ENV

python3 -m venv venv/ source venv/bin/activate pip install -r requirements.txt

Lab 1

Lab 1 decision trees

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Assignment 0

The hardest set to classify is MONK-2 since it can't be efficiently mapped by a decision tree whilst MONK-1 and MONK-3 can be. We need 2 element to exclusively be equal to 1 which is essentially the XOR problem, which is aknow hard problem for descision trees scikit.

Assignment 1

Monk	Entropy
MONK 1	1
MONK 2	0.957117428264771
MONK 3	0.9998061328047111

Assignment 2

high entropy = low predictability low entropy = high predictability

In uniform distribution, all cases has an equal probability, this makes it hard to predict the outcome. This will result in a low predictability and therefore a high entropy. In non-uniform distributions, some cases will have higher chance of happening, which result in a possibility to predict these higher probable outcomes. Therefore, a non-uniform distribution is more predicable and will result in low entropy.

An example for a high entropy would be a fair die. Whilst an example of a distribution with low entropy would be a normal gaussian distribution.

Assignment 3

Dataset	a1	a2	a3	a4	a5	a6
Monk-1	0.0753	0.0058	0.0047	0.0263	0.287	0.0008
Monk-2	0.0038	0.0025	0.0011	0.0157	0.0173	0.0062
Monk-3	0.0071	0.2937	0.0008	0.0029	0.2559	0.0071

Monk 1: Max attribute 5 gain: 0.287

Monk 2: Max attribute 5 gain: 0.0173

Monk 3: Max attribute 2 gain: 0.2937

For Monk 1 we choose attribute 5, for Monk 2 attribute 5 and for Monk 3 attribute 2. This based on the information gain, which these attributes maximizes.

Assignement 4

When the information gain is maximized, the entropy for the subset S_k is low compared to the entropy of the current node.

This means when maximizing the information gain we are searching for the path (subset) which gives us the largest difference in entropy, meaning that we choose to enter the path which gives us the highest amount of predictability for future guesses. We're actively minimizing the entropy by maximizing the gain in each tree node. This is preciesly why it's a good heuristic. It locally searches for the best path down the decision tree which is the attribute we want to choose.

Assignment 5

Manual tree vs buildTreee()

Split 1: Attribute 5
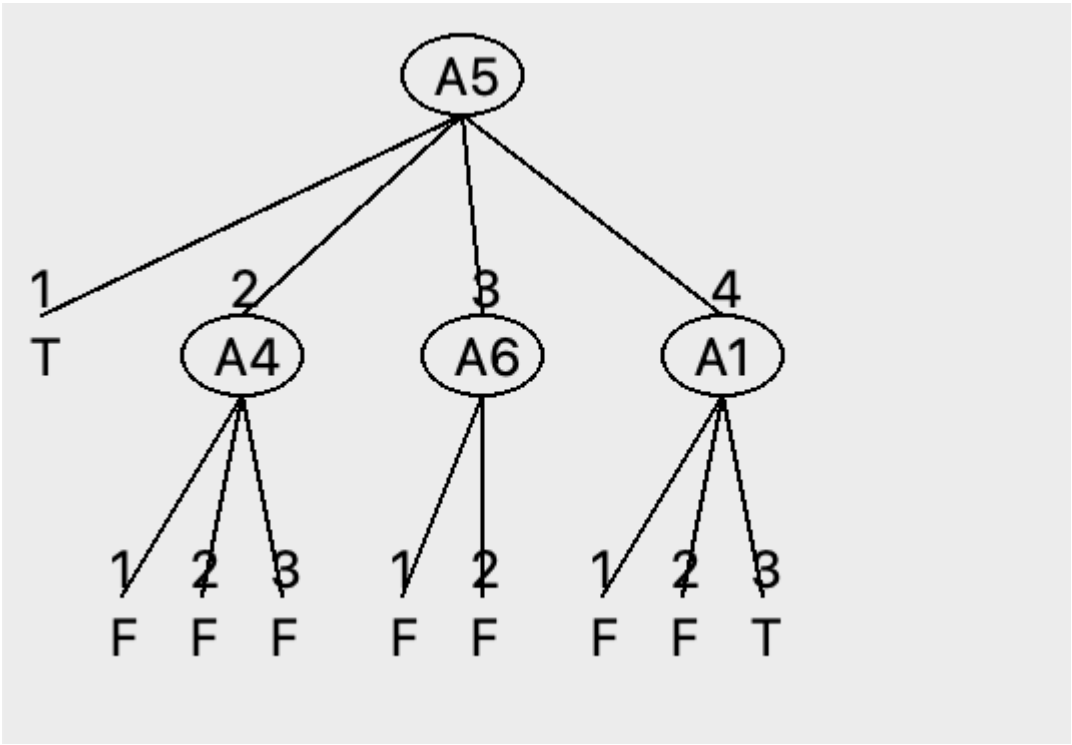
Max gain for value 1: attribute 1

Max gain for value 2: attribute 4

Max gain for value 3: attribute 6

Max gain for value 4: attribute 1

So for the value 1 node, we should select attribute 1, for value node 2 attribute 4, for value node 3 attribute 6 and for value node 4 attribute 1.

```
Max for sample 1: attribute 1
Majority class for sample 1: True
Max for sample 2: attribute 4
Majority class for sample 2: False
Max for sample 3: attribute 6
Majority class for sample 3: False
Max for sample 4: attribute 1
Majority class for sample 4: False
```

Using buildTree()

Monk	E_{train}	E_{test}
MONK 1	1.0	0.8287037037037037
MONK 2	1.0	0.6921296296296297
MONK 3	1.0	0.9444444444444444

As our hypthesis in **Assignment 0**, the Monk 2 will be the hardest problem for a descision tree algorithm to solve which aligns with the test performance shown above.

It also shows that the build tree can correctly map all of the training data which is why its accuracy is 100%.

Assignemnt 6

By pruning we will remove one or more nodes in the tree, this will decrease the varaince of the results. This will according to the bias-variance trade-off lead to increased bias, making the training more generlised for the validation and testing data. However, it still tells that the model has something "wrong" since bias indicates that we need to adjust for something which necessarily isn't there, it's a value we've created to adjust to the uncertainity in the model.

Assignment 7

Model test performance with varying validation fractions