

Project for the Agent Systems course



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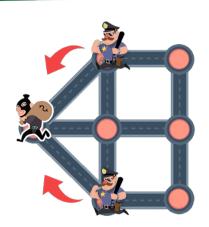
1 Introduction

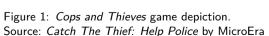


Introduction

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Cops And Thieves (cops and robbers) is a strategic pursuit-and-evasion game where two opposing agent types operate in a shared environment. Thieves aim to evade capture, while cops patrol, chase, and arrest thieves to maintain order. The game mechanics involve agent coordination, pathfinding, and adaptive decision-making.







Motivation

Comparison of other approach for a problem considered previously on engineering studies course *Development Workshop*. Our project – *Chase model* – was also implementation of the cops and thieves game. This project aims to hopefully improve our earlier attempt.

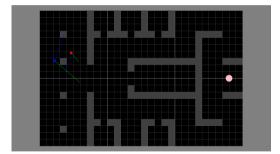


Figure 2: Chase model – game area.

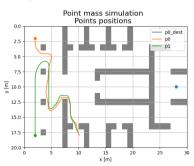


Figure 3: *Chase model* – movement chart.







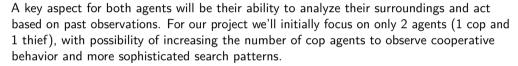
Figure 4: We are back

As depicted in fig. 4, we are back to face the challenge of the cops and thieves problem, but this time with a different approach.

Goal

The main goal of this project is to train *environment-agnostic* agents:

- *Cops*: search and chase the thief.
- *Thief*: hide and try not to get caught.



We expect to achieve the following behaviors from agents:

Agent Type	Expected Description
Cop	Search and chase (if more cops, cooperation)
Thief	Evade capture and hide efficiently



Technological Stack

In our project we intend to use the following frameworks:

- skrl (fig. 5) for MARL implementation.
- Gymnasium (fig. 6) to guarantee MARL environment standards.
- pymunk (fig. 7) as 2D physics engine, complemented by:
 - pygame (fig. 8) for visualization.







Figure 7: pymunk logo



Figure 8: pygame logo

Figure 5: skrl logo

Figure 6: Gymnasium logo

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Thank you for your attention



Questions?