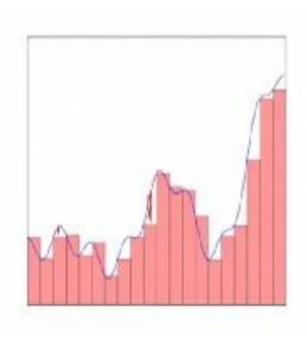
# Deep Learning

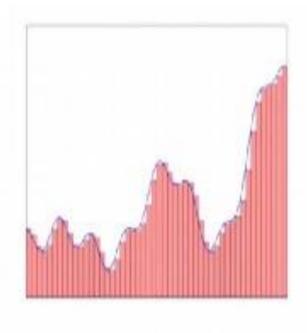
# Representative Power of Multilayer Networks

 A multilayer network of perceptrons with a single hidden layer can be used to approximate any Boolean function precisely

 A multilayer network of sigmoid neurons with a single hidden layer can be used to approximate any continuous function to any desired precision

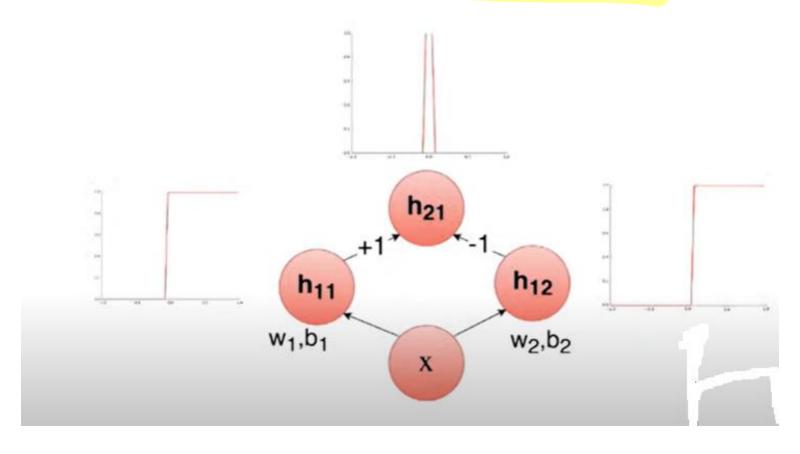
- For any function f(x):  $\mathbb{R}^n \to \mathbb{R}^m$ , we can find a network with enough neurons, whose output g(x) satisfies  $|g(x) f(x)| < \epsilon$
- Such an arbitrary function can be represented by several tower functions



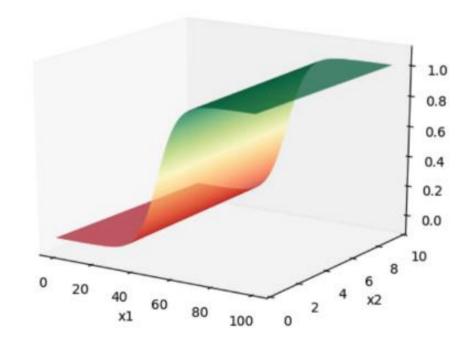


- All tower functions are similar and only differ in height and position on x-axis
- A black box takes some input and constructs a tower function
  - A network can add them up to approximate the function
- If we take the logistic function and set w to a very high value, we can recover step function
  - w controls the slope of the logistic function
- Can also adjust value of b to control position on xaxis at which function transitions from 0 to 1

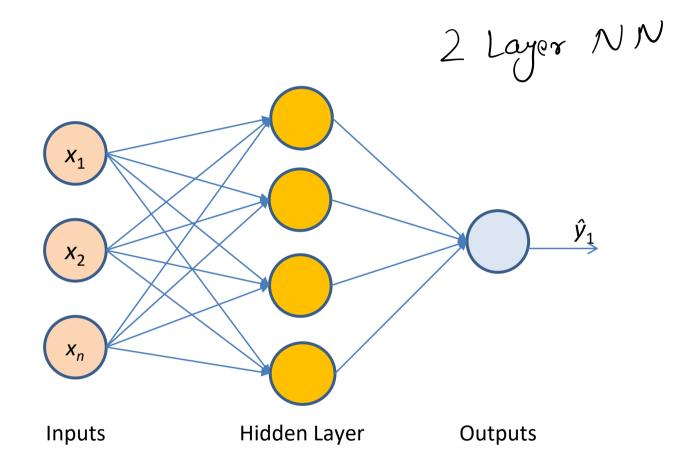
Take two such sigmoid functions, with different b's, and subtract them – will get a tower function



- More input parameters??
- Ex. 2 parameters

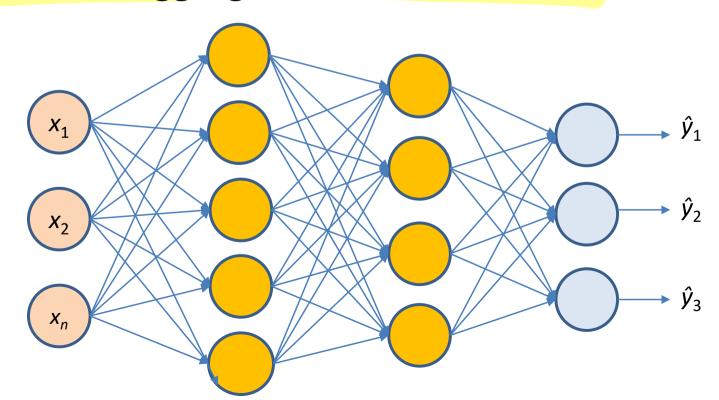


### Single Hidden Layer Neural Network

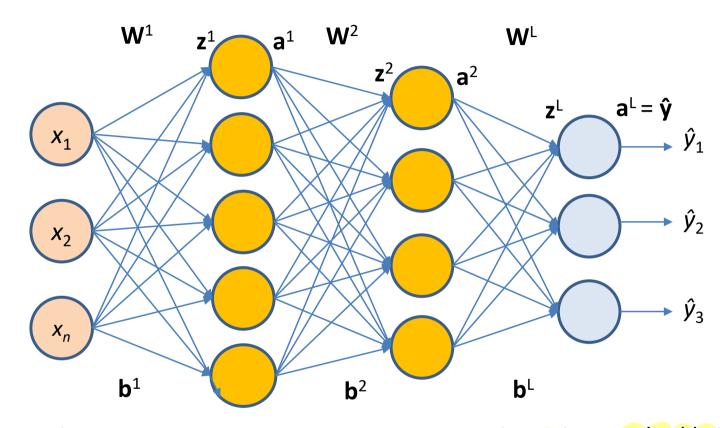


### Feedforward Neural Network

- Input is an n-dimensional vector (0<sup>th</sup> layer) ∈ R<sup>n</sup>
- Network has L-1 hidden layers
- 1 output layer containing k neurons (ex. for k classes)
- Each neuron aggregation and activation

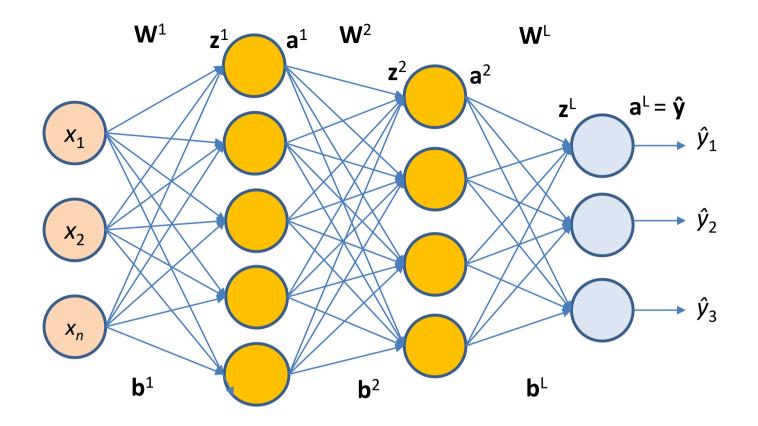


### Feedforward Neural Network



Assuming  $n^i$  neurons in hidden layer  $h^i$ ,  $W^i \in \mathbb{R}^{n(i-1)*ni}$  and  $b^i \in \mathbb{R}^{ni}$  between layers i -1 and i for 0 < i < L

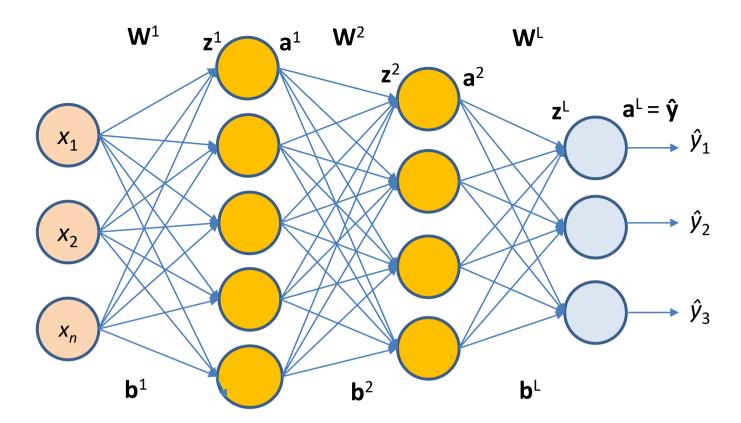
 $W^L \in \mathbb{R}^{ni^*k}$  and  $b^L \in \mathbb{R}^k$  between last hidden layer and output layer



Aggregation at layer  $i : \mathbf{z}^i = \mathbf{W}^i \mathbf{a}^{i-1} + \mathbf{b}^i$ 

For first hidden layer:  $\mathbf{z}^1 = \mathbf{W}^1 \mathbf{a}^0 + \mathbf{b}^1$ 

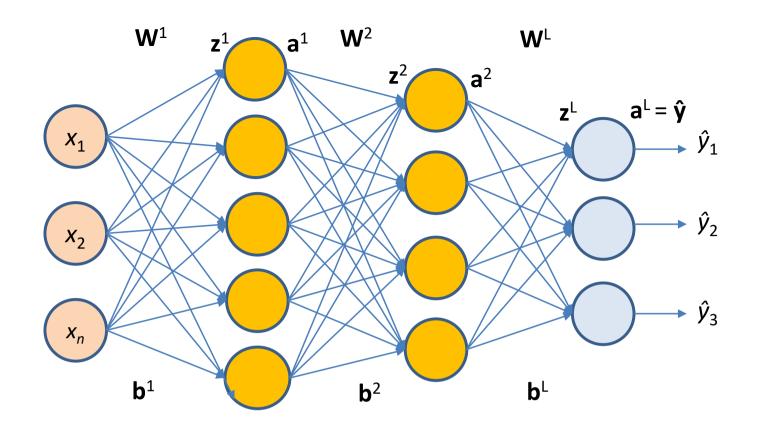
$$\begin{bmatrix} z_1^1 \\ z_2^1 \\ z_3^1 \end{bmatrix} = \begin{bmatrix} W_{11} & W_{12} & W_{13} \\ W_{21} & W_{22} & W_{23} \\ W_{31} & W_{32} & W_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} \sum W_{1i} x_i + b_1 \\ \sum W_{2i} x_i + b_2 \\ \sum W_{3i} x_i + b_3 \end{bmatrix}$$



Activation at layer  $i = g(\mathbf{z}^i) = g(\mathbf{b}^i + \mathbf{W}^i \mathbf{a}^{i-1})$ For first hidden layer:  $g(\mathbf{z}^1) = g(\mathbf{b}^1 + \mathbf{W}^1 \mathbf{a}^0)$ 

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = \begin{pmatrix} g(z_1) \\ g(z_2) \\ g(z_3) \end{pmatrix}$$

Eg.  $g(z_1) = \sigma(z_1) = 1 / (1 + e^{-z_1})$ g: activation function (logistic, tanh, linear etc.)



Aggregation at output layer  $L = z^{L} = \mathbf{W}^{L} \mathbf{a}^{L-1} + \mathbf{b}^{L}$ 

$$z_1 = w_{11}x_1 + w_{12}x_2 + w_{13}x_3 + b$$

$$z_2 = w_{21}x_1 + w_{22}x_2 + w_{23}x_3 + b$$

Activation at output layer  $L = \hat{\mathbf{y}} = g(z^L) = g(\mathbf{W}^L \mathbf{a}^{L-1} + \mathbf{b}^L)$ 

$$\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} g(z_1) \\ g(z_2) \end{pmatrix}$$

# Learning parameters

In given example, dimensions of parameters:

- $W^1: n^{1*}n$   $b^1:n^1$
- $W^2$ :  $n^2*n^1$   $b^2:n^2$
- $W^{L}$ :  $n^{2}*k$  **b**<sup>L</sup>:k
- Assuming L layers and n<sup>i</sup> neurons in hidden layer h<sup>i</sup>
  and k neurons in output layer, no. of parameters to
  be learned:
  - Weights:  $(L-1)*(n^{i-1}*n^i) + (n*k)$  for 0 < i < L
  - Bias:  $(L-1)*n^i + k$

## Learning parameters

- Data:  $\{x_i, y_i\}$  i = 1..m
- Model:

$$\hat{\mathbf{y}} = f(\mathbf{x}) = g(\mathbf{W}^3 g(\mathbf{W}^2 g(\mathbf{W}^1 \mathbf{x} + \mathbf{b}^1) + \mathbf{b}^2) + \mathbf{b}^3)$$
  
 $\hat{\mathbf{y}} = [\hat{y}^1 \quad \hat{y}^2 \dots \hat{y}^k]$ 

- Algorithm: Gradient Descent with back Propagation
- Loss/Error function: Sum of squared error loss

$$min \frac{1}{N} \sum_{i=1}^{m} \sum_{j=1}^{k} (\hat{y}_j^i - y_j^i)$$
 for  $i^{th}$  sample for all classes  $j$ 

## Learning parameters

#### Gradient Descent:

```
t:=0;  \begin{aligned} & max\_iterations \text{:=} 1000; \\ & \text{Initialize } \boldsymbol{\theta_0} \text{:=} [\mathbf{W^1}_0, ... \mathbf{W^L}_0, \, \mathbf{b^1}_0 \, ... \, \mathbf{b^L}_0]; \\ & \text{while } t\text{++} < & max\_iterations \text{ do} \\ & \boldsymbol{\theta_{t+1}} \text{:=} \boldsymbol{\theta_t} - \eta \nabla \boldsymbol{\theta_t}; \\ & \text{end} \end{aligned}
```

where, 
$$\nabla \theta_t = \left[ \frac{\partial L(\theta)}{\partial W_t}, \frac{\partial L(\theta)}{\partial b_t} \right]^T$$

#### $\nabla\theta$ composed of:

- $-\nabla W^{1}$ ,  $\nabla W^{2}$ ,... $\nabla W^{L-1} \in R^{n(i-1)xni}$ ,  $\nabla W^{L} \in R^{nxk}$
- $-\nabla b^1$ ,  $\nabla b^2$ ,...  $\nabla b^{L-1} \in \mathbb{R}^{ni}$ ,  $\nabla b^L \in \mathbb{R}^k$

- Loss function should capture how much  $\hat{y}_i$  deviates from  $y_i$
- $y_i \in \mathbb{R}^n$  then squared error loss can be used:

$$L(\theta) = (1/N)^* \sum (y_i - \hat{y}_i)^2$$

Problems with squared error loss:

$$\frac{\partial L(w,b)}{\partial w} = (\hat{y} - y) * \hat{y}*(1-\hat{y})*x$$

**Undesirable** 

- If 
$$y_i = 1$$
 and  $\hat{y}_i \sim 0$ ,  $\frac{\partial L(w,b)}{\partial w} \sim 0$ 

- If 
$$y_i = 0$$
 and  $\hat{y}_i \sim 1$ ,  $\frac{\partial L(w,b)}{\partial w} \sim 0$  Undesirable

Weight updation becomes very slow

- Information content (IC):
  - Events with high probability have low information content
    - "The sun will rise tomorrow"
  - Events with low probability have high information content
    - "There will be a cyclone tomorrow"
- $IC(A) = -\log_2(p(A))$
- Entropy: Expected information content =  $\sum p_i * IC(i)$

$$= -\sum p_i \log_2(p_i)$$

```
Entropy: y_i = \begin{bmatrix} 0 & 1 & 0 & 0 \end{bmatrix} //Team B wins game \hat{y}_i = \begin{bmatrix} 0.2 & 0.1 & 0.4 & 0.3 \end{bmatrix} //Our prediction 10K 5K 8K 1K //Profit for each team win Expected profit??
```

• Entropy: Expected information content =  $\sum p_i IC(i)$ =  $-\sum p_i \log_2(p_i)$ 

- Cross-entropy: gives a measure on how close a predicted distribution is to a true distribution
  - True distribution  $p_i$ , Estimated distribution  $q_i$
  - Estimated information content =  $-\sum p_i \log_2(q_i)$
  - Capture difference between two probability distributions
  - If prediction is close to actual, cross entropy will be low

$$L(\theta) = -\sum y_c \log_2(\hat{y}_c)$$
 for all  $k$  classes  
 $y_c = 1$  if  $c = t$  (true class)  
 $= 0$  otherwise  
 $L(\theta) = -\log_2(\hat{y}_t)$ 

- Objective function for classification:
  - Cross-entropy Loss

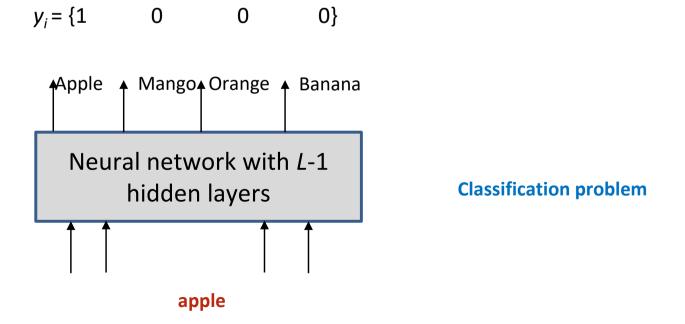
```
minimize: L(\theta) = -\log_2(\hat{y}_t)
```

 $\hat{y}_t$ : predicted probability of correct event

 $\log_2(\hat{y}_t)$ : probability that x belongs to  $t^{\text{th}}$  class, log-likelihood of data

### Output and Loss function

- Output activation function:
  - Sum of outputs should be 1
  - $-\hat{y}$  should be a probability distribution
  - Sigmoid probabilities will be 0<p<1 but sum not equal to 1</li>



### **Output Activation Function**

Softmax function

$$z^{L} = b^{L} + W^{L} a^{L-1}$$

$$\hat{y} = g(z^{L}_{j}) = e^{z}_{j} / \sum e^{z}_{j} \qquad \text{for } j = 1..k$$

$$z^{L}_{j} \text{ is } j^{\text{th}} \text{ element of } z^{L}$$

• Example:  $z^L = \begin{bmatrix} 10 & 20 & -30 \end{bmatrix}$  $\hat{y} = \begin{bmatrix} e^{10}/(e^{10} + e^{20} + e^{-30}) & e^{20}/(e^{10} + e^{20} + e^{-30}) & e^{-30}/(e^{10} + e^{20} + e^{-30}) \end{bmatrix}$ 

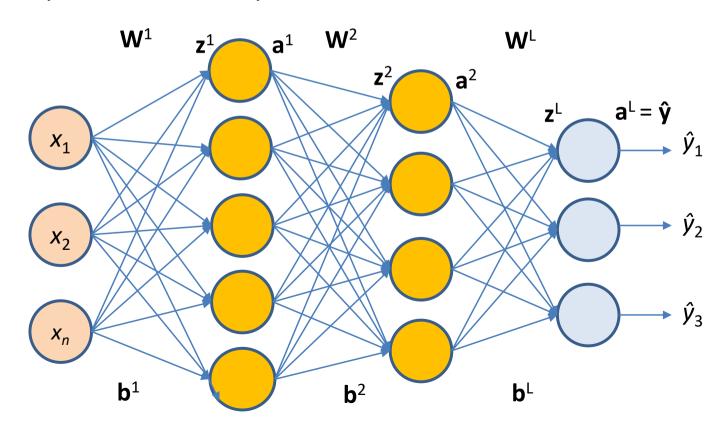
NOTE: Exponent converts –ve values to +ve values

	Outputs	
	Real values	Probabilities
Output activation	Linear	Softmax
Loss function	Squared error	Cross-entropy

## Backpropagation

How to compute  $\nabla\theta$  composed of:

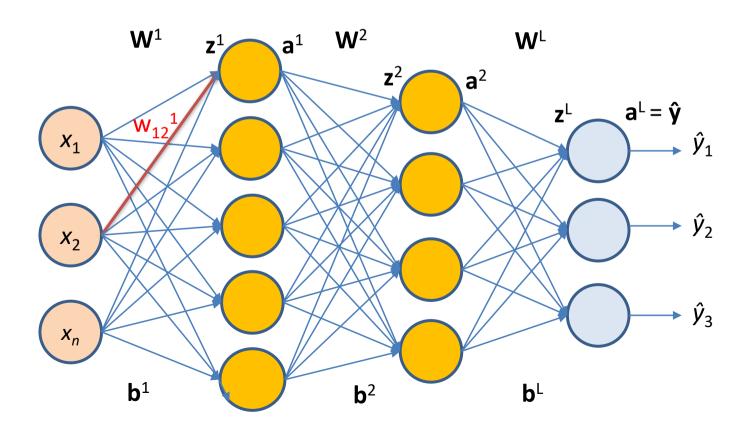
 $\nabla W^1$ ,  $\nabla W^2$ ,...  $\nabla W^{L-1} \in R^{nxn}$ ,  $\nabla W^L \in R^{nxk}$  $\nabla b^1$ ,  $\nabla b^2$ ,...  $\nabla b^{L-1} \in R^n$ ,  $\nabla b^L \in R^k$ 



# Backpropagation

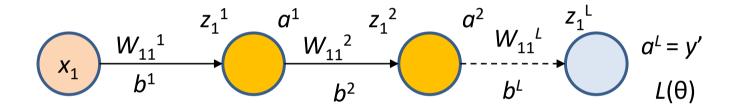
Assuming classification problem,  $L(\theta) = -\log_2(\hat{y}_t)$ 

• To learn weight  $w_{12}^{-1}$  use SGD and compute  $\frac{\partial L(w,b)}{\partial W_{12}}$ 



# Backpropagation

Assume a deep thin network, who is responsible for the loss??



Find derivative by chain rule:

$$\frac{\partial L(\theta)}{\partial W_{11}^{1}} = \frac{\partial L(\theta)}{\partial \hat{y}} * \frac{\partial \hat{y}}{\partial z_{1}^{L}} * \frac{\partial z_{1}^{L}}{\partial a_{1}^{2}} * \frac{\partial a_{1}^{2}}{\partial z_{1}^{2}} * \frac{\partial z_{1}^{2}}{\partial a_{1}^{1}} * \frac{\partial a_{1}^{1}}{\partial z_{1}^{1}} * \frac{\partial z_{1}^{1}}{\partial W_{11}^{1}}$$
Output layer
$$\frac{\partial L(\theta)}{\partial z_{1}^{L}} * \frac{\partial z_{1}^{L}}{\partial z_{1}^{2}} * \frac{\partial z_{1}^{2}}{\partial z_{1}^{2}} * \frac{\partial z_{1}^{2}}{\partial z_{1}^{1}} * \frac{\partial z_{1}^{1}}{\partial z_{1}^{1}} * \frac{\partial z_{1}^{1}}{\partial W_{11}^{1}}$$
Output layer
$$\frac{\partial L(\theta)}{\partial z_{1}^{L}} * \frac{\partial z_{1}^{L}}{\partial z_{1}^{2}} * \frac{\partial z_{1}^{2}}{\partial z_{1}^{2}} * \frac{\partial z_{1}^{2}}{\partial z_{1}^{1}} * \frac{\partial z_{1}^{1}}{\partial z_{1}^{1}} * \frac{\partial z_{1}^{1}}{\partial W_{11}^{1}}$$
Output layer
$$\frac{\partial L(\theta)}{\partial z_{1}^{L}} * \frac{\partial z_{1}^{L}}{\partial z_{1}^{2}} * \frac{\partial z_{1}^{2}}{\partial z_{1}^{2}} * \frac{\partial z_{1}^{2}}{\partial z_{1}^{1}} * \frac{\partial z_{1}^{1}}{\partial z_{1}^{1}} * \frac{\partial z_{1}^{1}}{\partial W_{11}^{1}}$$
Output layer

If we change W<sub>11</sub>, how much does the loss change

$$L = -y \log \hat{g} - (1-y) \log (1-\hat{g})$$

$$\frac{\partial L}{\partial \hat{g}} = -\frac{y}{\hat{g}} + \frac{1-y}{1-\hat{g}}$$

$$\frac{\partial \hat{g}}{\partial \hat{g}} = \mathcal{J}(1-\mathcal{G}(2))$$

$$\frac{\partial L}{\partial z} = \hat{g}(1-\hat{g})$$

$$\frac{\partial L}{\partial z} = \hat{g}(1-\hat{g})$$

$$\frac{\partial L}{\partial z} = \hat{g}(1-\hat{g}) + \hat{g}(1-y)$$

$$= -y(1-\hat{g}) + \hat{g}(1-y)$$

$$= -y$$

$$= \hat{g}-y$$

$$\frac{\partial L}{\partial w} = \frac{\partial L}{\partial y} \times \frac{\partial y}{\partial z} \times \frac{\partial z}{\partial w}$$
$$= (\ddot{y} - y) x.$$

$$\frac{\partial L}{\partial \alpha'} = \frac{\partial L}{\partial \dot{y}} \times \frac{\partial \dot{y}}{\partial \dot{\alpha'}} \times \frac{\partial z^2}{\partial \alpha'}$$

$$\Rightarrow 2^2 = (\hat{y} - y) \times \omega^2$$

$$= (\hat{y} - y) \times \omega^2$$

$$\frac{\partial L}{\partial z'} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z^2} \times \frac{\partial z^2}{\partial a_f} \times \frac{\partial a'}{\partial z'}$$

$$\frac{\partial L}{\partial w_{1}^{2}} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial z} \times \frac{\partial z}{\partial w}$$

$$\frac{\partial L}{\partial \hat{y}} = \frac{-y}{y} + \frac{1-y}{1-\hat{y}} = -4$$

$$\frac{\partial L}{\partial z} = \frac{\partial L}{\partial \hat{y}} \times \frac{\partial \hat{y}}{\partial \hat{z}} = \hat{y} - y = -0.75$$

$$\frac{\partial L}{\partial w} = (-0.75)(0.37) = -0.2775$$

$$w_{11}^{2} = w_{11}^{2} - y \times \frac{\partial L}{\partial w_{11}^{2}} = 12 - 0.00(-0.2775)$$

$$\frac{\partial L}{\partial w_{ii}^{2}} = \frac{\partial L}{\partial y^{2}} \times \frac{\partial \hat{y}}{\partial z_{i}^{2}} \times \frac{\partial z_{i}^{2}}{\partial a_{i}^{2}} \times \frac{\partial a_{i}^{2}}{\partial w_{ii}^{2}}$$

$$= -0.75 \times 12 \times 0.5 (1-0.5) \times 6$$

$$= -135$$

Homowork

DL =