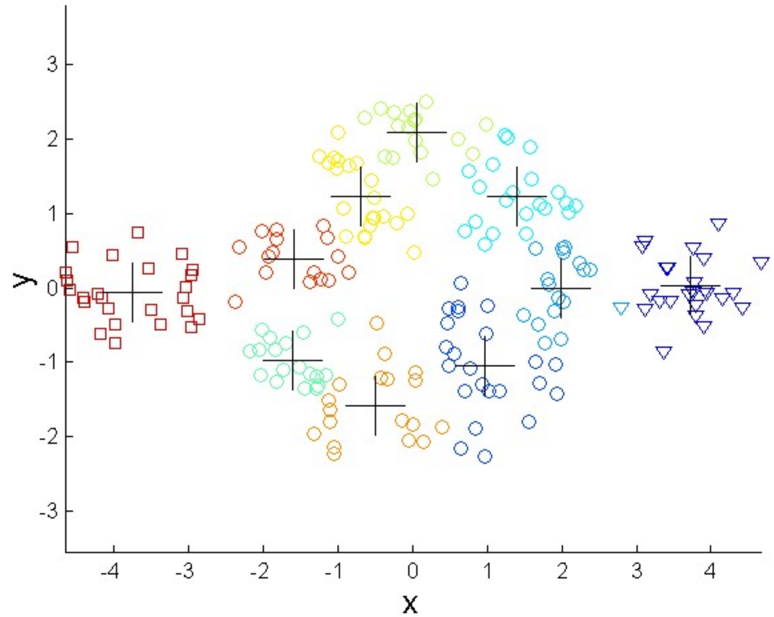
Original Points



K-means (2 Clusters)

Overcoming K-means Limitations

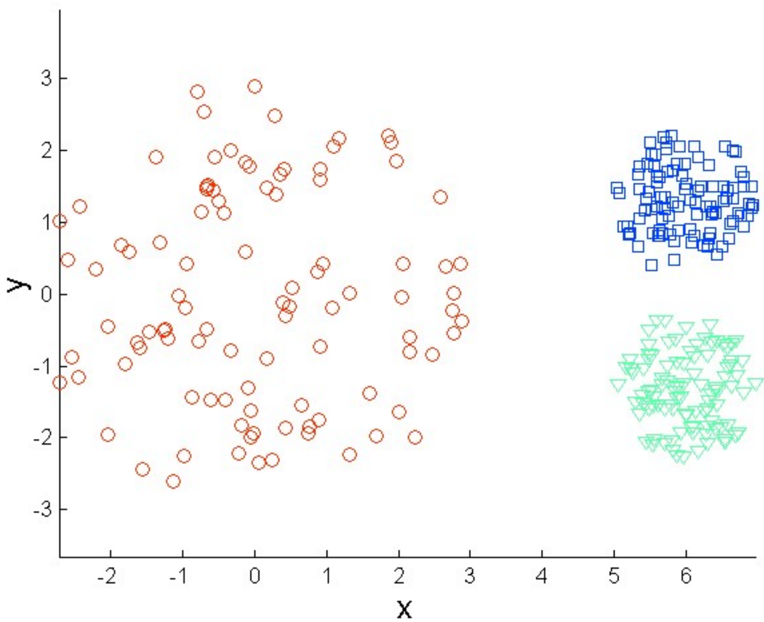




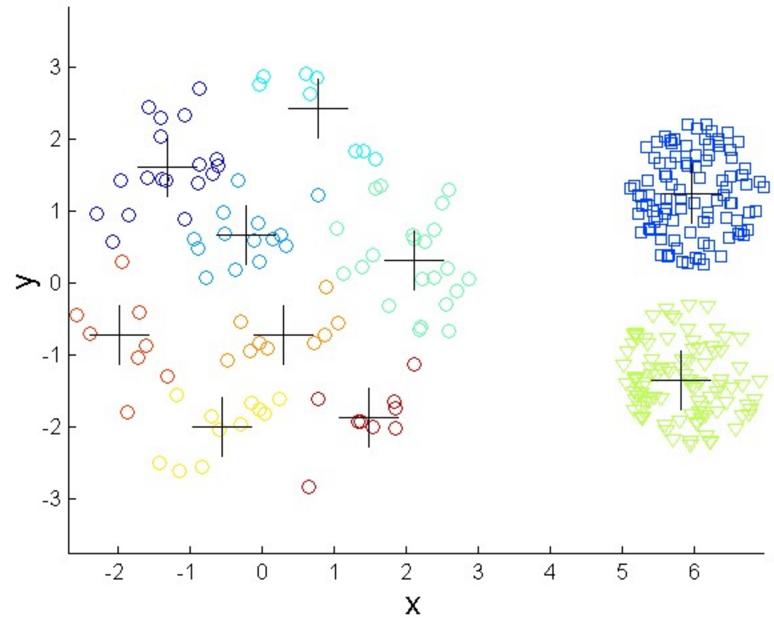
Original Points **K-means Clusters**

One solution is to use many clusters.
Find parts of clusters, but need to put together.

Overcoming K-means Limitations

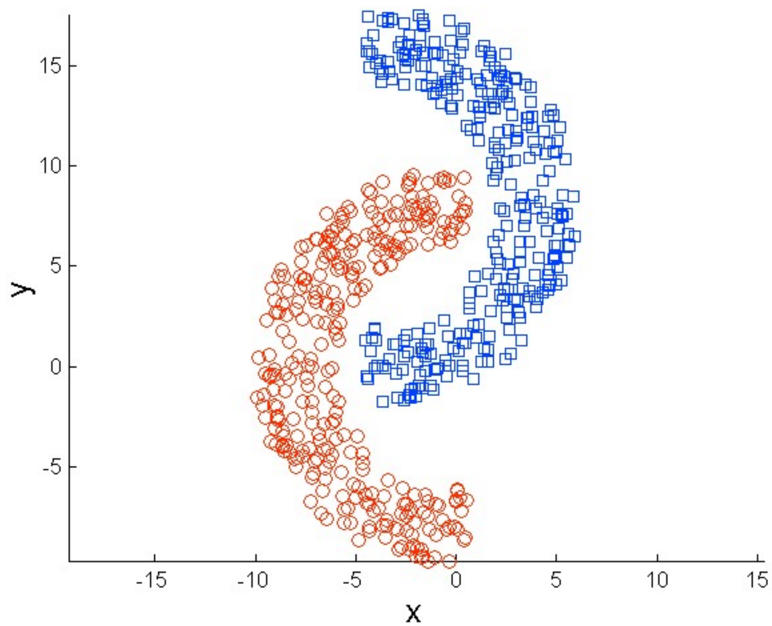


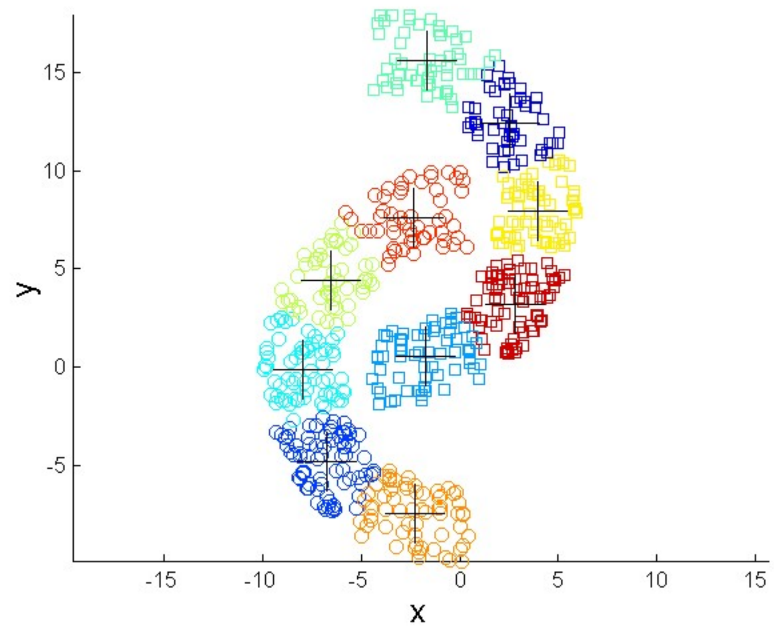
Original Points



K-means Clusters

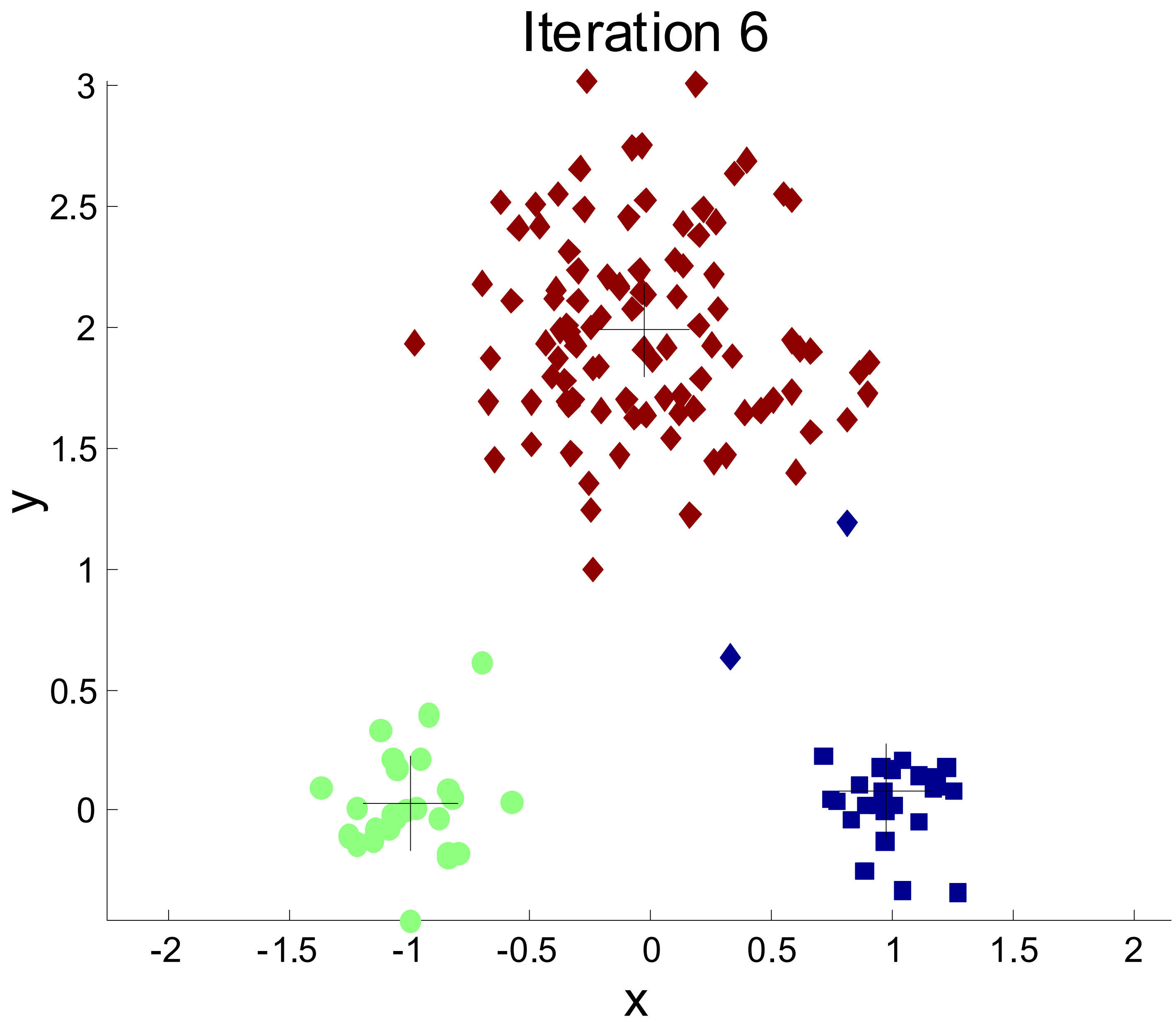
Overcoming K-means Limitations



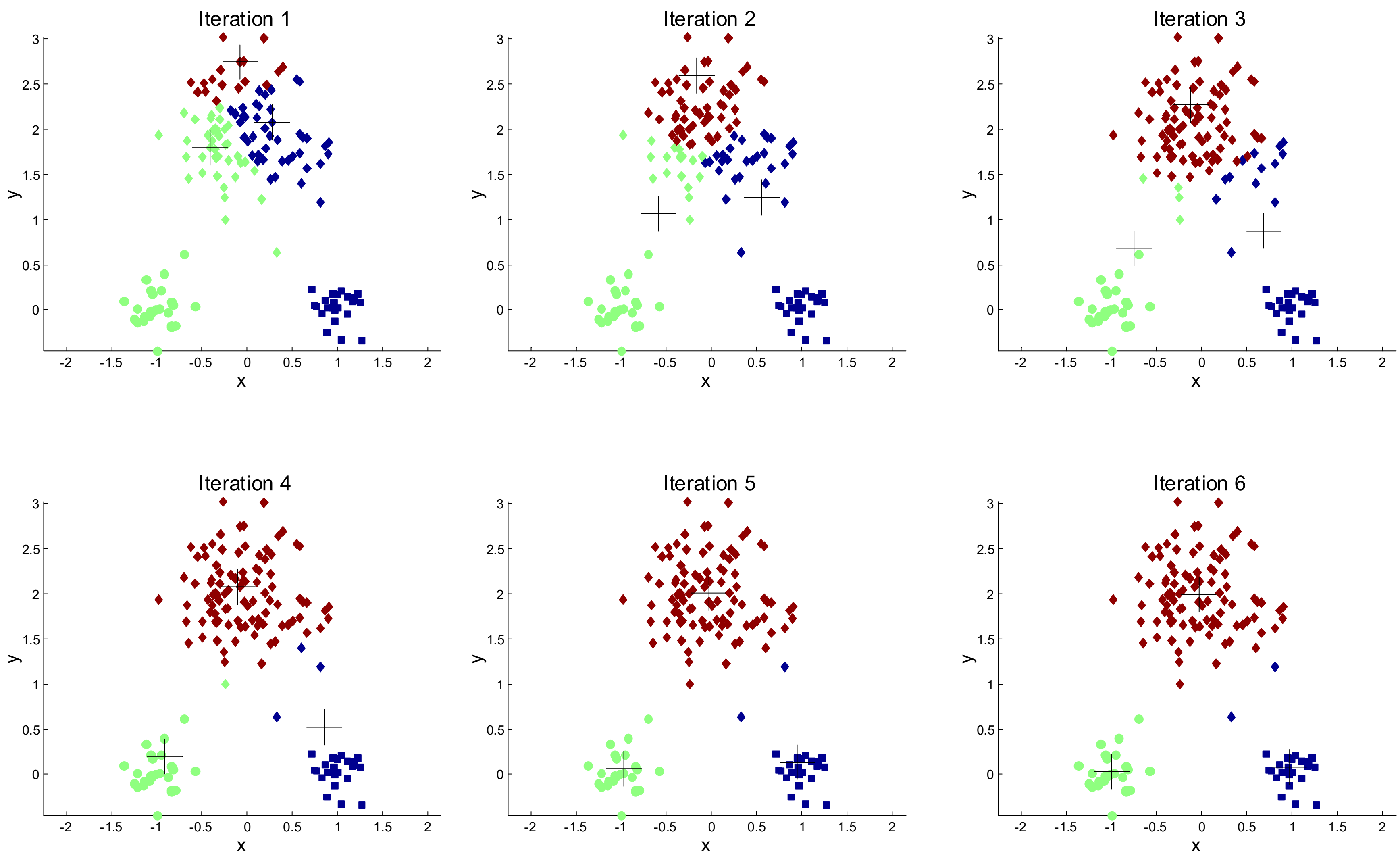


Original Points **K-means Clusters**

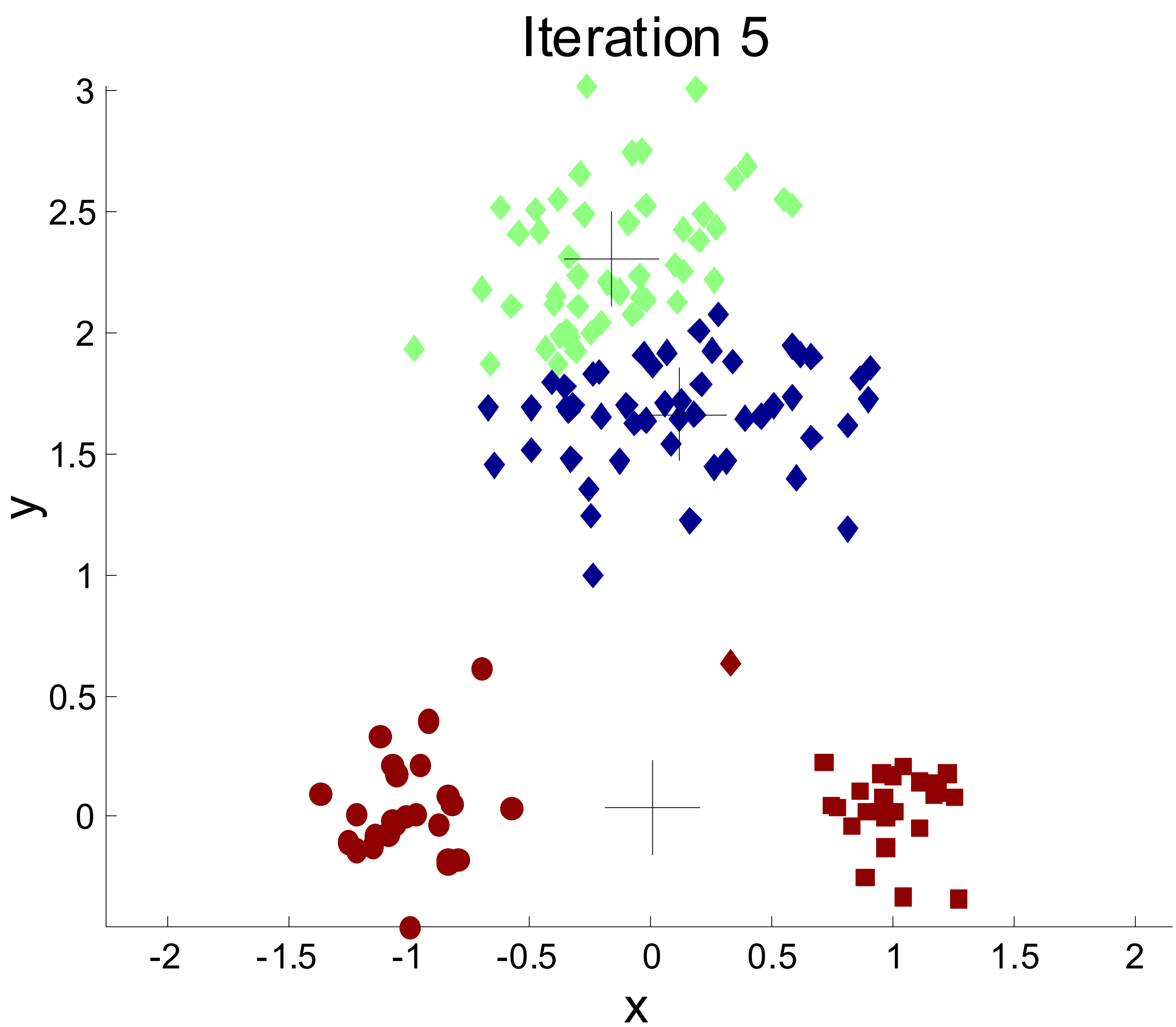
Importance of Choosing Initial Centroids



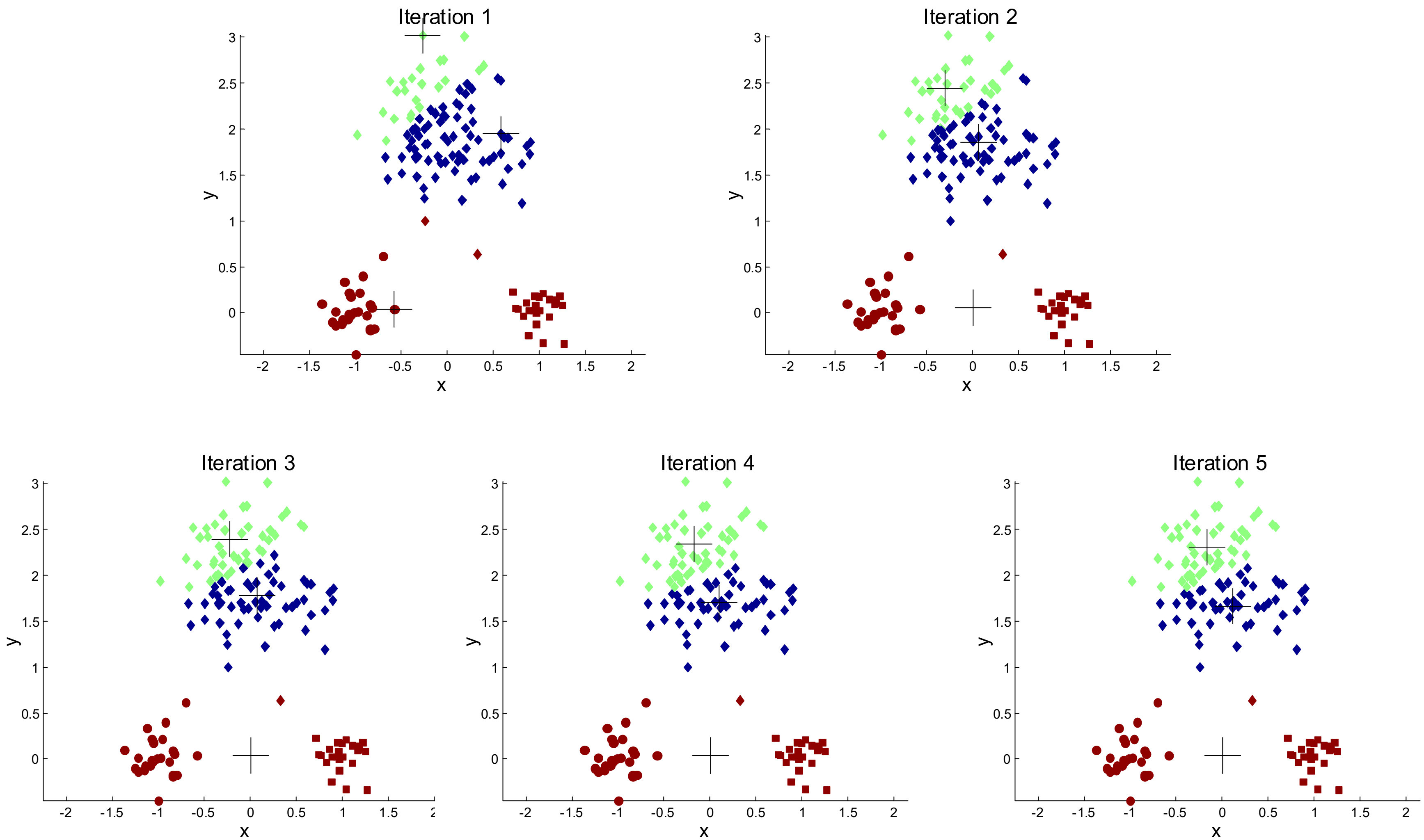
Importance of Choosing Initial Centroids



Importance of Choosing Initial Centroids …



Importance of Choosing Initial Centroids …



Problems with Selecting Initial Points

- If there are K 'real' clusters then the chance of selecting one centroid from each cluster is small.
  - Chance is relatively small when K is large
  - If clusters are the same size, n, then

$$P = \frac{\text{number of ways to select one centroid from each cluster}}{\text{number of ways to select } K \text{ centroids}} = \frac{K!n^K}{(Kn)^K} = \frac{K!}{K^K}$$

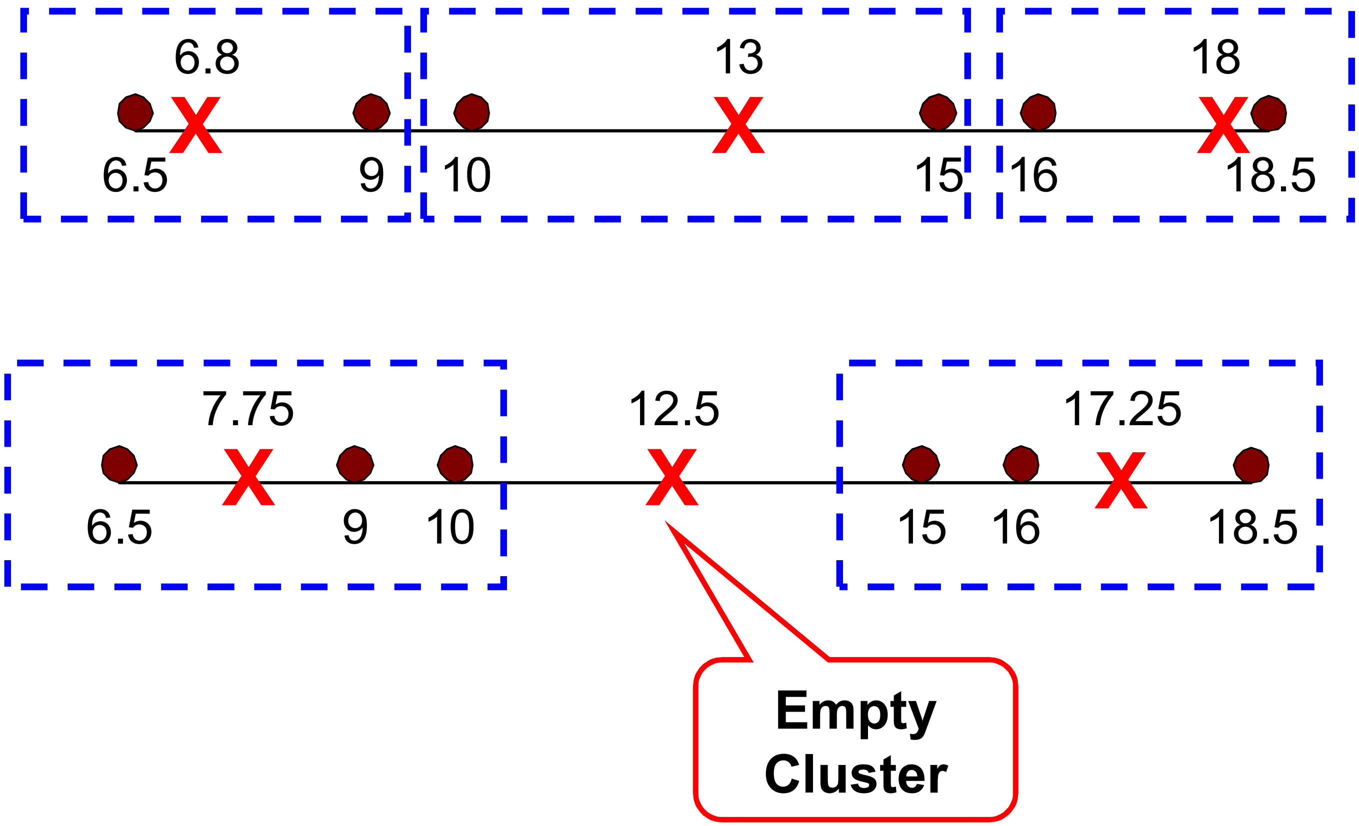
  - For example, if K = 10, then probability = $10!/10^{10}$ = 0.00036
  - Sometimes the initial centroids will readjust themselves in 'right' way, and sometimes they don't
  - Consider an example of five pairs of clusters

Solutions to Initial Centroids Problem

- Multiple runs
  - Helps, but probability is not on your side
- Sample and use hierarchical clustering to determine initial centroids
- Select **more than *k*** initial centroids and then select among these initial centroids
  - Select most widely separated
- Postprocessing
- Generate a larger number of clusters and then perform a hierarchical clustering
- Bisecting K-means
  - Not as susceptible to initialization issues

Empty Clusters

- K-means can yield empty clusters



Handling Empty Clusters

- Basic K-means algorithm can yield empty clusters

- Several strategies
  - Choose the point that contributes most to SSE
  - Choose a point from the cluster with the highest SSE
  - If there are several empty clusters, the above can be repeated several times.

Updating Centers Incrementally

- In the basic K-means algorithm, centroids are updated after all points are assigned to a centroid

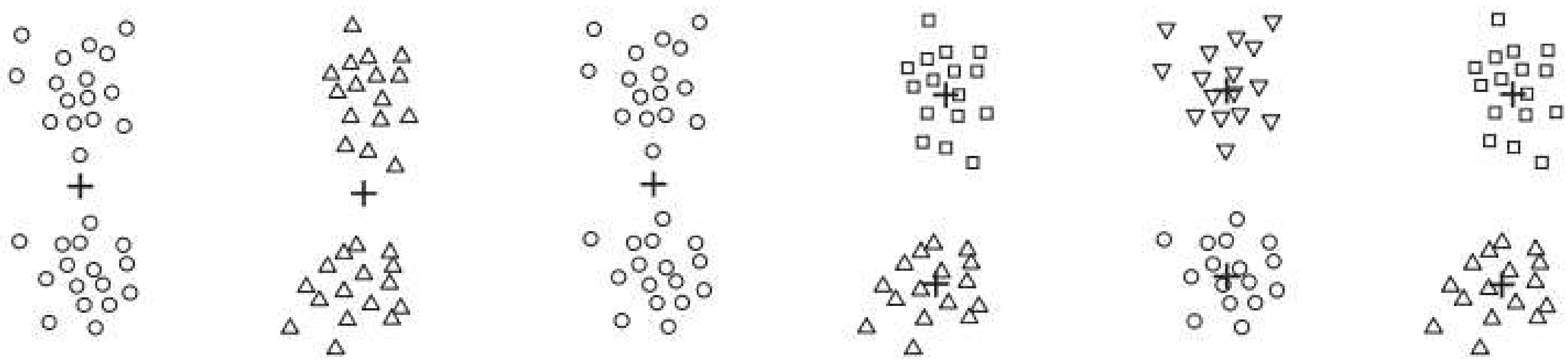
- An alternative is to update the centroids after each assignment (incremental approach)
  - Each assignment updates zero or two centroids
  - More expensive
  - Introduces an order dependency
  - Never get an empty cluster
  - Can use “weights” to change the impact

Bisecting K-means

Initialize the list of clusters to contain the cluster consisting of all points.
repeat
    Remove a cluster from the list of clusters.
    {Perform several "trial" bisections of the chosen cluster.}
    for $i = 1$ to $number\ of\ trials$ **do**
        Bisect the selected cluster using basic K-means.
    end for
    Select the two clusters from the bisection with the lowest total SSE.
    Add these two clusters to the list of clusters.
until The list of clusters contains K clusters.

- How to choose/select a cluster?
  - The largest cluster
  - Cluster with largest SSE
  - Other technique

Bisecting K-means



(a) Iteration 1. (b) Iteration 2. (c) Iteration 3.